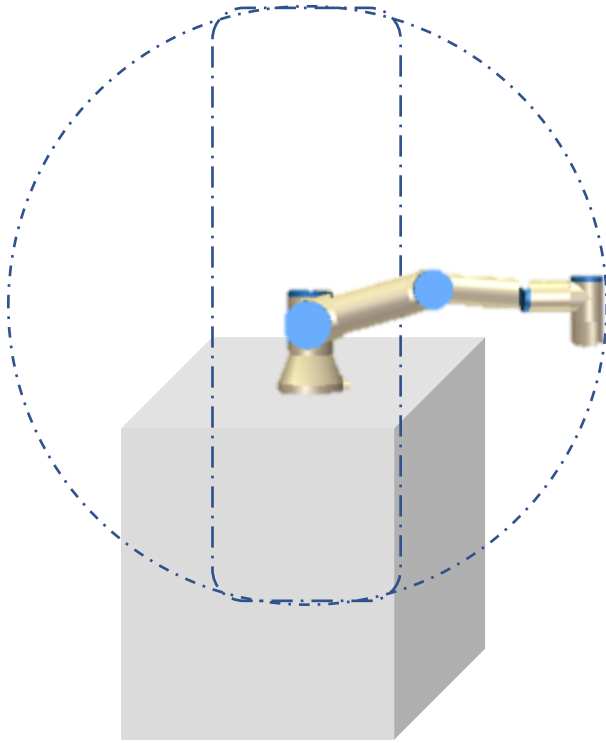
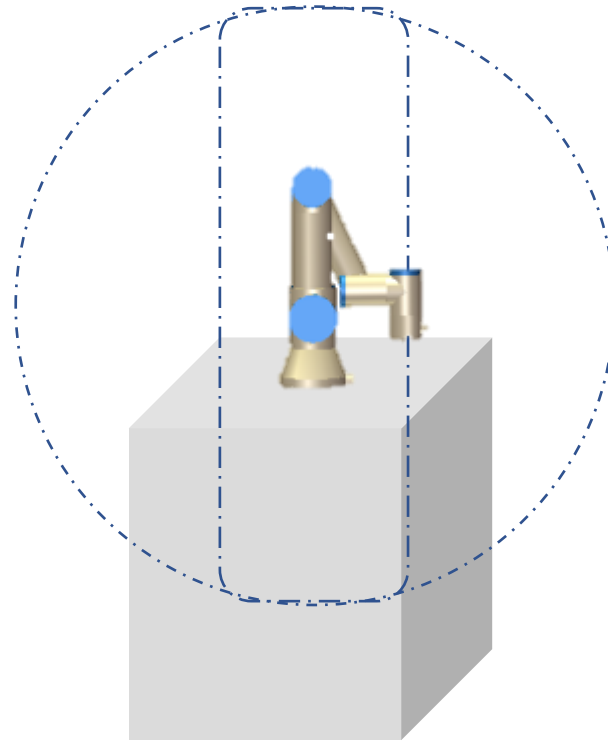


Robot	
Feature	Active TCP
Base	TCP

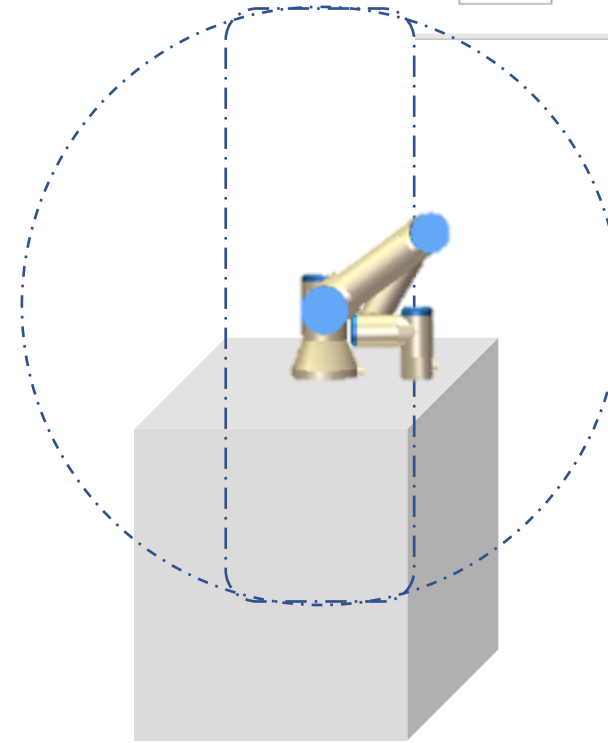
Tool Position			
X	120.00 mm	RX	3.153 rad
Y	182.53 mm	RY	0.013 rad
Z	19.34 mm	RZ	-0.047 rad



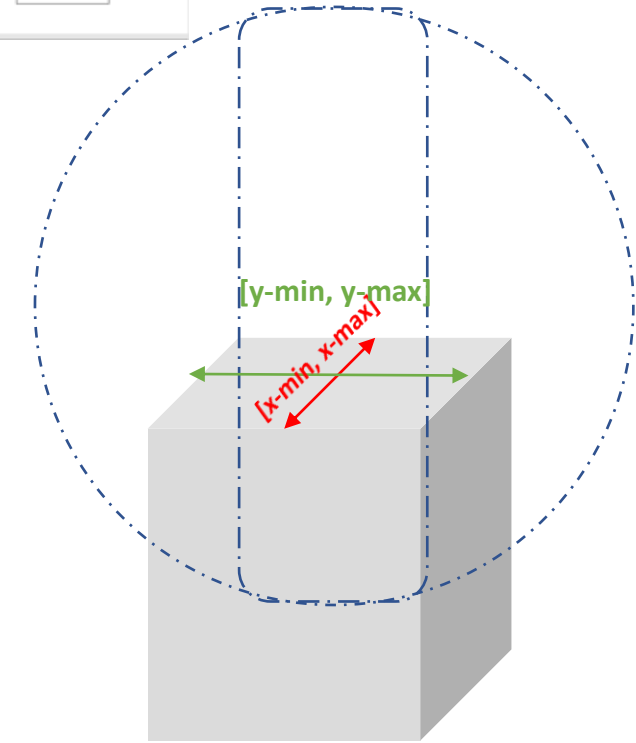
[A]
max displacement
square



[B]
min displacement
square



[C]
tcp z-axis before
collision z-min



[D]
[x-min, x-max, y-min, y-max]
defining the mount surface