



3V3 3V3 3V3 DRV8874PWPR I_trip = Max Driver Current R32 MOT1 PWM EN/IN1 **PMODE** ₹10K $I_{trip} = Vref / (R_{irop} * 0.000455)$ MOT1 DIR PH/IN2 **GND** 14 NSLEEP CPL ÷ Using R = 2K and VREF = 3.3 13 NFAULT CPH 22nF/50V $I_{trip} = 3.626A$ GND VREF VCP MOT1 ADC MOT1 B 11 C21 IPROPI VM VCC 10 MOT1_B **IMODE** OUT2 MOT1_A 8 Motor Connector OUT1 PGND R33 100nF/16V ₹2K MOT1_ADC cannot be larger than adc max value. GND So: 17 -C23 100nF 22uF/25V V = R*I = R*Aipropi*i =>GND GND ÷ V = 2000 * 0.000455 * i GND = GND Para V = 3.3, I = 3.623V3 3V3 3V3 Precisão do ADC: 3.3/4096 -> 0.000805664mV DRV8874PWPR R34 Precisão da corrente: MOT2 PWM EN/IN1 PMODE ₹10K V = R*I = R * Aipropi * i MOT2 DIR PH/IN2 GND i = 0.000805664 / (2000 * 0.000455) = 0.88mA NSLEEP CPL 를 GND 13 NFAULT CPH 22nF/50V VREF VCP MOT2_ADC C25 IPROPI VM VCC MOT2 10 MOT2 B **IMODE** OUT2 MOT2_A 8 MOT2_B OUT1 PGND R35 100nF/16V ÷ **₹**2K Motor Connector **GND** C26 17 ÷ 100nF 22uF/25V GND GND 를 GND VCC END D10 3V3 Motor Connector SPI_CLK SPI_MISO ENC_1_A Q7 \IRLML6344TRPBF SPI MOSI 4 ENC 1 B **GND** MOT_FAN R36 ENCODER CONNECTOR R37 47K SPI_CS_2 SPI_CLK SPI_MISO 3 ENC_2_A SPI_MOSI ENC 2 B ÷ GND ENCODER_CONNECTOR GND Title Size Number Revision A4 Date: Sheet Of

File:

Drawn By:

