

### Neural Networks & Deep Learning

Introduction to Neural Networks

CSE & IT Department

ECE School

Shiraz University

## **Biological Inspiration**



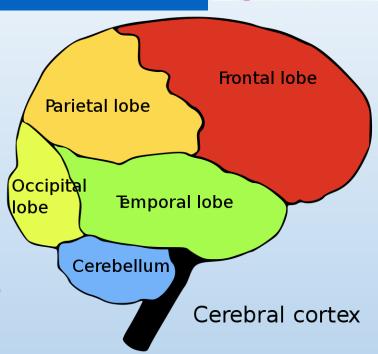
- Brain is a highly complex, nonlinear, and parallel computer
  - Simple processing units called neurons
  - Cycle times in milliseconds
  - Massive number of neurons (~ 10<sup>11</sup> in humans)
  - Massive interconnection (~ 60<sup>12</sup> connections)
- Brain can perform certain tasks (pattern recognition, perception) many times faster than fastest digital computers

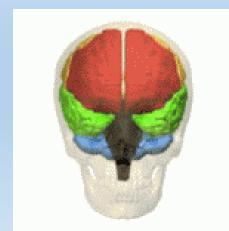
# Natural Intelligence



#### Structure of human brain

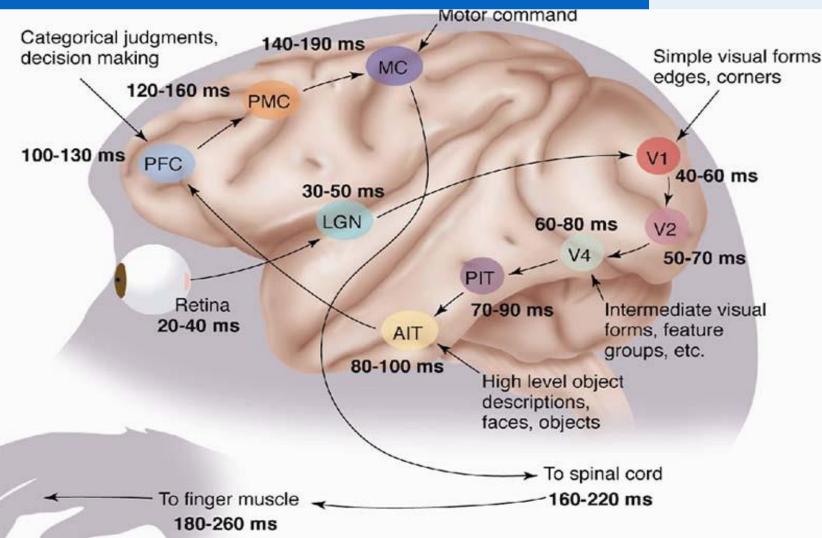
- Frontal lobe
  - Reward, attention, planning, short-term memory, motivation
- Parietal lobe
  - Sensory inputs from skin (touch, temperature, pain)
- Occipital lobe
  - Visual processing center
- Temporal lobe
  - Visual memories, language comprehension, emotion





# From Receptor to Effector (~1s)

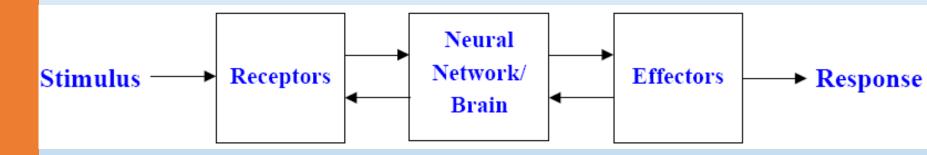




# Human Nervous System Operation



May be broken down into three stages:



- Receptors
  - Collect information from the environment (e.g. photons on the retina)
  - Convert stimuli from human body or environment into electrical pulses as information conveyer to brain

# Organization of Human Nervous Systems

#### Neural network

Represents the brain which receives information and makes appropriate decisions

#### Effectors

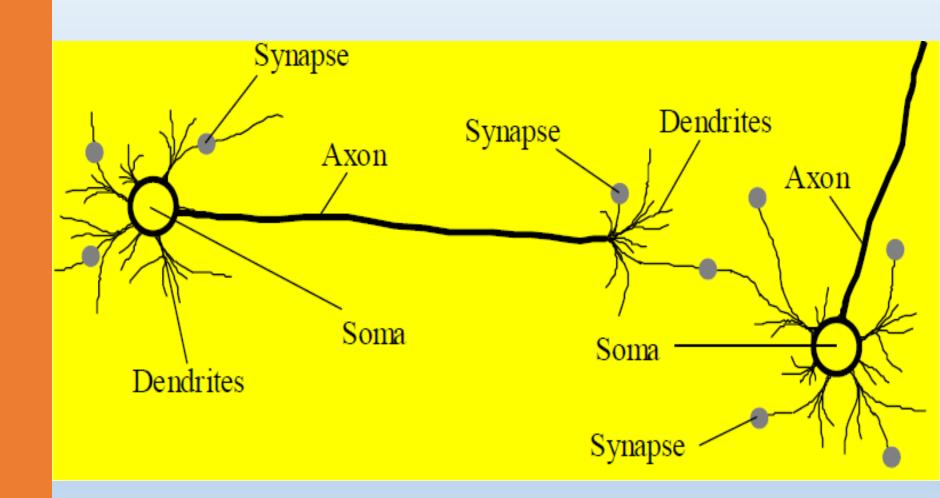
- Convert electrical impulses generated by the neural network into responses as system outputs
- Generate interactions with the environment (e.g. activate muscles)

#### Arrows

 Represent the flow of information/activation (feed-forward and feed-back)

# **Biological Neuron**





# **Biological Neuron**



#### Dendrites

 Receptive zones that receive activation from other neurons

#### Cell body (soma)

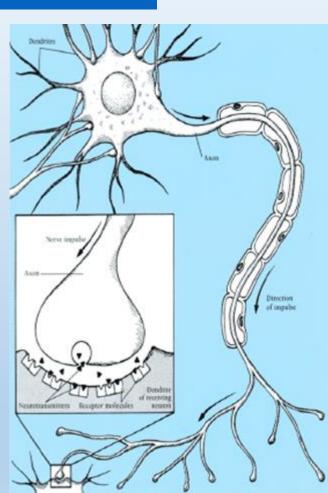
 Processes incoming activations and converts them into output activations

#### Axons

 Transmission lines that send activation to other neurons

#### Synapses

 Allow weighted transmission of signals (using neurotransmitters) between axons and dendrites



### Brain: Amazingly Efficient Computer

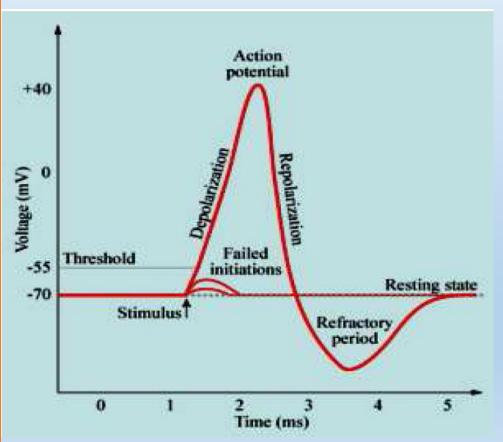


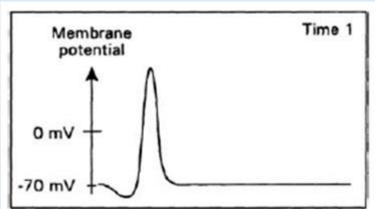
- ~ 10<sup>11</sup> neurons
- ~ 10<sup>4</sup> synapses per neuron
- ~ 10 spikes go through each synapse per second
- ~ 10<sup>16</sup> operations per second
- ~ 25 Watts (Very efficient)
- ~ 1.4 Kg, 1.7 liters
- ~ 2500 cm<sup>2</sup> (Unfolded cortex)

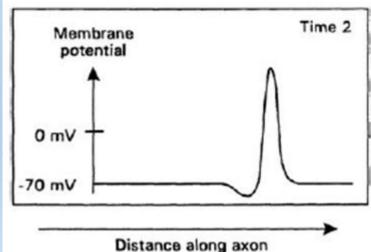
# **Action of Biological Neuron**



 Majority of neurons encode their outputs/activations as a series of brief electrical pulses (spikes or action potentials)







# Firing of Neuron



- Behavior is binary (a neuron either fires or not)
- Neurons don't fire if their accumulated activity stay below threshold
- If activity is above threshold, a neuron fires (produces a spike)
- The firing frequency increases with accumulated activity until max. firing frequency reached
- The firing frequency is limited by refractory period of about
   1-10 ms

# Man vs. Machine (Hardware)



Features	Human brain	Von Neumann computer
# elements	10 <sup>10</sup> - 10 <sup>12</sup> simple neurons	10 <sup>7</sup> - 10 <sup>8</sup> transistors 10 <sup>4</sup> complex processors
# connections/element	massive	little or no
Switching frequency	slow (10 <sup>3</sup> Hz)	fast (109 - 1010 Hz)
Energy/operation/sec.	10 <sup>-16</sup> Joule	10 <sup>-6</sup> Joule
Power consumption	10 Watt	100 - 500 Watt
Structure	dynamic	static
Reliability of elements	low	reasonable
Reliability of system	high	reasonable
Decision speed/power	high	reasonable

# Man vs. Machine (Software)



Features	Human brain	Digital computer		
Data representation	analog	digital		
Memory localization	distributed	localized		
Control	distributed	localized		
Processing	parallel	sequential		
Skill acquisition	adaptive-learnable	pre-programming		
Fault/error tolerance	fault tolerant	intolerant to errors		
Structure	trained	designed		
Activation	nonlinear	linear		

### What are NNs?



- Artificial neurons are crude approximations of neurons found in brains
  - Physical devices
  - Mathematical constructs

 Artificial NNs (ANN) are networks of artificial neurons as crude approximations to parts of biological brains

### Conceptual Definition of NNs



- An ANN
  - Is a machine, designed to model the brain how performs a particular task or function of interest
  - Is either implemented in hardware or simulated in software
  - Mimics the brain or nervous system, in senses:
    - Structure (simple processing units, massive interconnection, ...)
    - Functionality (learning, adaptability, fault tolerance, ...)

# **Pragmatic Definition of NNs**



#### An ANN

- Is a massively connected parallel computational system
- Made up of many simple processing units
- Has propensity of storing experimental knowledge
- Can perform tasks analogously to biological brains
- Resembles the brain in two respects:
  - Knowledge is acquired by the network from the environment through a learning process
  - Inter-neuron connection strengths are used to store the acquired knowledge

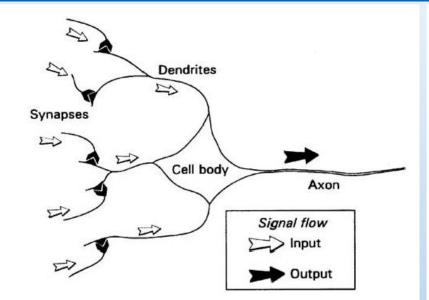
# Why NNs?

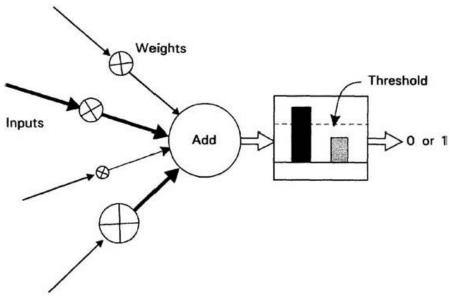


- They are extremely powerful computational devices
- Massive parallelism makes them very efficient
- They can learn from training data and generalize to new situations
- They are particularly fault tolerant (as "graceful degradation" in biological systems)
- They are robust and noise tolerant
- They can do anything a symbolic/logic system can do, and more

# Mathematical Model of a Neuron







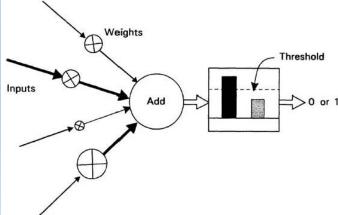
Biological Neural Network	Artificial Neural Network
Soma	Neuron
Dendrite	Input
Axon	Output
Synapse	Weight

### Characteristic of Neuron



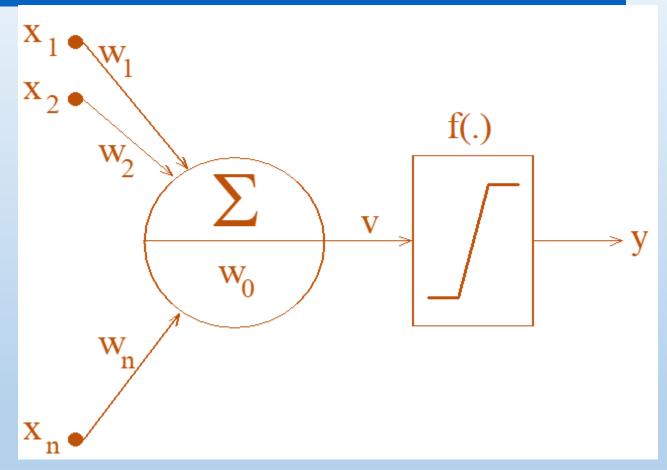
- A neuron can receive many inputs
- Inputs may be modified by synaptic weights at receiving dendrites
- A neuron sums its weighted inputs
- An activation function limits amplitude of output to {0, 1}
- A neuron can transmit an output signal

Output can go to many other neurons



### **Artificial Neuron**



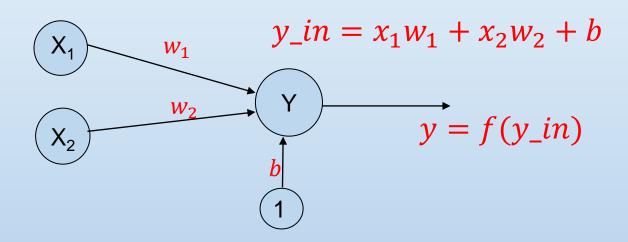


Mathematically, 
$$v = w_0 + \sum_{i=1}^n x_i w_i \implies y = f(v)$$

*f*(.): threshold function







#### **ANN Features**



- Neurons act nonlinearly
- Information processing is local
- Memory is distributed
- The dendrite weights learn through experience
- The weights may be inhibitory or excitatory
- Neurons can generalize novel input stimuli
- Neurons are fault tolerant and can sustain damage

### **ANN Categories**



- Direction of information (signal) flow
  - Feed-forward network (no feed-back connections)
  - Recurrent network (with at least one feed-back connection)
- Number of layers
  - Single layer network
  - Single hidden-layer network
  - Multilayer network (shallow/deep network)
- Connectivity
  - Fully-connected network
  - Partially-connected network

### **ANN Categories**



#### Activation function

- Threshold (binary, bipolar)
- Linear (identity)
- Nonlinear (sigmoid, radial-basis)

#### Learning methodology

- Supervised learning
- Unsupervised learning
- Reinforced learning

#### Training method

- Static
- Dynamic

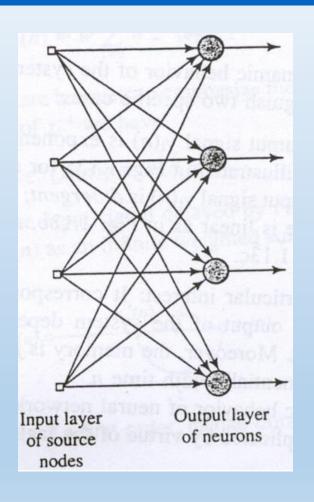
### **NN Design Decisions**

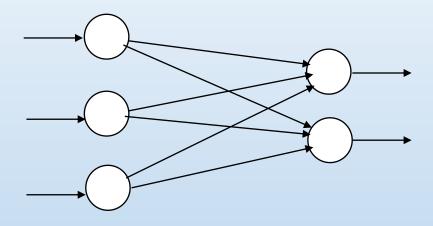


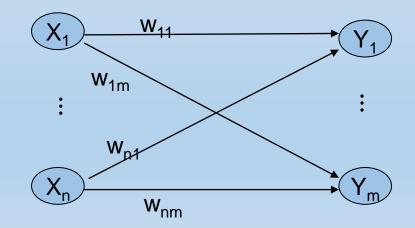
- Architecture: pattern of connections between neurons
  - No. of layers, no. of neurons in each layer, no. of links
  - Connectivity
- Learning algorithm: method of determining the connection weights
  - Supervised, self-organizing, competitive
- Activation function: mapping of neurons' behavior
  - Threshold, linear, nonlinear

# Single-layer Feed-forward NN



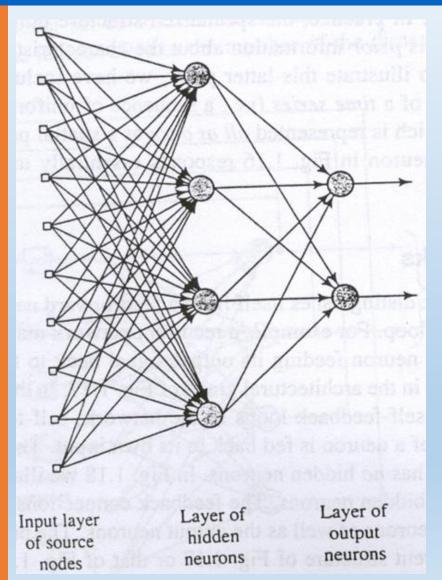


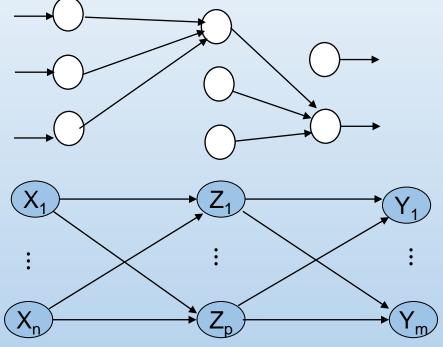




# Multilayer Feed-forward NN



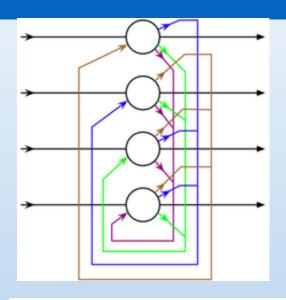


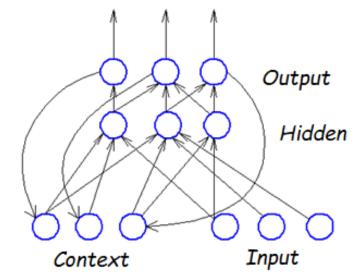


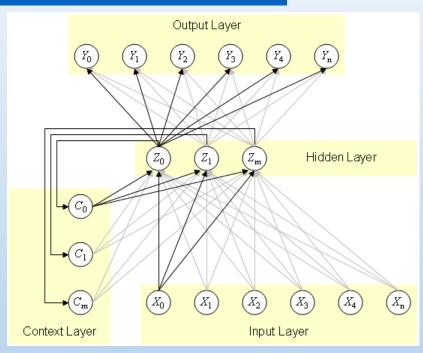
- More powerful
- Harder to train
- Open loop

### Recurrent NN









- More powerful
- Harder to train
- Closed loop

# Knowledge Representation in ANN

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- What is knowledge?
  - Information or models used to interpret, predict and appropriately respond to outside world (environment)
- Quality of knowledge representation generally translates into quality of solution
  - Better representation means better solution
- Knowledge representation in NNs is not well-understood
  - There is little theory that relates a given weight to a particular piece of information
- Knowledge is encoded in free parameters of NN
  - Weights and thresholds

# **Knowledge Representation Rules**



#### Rule 1:

 Similar inputs from similar classes should usually produce similar representations inside the network, and should, therefore, be classified as belonging to the same category

#### Rule 2:

 Inputs to be characterized as separate classes should be given widely different representations in the network

#### Rule 3:

 If a particular feature is important, then there should be a large number of neurons involved in representation of that item in network

#### Rule 4:

 Prior knowledge and invariances should be built into design of network, thus simplifying learning

# **Knowledge Representation Rules**



- Advantages of building-in prior knowledge
  - Specialized structure
  - Benefits of specialized structure
    - Biologically plausible, less complication, fewer free parameters, faster training, fewer examples needed, better generalization
- How to build-in prior knowledge
  - No hard and fast rules
  - In general, use domain knowledge to reduce complexity of NN based on its performance characteristics
- Built-in Invariances
  - Invariance?
    - Fault tolerance
    - Immunity to transformations
  - Invariance by structure, training, feature space

### NN Learning



- Learning:
  - To acquire and maintain knowledge of interest
- Knowledge of environment that will enable NN to achieve its goals
  - Prior information
  - Current information
- Knowledge can be built into NNs from input-output examples via learning using training algorithms
- The most powerful property of NNs: ability to learn and generalize from a set of training data

### NN Learning



- NNs adapt the weights of connections between neurons so that final output activations are correct
- Three broad types of learning:
  - Supervised Learning (learning with a teacher)
  - Reinforcement learning (learning with environment feedback)
  - Unsupervised learning (learning with no help)
- Most of human/animal learning is unsupervised
- If intelligence was a cherry ice-cream cake,
  - unsupervised learning would be cake
  - supervised learning would be icing on cake
  - reinforcement learning would be cherry on cake

### An Example



- Using NN for signature verification
- Prior knowledge
  - Architecture of NN
- Current knowledge
  - Input-output examples, being used for NN training
- Learning
  - Modification of free parameters (weights, thresholds, ...)
- Generalization
  - Using the trained NN for predicting output for unseen input

# **Advantages of ANNs**



- Efficiency
  - Inherent massively parallel
- Robustness
  - Can deal with incomplete and/or noisy data
- Fault tolerance
  - Still works when part of net fails
- User friendly
  - Learning instead of programming

### **Drawbacks of ANNs**



- Difficult to design
  - No clear design rules for arbitrary applications
- Hard or impossible to train
  - When training data are rare
- Difficult to assess internal operation (black box)
  - Difficult to find out what tasks are performed by different parts of the net
- Unpredictable
  - Difficult to estimate future network performance based or current behavior

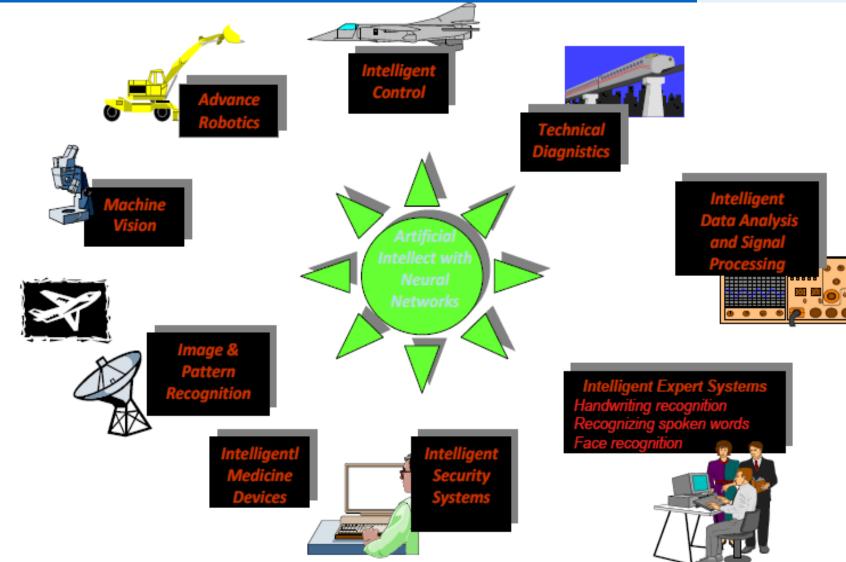
## Real-world NN applications



- Financial modeling (predicting stocks, currency exchange rates)
- Time series prediction (climate, weather, airline marketing)
- Computer games (intelligent agents, backgammon)
- Control systems (autonomous robots, microwave controllers)
- Pattern recognition (speech recognition, hand-writing recognition)
- Data analysis (data compression, data mining)
- Noise reduction (function approximation, ECG noise reduction)
- Bioinformatics (protein secondary structure, DNA sequencing)

# Other Applications of NNs





### **History of NN**



- 1943 McCulloch-Pitts neuron model
- 1949 Hebbian learning rule
- 1958 Single layer network, Perceptron
- 1960 Adaline
- 1969 Limitations of Perceptrons
- 1982 Kohonen nets, Associative memory, Hopfield net
- 1985 ART

### **History of NN**



- 1986 Back-propagation learning algorithm for multi-layer Perceptron
- 1990s Radial basis function networks
- 2000 Ensembles of NNs, Cascaded Networks
- 2004 Deep Belief Networks
- 2010~ Convolutional Networks, Autoencoders, LSTMs

### Some Useful Notations



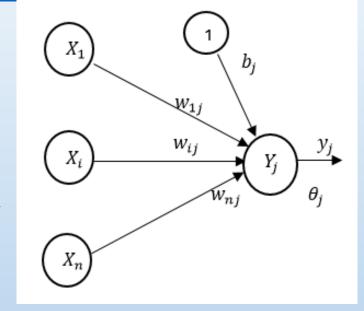
 $x_i, y_j$ : outputs of units  $X_i$  and  $Y_j$ 

 $w_{ij}$ : weight on connection between  $X_i$  and  $Y_j$ 

 $b_j$ ,  $\theta_j$ : bias and threshold of neuron  $Y_j$ 

$$W = \{w_{ij}, i = 1, \dots, n \mid j = 1, \dots, m\} = W_{n \times m}$$

$$\overrightarrow{w}_{\cdot j} = \begin{bmatrix} w_{1j} \\ \vdots \\ \vdots \\ w_{nj} \end{bmatrix} \text{ vector of weights to } Y_j$$



 $y_i n_i = \text{net input to neuron } Y_i$ 

$$y_i i n_j = b_j + \sum_{i=1}^n x_i w_{ij} = b_j + \vec{x} \cdot \vec{w}_{ij} \implies y_j = f(y_i i n_j)$$



# If the brain were so simple that we could understand it then we would be so simple that we couldn't understand it

Lyall Watson