

Neural Network & Deep Learning

Convolutional NN

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Convolutional NN (CNN)(ConvNet)

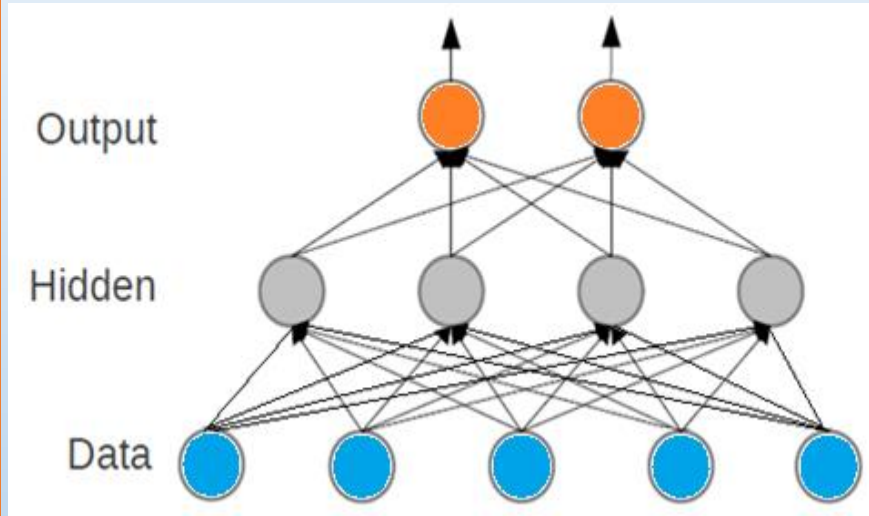
- A type of **feed-forward** neural network
- **Connectivity** pattern between its neurons is inspired by the organization of the **animal visual cortex**
- Individual **cortical neurons** respond to **stimuli** in a restricted region of space known as **receptive field**
- **Receptive fields** of different neurons partially **overlap** such that they **tile** visual field

ConvNet

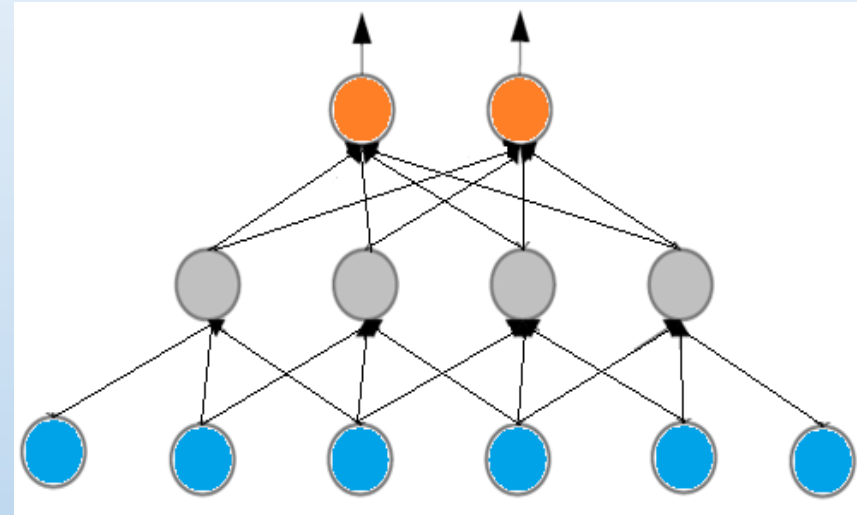
- Response of an **individual** neuron to stimuli within its **receptive field** can be approximated mathematically by a **convolution** operation
- Convolutional networks were **inspired** by biological processes and are variations of **MLPs**, designed to use minimal amounts of **preprocessing**
- Wide applications in **image and video recognition**, **recommender systems** and **natural language processing**

ConvNet

common NN



convolutional NN



- Each hidden neuron applies the same **localized**, **nonlinear** filter to input
- Like most NNs, ConvNets are **trained** with a version of **back-propagation** algorithm

ConvNet History

- Concept of **ConvNet** introduced in **1995**



Yann LeCun

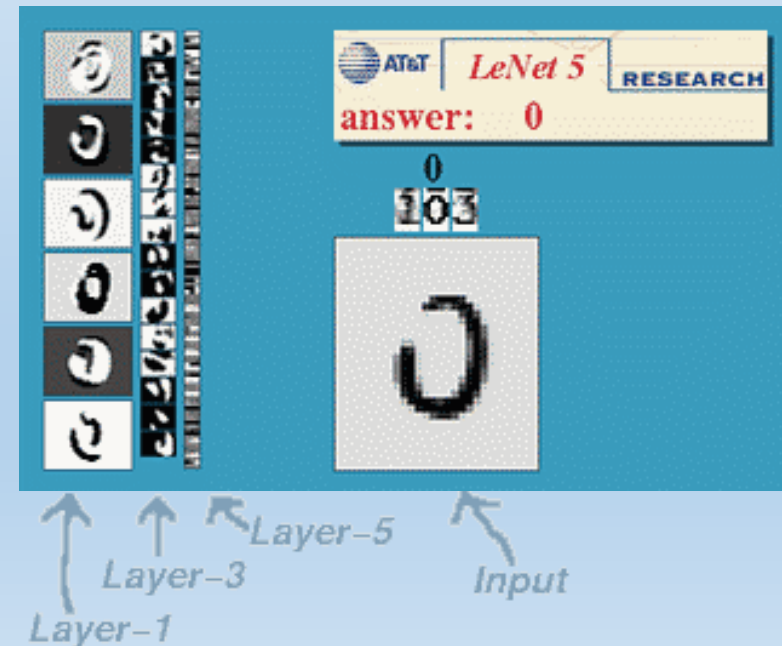
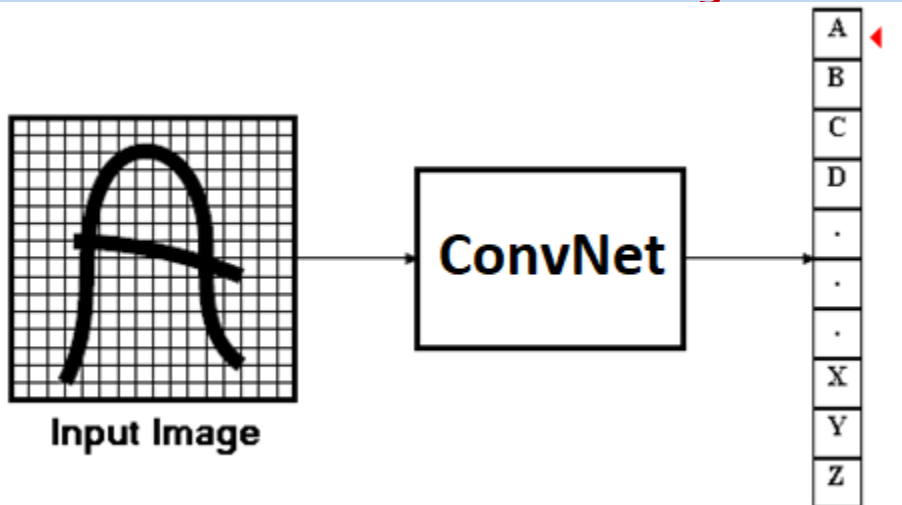


Yoshua Bengio

0 1 2 3 4 5 6 7 8 9



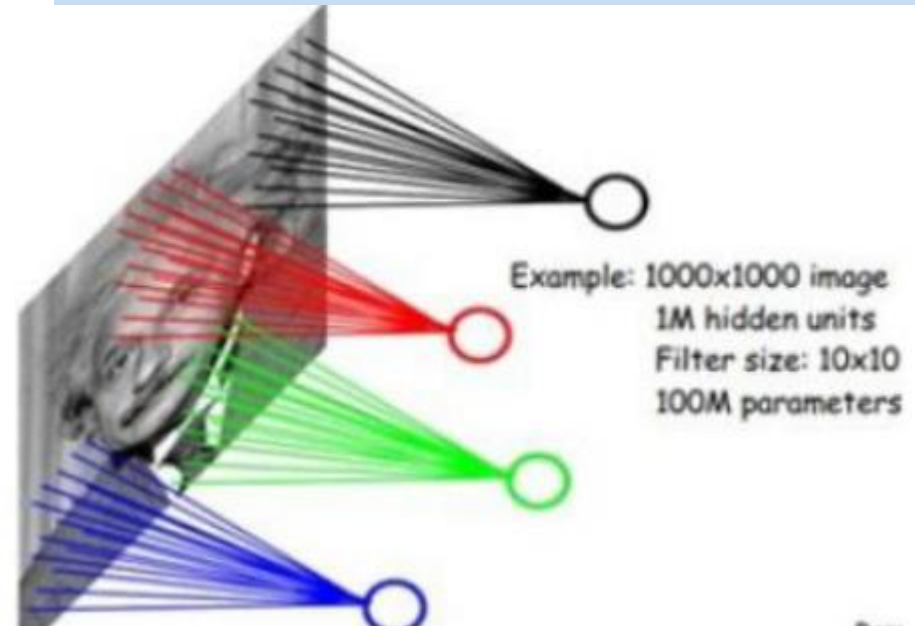
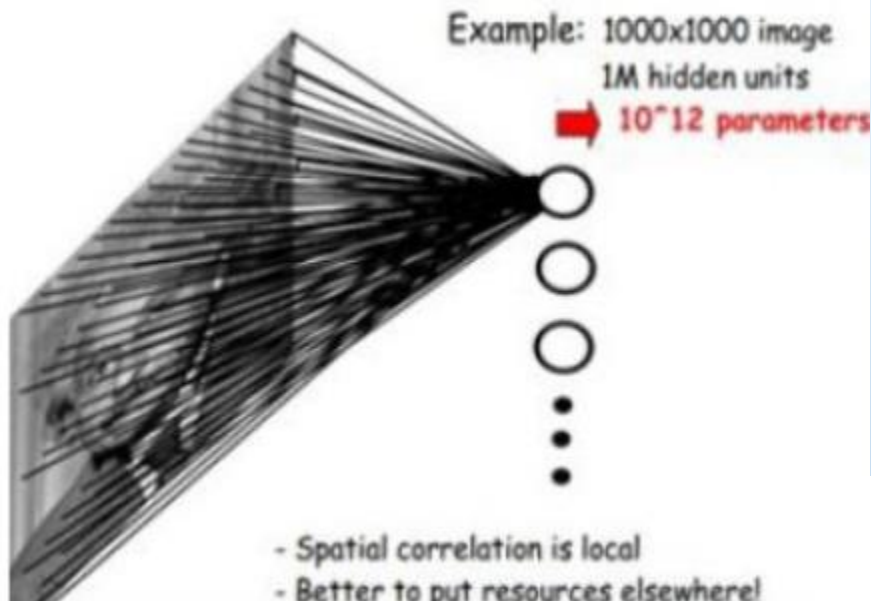
0 1 2 3 4 5 6 7 8 9



ConvNet Motivation

- Natural images are **stationary**
 - **Statistics** of one part of an image is the **same** as any other part
 - **Features** which are **learned** at one part of an image can also be applied to its other parts
 - The same **features** can also be used at all **locations**
- These models have **revolutionized** speech and object recognition

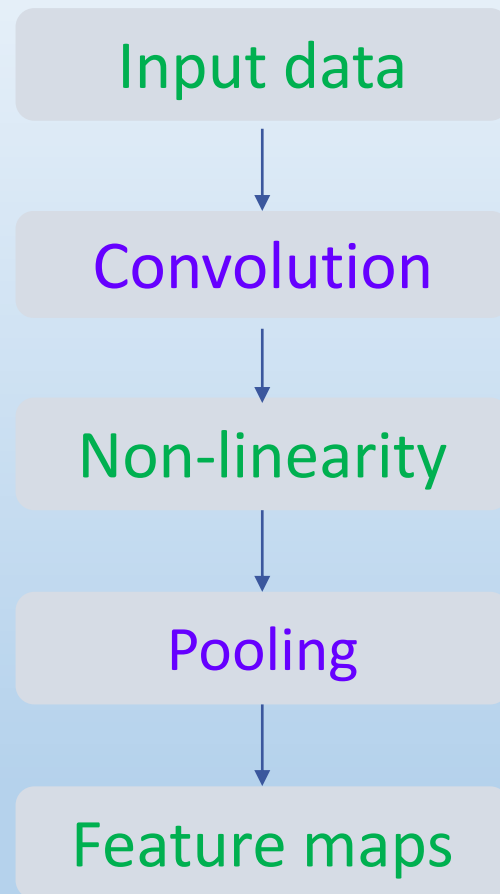
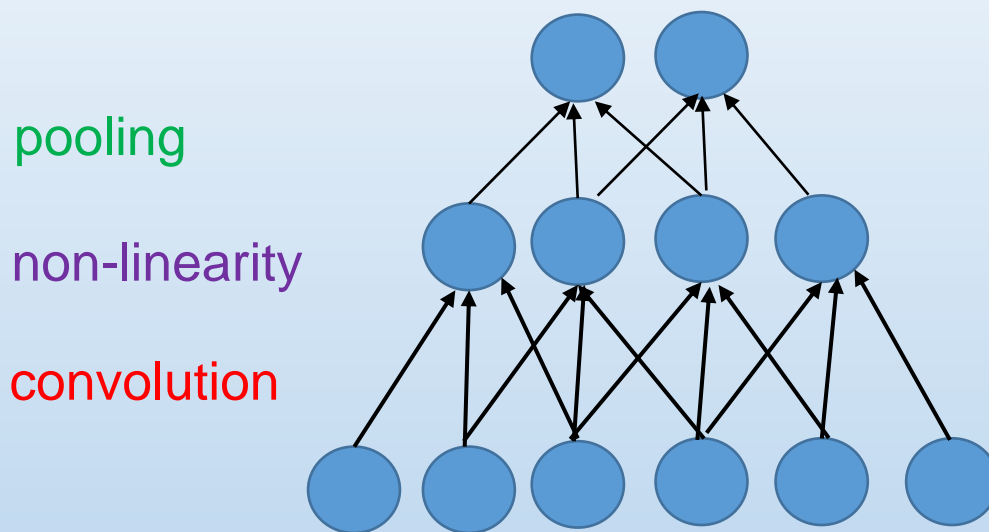
ConvNet Motivation



ConvNet Features

- Convolution leverages three important ideas that can help improve a machine learning system:
 - Sparse interactions (sparse connectivity/weights)
 - Parameter sharing
 - Equivariant representations
- ConvNet can implicitly extract relevant features
- It can extract topological properties from an image

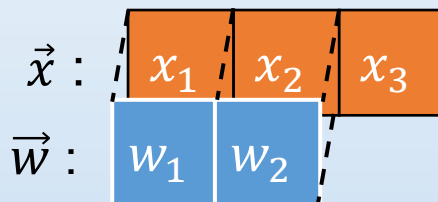
Recap of ConvNet



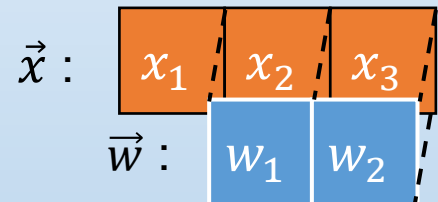
- Feed-forward
 - Convolving input
 - Non-linearity in activation function
 - Pooling
- Supervisedly trained by back-propagating error

1D Convolution

Correlation (Similarity):



$$z_{in_1} = w_1 x_1 + w_2 x_2$$



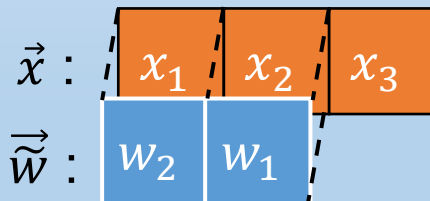
\vec{z} : 

$$z_{in_2} = w_1 x_2 + w_2 x_3$$


$$z_{in_j} = \sum_{i=1}^F w_i x_{j+i-1}$$

where $F = |\vec{w}|$: size of filter

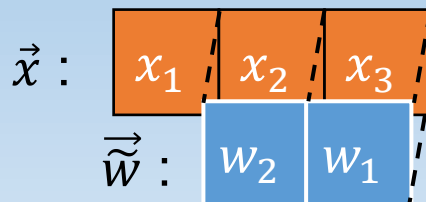
Convolution:



$$z_{in_1} = w_2 x_1 + w_1 x_2$$

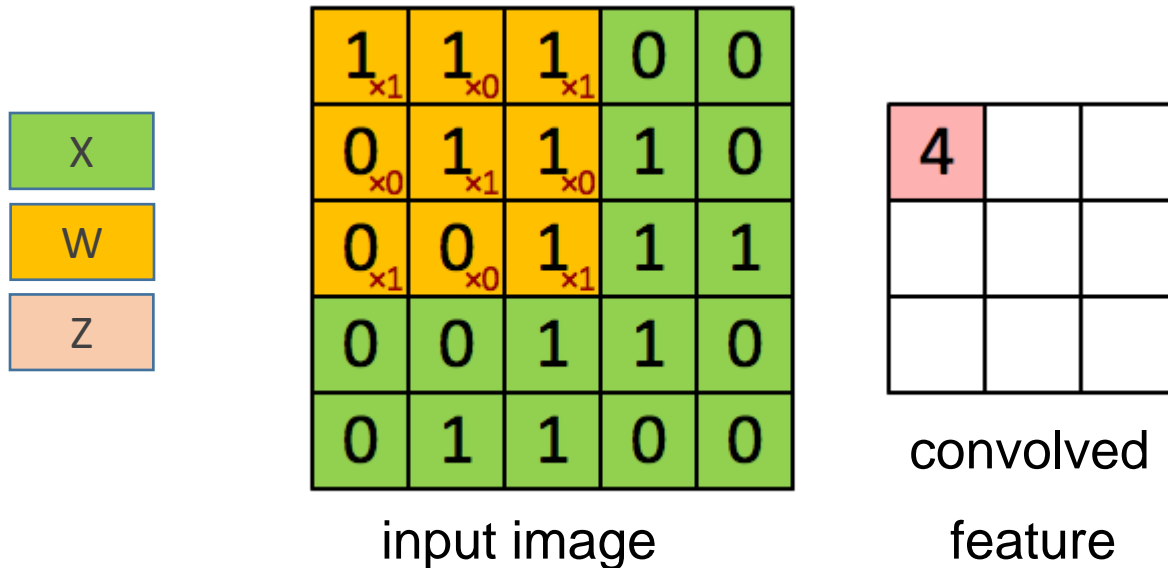
\vec{z} : 

$$z_{in_j} = \sum_{i=1}^F \tilde{w}_{F-i+1} x_{j+i-1}$$

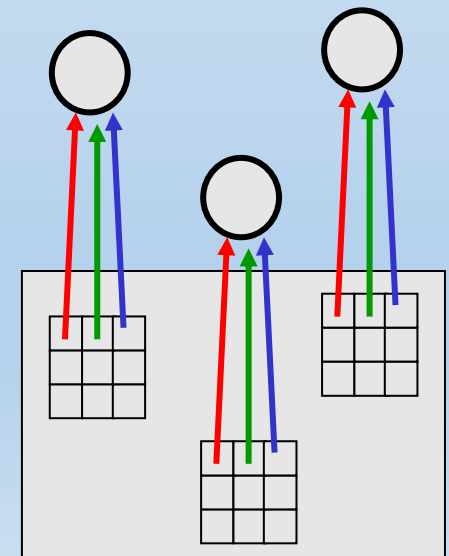


$$z_{in_2} = w_2 x_2 + w_1 x_3$$

2D Convolution

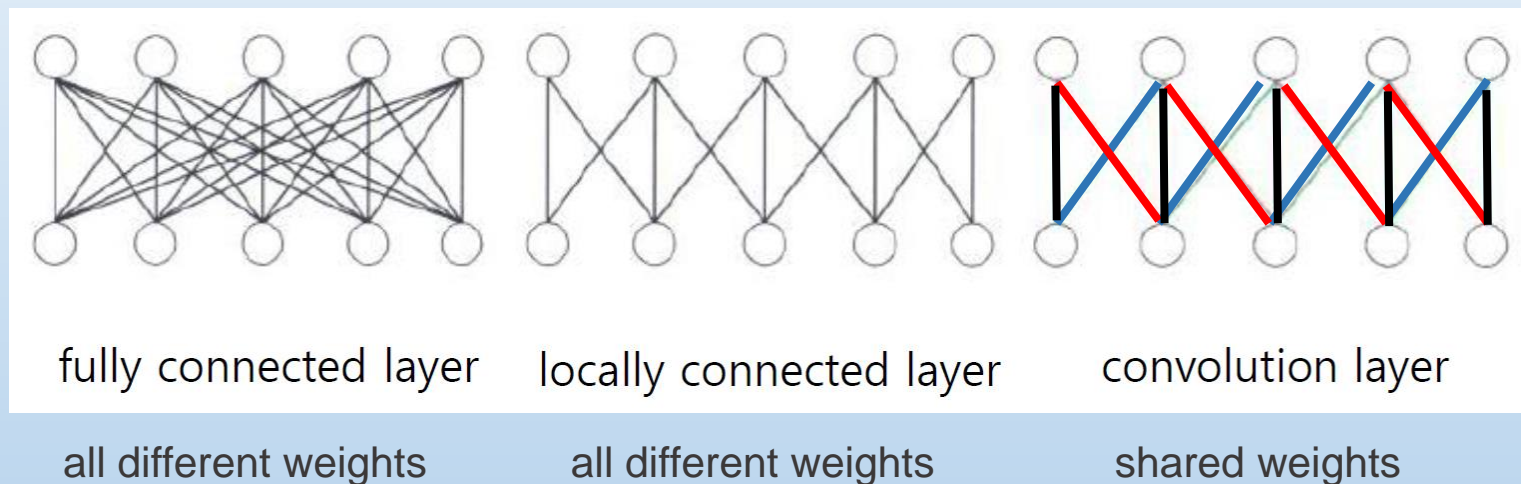


- The same **colored** connections all have the same **weight**



Convolution (Weight Sharing)

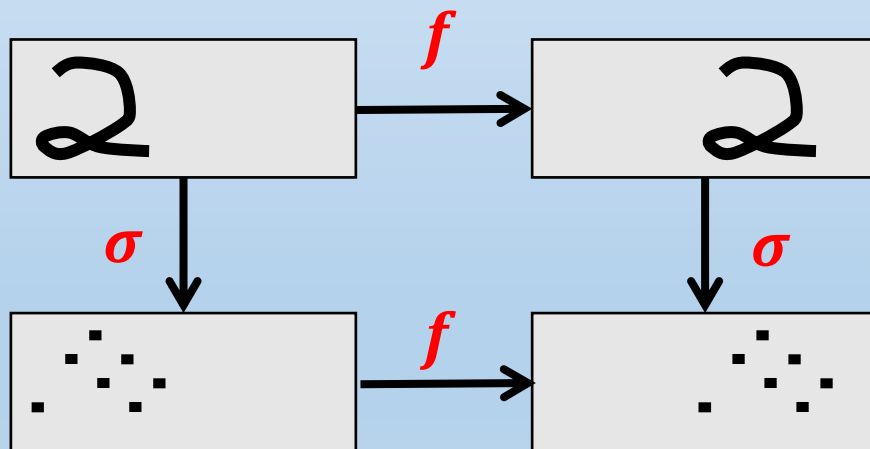
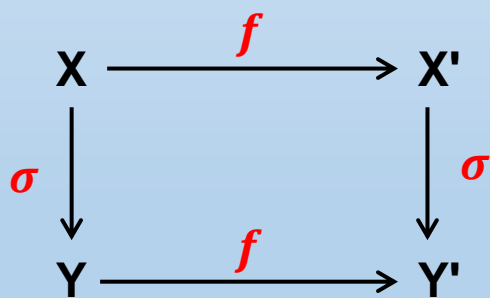
- Connectivity and weight **sharing** depends on layer



- Convolution** layer has much **smaller** number of parameters by **local** connection and weight **sharing**

Convolution (Equivariance)

- Convolutional structure of ConvNets preserves symmetries of input data (outputs of ConvNets retain symmetries of inputs)
- For any symmetry operation $\sigma(\cdot)$, applying σ to input data and then passing it through model $f(\cdot)$ would be the same as applying σ to output of model f : $f(\sigma(x)) = \sigma(f(x))$



- Model f is **equivariant** with respect to symmetry operation σ

Convolution (Equivariance)

- **Equivariance** of ConvNets with respect to **translation**
- **Shift to input image corresponds to shift of output features**

Existing CNNs: Translation Equivariance

Input



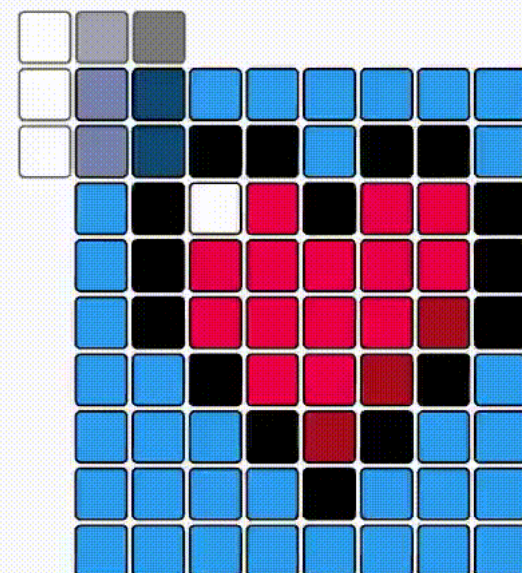
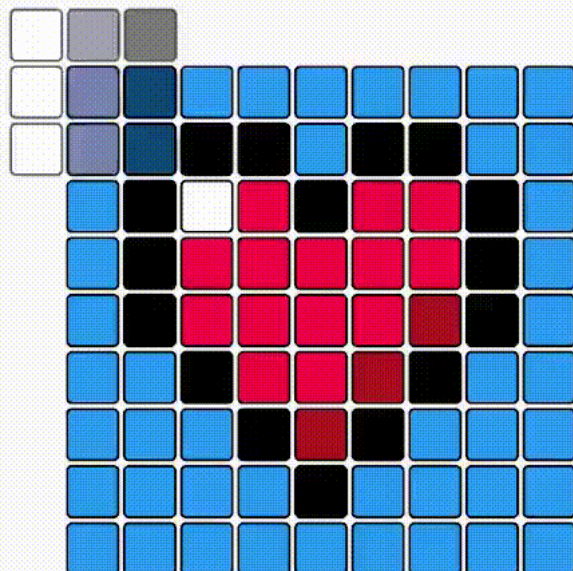
Features



Windowed
view

Convolution (Equivariance)

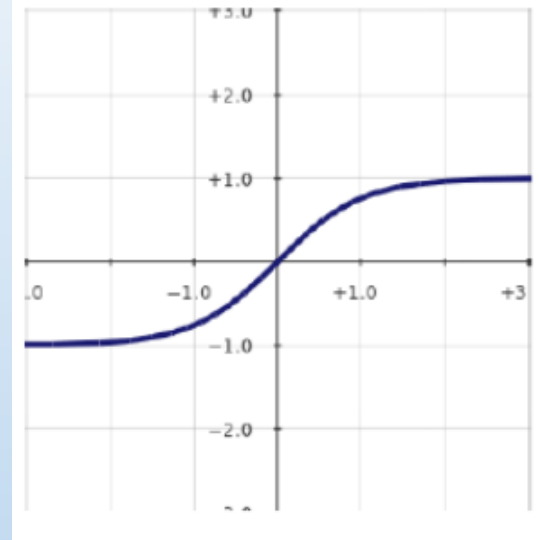
- Equivariance of ConvNets with respect to translation



Non-linearity in ConvNet

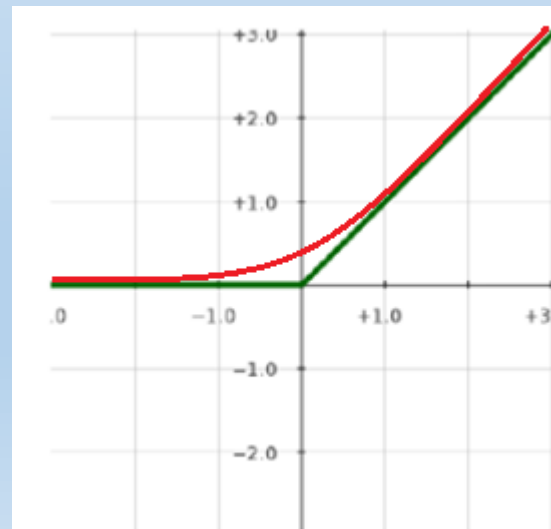
- Bipolar sigmoid

- $f(z_{in}) = \tanh(z_{in}) = \frac{1 - e^{-z_{in}}}{1 + e^{-z_{in}}}$
- Slow to train
- Has vanishing gradient problem
- Commonly used



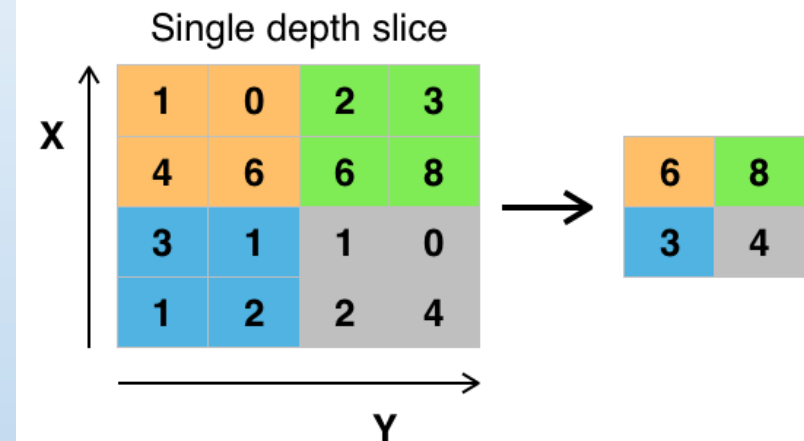
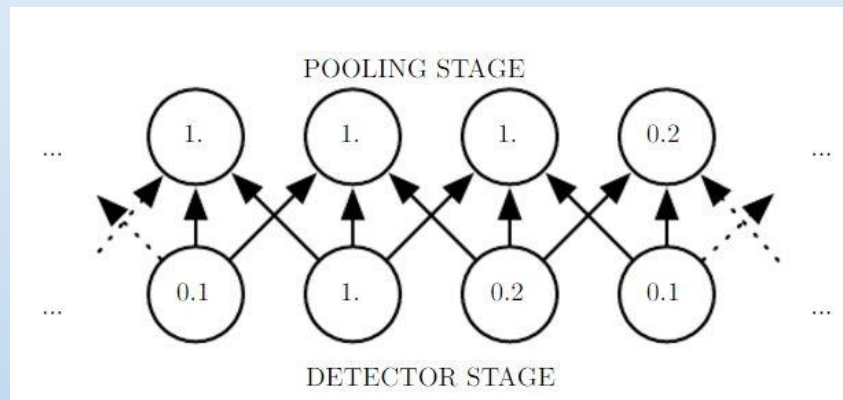
- Rectifier linear unit (ReLU)

- $f(z_{in}) = \text{ReLU}(z_{in}) = \max(z_{in}, 0)$
- $f(z_{in}) = \ln(1 + e^x)$
- Quick to train
- Less vanishes gradient
- Recently used



Popular Pooling Functions

- Maximum of a rectangular neighborhood (max pooling)

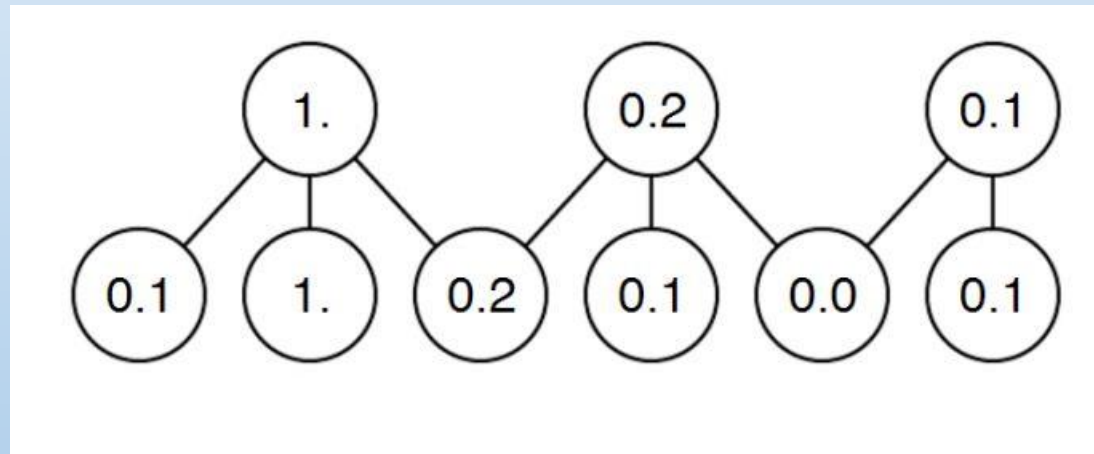


- Weighting of a rectangular neighborhood
- l_2 norm of a rectangular neighborhood
- Average of a rectangular neighborhood
- Weighted average based on distance from central pixel

Pooling with Down-sampling

Down-sampling (**subsampling**) during pooling

- **Max-pooling** with a pool width of **3** and a **stride** between pools of 2



- This **reduces** the representation size by a factor of **2**, which reduces the computational and statistical burden

Back-propagation in ConvNet

- Output layer:

for $k = 1..m$

$$\delta_k^O = -(t_k - y_k) f^{O'}(y_{in_k})$$

- Pooling weights W :

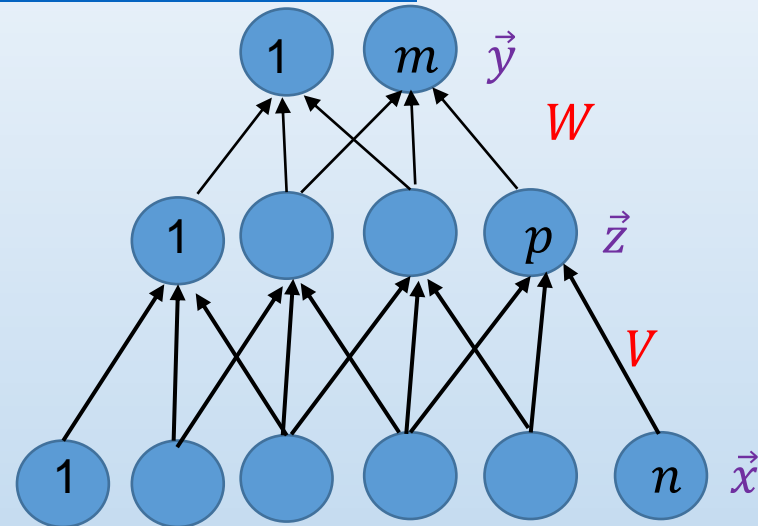
- To propagate the error through the pooling layer by calculating the error w.r.t to each unit incoming to the pooling layer

for $k = 1..m$

$$J_k = \text{upsample}(k, 1..p)$$

$$\text{All } \Delta w_{jk} = -\alpha \delta_k^O z_j$$

- $\text{upsample}(k, 1..p)$: neurons in $Z_1..Z_p$ connected to Y_k



Back-propagation in ConvNet

- Hidden layer:

for $j = 1..p$

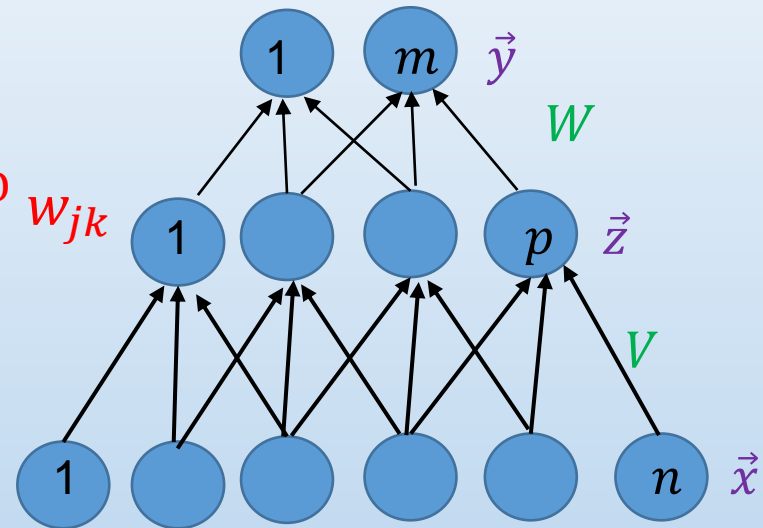
$$\delta_j^H = f^{H'}(z_{in_j}) \sum_{k=1..m | j \in J_k} \delta_k^O w_{jk}$$

- Convolutional weights V :

for $j = 1..p$

$$I_j = \text{upsample}(j, 1..n)$$

$$\text{All } \Delta v_{ij} = -\alpha \delta_j^H x_i$$



ConvNet in MATLAB

```
layers = [ imageInputLayer([28 28 1])  
          convolution2dLayer(5, 1)  
          reluLayer  
          maxPooling2dLayer(2, 'Stride', 2)];  
  
options = trainingOptions('sgdm', 'MaxEpochs',20,  
'InitialLearnRate',1e-4);  
  
net = trainNetwork(img, layers, options);  
  
y = classify(net, img);
```