

CSE 431/531: Algorithm Analysis and Design (Fall 2024)

Dynamic Programming

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Paradigms for Designing Algorithms

Greedy algorithm

- Make a greedy choice
- Prove that the greedy choice is safe
- Reduce the problem to a sub-problem and solve it iteratively
- Usually for optimization problems

Divide-and-conquer

- Break a problem into many **independent** sub-problems
- Solve each sub-problem separately
- Combine solutions for sub-problems to form a solution for the original one
- Usually used to design more efficient algorithms

Paradigms for Designing Algorithms

Dynamic Programming

- Break up a problem into many **overlapping** sub-problems
- Build solutions for larger and larger sub-problems
- Use a **table** to store solutions for sub-problems for reuse

Recall: Computing the n -th Fibonacci Number

- $F_0 = 0, F_1 = 1$
- $F_n = F_{n-1} + F_{n-2}, \forall n \geq 2$
- Fibonacci sequence: 0, 1, 1, 2, 3, 5, 8, 13, 21, 34, 55, 89, \dots

Fib(n)

```
1:  $F[0] \leftarrow 0$   
2:  $F[1] \leftarrow 1$   
3: for  $i \leftarrow 2$  to  $n$  do  
4:    $F[i] \leftarrow F[i - 1] + F[i - 2]$   
5: return  $F[n]$ 
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- Store each $F[i]$ for future use.

Outline

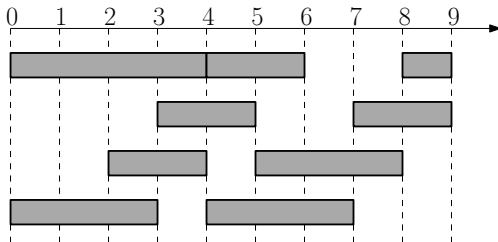
1 Weighted Interval Scheduling

Recall: Interval Scheduling

Input: n jobs, job i with start time s_i and finish time f_i

i and j are compatible if $[s_i, f_i)$ and $[s_j, f_j)$ are disjoint

Output: a maximum-size subset of mutually compatible jobs

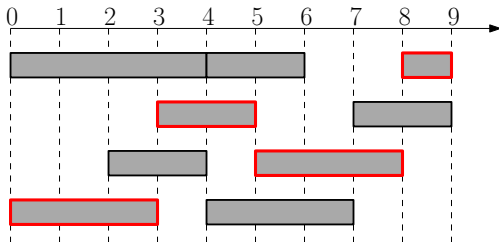


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Weighted Interval Scheduling

Input: n jobs, job i with start time s_i and finish time f_i

each job has a weight (or value) $v_i > 0$

i and j are compatible if $[s_i, f_i)$ and $[s_j, f_j)$ are disjoint

Output: a maximum-weight subset of mutually compatible jobs

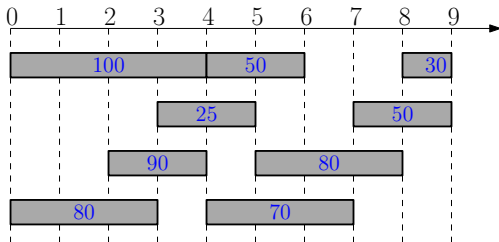
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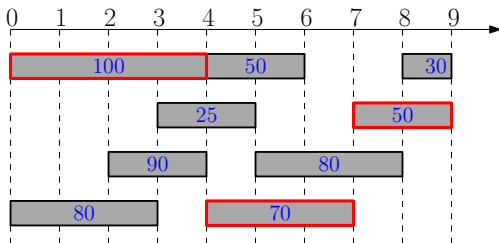
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Optimum value = 220

Hard to Design a Greedy Algorithm

Q: Which job is safe to schedule?

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- Job with the earliest finish time?

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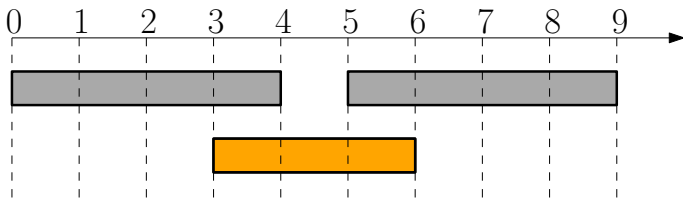
No, when weights are equal, this is the shortest job

Hard to Design a Greedy Algorithm

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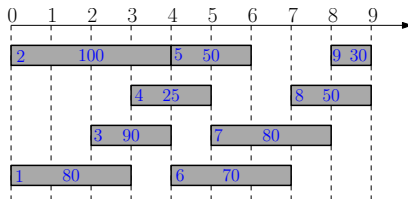
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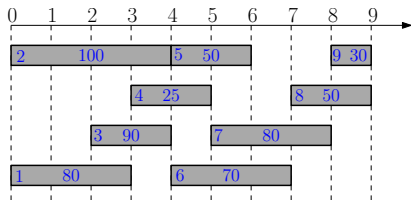
Designing a Dynamic Programming Algorithm

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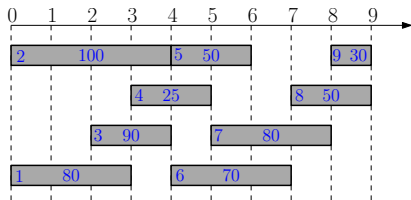
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Designing a Dynamic Programming Algorithm



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- $opt[i]$: optimal value for instance only containing jobs $\{1, 2, \dots, i\}$

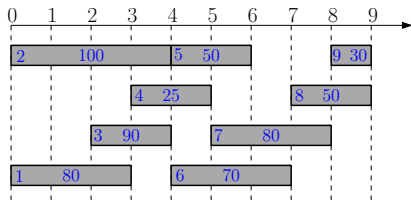
Designing a Dynamic Programming Algorithm



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i	$opt[i]$
0	
1	
2	
3	
4	
5	
6	
7	
8	
9	

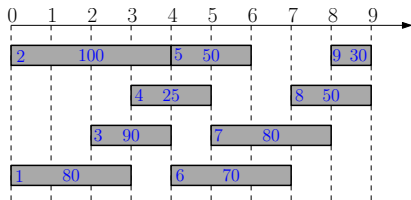
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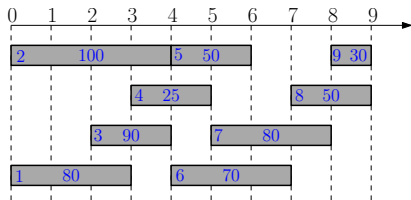
Designing a Dynamic Programming Algorithm



- Sort jobs according to non-decreasing order of finish times
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i	$opt[i]$
0	0
1	80
2	
3	
4	
5	
6	
7	
8	
9	

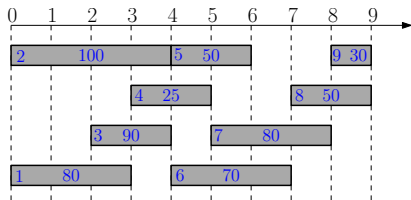
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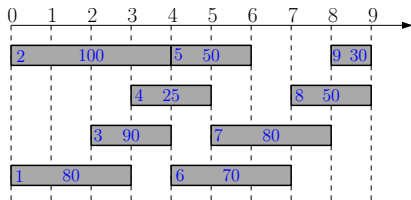
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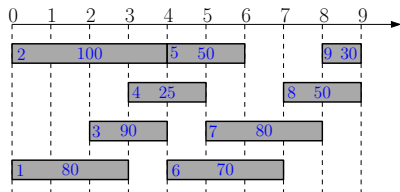
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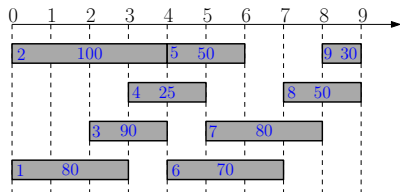
i	$opt[i]$
0	0
1	80
2	100
3	100
4	105
5	150
6	170
7	185
8	220
9	220

Designing a Dynamic Programming Algorithm



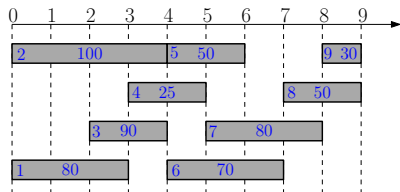
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Designing a Dynamic Programming Algorithm



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- assume we have computed $opt[0], opt[1], \dots, opt[i-1]$

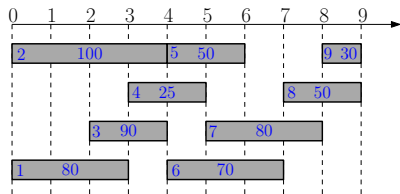
Designing a Dynamic Programming Algorithm



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Q: The value of optimal solution that **does not contain** i ?

Designing a Dynamic Programming Algorithm

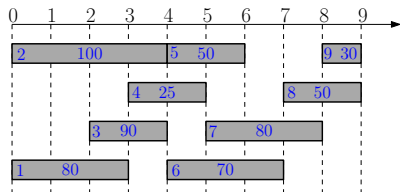


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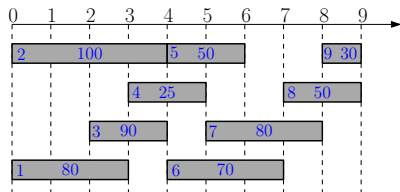
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Q: The value of optimal solution that **contains** job i ?

Designing a Dynamic Programming Algorithm



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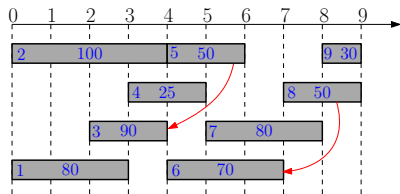
A: $opt[i-1]$

Q: The value of optimal solution that **contains** job i ?

A: $v_i + opt[p_i]$,

p_i = the largest j such that $f_j \leq s_i$

Designing a Dynamic Programming Algorithm



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Designing a Dynamic Programming Algorithm

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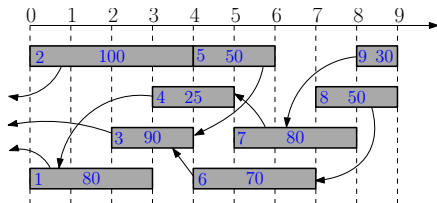
Recursion for $opt[i]$:

$$opt[i] = \max \{opt[i - 1], v_i + opt[p_i]\}$$

Designing a Dynamic Programming Algorithm

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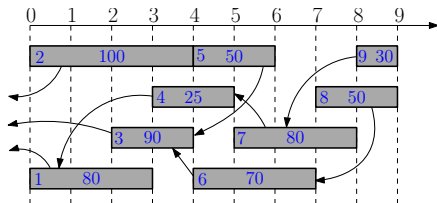


- $opt[0] = 0$
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- $opt[2] =$
- $opt[3] =$
- $opt[4] =$
- $opt[5] =$

Designing a Dynamic Programming Algorithm

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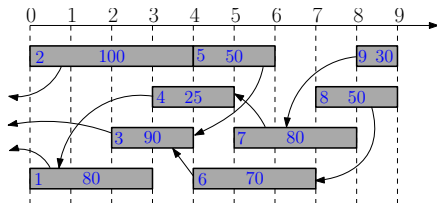


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Designing a Dynamic Programming Algorithm

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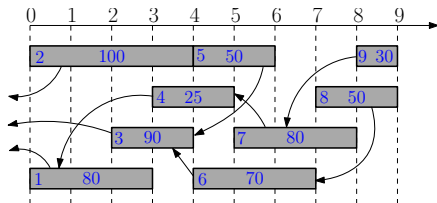


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Designing a Dynamic Programming Algorithm

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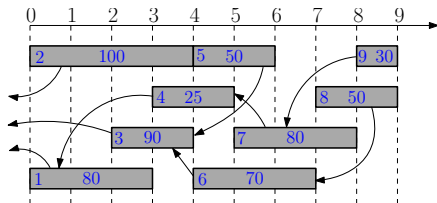


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Designing a Dynamic Programming Algorithm

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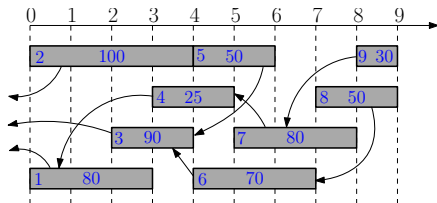


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- $opt[2] = \max\{opt[1], 100 + opt[0]\} = 100$
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- $opt[5] =$

Designing a Dynamic Programming Algorithm

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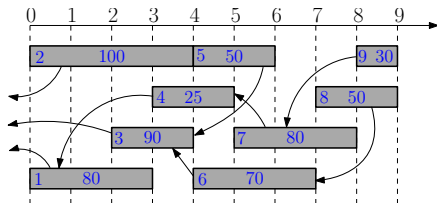


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Designing a Dynamic Programming Algorithm

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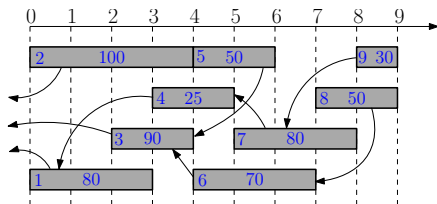


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Designing a Dynamic Programming Algorithm

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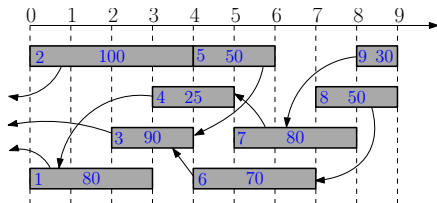


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Designing a Dynamic Programming Algorithm

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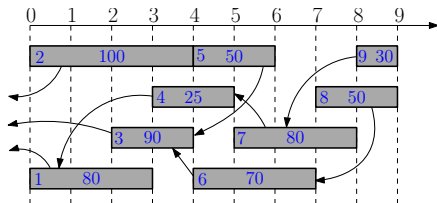


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- $opt[4] = \max\{opt[3], 25 + opt[1]\} = 105$
- $opt[5] = \max\{opt[4], 50 + opt[3]\}$

Designing a Dynamic Programming Algorithm

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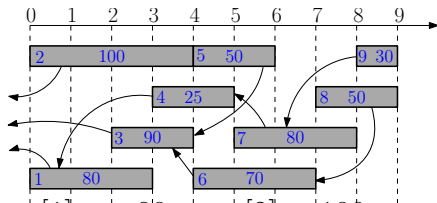


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Designing a Dynamic Programming Algorithm

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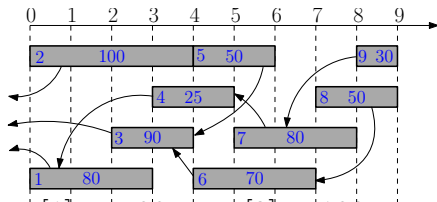


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Designing a Dynamic Programming Algorithm

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- $opt[0] = 0, \quad opt[1] = 80, \quad opt[2] = 100$
- $opt[3] = 100, \quad opt[4] = 105, \quad opt[5] = 150$
- $opt[6] = \max\{opt[5], 70 + opt[3]\} = 170$
- $opt[7] = \max\{opt[6], 80 + opt[4]\} = 185$
- $opt[8] = \max\{opt[7], 50 + opt[6]\} = 220$
- $opt[9] = \max\{opt[8], 30 + opt[7]\} = 220$

Dynamic Programming

- 1: sort jobs by non-decreasing order of finishing times
- 2: compute p_1, p_2, \dots, p_n
- 3: $opt[0] \leftarrow 0$
- 4: **for** $i \leftarrow 1$ to n **do**
- 5: $opt[i] \leftarrow \max\{opt[i - 1], v_i + opt[p_i]\}$

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```

- Running time sorting: $O(n \lg n)$
- Running time for computing p : $O(n \lg n)$ via binary search
- Running time for computing $opt[n]$: $O(n)$

How Can We Recover the Optimum Schedule?

```
1: sort jobs by non-decreasing order of
   finishing times
2: compute  $p_1, p_2, \dots, p_n$ 
3:  $opt[0] \leftarrow 0$ 
4: for  $i \leftarrow 1$  to  $n$  do
5:     if  $opt[i - 1] \geq v_i + opt[p_i]$  then
6:          $opt[i] \leftarrow opt[i - 1]$ 
7:
8:     else
9:          $opt[i] \leftarrow v_i + opt[p_i]$ 
10:
```

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3:  $opt[0] \leftarrow 0$ 
4: for  $i \leftarrow 1$  to  $n$  do
5:     if  $opt[i - 1] \geq v_i + opt[p_i]$  then
6:          $opt[i] \leftarrow opt[i - 1]$ 
7:          $b[i] \leftarrow \text{N}$ 
8:     else
9:          $opt[i] \leftarrow v_i + opt[p_i]$ 
10:         $b[i] \leftarrow \text{Y}$ 
```

How Can We Recover the Optimum Schedule?

```
1: sort jobs by non-decreasing order of
   finishing times
2: compute  $p_1, p_2, \dots, p_n$ 
3:  $opt[0] \leftarrow 0$ 
4: for  $i \leftarrow 1$  to  $n$  do
5:     if  $opt[i - 1] \geq v_i + opt[p_i]$  then
6:          $opt[i] \leftarrow opt[i - 1]$ 
7:          $b[i] \leftarrow N$ 
8:     else
9:          $opt[i] \leftarrow v_i + opt[p_i]$ 
10:         $b[i] \leftarrow Y$ 
```

```
1:  $i \leftarrow n, S \leftarrow \emptyset$ 
2: while  $i \neq 0$  do
3:     if  $b[i] = N$  then
4:          $i \leftarrow i - 1$ 
5:     else
6:          $S \leftarrow S \cup \{i\}$ 
7:          $i \leftarrow p_i$ 
8: return  $S$ 
```