AADL Textual Instance Model May 2016

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Textual Instance Model Implementation

Available in nightly build of OSATE

Invoke "Generate textual instance" in context menu on aaxl2 instance file

Syntax objective: compact, readable

- Size: 20-25% of XMI representation
- References into declarative model (grey)
 - References to unnamed elements (property association, mode transition, SOM)

```
system s_i_Instance : dummy::s.i {
   in out dataAccess dacc : dummy::s:dacc
   in dataPort inp : dummy::s:inp {
        Data_Model::Data_Representation => Integer : Base_Types::Integer:property#0
   }
   out eventPort outp : dummy::s:outp
   device sense : dummy::s.i:sense {
        out dataPort reading : dummy::sensor:reading
   }
   som "No Modes"
}
```

Declarative Example

```
package dummy
public
    with Base Types;
    system s
         features
             inp: in data port Base Types::Integer;
             outp: out event port;
             dacc: requires data access myd;
    end s;
    system implementation s.i
         subcomponents
             sense: device sensor;
    end s.i;
    device sensor
         features
             reading: out data port myd;
    end sensor;
    data myd
    end myd;
end dummy;
```

Connections and Flows

```
complete portConnection "SM_Motor.Step_Completion -> SM_ACT.Step_Completion":
SM_Motor.Step_Completion -> SM_ACT.Step_Completion {
    SM_Motor.Step_Completion -> SM_ACT.Step_Completion : CasePositionControl::SMS.Original:c4 in parent
}
complete portConnection "SM_PCS_App.SM_PCS.Commanded_Position -> SM_ACT.Commanded_Position":
SM_PCS_App.SM_PCS.Commanded_Position -> SM_ACT.Commanded_Position {
    SM_PCS_App.SM_PCS.Commanded_Position -> SM_PCS_App.Commanded_Position :
        CasePositionControl::SMS_App_Process_SMPC.original:CmdedPosition in SM_PCS_App
SM_PCS_App.Commanded_Position -> SM_ACT.Commanded_Position :
        CasePositionControl::SMS.Original:SendPositionChangeCommand in parent
        Deployment_Properties::Actual_Connection_Binding => ( reference ( DMA ) ) : CasePositionControl::SMS_Communication_Properties::Timing => immediate : CasePositionControl::SMS.Original:SendPositionChange() }
flow flowsink ( Desired_Position -> ) : CasePositionControl::SMS:flowsink
```