Higher degree approximations?

@ Implicit f(x,y) = 0

Defenes curves inplicitly as solution af equation rytem.

line: ax + by + c = 0Circle:  $n^2 + y^2 - R^2 = 0$ 

Porrtion on the curue is defined through a parameter.

Parametric curves form a rich variety of free form smooth curves.

"Splines"

Cubic Splines :-

 $f(t) = \beta_1 + \beta_2 t + \beta_3 t^2 + \beta_4 t^3$   $= \sum_{i=1}^{4} \beta_i t^{i-1} \qquad t_1 \le t \le t_2$ 

is defined as a cubic polynomial of the parameter t.

 $\Rightarrow X(t) = \sum_{i=1}^{4} \beta_{i} t^{i-1}$ 

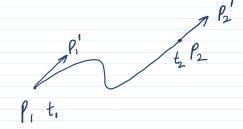
$$y(t) = \sum_{i=1}^{4} b_{i} t^{i-1}$$
Vetors

$$P'(t) = \beta_2 + 2\beta_3 t' + 3\beta_4 t^2$$

Tayent vectors at some location.

Example: -

Curven,



Two end points P, and P2 of the whice averue.

(position vedors)

 $P_1$  and  $P_2$  are the tangent vectors at point  $P_1$  and  $P_2$ .

There points are defined for the parameter values  $t_1$  and  $t_2$ .

To obtain the generalized curve,

Let 
$$t_1 = 0$$

$$l(0) = \beta_1 = \beta_1$$

$$l(t_2) = \beta_1 + \beta_2 t_2 + \beta_3 t_2^2 + \beta_4 t_2^3 = \beta_2$$

$$l(t_2) = \beta_2 = \beta_1$$

$$l(t_2) = \beta_2 + 2\beta_3 t_2^2 + 3\beta_4 t_2^2 = \beta_2^4$$

Salury for 
$$B_{1}$$
,  $B_{2}$ ,  $B_{3}$  and  $B_{4}$ 

$$B_{1} = P_{1}$$

$$B_{2} = P_{2}$$

$$B_{3} = \frac{3(P_{2} - P_{1})}{t_{2}^{2}} - \frac{2(P_{1})}{t_{2}} - \frac{P_{2}}{t_{2}}$$

$$B_{4} = \frac{2(P_{1} - P_{2})}{t_{2}^{2}} + \frac{P_{1}'}{t_{2}^{2}} + \frac{P_{2}'}{t_{2}^{2}}$$

where P, and P2 gives the position of the endpoints.

and P' and P2 gives the direction of the tangent vectors.

$$\begin{aligned}
P(t) &= P_1 + P_1't + \left(\frac{3(P_2 - P_1)}{t_2} - \frac{2P'}{t_2} - \frac{P_2'}{t_2}\right)t^2 \\
&+ \left(\frac{2(P_1 - P_2)}{t_2^3} + \frac{P_1'}{t_2^2} + \frac{P_2'}{t_2^2}\right)t^3
\end{aligned}$$

Extending this idea to set of n points.



Joining of segments

26 EAMENTS: P1 P2 P3 (Points)

P1 P2 P3 (Tangents)

where  $l_2$  and  $l_2'$  are the intermediate point and its tangent vector which is determined through some continuity contraint.

A lieuwine spline of degree k has continuity of order (k-1) at the internal joints.

Thus lubic oplines have second order continuity i.e.  $l_2''(t)$  is continuous over the joint.

 $\rho''(t) = \frac{4}{\xi_1}(i-i)(i-2)\,\beta_i t^{i-3}$   $t_i \le t \le t_2$ at  $t = t_2$ First Segment  $\rho'' = 6\,\beta_4\,t_2 + 2\,\beta_3$ Second Segment  $\rho'' = 2\,\beta_3$ So,  $(6\,\beta_4\,t_2 + 2\,\beta_3)_{seg,1} = (2\,\beta_3)_{seg,2}$ Substitute the expressions for  $\beta_4$  and  $\beta_3$  and regreaving