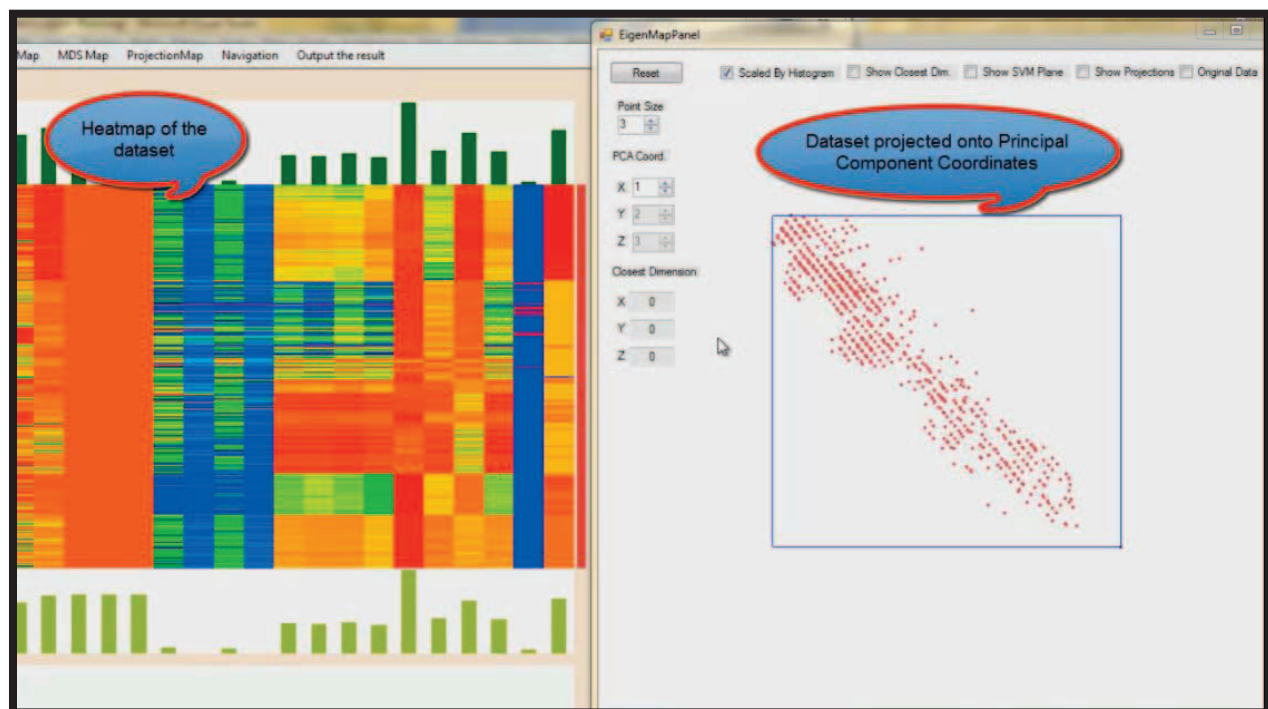
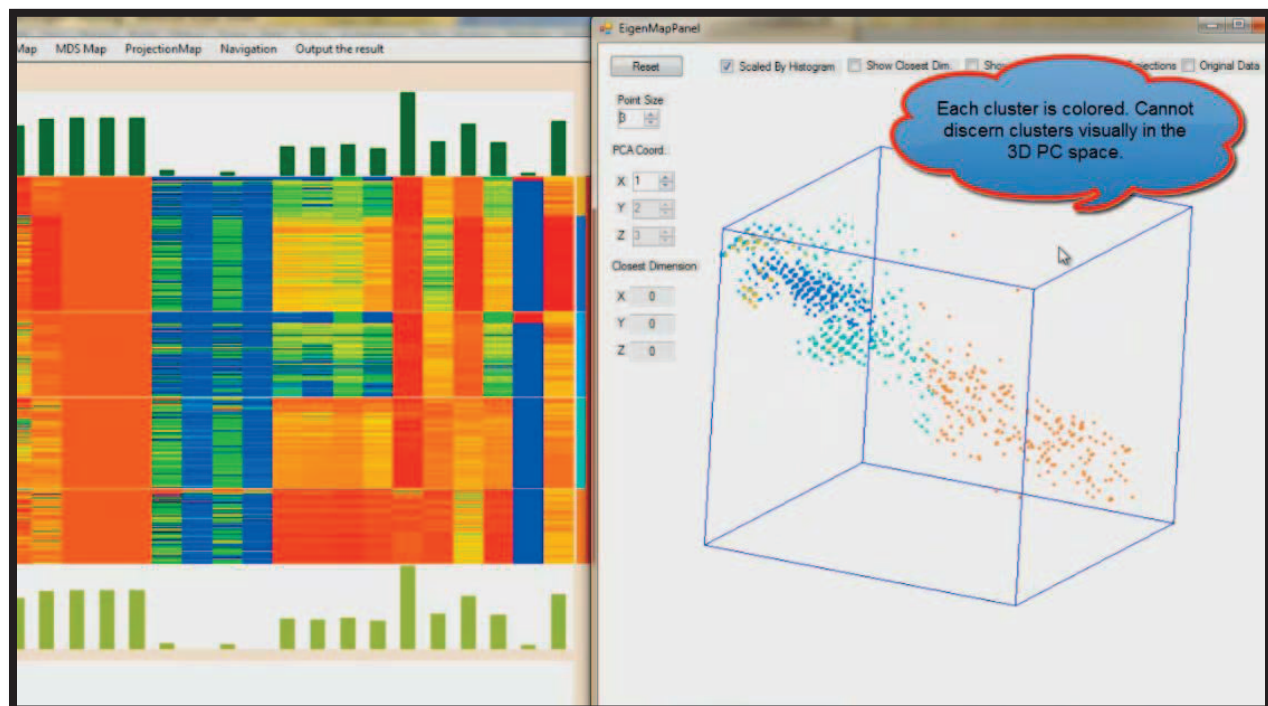
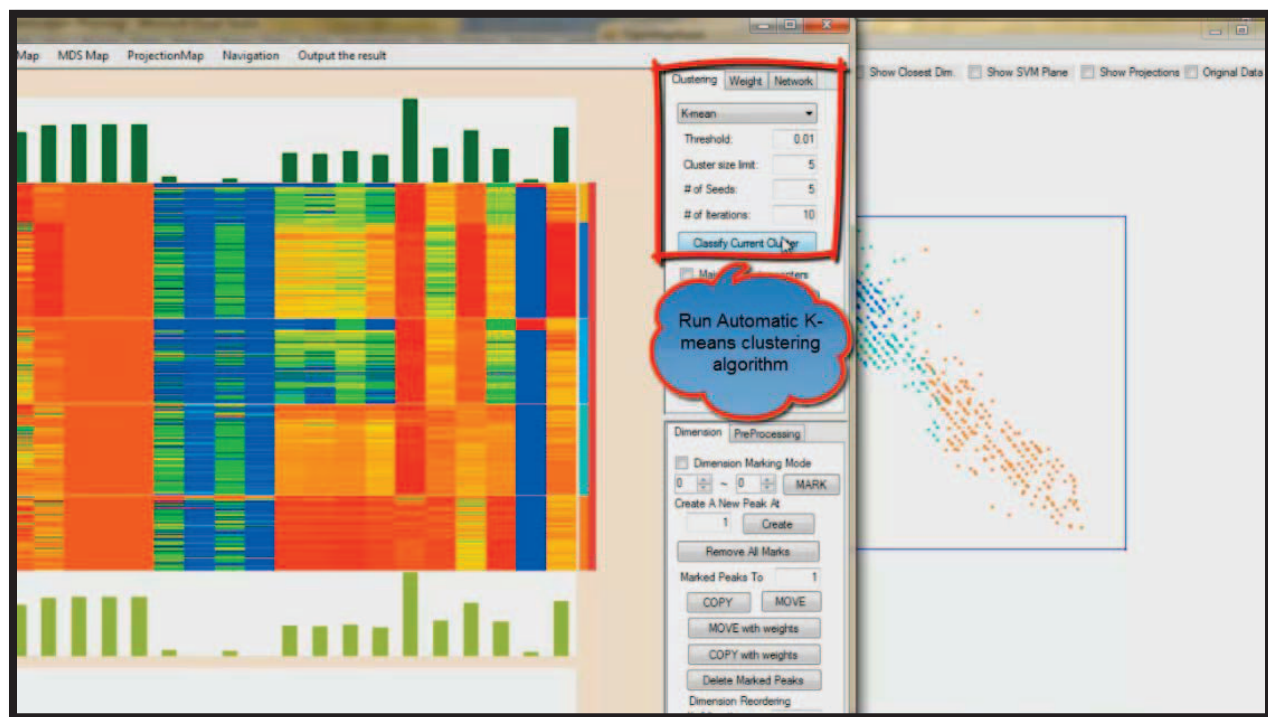
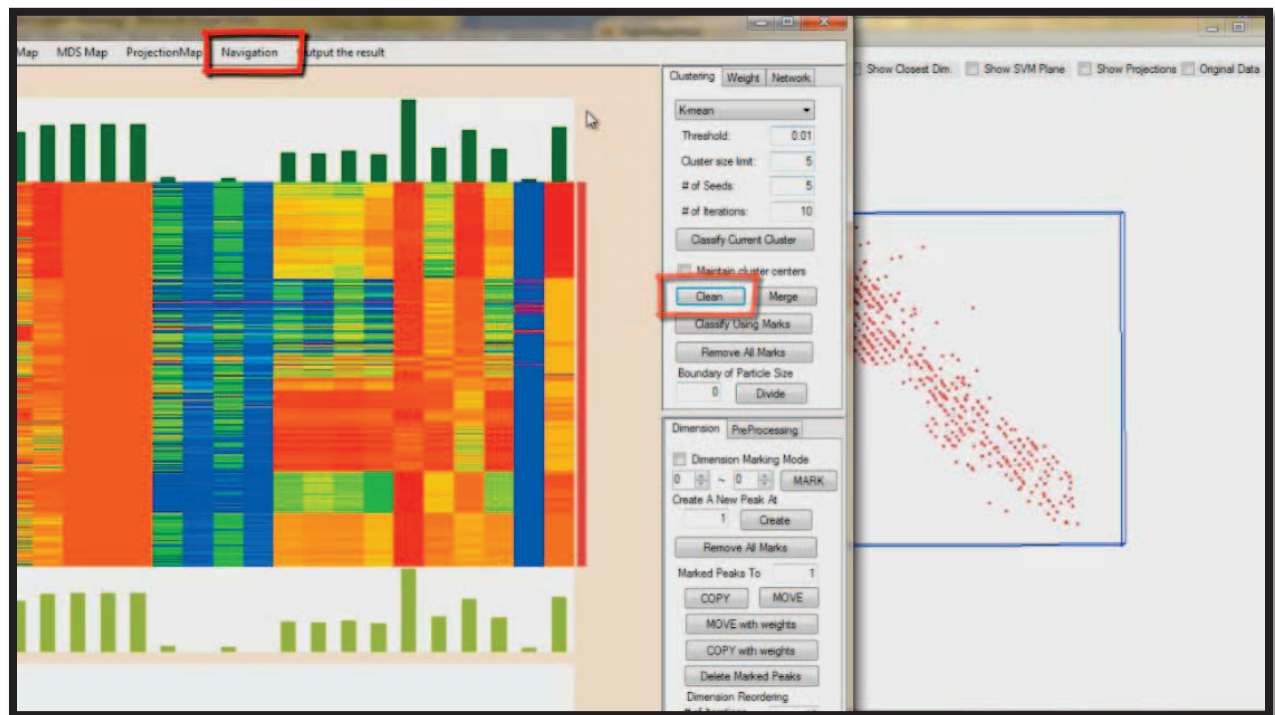


TripAdvisor N-D : A Photo-Tourism Inspired High-Dimensional Space Exploration Framework with Overview and Detail

Julia EunJu Nam, Klaus Mueller
Stony Brook University



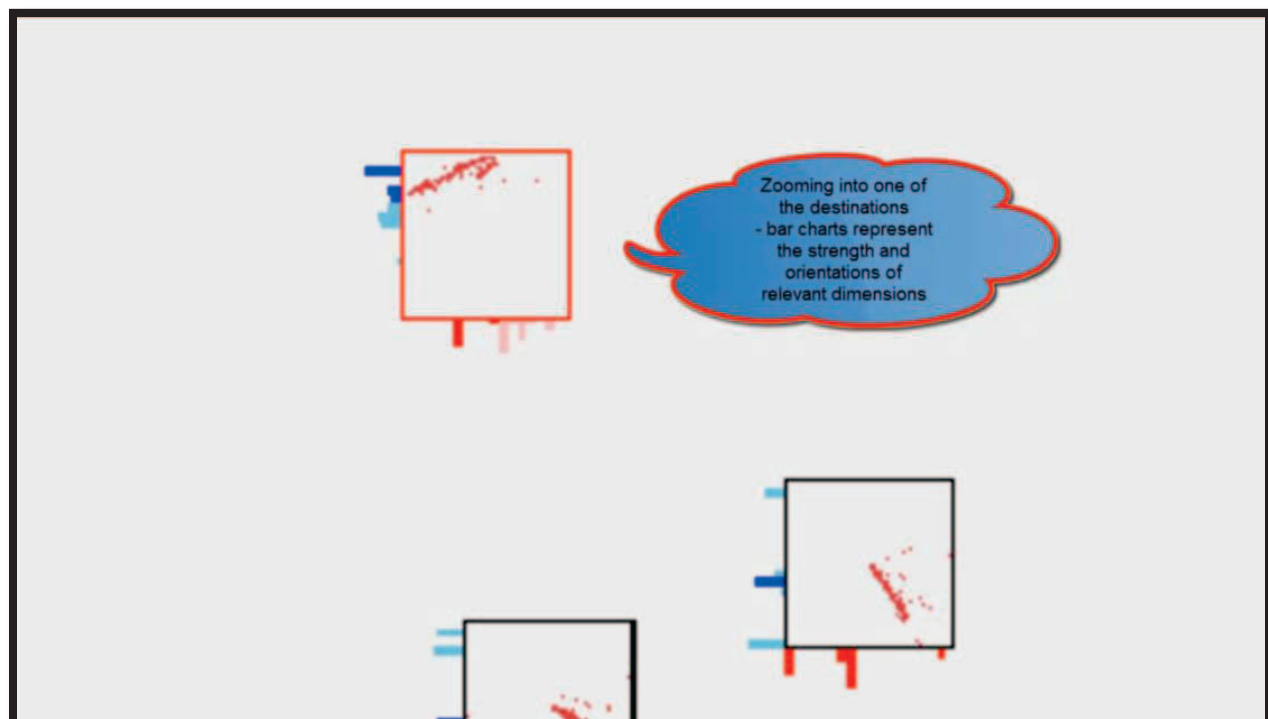
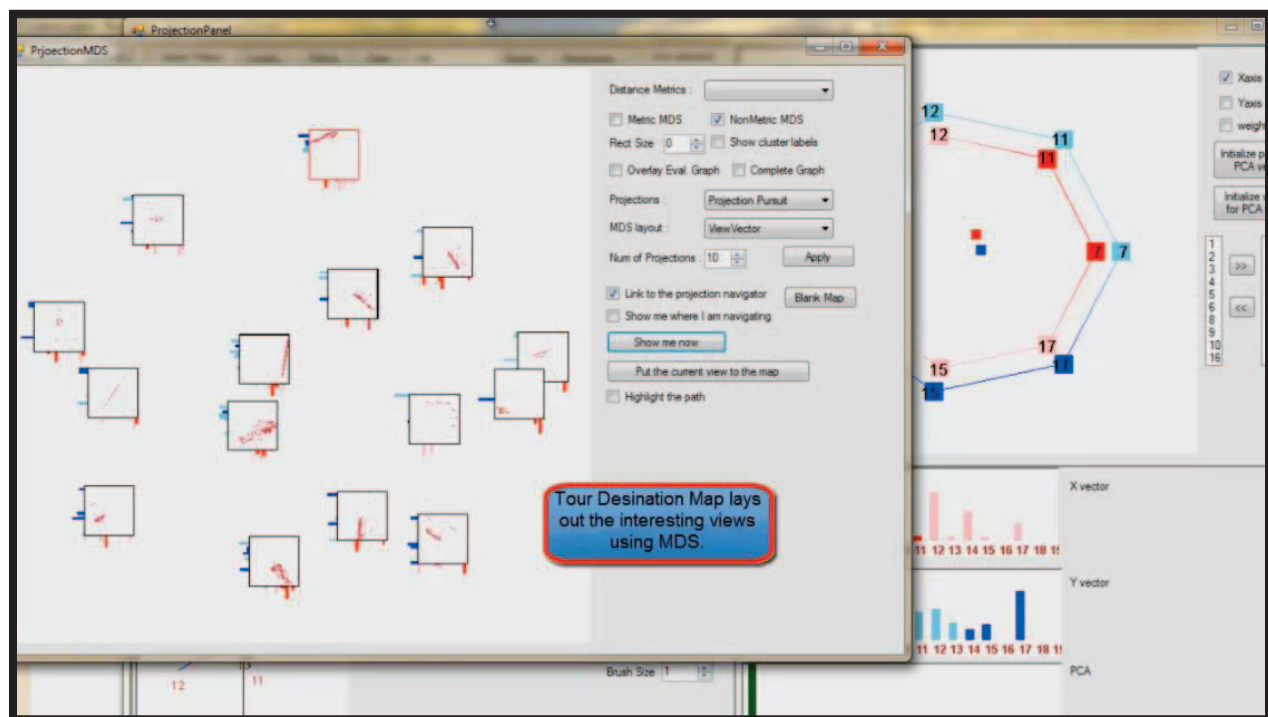


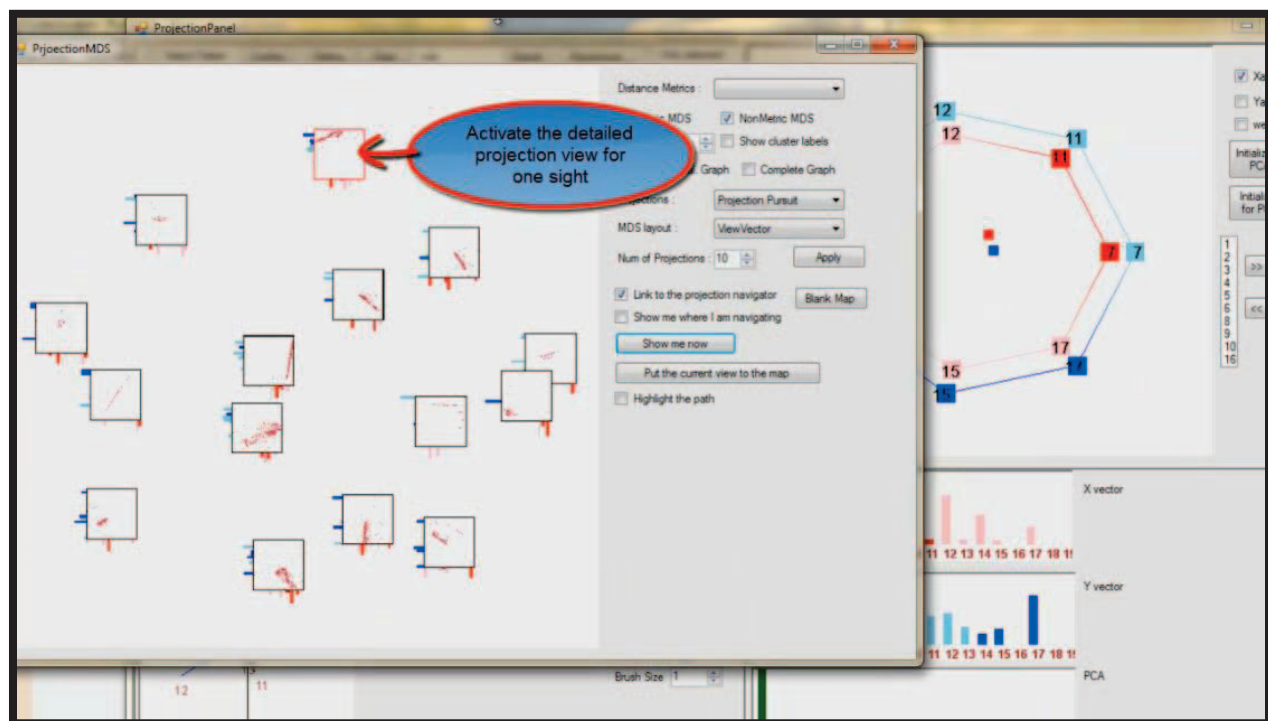


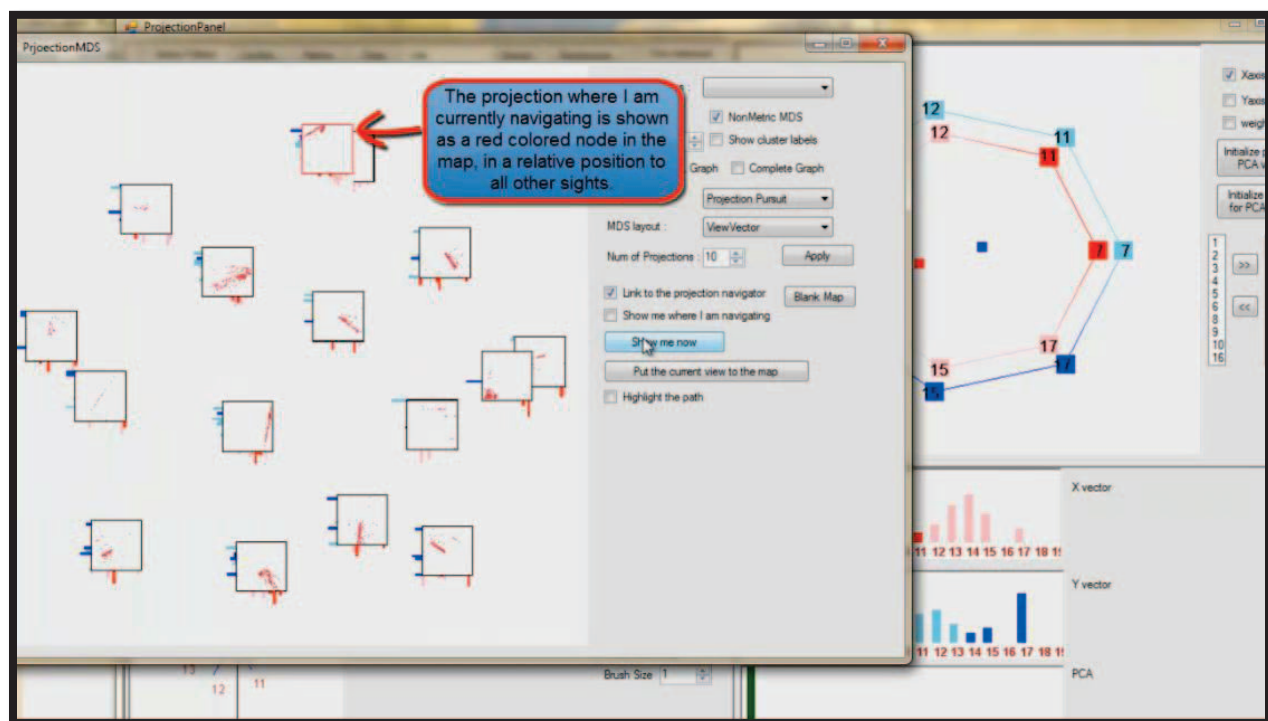
Now we introduce TripAdvisor N-D for the subspace navigation

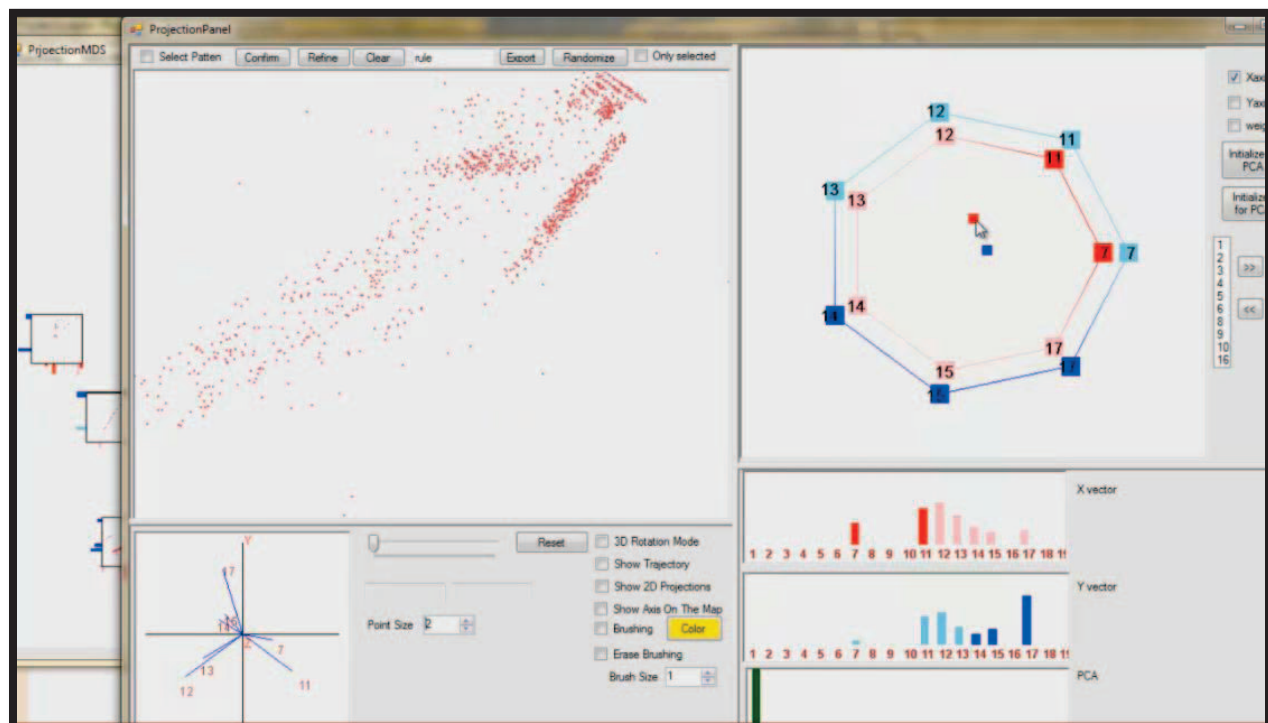
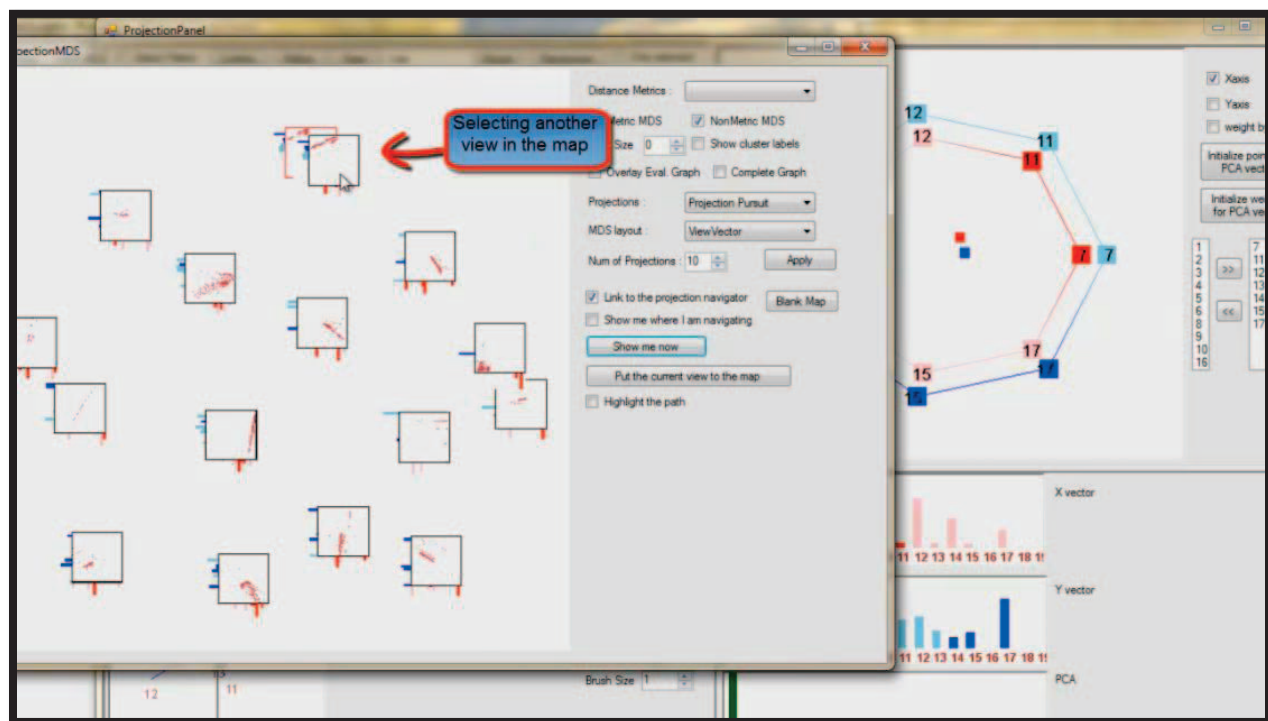
Identify the sights

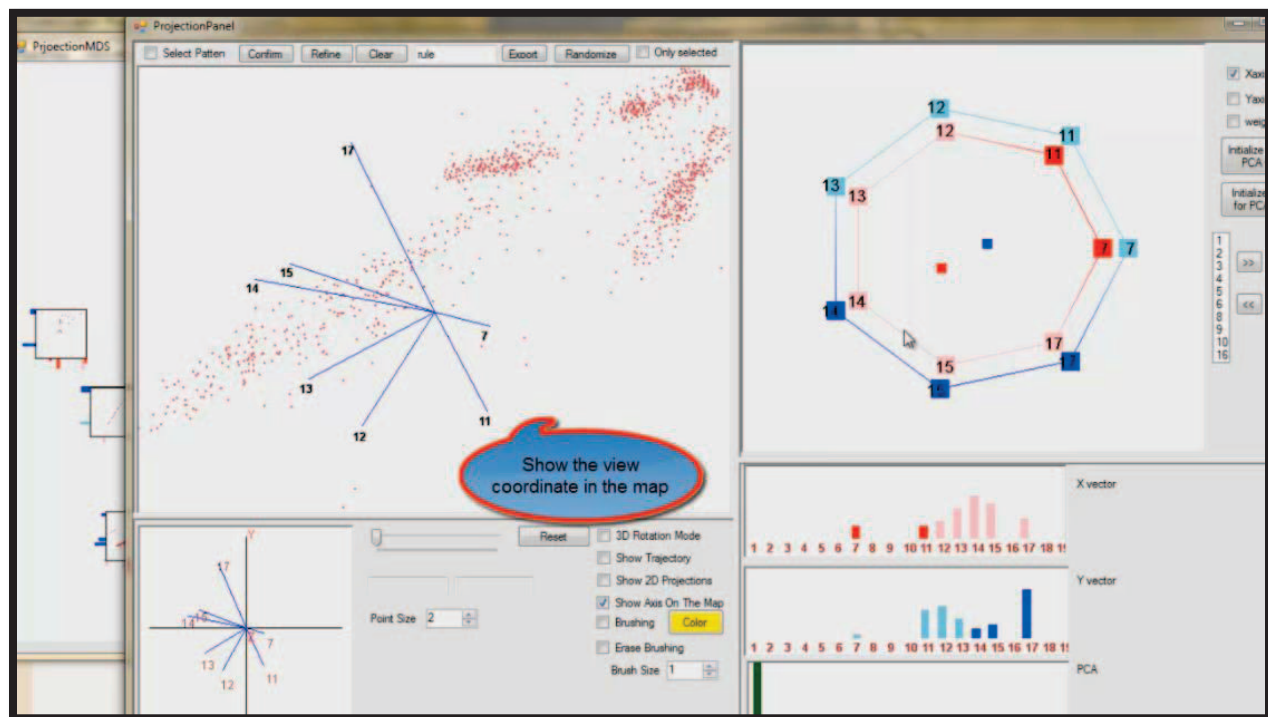
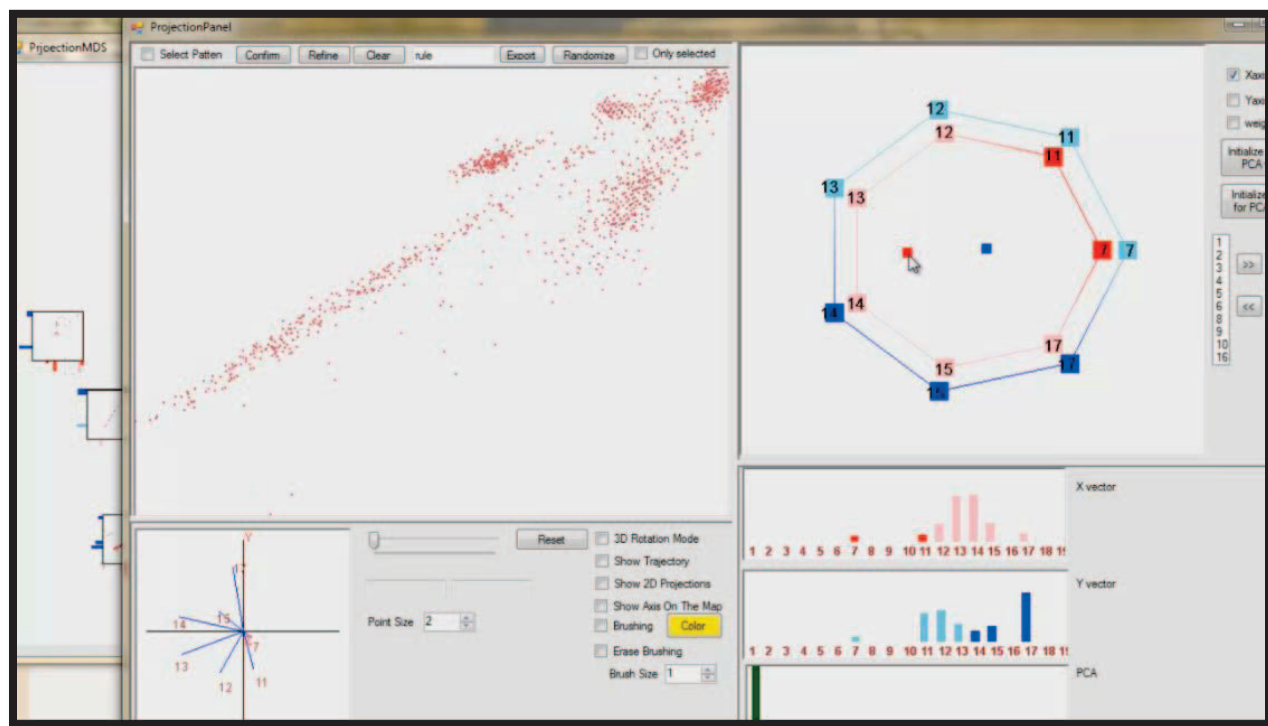
- We use ENCLUS(entropy-based subspace algorithm) to determine independent subspaces.
- Then we use Projection Pursuit algorithm to find interesting viewpoints in these subspaces

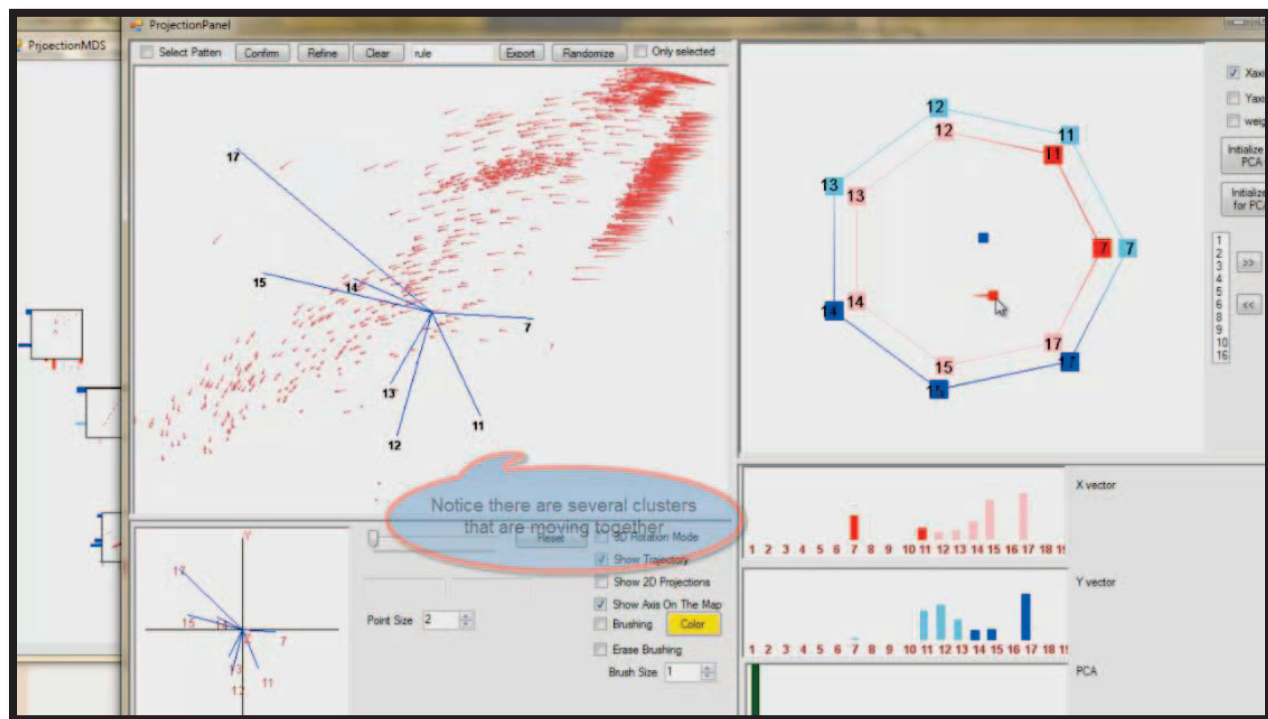
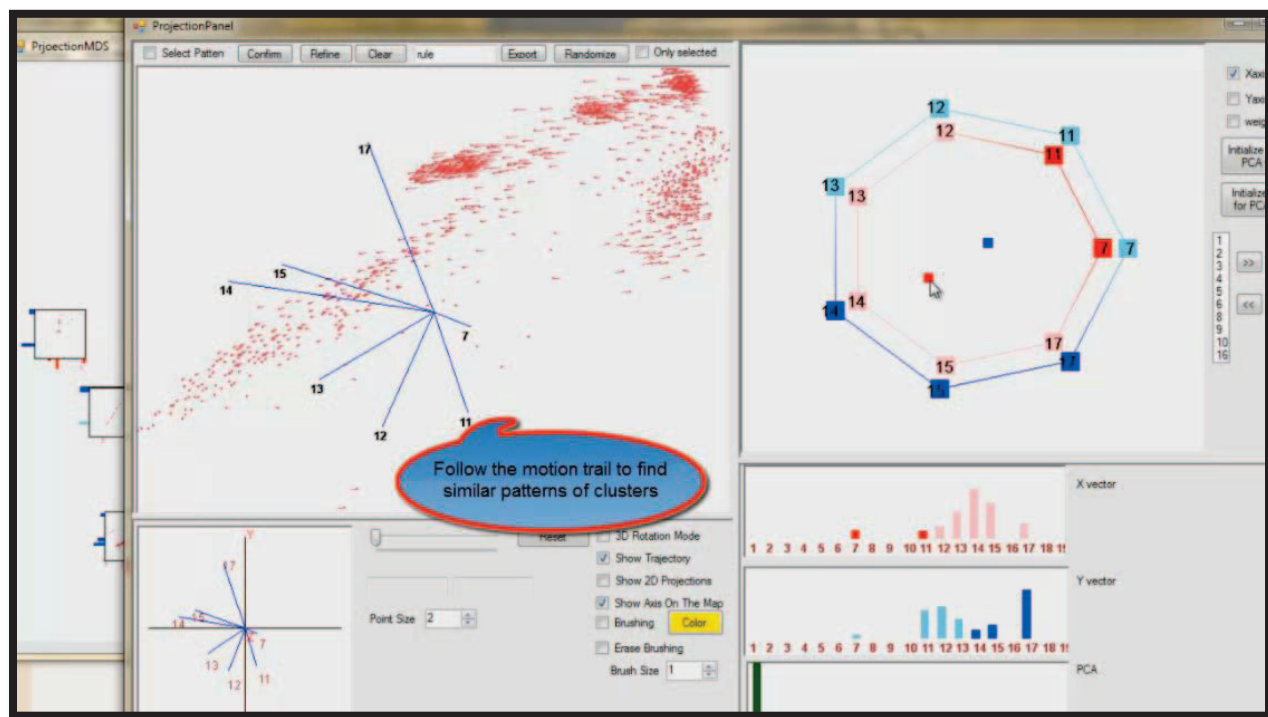


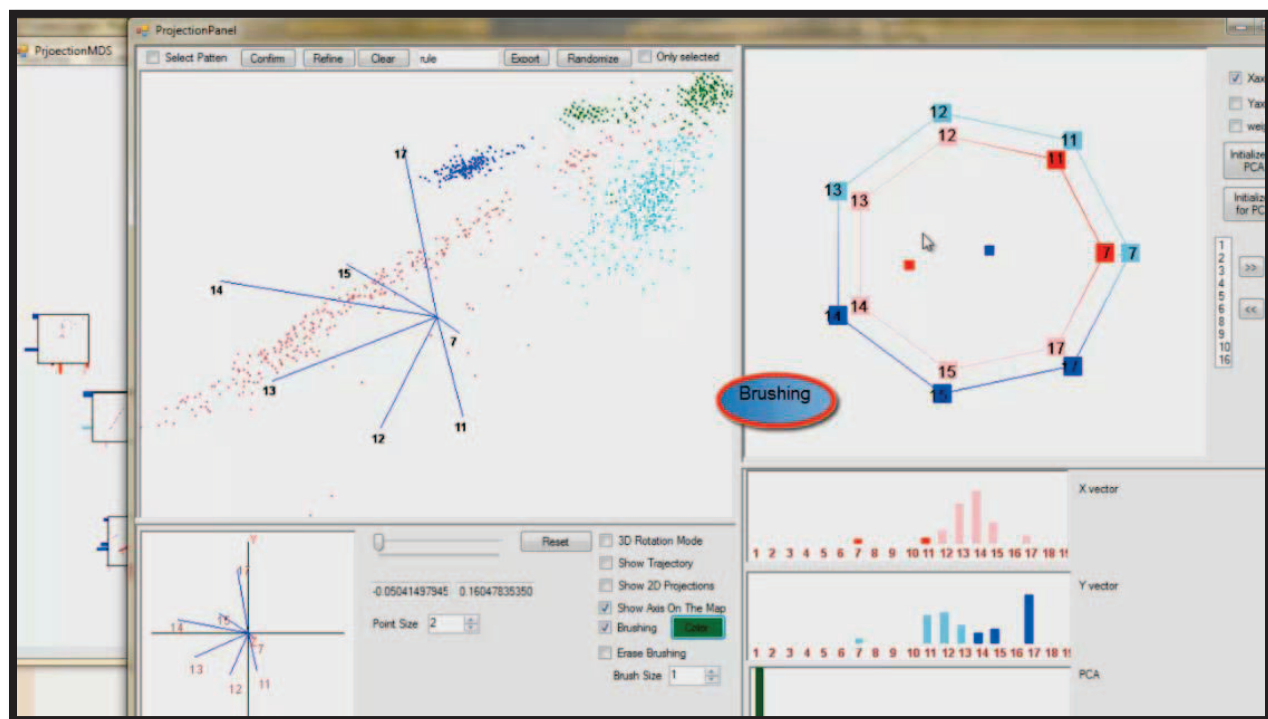


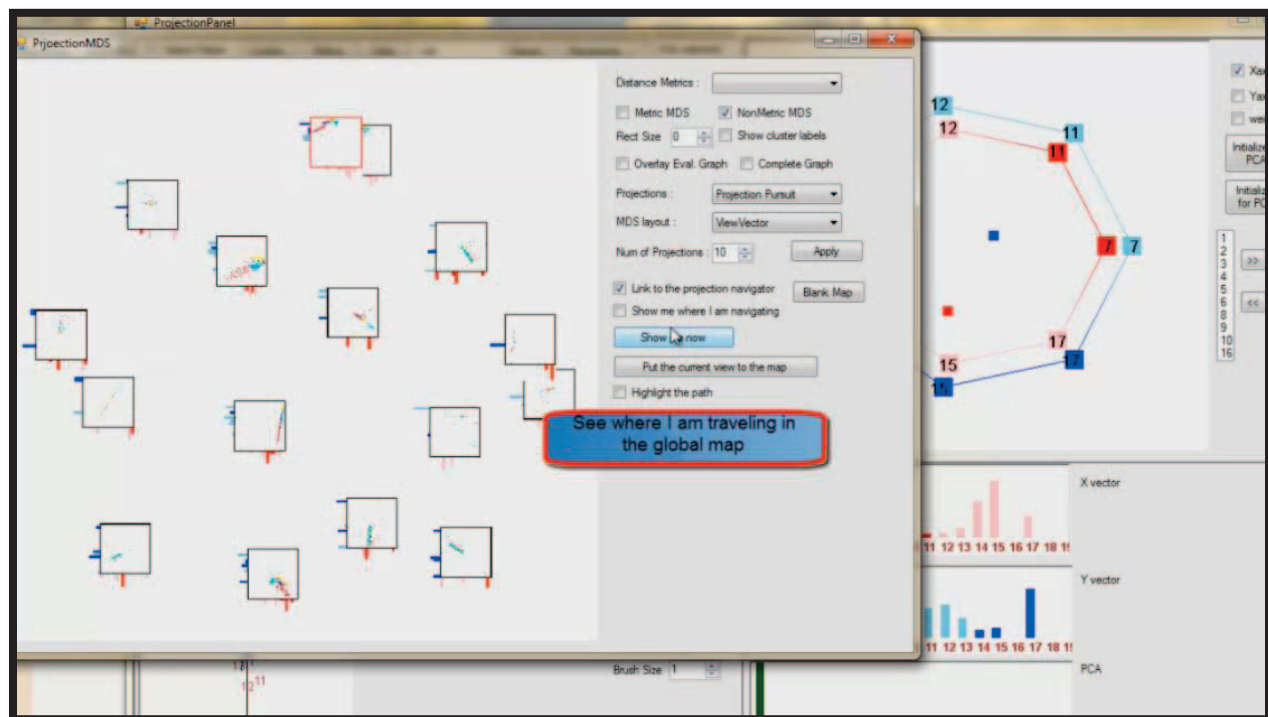
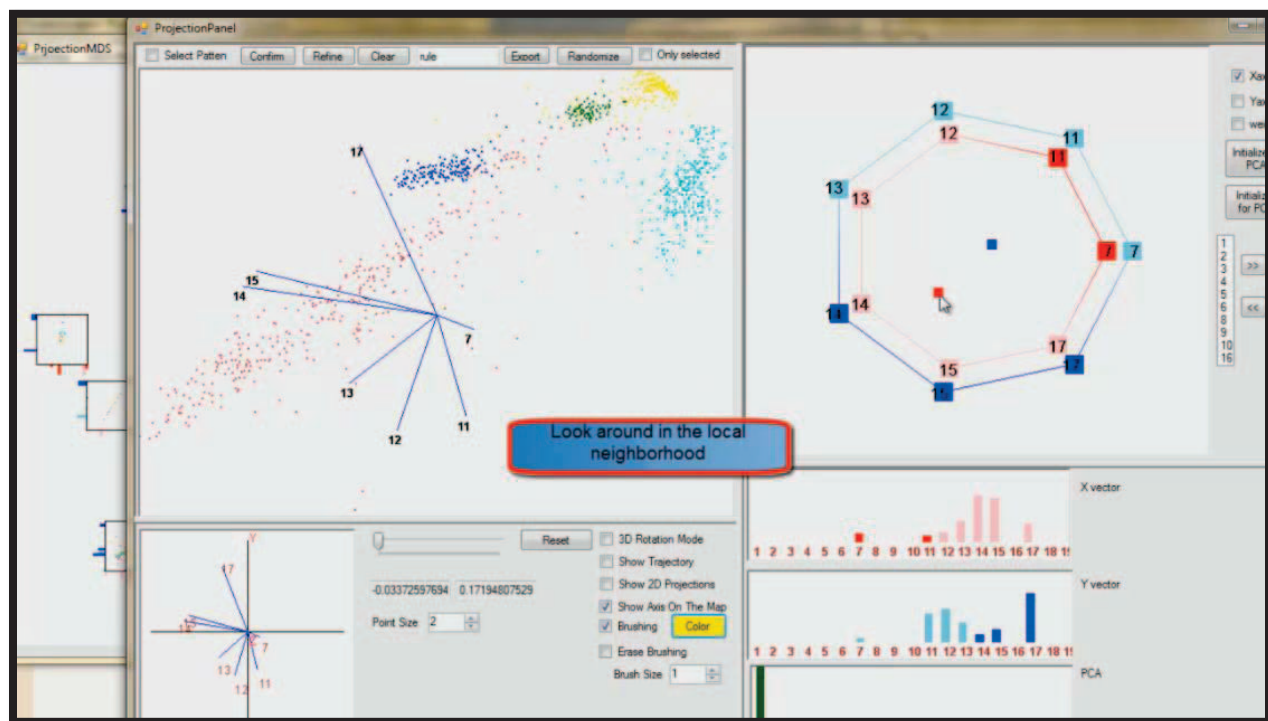


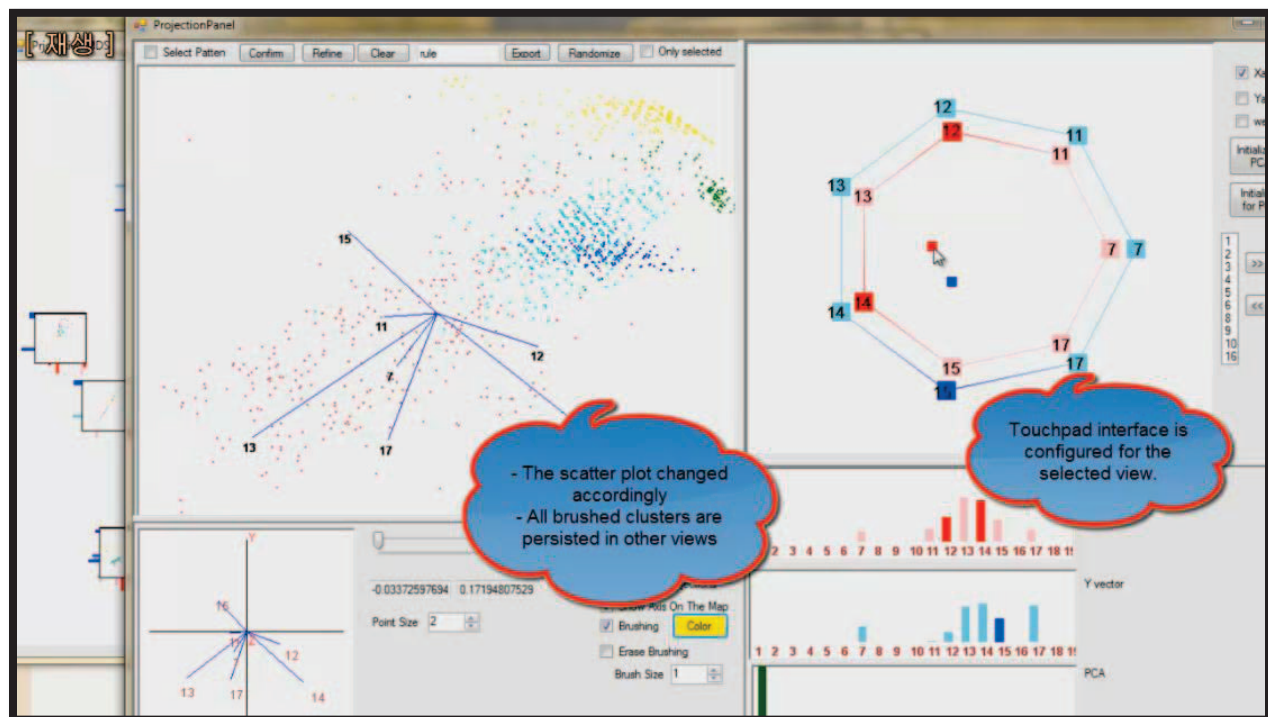
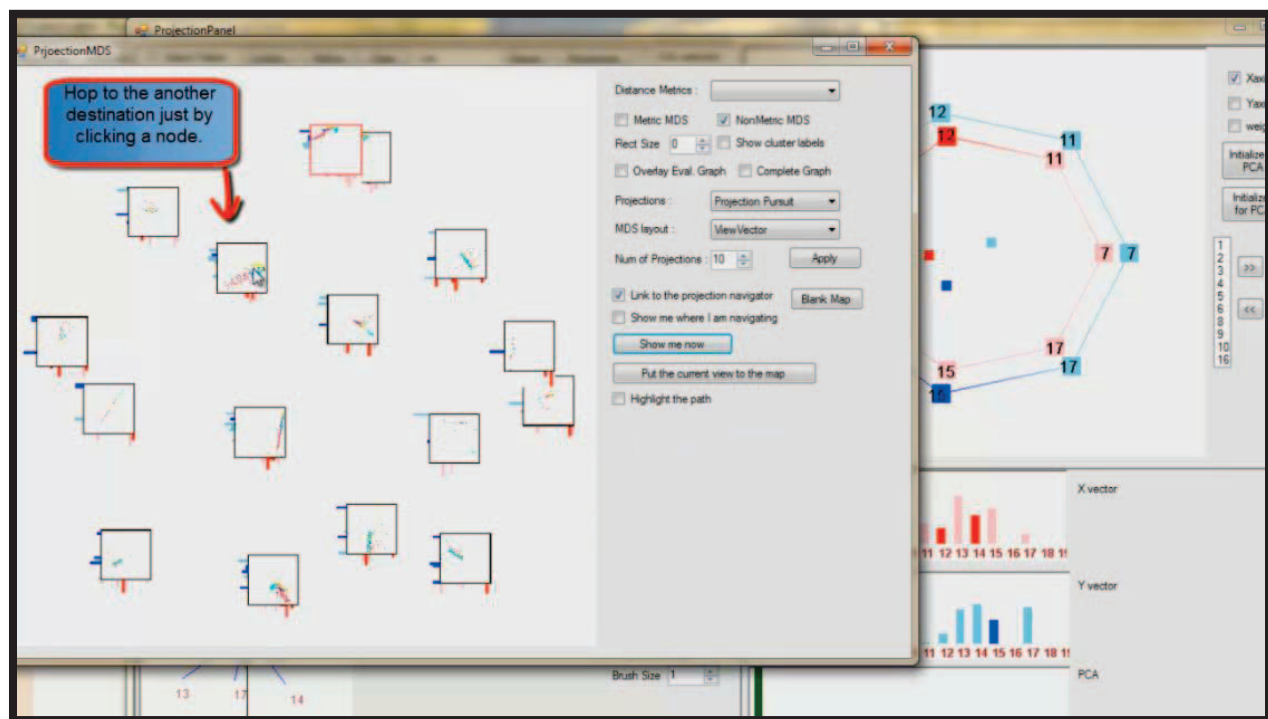


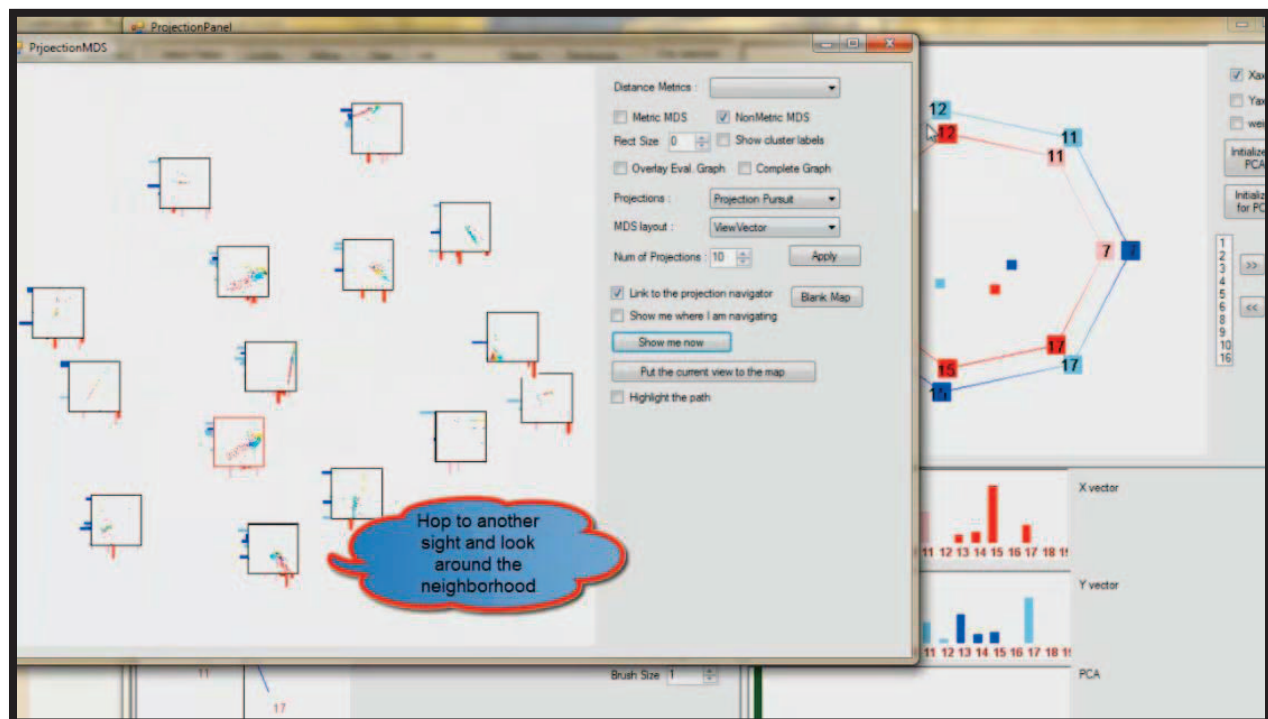
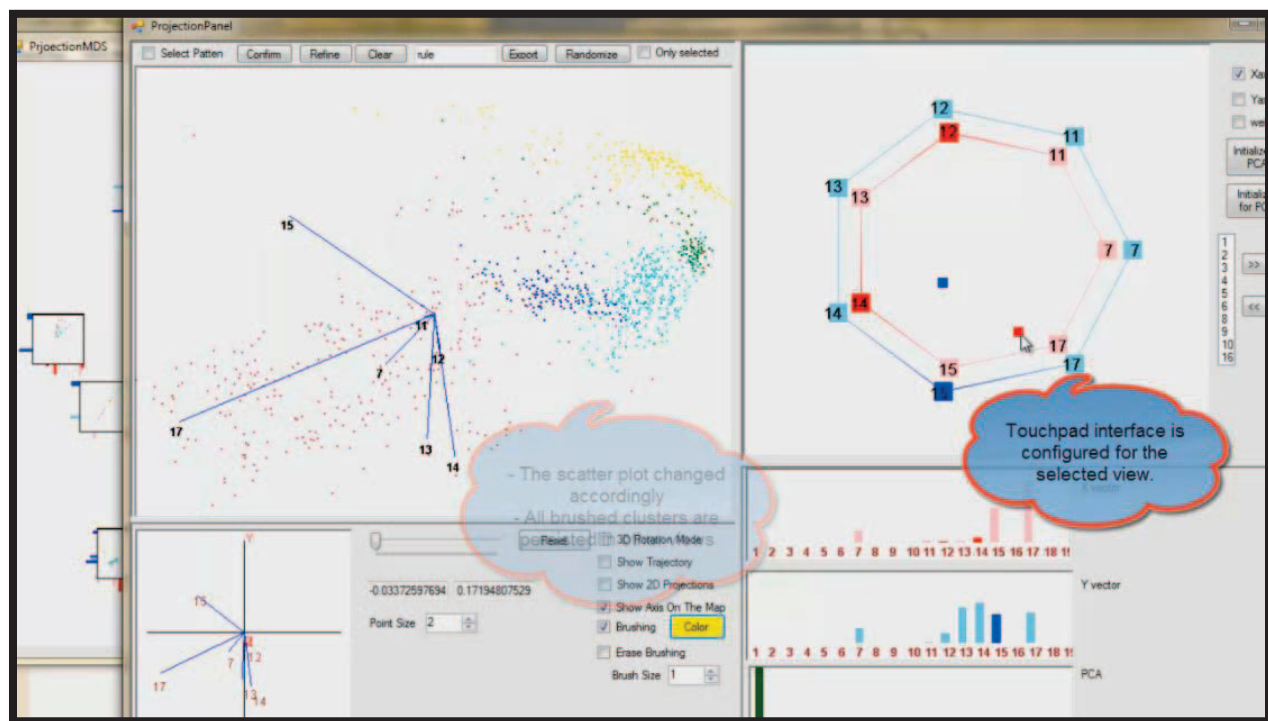


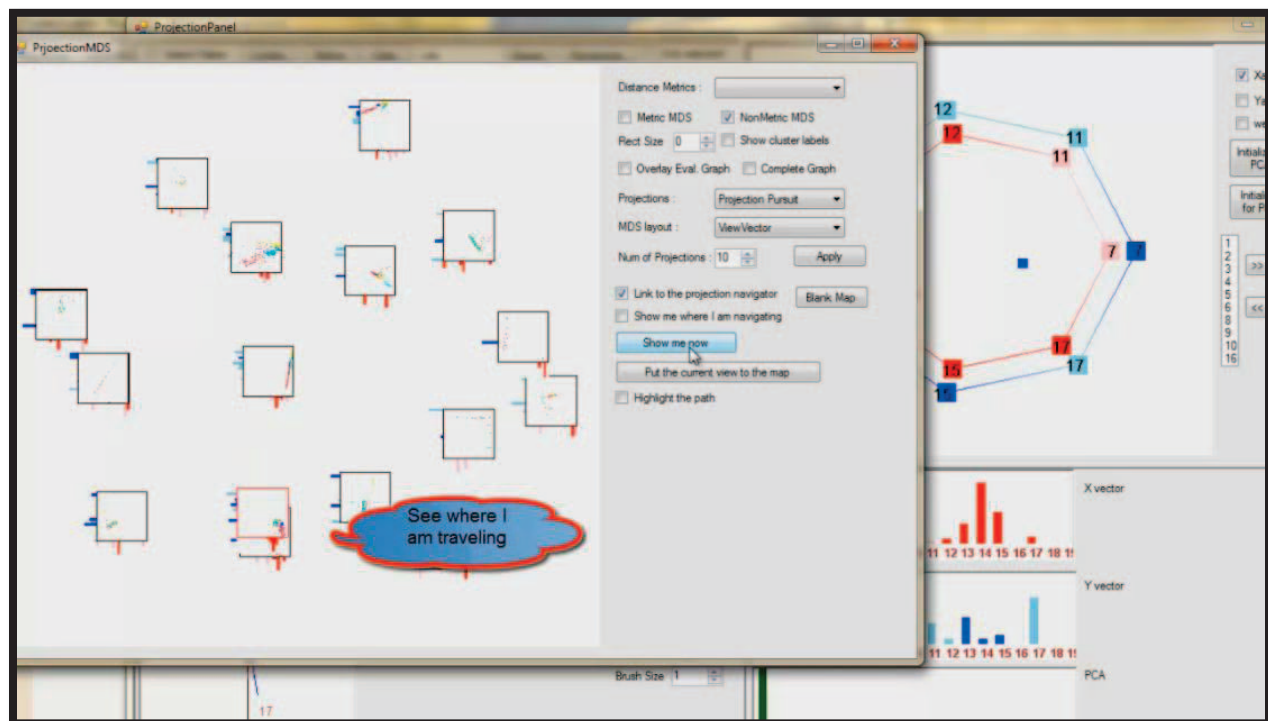
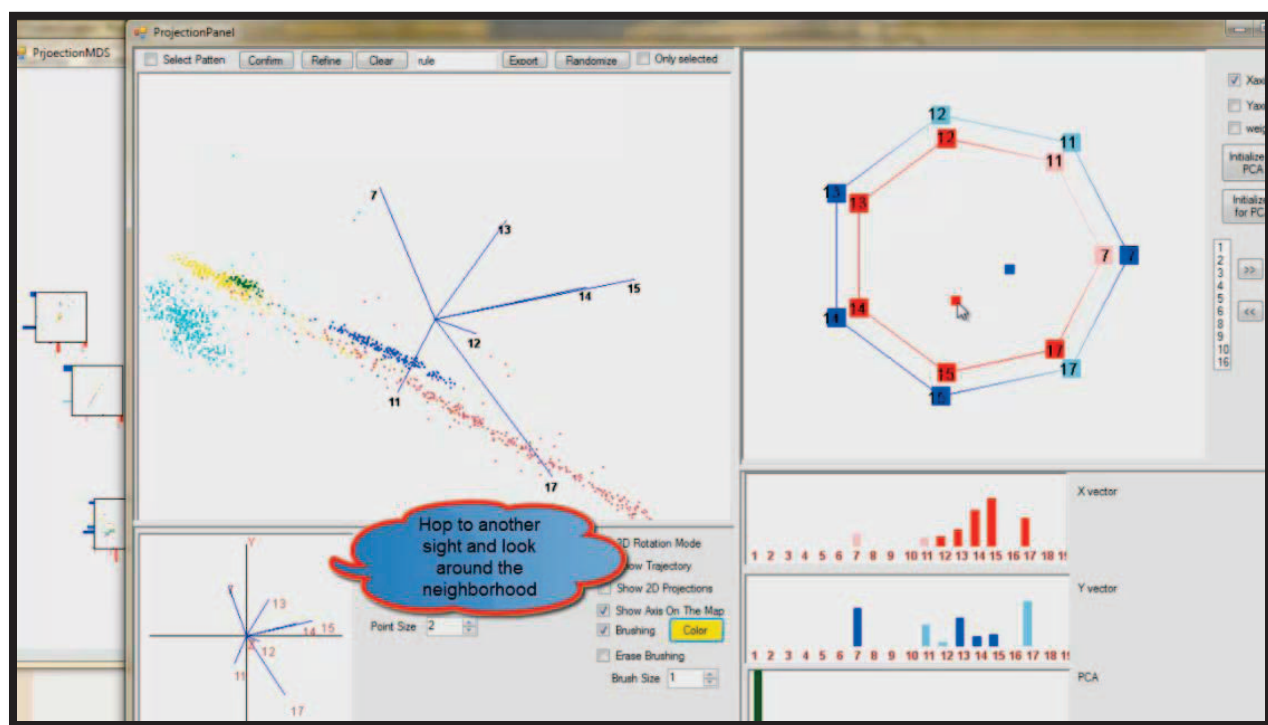


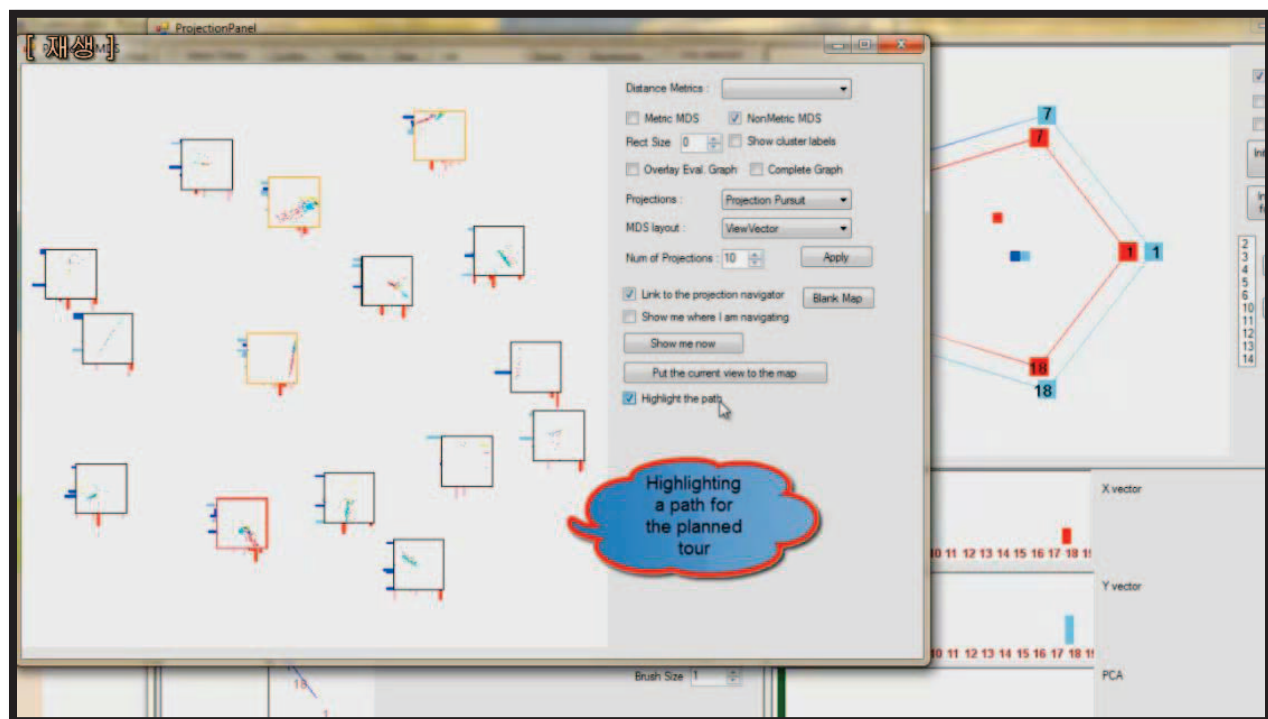












[재생]

Thank you!