

## **Bluetooth Communication Protocol**

1. Pick UUID Glove:
  - i. Online generator:
2. Control commands (from app to glove)
  - i. Used by the Android app to send commands to the glove, like starting an exercise or setting resistance.
3. Response commands (from glove to app)
  - i. Used by the glove to send data back to the app, like sensor readings.
  - ii. We need sensor data + ACK
4. Communication flow:
  - i. From Android to Glove: The app writes a command to the Control. For example, to set the resistance to level 3, it writes opcode for setting resistance.
  - ii. From Glove to Android: The glove notifies the Android app via the Response with sensor data or acknowledgments. If sending a sensor value of 120, it might notify with 0x81 + <value>.

### **Example:**

1. Setting Resistance:
  - a. Android writes 0x0205 to Control Commands to set resistance to level 5.
2. Android App Sends Command to Start Exercise:
  - a. Writes to Control Commands: EX: 0x01 (start command).
3. Glove Acknowledges and Starts Exercise:
  - a. writes 0x82 (ACK) to Acknowledge.
  - b. Begins the exercise.
4. Glove Sends Sensor Data:
  - a. Glove notifies the Response Commands with 0x81<sensor\_value> periodically, allowing the Android app to track the user's performance.

### **Opcodes**

C	S	EMPTY	EMPTY	EMPTY	SR	ST	SE
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SE: 0: power down mode, 1: start exercise (if connected 1000 0001 -> 0x81)

ST: 0: power down mode - no effect, 1: stop exercise (if connected 1000 0010 -> 0x82)

SR: 0: power down mode, 1: setting resistance + value (8 bits) = 2 bytes for SR (1000 0101 -> 0x85 + value (0xvalue))

S: 0: power mode down, 1: searching for Bluetooth devices (0100 0000 -> 0x40)

C: 0: disconnected device, 1: connected device (if connected, 0x80) (if not 0x00)

Default value: 1000 0000 iff connected (0x80)

0100 0000 → search  
1000 0000  
0100 0001 ← connected  
1000 0101 ← set R  
0000 0101 → 5  
1000 0010 → stop  
0000 0000 → disconnect