

CSE 431/531: Algorithm Analysis and Design (Fall 2024)

Graph Algorithms

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Outline

- 1 Minimum Spanning Tree
 - Kruskal's Algorithm
 - Reverse-Kruskal's Algorithm
 - Prim's Algorithm
- 2 Single Source Shortest Paths
- 3 Shortest Paths in Graphs with Negative Weights
- 4 All-Pair Shortest Paths and Floyd-Warshall

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Improved Running Time using Priority Queue

Dijkstra(G, w, s)

```
1:  $s \leftarrow$  arbitrary vertex in  $G$ 
2:  $S \leftarrow \emptyset, d(s) \leftarrow 0$  and  $d[v] \leftarrow \infty$  for every  $v \in V \setminus \{s\}$ 
3:  $Q \leftarrow$  empty queue, for each  $v \in V$ :  $Q.\text{insert}(v, d[v])$ 
4: while  $S \neq V$  do
5:    $u \leftarrow Q.\text{extract\_min}()$ 
6:    $S \leftarrow S \cup \{u\}$ 
7:   for each  $v \in V \setminus S$  such that  $(u, v) \in E$  do
8:     if  $d[u] + w(u, v) < d[v]$  then
9:        $d[v] \leftarrow d[u] + w(u, v), Q.\text{decrease\_key}(v, d[v])$ 
10:     $\pi[v] \leftarrow u$ 
11: return  $(\pi, d)$ 
```

Recall: Prim's Algorithm for MST

MST-Prim(G, w)

```
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10:       $\pi[v] \leftarrow u$ 
11: return  $\{(u, \pi[u]) \mid u \in V \setminus \{s\}\}$ 
```


Improved Running Time

Running time:

$$O(n) \times (\text{time for extract_min}) + O(m) \times (\text{time for decrease_key})$$

Priority-Queue	extract_min	decrease_key	Time
Heap	$O(\log n)$	$O(\log n)$	$O(m \log n)$
Fibonacci Heap	$O(\log n)$	$O(1)$	$O(n \log n + m)$

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Single Source Shortest Paths, Weights May be Negative

Input: directed graph $G = (V, E)$, $s \in V$

assume all vertices are reachable from s

$w : E \rightarrow \mathbb{R}$

Output: shortest paths from s to all other vertices $v \in V$

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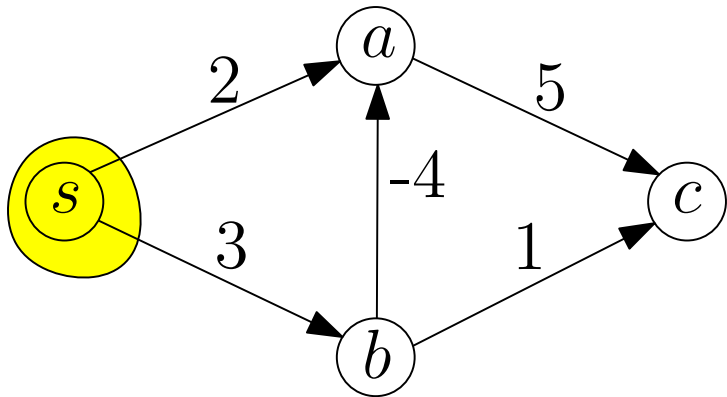
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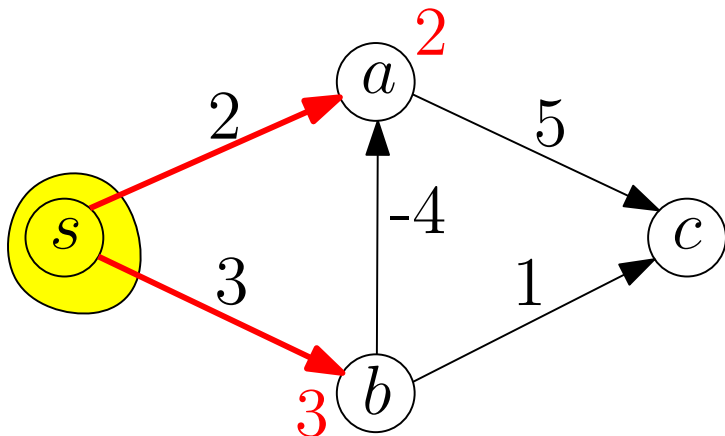
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- In transition graphs, negative weights make sense
- If we sell a item: 'having the item' \rightarrow 'not having the item', weight is negative (we gain money)
- Dijkstra's algorithm does not work any more!

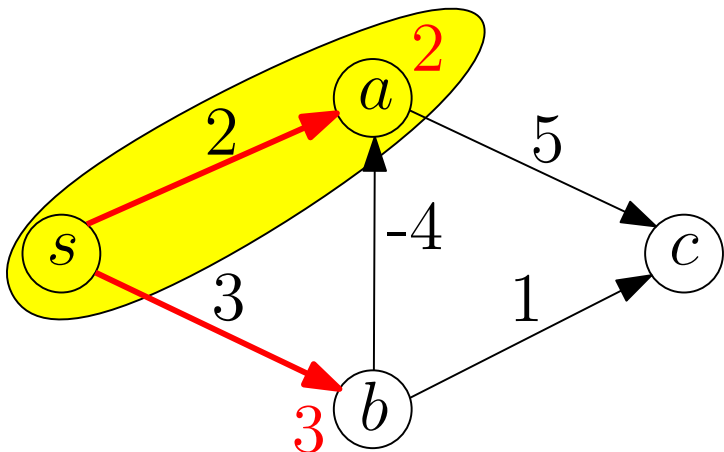
Dijkstra's Algorithm Fails if We Have Negative Weights



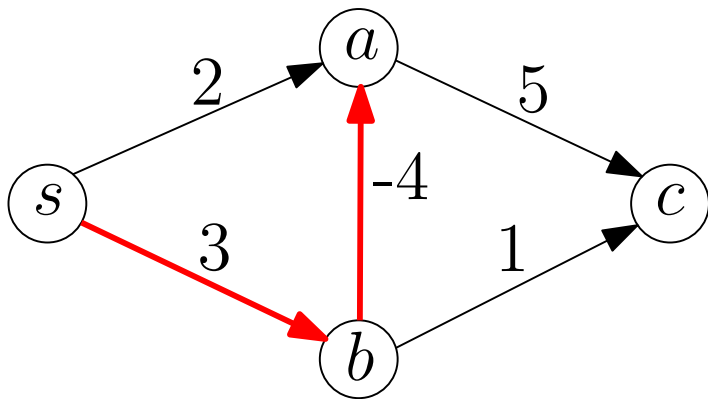
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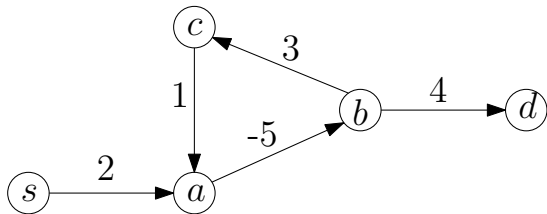


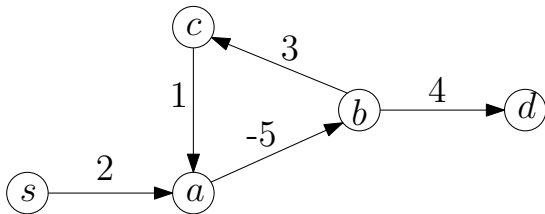
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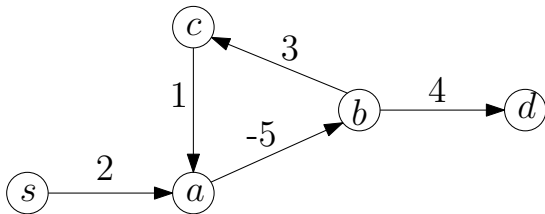
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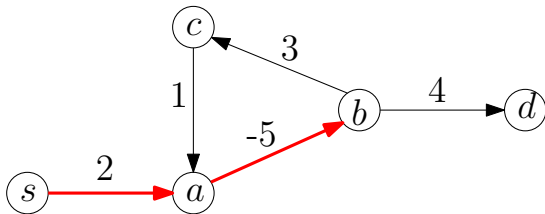


Q: What is the length of the shortest path from s to d ?



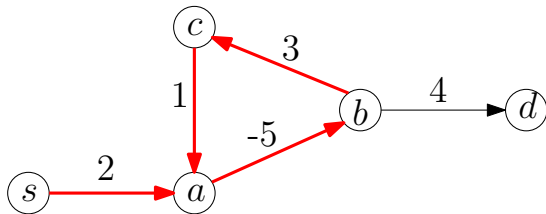
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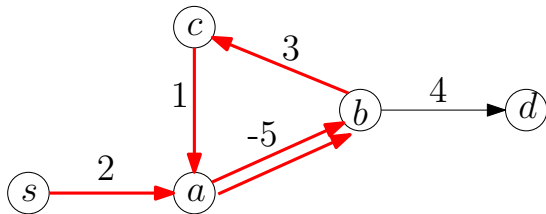
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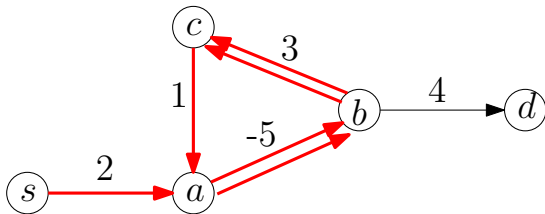
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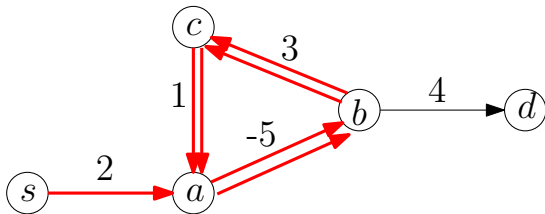
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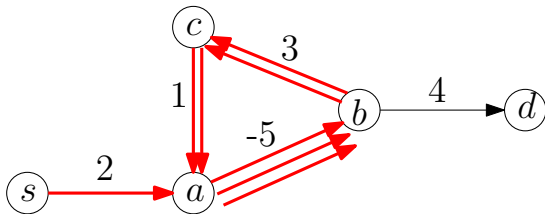
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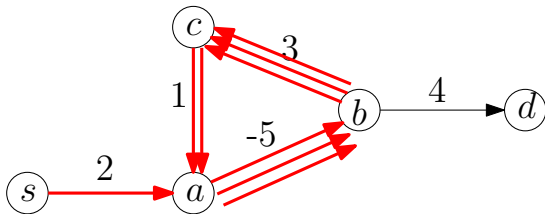
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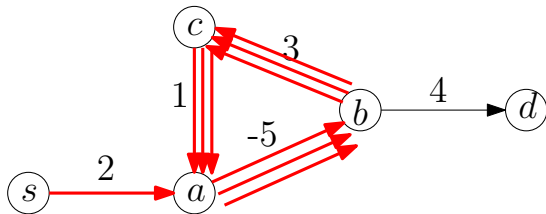
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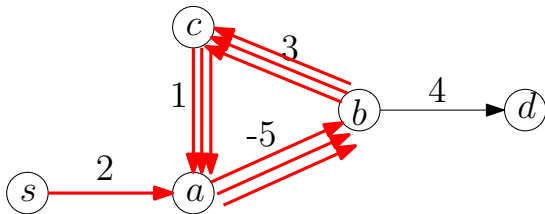
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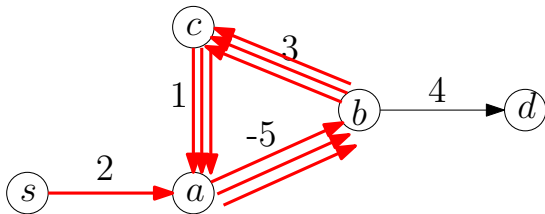
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Def. A negative cycle is a cycle in which the total weight of edges is negative.

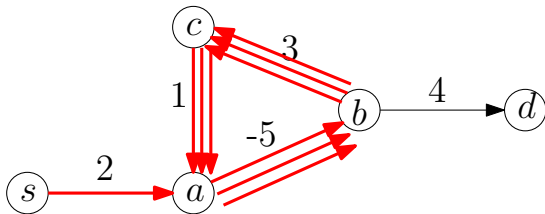


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Dealing with Negative Cycles



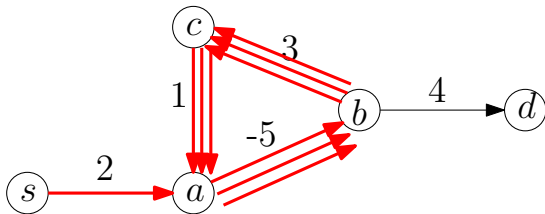
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- assume the input graph does not contain negative cycles, or



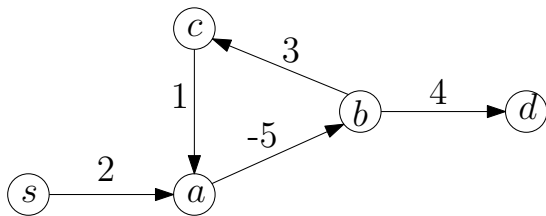
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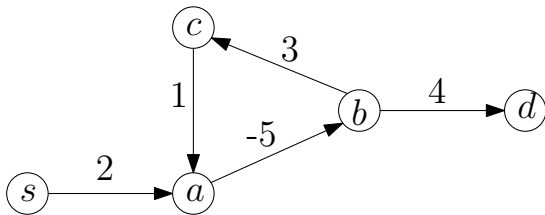
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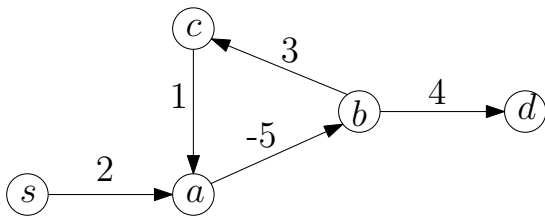
Dealing with Negative Cycles

- assume the input graph does not contain negative cycles, or
- allow algorithm to report “negative cycle exists”



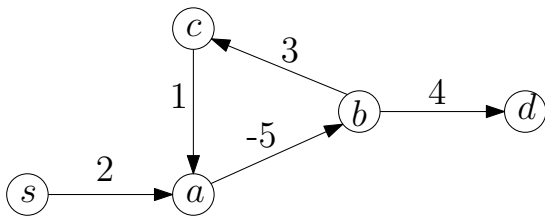


Q: What is the length of the shortest **simple** path from s to d ?



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- Unfortunately, computing the shortest simple path between two vertices is an **NP-hard** problem.

algorithm	graph	weights	SS?	running time
Simple DP	DAG	\mathbb{R}	SS	$O(n + m)$
Dijkstra	U/D	$\mathbb{R}_{\geq 0}$	SS	$O(n \log n + m)$
Bellman-Ford	U/D	\mathbb{R}	SS	$O(nm)$
Floyd-Warshall	U/D	\mathbb{R}	AP	$O(n^3)$

- DAG = directed acyclic graph U = undirected D = directed
- SS = single source AP = all pairs

Defining Cells of Table

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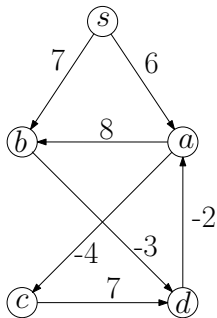
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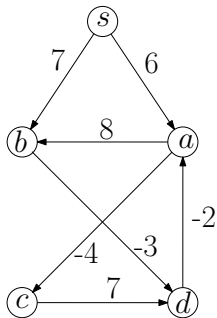
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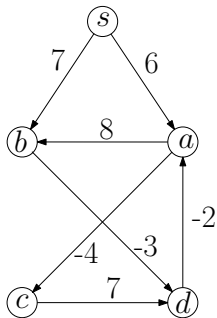
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- issue: do not know in which order we compute $f[v]$'s
- $f^\ell[v]$, $\ell \in \{0, 1, 2, 3, \dots, n-1\}$, $v \in V$: length of shortest path from s to v **that uses at most ℓ edges**



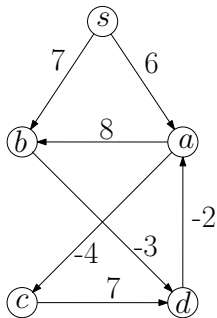
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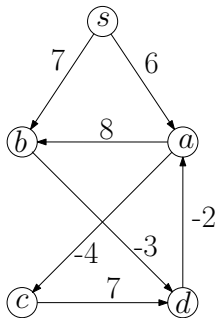
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- $f^2[a] =$



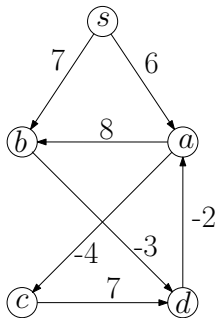
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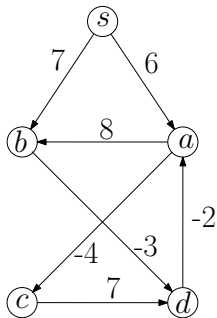
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$$f^\ell[v] = \left\{ \begin{array}{l} \end{array} \right.$$

$$\ell = 0, v = s$$

$$\ell = 0, v \neq s$$

$$\ell > 0$$



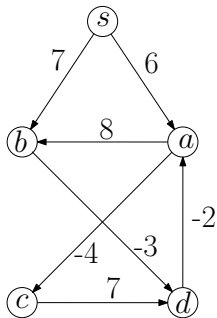
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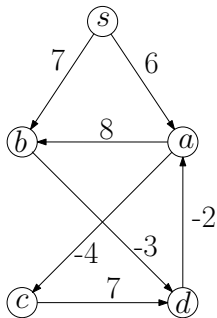
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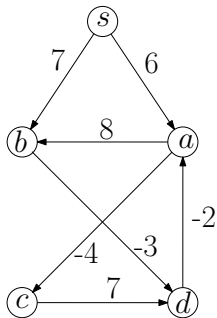
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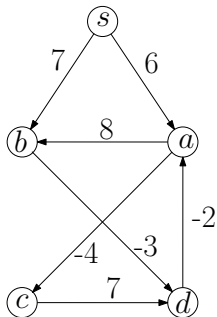
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$$f^{\ell-1}[v]$$

$$\ell = 0, v = s$$

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$$\ell > 0$$

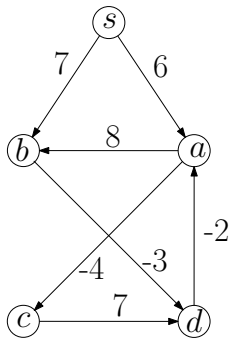


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length of shortest path from s to v **that uses at most ℓ edges**
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$$f^\ell[v] = \begin{cases} 0 & \ell = 0, v = s \\ \infty & \ell = 0, v \neq s \\ \min \left\{ \begin{array}{l} f^{\ell-1}[v] \\ \min_{u:(u,v) \in E} (f^{\ell-1}[u] + w(u, v)) \end{array} \right. & \ell > 0 \end{cases}$$

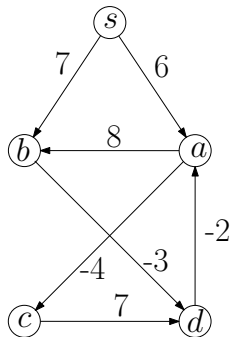
Dynamic Programming: Example

$$f^0 \quad \begin{array}{c} s \\ \textcircled{0} \end{array} \quad \begin{array}{c} a \\ \textcircled{\infty} \end{array} \quad \begin{array}{c} b \\ \textcircled{\infty} \end{array} \quad \begin{array}{c} c \\ \textcircled{\infty} \end{array} \quad \begin{array}{c} d \\ \textcircled{\infty} \end{array}$$

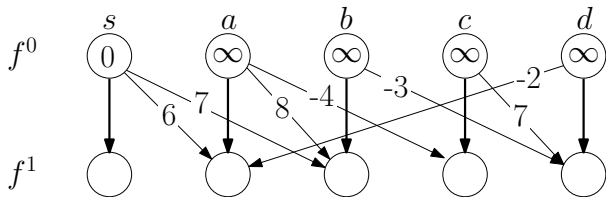


↓ length-0 edge

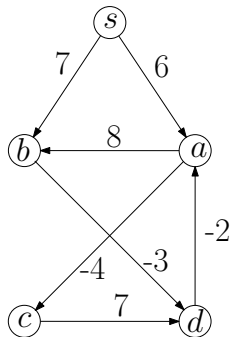
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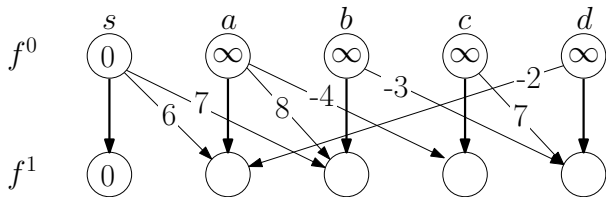
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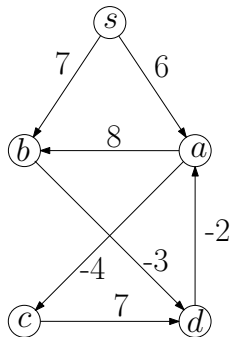
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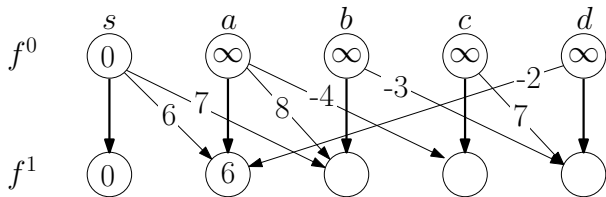
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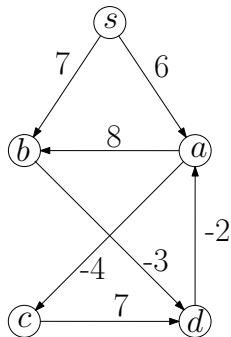
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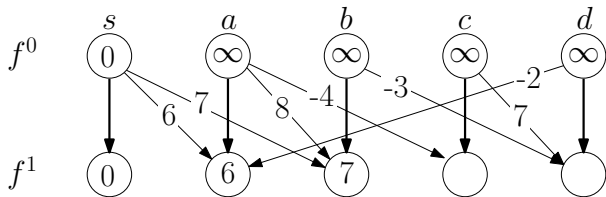
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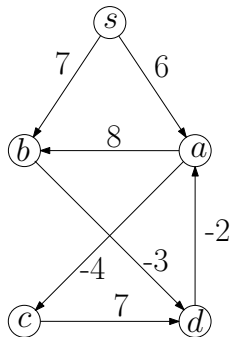
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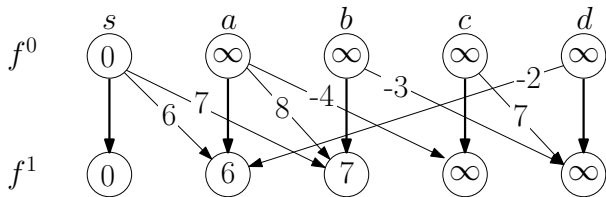
↓ length-0 edge



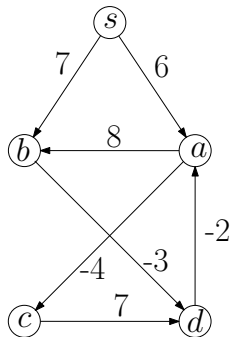
Dynamic Programming: Example



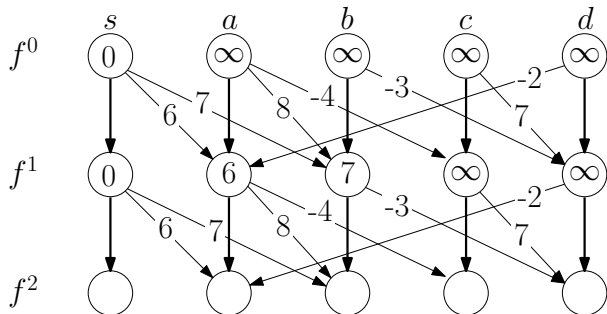
↓ length-0 edge



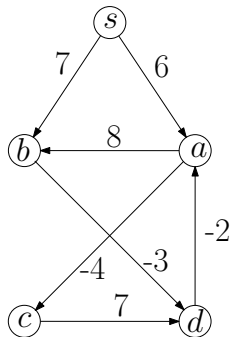
Dynamic Programming: Example



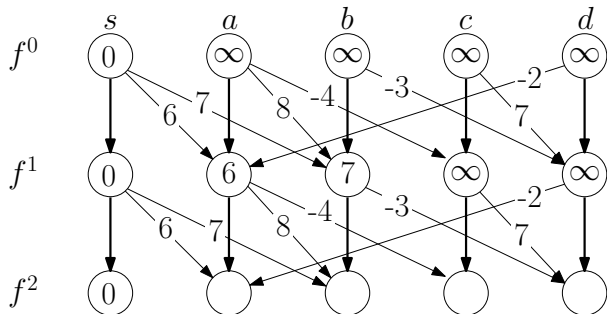
↓ length-0 edge



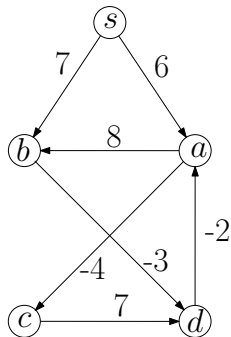
Dynamic Programming: Example



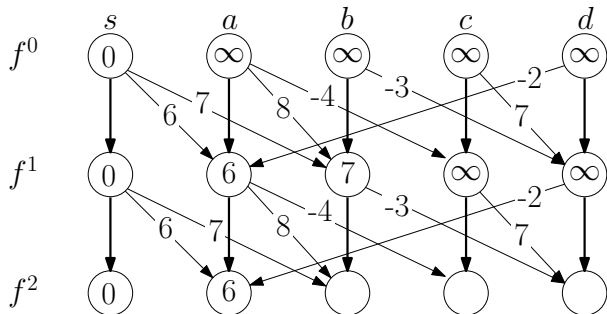
↓ length-0 edge



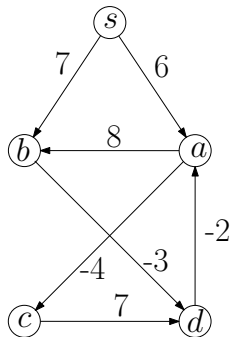
Dynamic Programming: Example



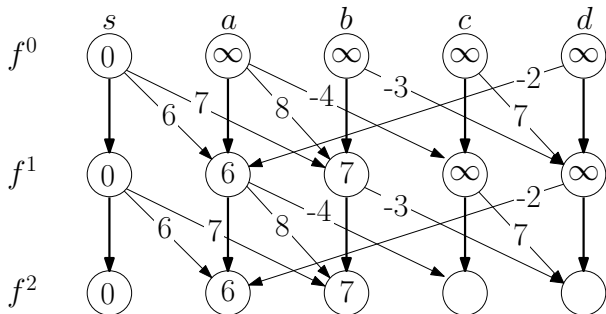
↓ length-0 edge



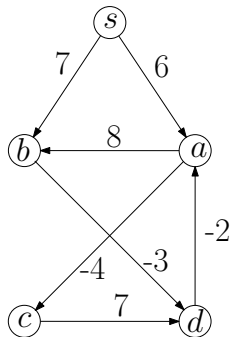
Dynamic Programming: Example



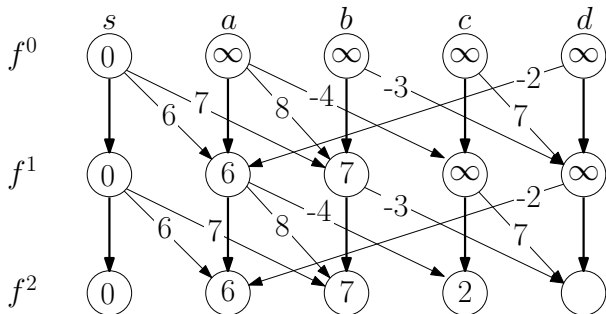
↓ length-0 edge



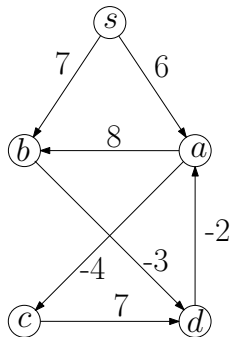
Dynamic Programming: Example



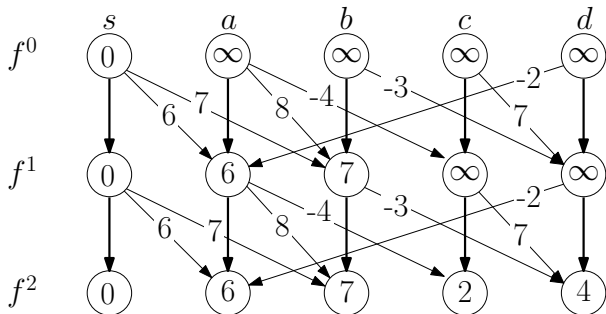
↓ length-0 edge



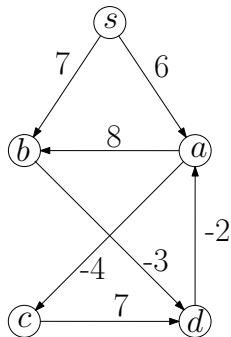
Dynamic Programming: Example



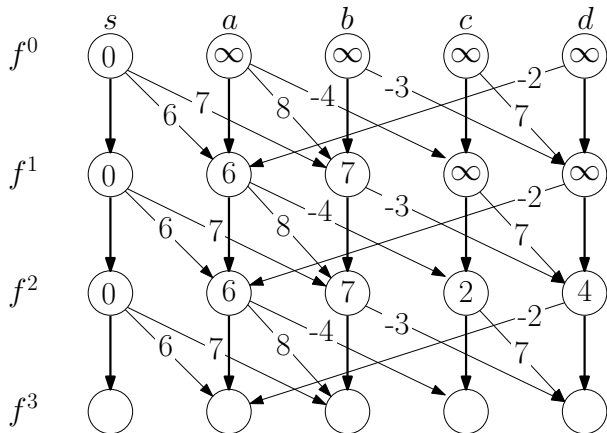
↓ length-0 edge



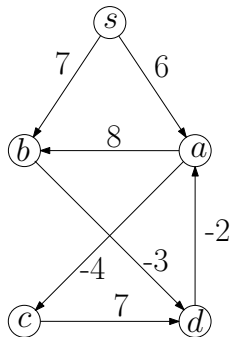
Dynamic Programming: Example



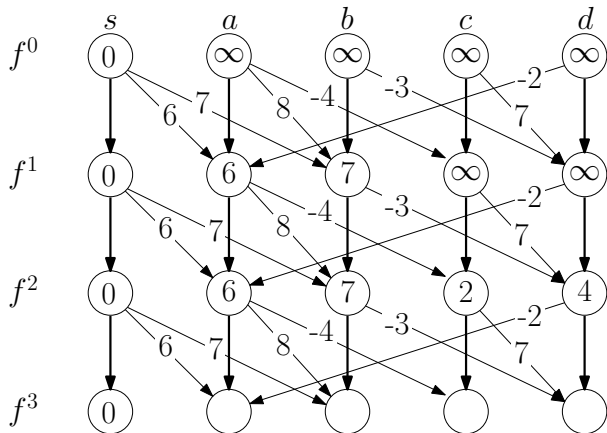
↓ length-0 edge



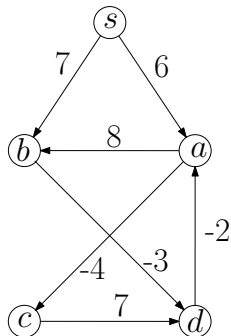
Dynamic Programming: Example



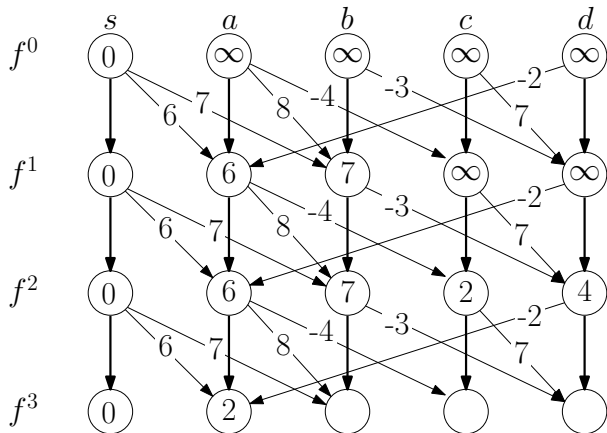
↓ length-0 edge



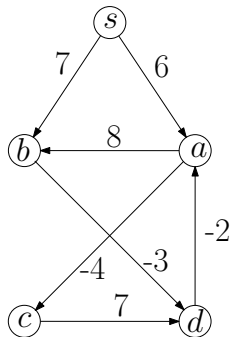
Dynamic Programming: Example



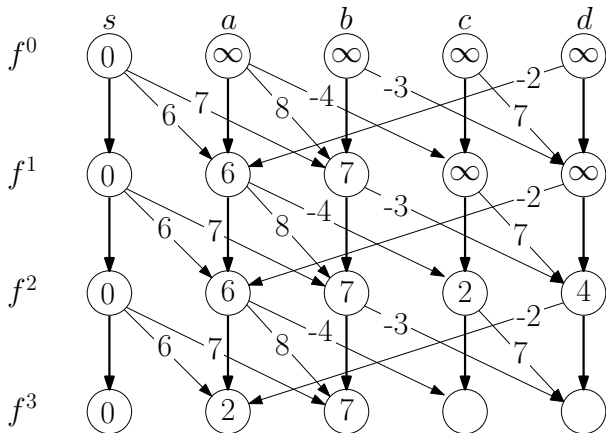
↓ length-0 edge



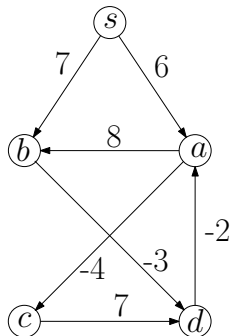
Dynamic Programming: Example



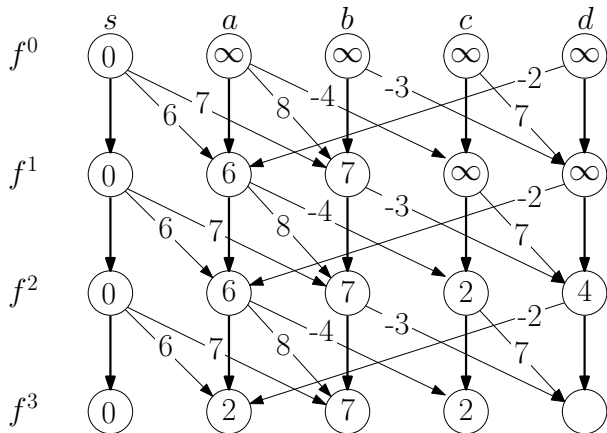
↓ length-0 edge



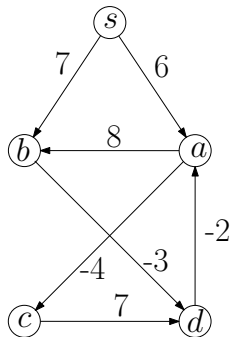
Dynamic Programming: Example



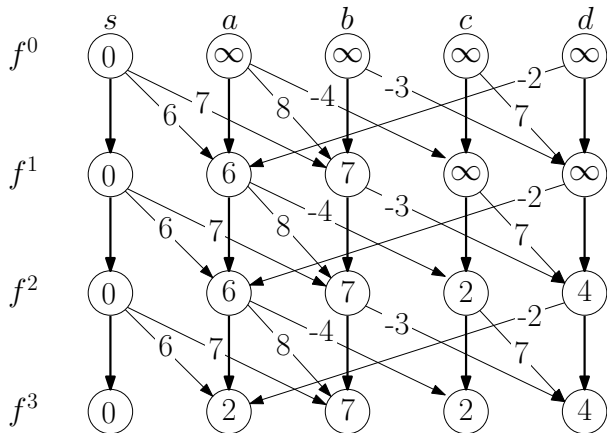
↓ length-0 edge



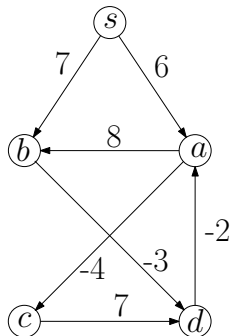
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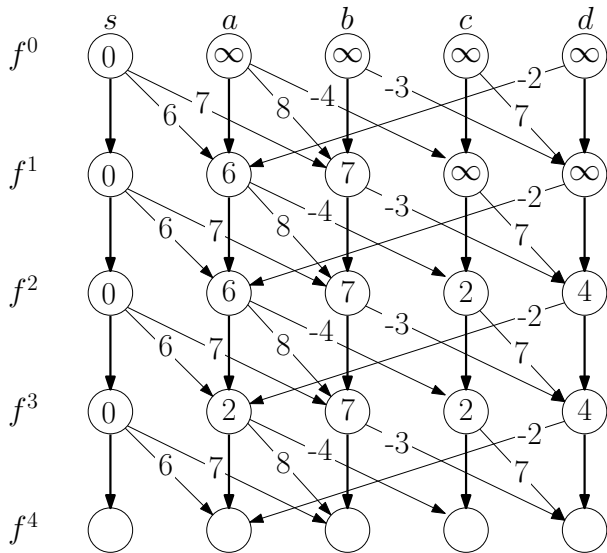
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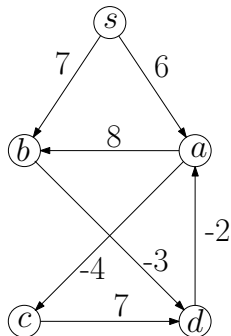
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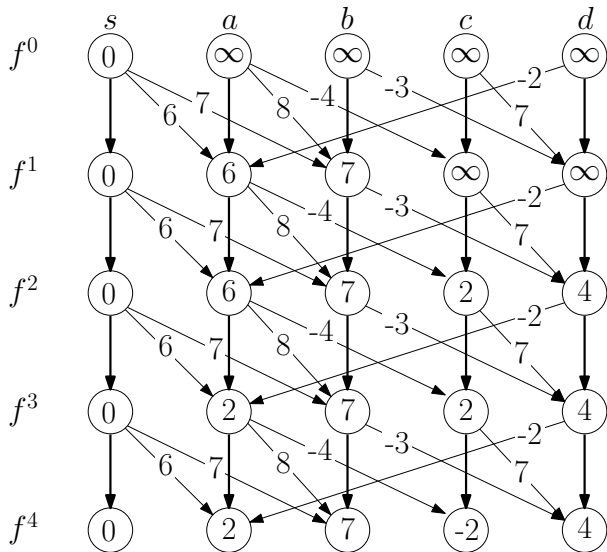
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Dynamic Programming: Example



↓ length-0 edge



dynamic-programming(G, w, s)

- 1: $f^0[s] \leftarrow 0$ and $f^0[v] \leftarrow \infty$ for any $v \in V \setminus \{s\}$
- 2: **for** $\ell \leftarrow 1$ to $n - 1$ **do**
- 3: copy $f^{\ell-1} \rightarrow f^\ell$
- 4: **for** each $(u, v) \in E$ **do**
- 5: **if** $f^{\ell-1}[u] + w(u, v) < f^\ell[v]$ **then**
- 6: $f^\ell[v] \leftarrow f^{\ell-1}[u] + w(u, v)$
- 7: **return** $(f^{n-1}[v])_{v \in V}$

dynamic-programming(G, w, s)

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Obs. Assuming there are no negative cycles, then a shortest path contains at most $n - 1$ edges

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Obs. Assuming there are no negative cycles, then a shortest path contains at most $n - 1$ edges

Proof.

If there is a path containing at least n edges, then it contains a cycle. Removing the cycle gives a path with the same or smaller length. \square

Dynamic Programming with Better Space Usage

dynamic-programming(G, w, s)

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1:  $f^{\text{old}}[s] \leftarrow 0$  and  $f^{\text{old}}[v] \leftarrow \infty$  for any  $v \in V \setminus \{s\}$ 
2: for  $\ell \leftarrow 1$  to  $n - 1$  do
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4:   for each  $(u, v) \in E$  do
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7:   copy  $f^{\text{new}} \rightarrow f^{\text{old}}$ 
8: return  $f^{\text{old}}$ 
```

- f^ℓ only depends on $f^{\ell-1}$: only need 2 vectors

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- After iteration ℓ , $f[v]$ is **at most** the length of the shortest path from s to v that uses at most ℓ edges

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```

- Issue: when we compute $f[u] + w(u, v)$, $f[u]$ may be changed since the end of last iteration
- This is OK: it can only “accelerate” the process!
- After iteration ℓ , $f[v]$ is **at most** the length of the shortest path from s to v that uses at most ℓ edges
- $f[v]$ is always the length of **some path** from s to v

Bellman-Ford Algorithm

- After iteration ℓ :

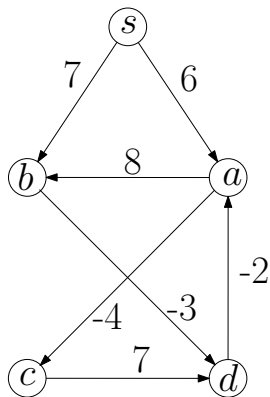
$$\begin{aligned} & \text{length of shortest } s\text{-}v \text{ path} \\ & \leq f[v] \\ & \leq \text{length of shortest } s\text{-}v \text{ path using at most } \ell \text{ edges} \end{aligned}$$

- Assuming there are no negative cycles:

$$\begin{aligned} & \text{length of shortest } s\text{-}v \text{ path} \\ & = \text{length of shortest } s\text{-}v \text{ path using at most } n - 1 \text{ edges} \end{aligned}$$

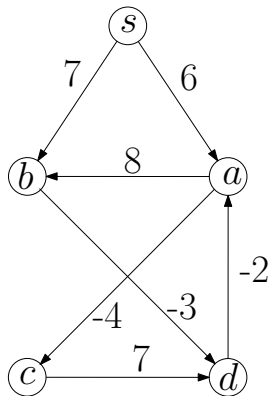
- So, assuming there are no negative cycles, after iteration $n - 1$:

$$f[v] = \text{length of shortest } s\text{-}v \text{ path}$$



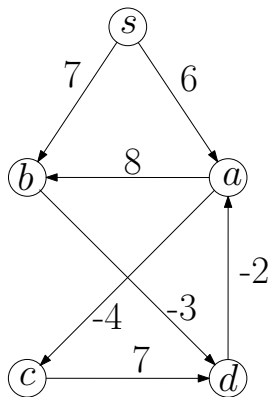
- order in which we consider edges:
 (s, a) , (s, b) , (a, b) , (a, c) , (b, d) ,
 (c, d) , (d, a)

vertices	s	a	b	c	d
f	0	∞	∞	∞	∞



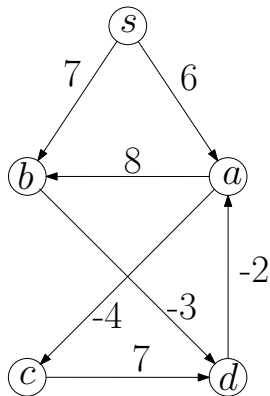
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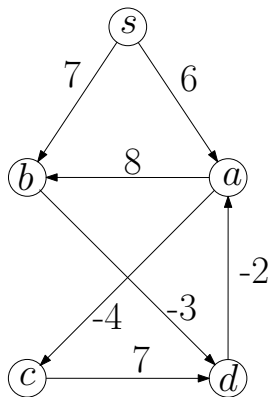
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vertices	s	a	b	c	d
f	0	6	∞	∞	∞



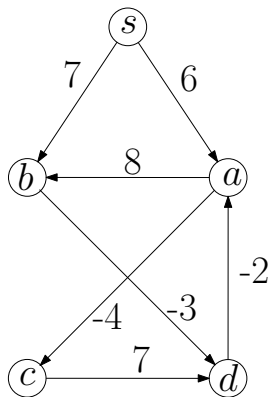
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vertices	s	a	b	c	d
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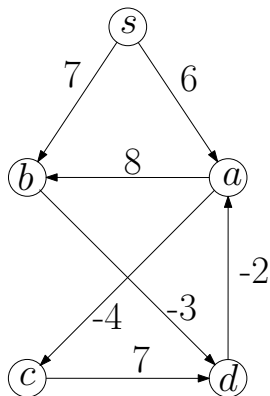
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 (c, d) , (d, a)

vertices	s	a	b	c	d
f	0	6	7	∞	∞



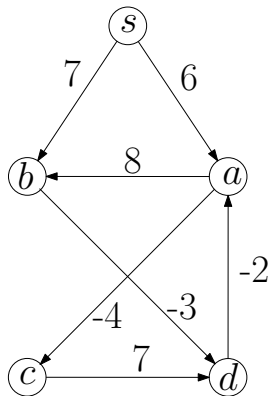
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vertices	s	a	b	c	d
f	0	6	7	∞	∞



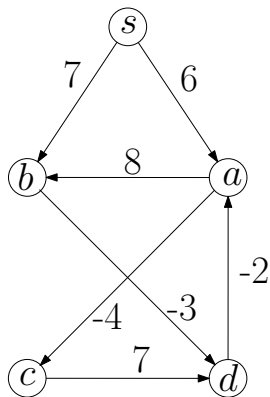
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vertices	s	a	b	c	d
f	0	6	7	∞	∞



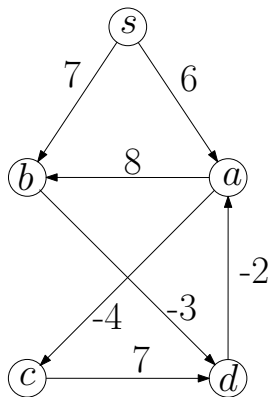
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vertices	s	a	b	c	d
f	0	6	7	2	∞



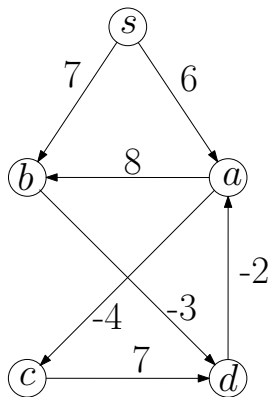
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vertices	s	a	b	c	d
f	0	6	7	2	∞



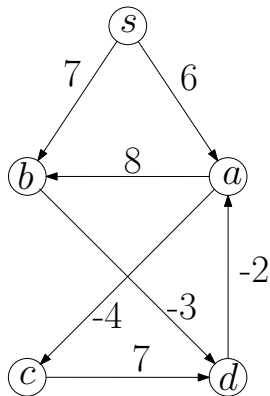
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vertices	s	a	b	c	d
f	0	6	7	2	4



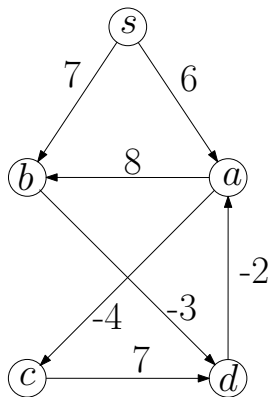
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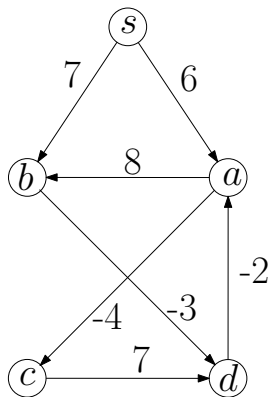
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vertices	s	a	b	c	d
f	0	6	7	2	4



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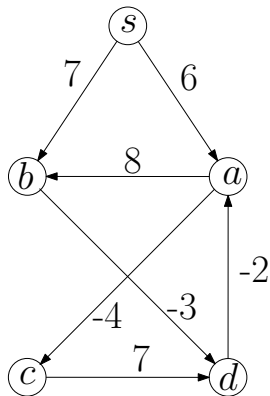
vertices	s	a	b	c	d
f	0	2	7	2	4



- order in which we consider edges:
 (s, a) , (s, b) , (a, b) , (a, c) , (b, d) ,
 (c, d) , (d, a)

vertices	<i>s</i>	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>
<i>f</i>	0	2	7	2	4

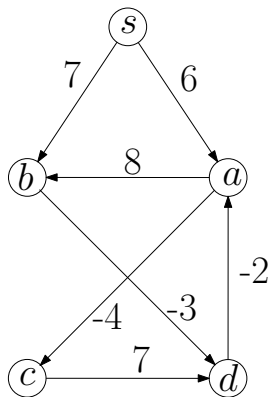
- end of iteration 1: 0, 2, 7, 2, 4



- order in which we consider edges:
 (s, a) , (s, b) , (a, b) , (a, c) , (b, d) ,
 (c, d) , (d, a)

vertices	<i>s</i>	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>
<i>f</i>	0	2	7	2	4

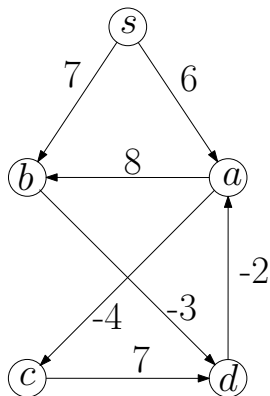
- end of iteration 1: 0, 2, 7, 2, 4



- order in which we consider edges:
 (s, a) , (s, b) , (a, b) , (a, c) , (b, d) ,
 (c, d) , (d, a)

vertices	<i>s</i>	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>
<i>f</i>	0	2	7	2	4

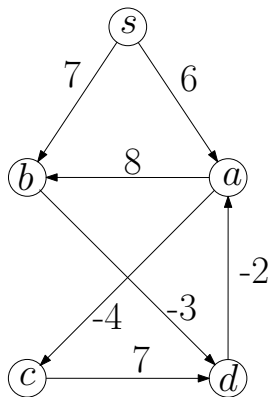
- end of iteration 1: 0, 2, 7, 2, 4



- order in which we consider edges:
 (s, a) , (s, b) , (a, b) , (a, c) , (b, d) ,
 (c, d) , (d, a)

vertices	<i>s</i>	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>
<i>f</i>	0	2	7	2	4

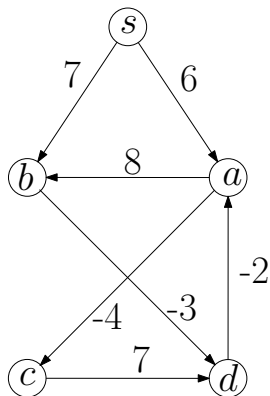
- end of iteration 1: 0, 2, 7, 2, 4



- order in which we consider edges:
 (s, a) , (s, b) , (a, b) , (a, c) , (b, d) ,
 (c, d) , (d, a)

vertices	s	a	b	c	d
f	0	2	7	2	4

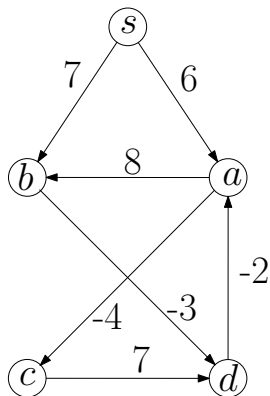
- end of iteration 1: 0, 2, 7, 2, 4



- order in which we consider edges:
 (s, a) , (s, b) , (a, b) , (a, c) , (b, d) ,
 (c, d) , (d, a)

vertices	<i>s</i>	<i>a</i>	<i>b</i>	<i>c</i>	<i>d</i>
<i>f</i>	0	2	7	-2	4

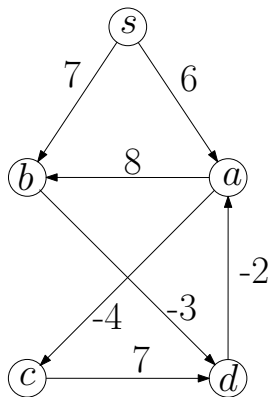
- end of iteration 1: 0, 2, 7, 2, 4



- order in which we consider edges:
 (s, a) , (s, b) , (a, b) , (a, c) , (b, d) ,
 (c, d) , (d, a)

vertices	s	a	b	c	d
f	0	2	7	-2	4

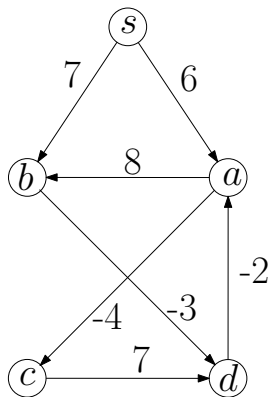
- end of iteration 1: 0, 2, 7, 2, 4



- order in which we consider edges:
 (s, a) , (s, b) , (a, b) , (a, c) , (b, d) ,
 (c, d) , (d, a)

vertices	s	a	b	c	d
f	0	2	7	-2	4

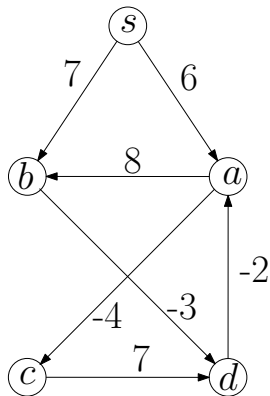
- end of iteration 1: 0, 2, 7, 2, 4



- order in which we consider edges:
 (s, a) , (s, b) , (a, b) , (a, c) , (b, d) ,
 (c, d) , (d, a)

vertices	s	a	b	c	d
f	0	2	7	-2	4

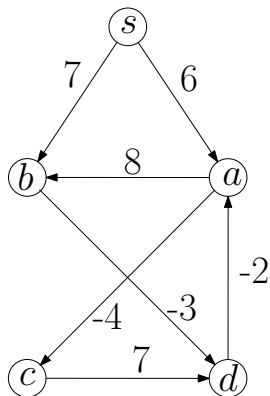
- end of iteration 1: 0, 2, 7, 2, 4



- order in which we consider edges:
 (s, a) , (s, b) , (a, b) , (a, c) , (b, d) ,
 (c, d) , (d, a)

vertices	s	a	b	c	d
f	0	2	7	-2	4

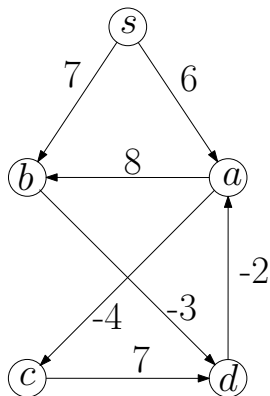
- end of iteration 1: 0, 2, 7, 2, 4
- end of iteration 2: 0, 2, 7, -2, 4



- order in which we consider edges:
 (s, a) , (s, b) , (a, b) , (a, c) , (b, d) ,
 (c, d) , (d, a)

vertices	s	a	b	c	d
f	0	2	7	-2	4

- end of iteration 1: 0, 2, 7, 2, 4
- end of iteration 2: 0, 2, 7, -2, 4
- end of iteration 3: 0, 2, 7, -2, 4



- order in which we consider edges:
 (s, a) , (s, b) , (a, b) , (a, c) , (b, d) ,
 (c, d) , (d, a)

vertices	s	a	b	c	d
f	0	2	7	-2	4

- end of iteration 1: 0, 2, 7, 2, 4
- end of iteration 2: 0, 2, 7, -2, 4
- end of iteration 3: 0, 2, 7, -2, 4
- Algorithm terminates in 3 iterations, instead of 4.

Bellman-Ford Algorithm

Bellman-Ford(G, w, s)

- 1: $f[s] \leftarrow 0$ and $f[v] \leftarrow \infty$ for any $v \in V \setminus \{s\}$
- 2: **for** $\ell \leftarrow 1$ to n **do**
- 3: $updated \leftarrow \text{false}$
- 4: **for each** $(u, v) \in E$ **do**
- 5: **if** $f[u] + w(u, v) < f[v]$ **then**
- 6: $f[v] \leftarrow f[u] + w(u, v)$
- 7: $updated \leftarrow \text{true}$
- 8: **if not** $updated$, then return f
- 9: output “negative cycle exists”