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GOD

1402/  
2023

# Neural Network & Deep Learning

Single-Layer  
Feedforward Networks  
for Association

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# Biological Memory

- In neurobiological context
  - Memory refers to relatively enduring neural alterations induced by interactions of organism with its environment
  - Has capabilities of storing and retrieving data patterns
- Biological memory
  - Is physically distributed
  - Operates by association , rather than addressing
  - Content-addressable memory, no address-addressable memory



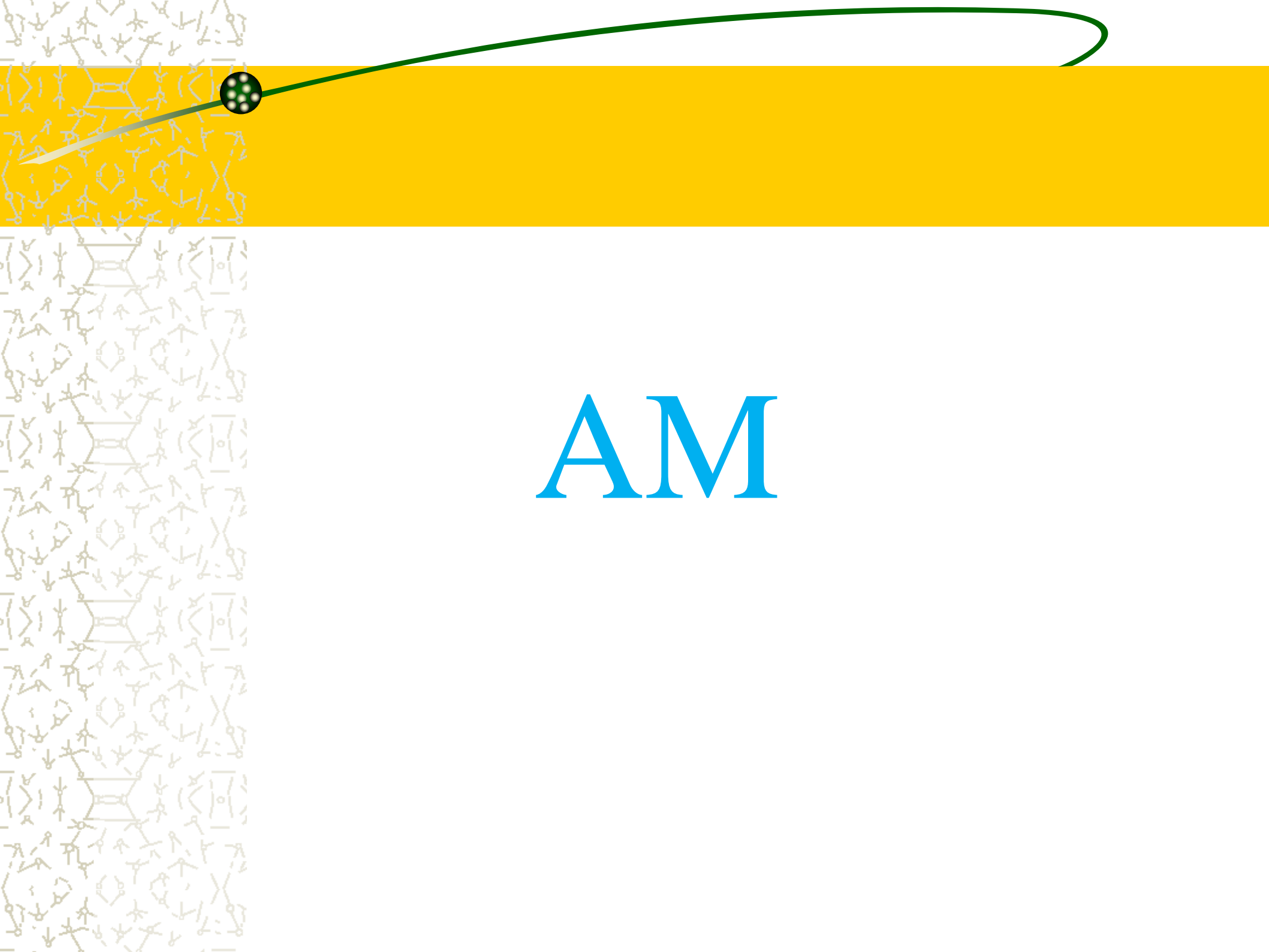
# Pattern Association

- Learning is process of forming **association** between related patterns
- **Memorization** of a pattern is an association of a pattern with **itself**
- An **input stimulus** (a **sensory cue**) similar to associated one will invoke associated pattern
- Example:
  - name of a cartoon** ---> recalls TV series about it
  - Picture of a place** ---> recalls memories of people are met
  - Recognizing a person** with unlimited appearances
- There is some underlying collection of stored data which is **ordered** and **interrelated** in some way
- This data constitute a stored pattern or **memory**



# Pattern Association

- In recalling:
  - When **part** of pattern of data is presented in form of sensory cue, rest of pattern (memory) is **recalled** or associated with it
  - When an **imperfect** version of stored memory is offered, true and **uncorrupted** pattern should be associated with it
- A very limited form of association in conventional computers:
  - **Key** (index) term is a sensory cue when searching a **database**



AM



# Associative Memory (AM)

- Associative memory
  - Content-addressable memory
  - Memory that operates by association
  - Mapping of an input to an output (stimulus to output)
  - Example: face recognition
- Characteristics of associative memory
  - Distributed
  - Both key (stimulus) and output (stored pattern) are data vectors (as opposed to address and data)
  - Storage pattern different from key and is spatially distributed
  - Stimulus is address as well as stored pattern (with imperfections)
  - Tolerant to noise and damage



## Architecture of an AM net:

- Feed-forward:
  - Can store pattern associations in **weights** of net and can retrieve them
- Recurrent:
  - Can store patterns as **stable states** of a dynamic physical system with minimum energy



# Feed-forward AM Net

- A highly simplified model of **human** memory
- **Single-layer** net:
  - Can store pattern associations in **weights** through training
  - Can recall known patterns by providing **imperfect** or **incomplete** form of them
- **Distributed memory**: simultaneous activities of many neurons that contain information about external stimuli
- Each **association** is an input-output vector pair  $\langle \vec{s} : \vec{t} \rangle$   
 $\vec{s}$ : key pattern,  $\vec{t}$ : stored or memorized pattern
- All associations  $\langle S : T \rangle = \langle [\vec{s}(1) \dots \vec{s}(P)] : [\vec{t}(1) \dots \vec{t}(P)] \rangle$
- **Bipolar** representation is more powerful than **binary** in pattern association





# Feed-forward AM Net

- **Distributed** memory mapping: each pair  $\langle \vec{s} : \vec{t} \rangle$  transforms activity pattern  $\vec{s}$  in input space to activity pattern  $\vec{t}$  in output space
- Types of **AMs**:
  - **Auto-associative (AAM)**
    - A key vector is associated with **itself** in memory
    - Dimension of input and output are **same**
    - $\vec{t} = \vec{s}$  in each association pair  $\langle \vec{s} : \vec{t} \rangle$
  - **Hetro-associative (HAM)**
    - A key vector is associated with **another** memorized vector
    - Dimension of input and output **may or may not** be same
    - $\vec{t} \neq \vec{s}$  in each association pair  $\langle \vec{s} : \vec{t} \rangle$



# AM Training

- Training methods:
  - Hebb rule: for threshold activation functions
  - Delta rule: for differentiable activation functions
- AM capacity of a net:
  - How many patterns can be stored before net starts to forget learned patterns
  - Some factors influence it (as in human memory)
    - Complexity of patterns (number of components of  $\vec{s}, \vec{t}$ )
    - Similarity of input patterns that are associated with significantly different response patterns

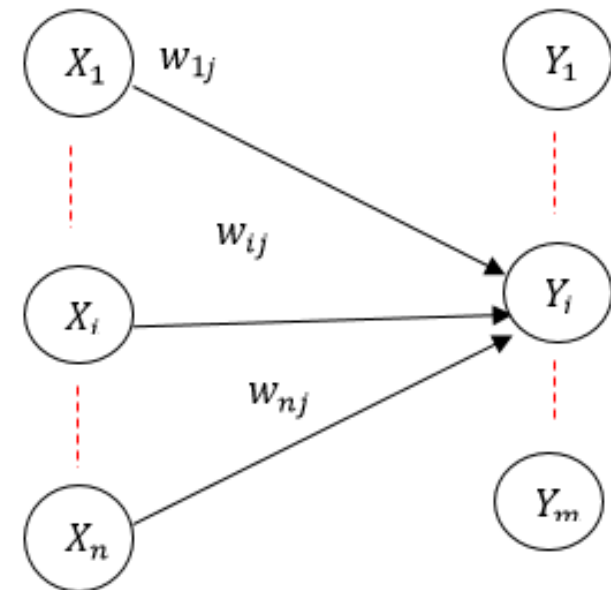


# Hebb Rule in AM Net

## Hebb rule for pattern association

- The **simplest** and most **common** method for determining weights of an associative memory NN
- A **non-iterative** learning method
- Can be used with patterns in **binary** or **bipolar** representation

$$\Delta w_{ij} = x_i y_j$$





# Hebb Rule in AM Net

## Algorithm:

1. Initialize all weights

$$w_{ij} = 0 \quad (i = 1, \dots, n; j = 1, \dots, m)$$

2. For each training input-output vector pair

$$\langle \vec{s} : \vec{t} \rangle = \langle \vec{s}(p) : \vec{t}(p) \rangle$$

2.1. Set activation for input and output units

$$x_i = s_i \quad (i = 1, \dots, n), \quad y_j = t_j \quad (j = 1, \dots, m)$$

2.2. Adjust the weights

$$w_{ij}(\text{new}) = w_{ij}(\text{old}) + x_i y_j, \quad (i = 1, \dots, n; j = 1, \dots, m)$$

3. Stop



# Hebb Rule in AM Net

- The weights found by **Hebb** rule (with zero initials) can be obtained by **outer product** of association vector pair  $\langle \vec{s}: \vec{t} \rangle$

$$\vec{s} = \begin{bmatrix} s_1 \\ \vdots \\ s_i \\ \vdots \\ s_n \end{bmatrix}, \vec{t} = \begin{bmatrix} t_1 \\ \vdots \\ t_j \\ \vdots \\ t_m \end{bmatrix} \Rightarrow \vec{s} \vec{t}^T = \begin{bmatrix} s_1 t_1 & \cdots & s_1 t_j & \cdots & s_1 t_m \\ \vdots & & \vdots & & \vdots \\ s_i t_1 & \cdots & s_i t_j & \cdots & s_i t_m \\ \vdots & & \vdots & & \vdots \\ s_n t_1 & \cdots & s_n t_j & \cdots & s_n t_m \end{bmatrix} = W = \{w_{ij}\}, w_{ij} = s_i t_j$$

$W$ : correlation memory matrix for association pair  $\langle \vec{s}: \vec{t} \rangle$

- Using all associations  $\langle S: T \rangle = \{ \langle \vec{s}(p): \vec{t}(p) \rangle, p = 1, \dots, P \}$   
 $W = \{w_{ij}\}, w_{ij} = \sum_{p=1}^P s_i(p) t_j(p) \Rightarrow W = \sum_{p=1}^P \vec{s}(p) \vec{t}(p)^T = ST^T$

$W$ : correlation memory matrix for all association pairs



# Hebb Rule in AM Net

- Example:

$$\vec{s}(1) = \begin{bmatrix} -1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \quad \vec{s}(2) = \begin{bmatrix} 1 \\ -1 \\ 1 \\ 1 \end{bmatrix}, \quad \vec{s}(3) = \begin{bmatrix} 1 \\ 1 \\ -1 \\ 1 \end{bmatrix}, \quad \vec{s}(4) = \begin{bmatrix} 1 \\ 1 \\ 1 \\ -1 \end{bmatrix}$$

$$\vec{t}(1) = \begin{bmatrix} -1 \\ -1 \end{bmatrix}, \quad \vec{t}(2) = \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \quad \vec{t}(3) = \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \quad \vec{t}(4) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$W(1) = \begin{bmatrix} 1 & 1 \\ -1 & -1 \\ -1 & -1 \\ -1 & -1 \end{bmatrix}, \quad W(2) = \begin{bmatrix} -1 & 1 \\ 1 & -1 \\ -1 & 1 \\ -1 & 1 \end{bmatrix}, \quad W(3) = \begin{bmatrix} 1 & -1 \\ 1 & -1 \\ -1 & 1 \\ 1 & -1 \end{bmatrix}, \quad W(4) =$$

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \\ -1 & -1 \end{bmatrix},$$

$$\Rightarrow W = \sum_{p=1}^4 W(p) = \begin{bmatrix} 2 & 2 \\ 2 & -2 \\ -2 & 2 \end{bmatrix}$$



# Hebb Rule in AM Net

- Suitability of Hebb rule depends on **correlation** among **input training vectors**
  - For **uncorrelated** (orthogonal) input vectors (**linearly independent**), Hebb rule will produce correct weights and can recall all stored patterns perfectly
    - **Two orthogonal vectors have zero dot product**
  - For **non-orthogonal** input vectors, response will include a **portion** of each of target values (**cross talk**)
- Correlation memory matrix (weights  **$W$** ) has no mechanism for feedback since it is based on Hebbian learning
- Consequently, there are errors in recall
- How continually update  **$W$**  to reduce error?



# Delta Rule in AM Net

## Delta rule for pattern association:

- Impose error-correction learning (delta rule) to update  $W$ 
  - An **iterative** learning method
  - Can be used for input (key) vectors that are **linearly independent** but **not orthogonal**
  - Can produce **least square solution** when input patterns are **not linearly independent**

$$y_{in_j} = b_j + \sum_{i=1}^n x_i w_{ij} = b_j + \vec{w}_{.j}^T \vec{x}$$

$$y_j = f(y_{in_j}) , \quad (j = 1, \dots, m)$$

$$w_{ij}(\text{new}) = w_{ij}(\text{old}) + \alpha(t_j - y_j) f'(y_{in_j}) x_i$$





# Recalling in HAM Net

How **memory** is addressed and how stored information is **recalled**?

- To recall any pattern  $\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_i \\ \vdots \\ x_n \end{bmatrix}$ , compute  $\vec{y} = \begin{bmatrix} y_1 \\ \vdots \\ y_j \\ \vdots \\ y_m \end{bmatrix}$  as:

$$y\_in_j = \sum_{i=1}^n x_i w_{ij}, \quad y_j = f(y\_in_j) = \text{sgn}(y\_in_j) = \begin{cases} 1, & \text{if } y\_in_j > 0 \\ 0, & \text{if } y\_in_j = 0 \\ -1, & \text{if } y\_in_j < 0 \end{cases}$$

- Other association functions:

- In nets using Hebb rule:  $f(x) = \begin{cases} 1, & \text{if } x > \theta \\ \theta, & \text{if } x = \theta \\ -1, & \text{if } x < \theta \end{cases}$

- In nets using delta rule:  $f(x) = \frac{1-e^{-x}}{1+e^{-x}}$

- Using **product** operation to recall a vector

$$y\_in_j = \sum_{i=1}^n x_i w_{ij} = \vec{w}_{.j}^T \vec{x} \Rightarrow \overline{y\_in} = W^T \vec{x} \Rightarrow \vec{y} = f(W^T \vec{x})$$



# Recalling in HAM Net

Example:

$$\langle \vec{s} : \vec{t} \rangle = \{ \langle -1, 1, 1, 1 : -1, -1 \rangle, \langle 1, -1, 1, 1 : -1, 1 \rangle, \\ \langle 1, 1, -1, 1 : 1, -1 \rangle, \langle 1, 1, 1, -1 : 1, 1 \rangle \}$$

- Since stored patterns are **orthogonal**, all patterns can be recalled **perfectly**

$$W = \begin{bmatrix} 2 & 2 \\ 2 & -2 \\ -2 & 2 \\ -2 & -2 \end{bmatrix}, \quad \vec{x} = \begin{bmatrix} 1 \\ -1 \\ 1 \\ 1 \end{bmatrix} \Rightarrow \overrightarrow{y\_in} = W^T \vec{x} = \begin{bmatrix} 2 & 2 & -2 & -2 \\ 2 & -2 & 2 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 1 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} -4 \\ 4 \end{bmatrix} \Rightarrow \vec{y} = f(\overrightarrow{y\_in}) = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$



# Recalling in HAM Net

Example:

$$W = \begin{bmatrix} 2 & 2 \\ 2 & -2 \\ -2 & 2 \\ -2 & -2 \end{bmatrix}$$

- A pattern with **one missed** component **can be** recalled

$$\vec{x} = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 1 \end{bmatrix} \Rightarrow \overrightarrow{y\_in} = W^T \vec{x} = \begin{bmatrix} -2 \\ 2 \end{bmatrix} \Rightarrow \vec{y} = f(\overrightarrow{y\_in}) = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

- A pattern with **one mistaken** component **cannot be** recalled

$$\vec{x} = \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} \Rightarrow \overrightarrow{y\_in} = W^T \vec{x} = \begin{bmatrix} 0 \\ 8 \end{bmatrix} \Rightarrow \vec{y} = f(\overrightarrow{y\_in}) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \text{ (cross talk)}$$



AAM



# AAM Net

- Is a special case of HAM NN where  $\vec{t} = \vec{s}$  for all training pairs  $\langle \vec{s}: \vec{t} \rangle$
- Can be used to determine whether an input vector is **known** or **unknown** to net
- Net **recognizes** a known vector by producing that pattern on output units if is given as input
- Training vectors stores associations in **weights**
- A stored vector can be retrieved from **distorted** (noisy) or **partial** input (to show its **generalization**)



# Weights in AAM Net

- To store a single bipolar vector  $\vec{x} = \vec{s}(1)$ , choose weight matrix  $W(1)$  as (using Hebb rule):

$$W(1) = \vec{x} \vec{x}^T - I \Rightarrow W(1) = W(1)^T$$

- To prove  $\vec{x} = \vec{s}(1)$  is known vector for net:

$$\overrightarrow{y\_in} = W(1)^T \vec{x} = (\vec{x} \vec{x}^T - I) \vec{x} = \vec{x} \vec{x}^T \vec{x} - I \vec{x} = n \vec{x} - \vec{x} = (n - 1) \vec{x}$$

$$\Rightarrow \vec{y} = \text{sgn}(\overrightarrow{y\_in}) = \text{sgn}((n - 1) \vec{x}) = \text{sgn}(\vec{x}) = \vec{x}$$

- For  $P$  mutually orthogonal vectors in  $S$ , weights can also be set:

$$W = \sum_{p=1}^P W(p)$$

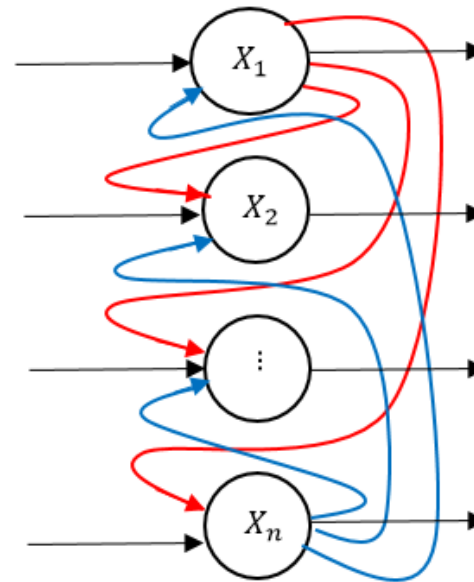
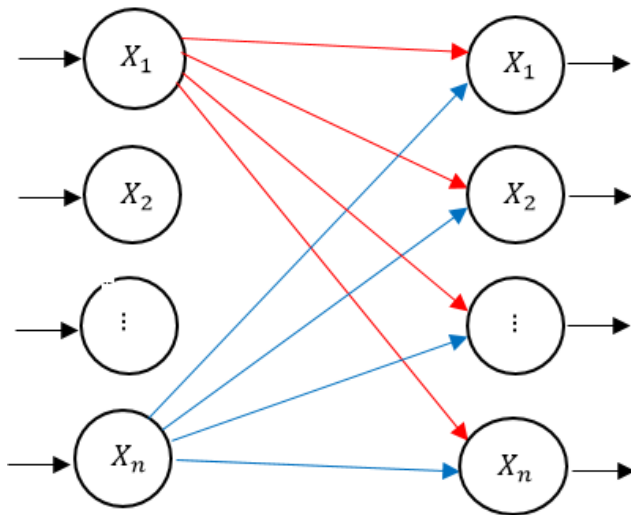
Or

$$W = \sum_{p=1}^P \vec{s}(p) \vec{s}(p)^T = S S^T, \text{ then set diagonal weights to zero}$$

$W$ : correlation memory matrix



# AAM Net



- Weights on **diagonal** of  $W$  are set to **zero**:
  - To improve **generalization** ability of net
  - To increase biological **plausibility** of net
  - Necessary for **iterative** AM NNs
  - Necessary if **delta** rule is used for training



Example:  $\vec{s} = \{ \langle -1, 1, 1, 1 \rangle, \langle 1, -1, 1, 1 \rangle, \langle 1, 1, -1, 1 \rangle \}$

$$W = \begin{bmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{bmatrix} + \begin{bmatrix} 1 & -1 & 1 & 1 \\ -1 & 1 & -1 & -1 \\ 1 & -1 & 1 & 1 \\ 1 & -1 & 1 & 1 \end{bmatrix} + \begin{bmatrix} 1 & 1 & -1 & 1 \\ 1 & 1 & -1 & 1 \\ -1 & -1 & 1 & -1 \\ 1 & 1 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 3 & -1 & -1 & 1 \\ -1 & 3 & -1 & 1 \\ -1 & -1 & 3 & 1 \\ 1 & 1 & 1 & 3 \end{bmatrix}$$

$$\Rightarrow W' = \begin{bmatrix} 0 & -1 & -1 & 1 \\ -1 & 0 & -1 & 1 \\ -1 & -1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}$$

- Recalling a stored pattern:

$$\vec{x} = \begin{bmatrix} 1 \\ -1 \\ 1 \\ 1 \end{bmatrix} \Rightarrow \begin{cases} \vec{y_{in}} = W^T \vec{x} = \begin{bmatrix} 4 \\ -4 \\ 4 \\ 4 \end{bmatrix} \Rightarrow \vec{y} = \begin{bmatrix} 1 \\ -1 \\ 1 \\ 1 \end{bmatrix} \\ \vec{y_{in}} = W'^T \vec{x} = \begin{bmatrix} 1 \\ -1 \\ 1 \\ 1 \end{bmatrix} \Rightarrow \vec{y} = \begin{bmatrix} 1 \\ -1 \\ 1 \\ 1 \end{bmatrix} \end{cases}$$





# AAM Net

Example:  $\vec{s} = \{ \langle -1, 1, 1, 1 \rangle, \langle 1, -1, 1, 1 \rangle, \langle 1, 1, -1, 1 \rangle \}$

$$W = \begin{bmatrix} 3 & -1 & -1 & 1 \\ -1 & 3 & -1 & 1 \\ -1 & -1 & 3 & 1 \\ 1 & 1 & 1 & 3 \end{bmatrix} \Rightarrow W' = \begin{bmatrix} 0 & -1 & -1 & 1 \\ -1 & 0 & -1 & 1 \\ -1 & -1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}$$

- Recalling a pattern with one missed component

$$\vec{x} = \begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix} \Rightarrow \begin{cases} \overrightarrow{y_{in}} = W^T \vec{x} = \begin{bmatrix} 3 \\ -5 \\ 3 \\ 1 \end{bmatrix} \Rightarrow \vec{y} = \begin{bmatrix} 1 \\ -1 \\ 1 \\ 1 \end{bmatrix} \\ \overrightarrow{y_{in}} = W'^T \vec{x} = \begin{bmatrix} 0 \\ -2 \\ 0 \\ 1 \end{bmatrix} \Rightarrow \vec{y} = \begin{bmatrix} 1 \\ 0 \\ -1 \\ 1 \end{bmatrix} \end{cases}$$



## Storage capacity of AAM nets

- Input (key) vectors  $S = [\vec{s}(1) \dots \vec{s}(P)]$  are orthonormal if

$$\vec{s}(i)^T \vec{s}(j) = \begin{cases} 1, & \text{if } i = j \\ 0, & \text{if } i \neq j \end{cases}$$

- Number of patterns stored (storage capacity) by AAM is
  - $n$  if  $S$  is orthonormal
  - rank of correlation memory matrix if  $S$  is not orthonormal
    - $\text{rank}(W) < n$  where  $n$  is input dimension
- So, correlation memory matrix can reliably store a maximum of  $n$  patterns



## Storage capacity of AAM nets:

- Real-world patterns are not **orthonormal**
- If key vectors in  $S$  are **linearly independent**, they can be preprocessed to form an orthonormal set (**Gram-Schmidt** procedure)
- Preprocessing to enhance separability of key vectors in  $S$  (i.e. feature enhancement) helps **improve** storage capacity
- Correlation memory matrix may recall patterns that it has never seen before
  - It can make errors if new pattern is **not orthonormal** against key vectors in  $S$



## Storage capacity of AAM nets:

- **Szu theorem:**  $n - 1$  mutually orthogonal bipolar vectors with  $n$  components can be stored using sum of outer product weight matrices (with diagonal terms set to zero)
- Storing  $n$  mutually orthogonal vectors will result in a weight matrix that cannot recall any of stored patterns

Example:

$$\vec{s} = \{ \langle 1, 1, -1, -1 \rangle, \langle -1, 1, 1, -1 \rangle, \langle -1, 1, -1, 1 \rangle \}$$

$$W = W(1) + W(2) + W(3) = \begin{bmatrix} 0 & -1 & -1 & -1 \\ -1 & 0 & -1 & -1 \\ -1 & -1 & 0 & -1 \\ -1 & -1 & -1 & 0 \end{bmatrix}$$

$$\vec{s}' = \vec{s} \cup \{ \langle 1, 1, 1, 1 \rangle \} \Rightarrow W' = W + W(4) = W + \begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$



# Iterative AAM Net

- In some cases, when net does not respond **immediately** to an input signal, but response is like a stored pattern, it can be applied to net **again**

$$\vec{s} = \{< 1, 1, -1, -1 >\} \Rightarrow W = \begin{bmatrix} 0 & 1 & -1 & -1 \\ 1 & 0 & -1 & -1 \\ -1 & -1 & 0 & 1 \\ -1 & -1 & 1 & 0 \end{bmatrix}$$

$$\vec{x} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \overrightarrow{y_{in}} = \begin{bmatrix} 0 \\ 1 \\ -1 \\ -1 \end{bmatrix} \Rightarrow \vec{y} = \begin{bmatrix} 0 \\ 1 \\ -1 \\ -1 \end{bmatrix}$$

$$\vec{x} = \begin{bmatrix} 0 \\ 1 \\ -1 \\ -1 \end{bmatrix} \Rightarrow \overrightarrow{y_{in}} = \begin{bmatrix} 3 \\ 2 \\ -2 \\ -2 \end{bmatrix} \Rightarrow \vec{y} = \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}$$