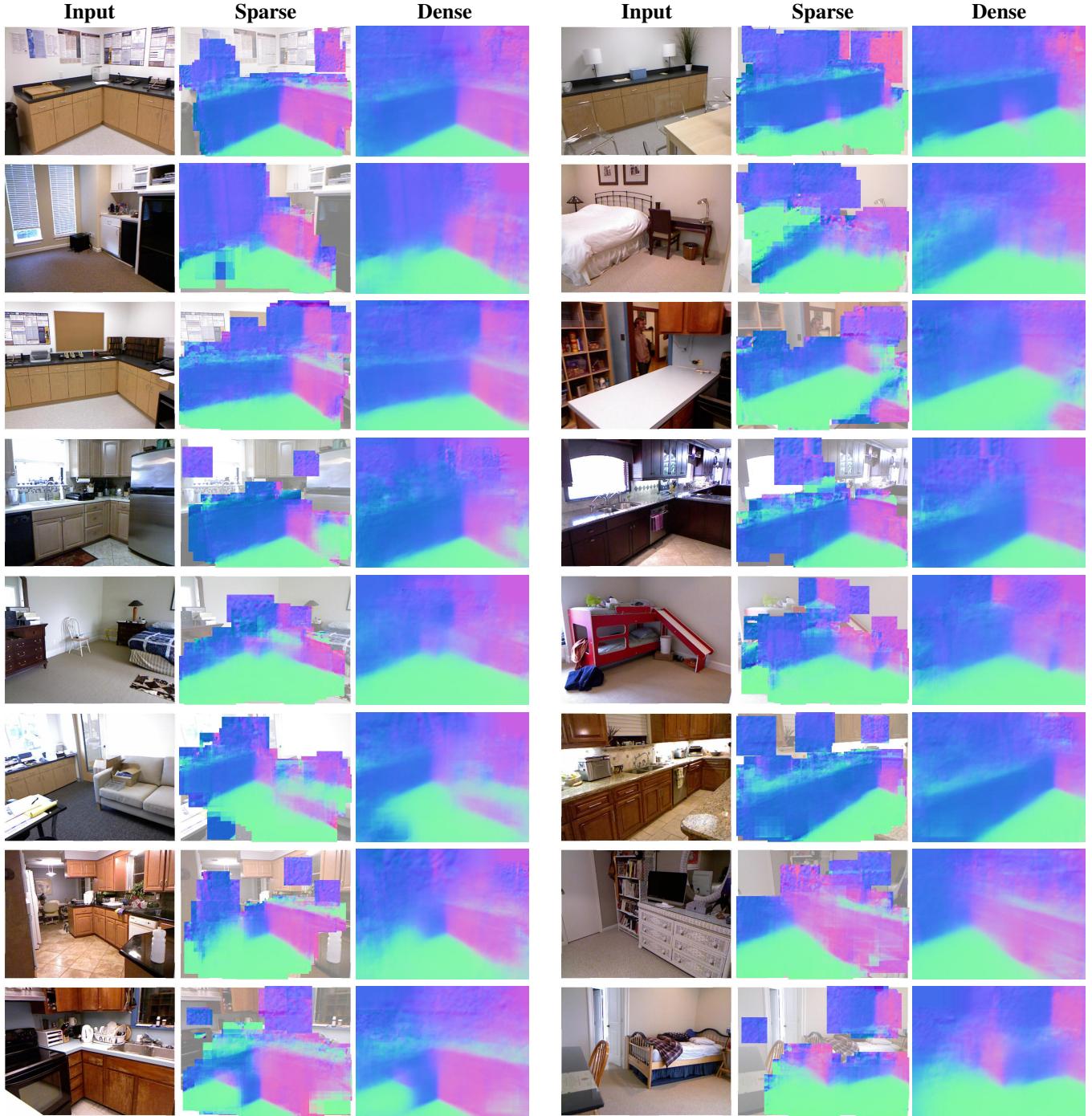
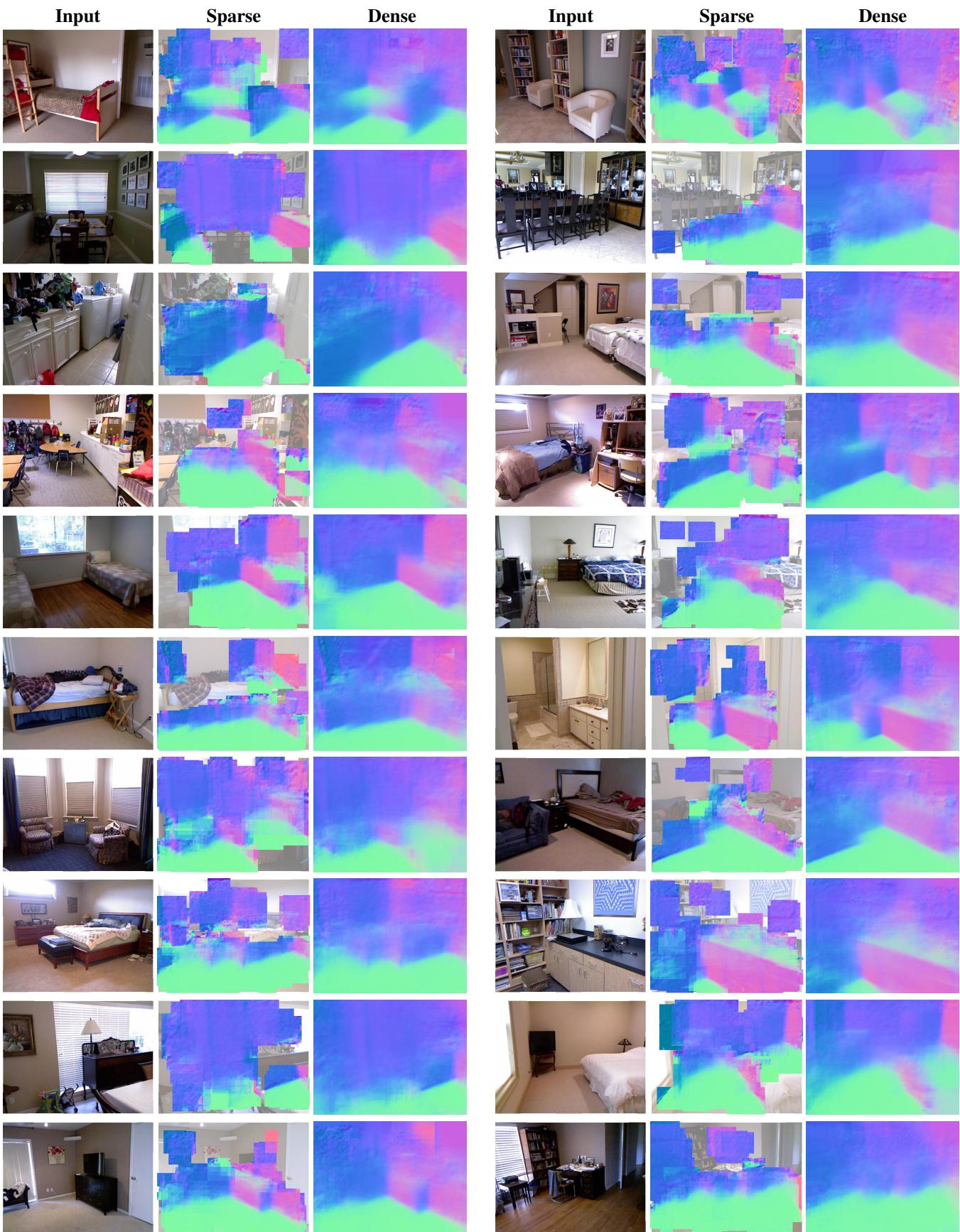
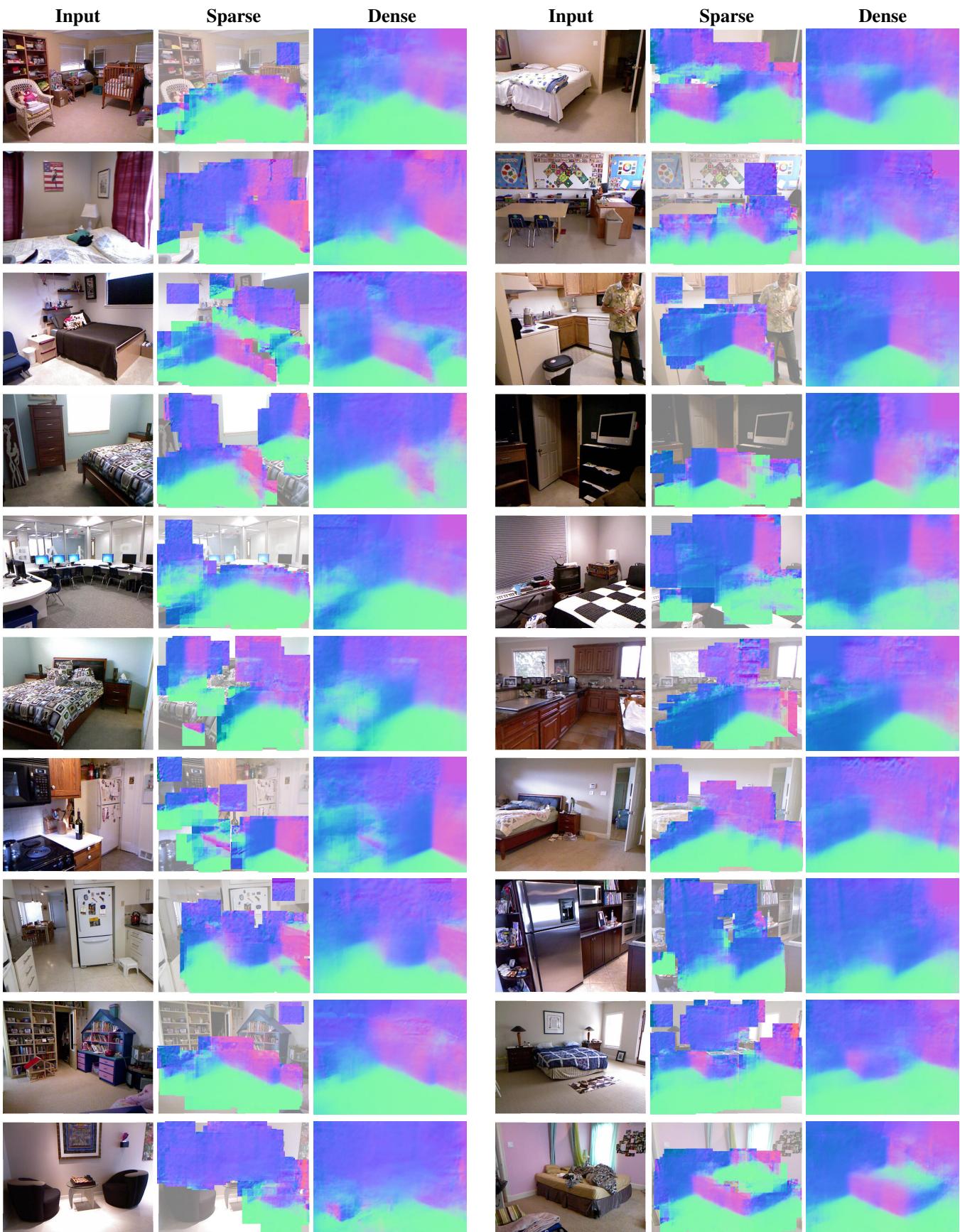


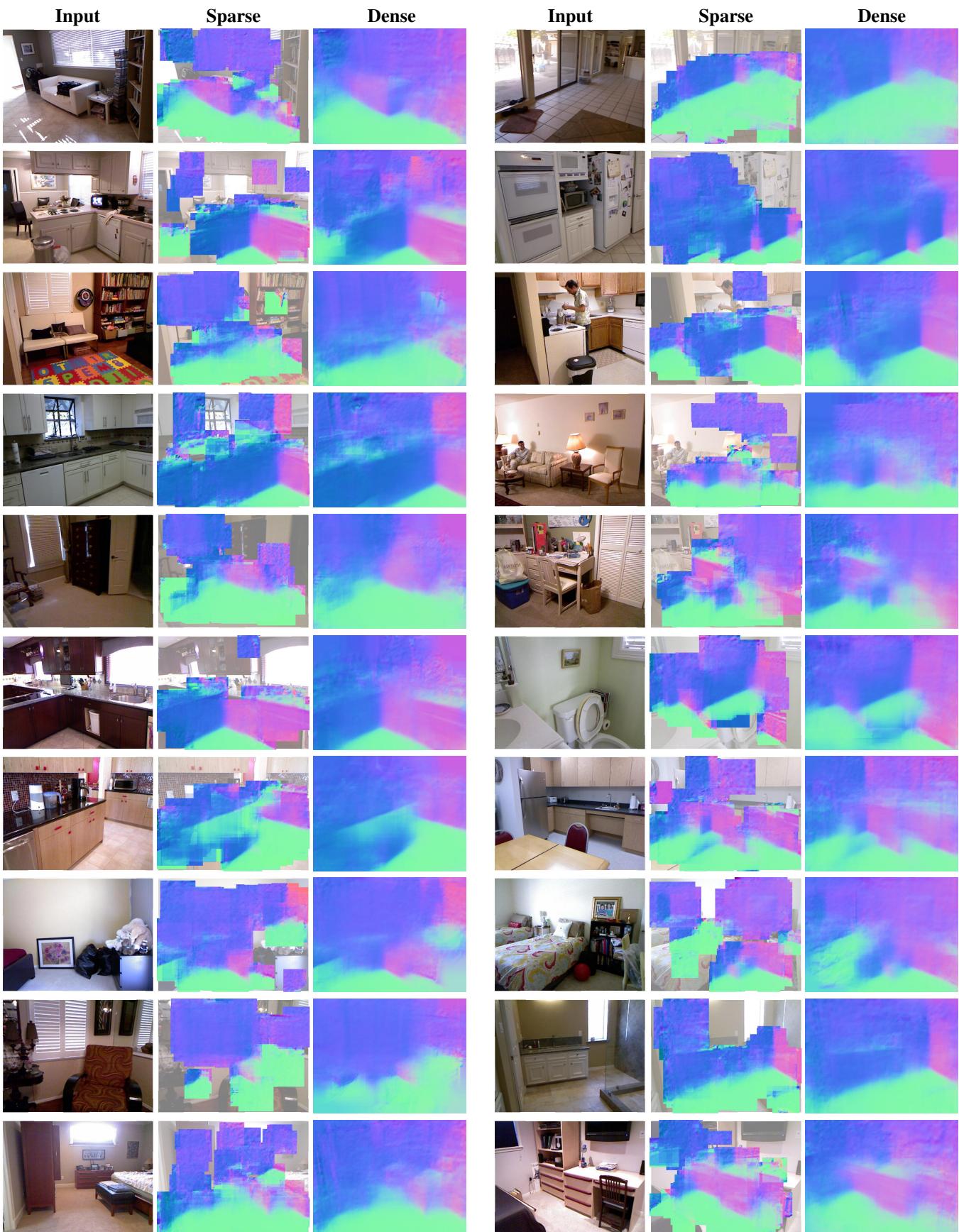
Data-Driven 3D Primitives for Single Image Understanding
Additional Inference Results on NYU v2
David F. Fouhey, Abhinav Gupta, Martial Hebert

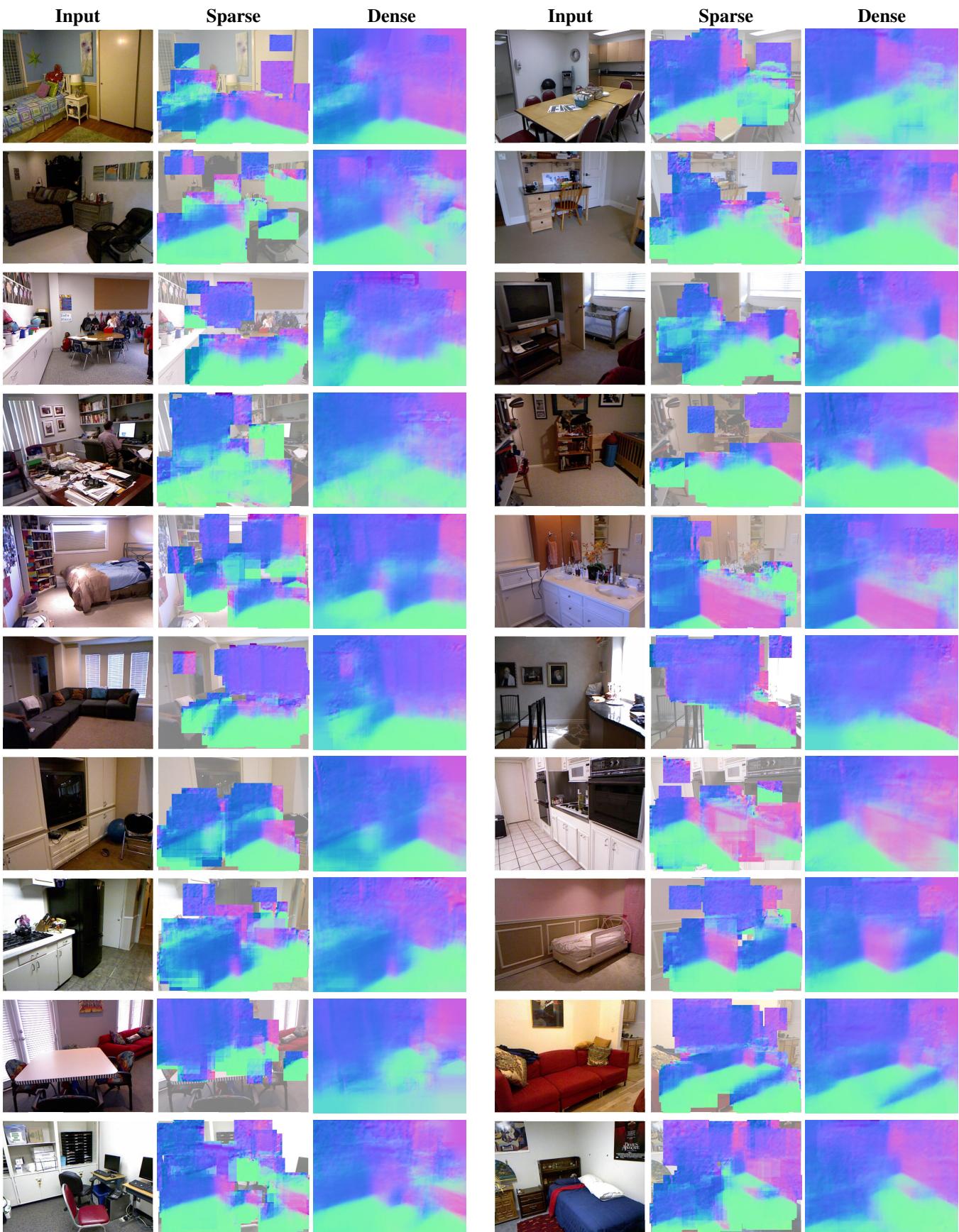
We first present our sparse and dense interpretations for the top 100 most confident results, ordered by confidence. Confidence is defined as the mean value of the weight image (i.e., the normalization constant Z) and is roughly equivalent to the number of detections, weighted by calibrated score. We then present results automatically evenly spaced among the remaining results.

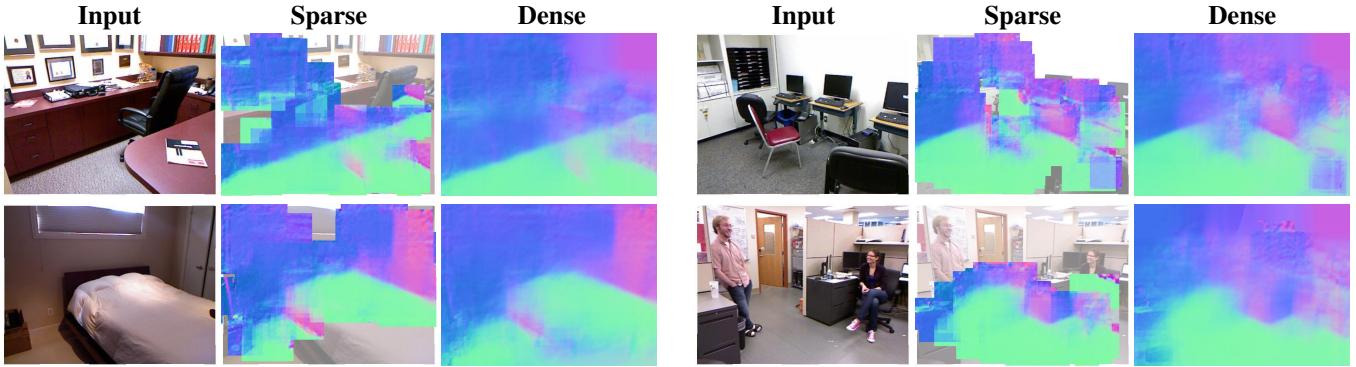












Evenly spaced results from the remainder of the dataset, sorted by confidence

