



## **Programming Assignment # 1**

**Course code: CSE- 6239**

**Course Title: Computer Vision**

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1. Write a function that convolves an image with a given convolution filter

*function [output\_Image]= myImageFilter( Input\_image, filter) .*

Your function should output image of the same size as that of input Image (use padding).

Test your function (on attached images House1.jpg and House2.jpg) and show results on the following Kernels.

A. Average Kernel (3\*3 and 5\*5)

```
import cv2
from skimage import io, color
import matplotlib.pyplot as plt
import numpy as np

#input image from directory
img1=cv2.imread('House1.jpg', cv2.CV_8UC1)
img1 = color.rgb2gray(img1)

img2=cv2.imread('House2.jpg', cv2.CV_8UC1)
img2 = color.rgb2gray(img2)

def convolve2d(image,
kernel,kernel_height,kernel_width):
    output = np.zeros_like(image)
    for x in range(image.shape[1]-kernel_width+1):
        for y in range(image.shape[0]-kernel_height+1):
            output[y,x]=(kernel*image[y:y+kernel_height,x:x+kernel_width]).sum()/(kernel_width*kernel_height)
    return output

# Average kernel 3by3

kernel = np.array([[1,1,1],[1,1,1],[1,1,1]])
result1 = convolve2d(img1, kernel, 3, 3)
result2 = convolve2d(img2, kernel, 3, 3)

cv2.imwrite('Output
image/AveragekernelThreeByThreeHouse1.jpg',result1)
cv2.imwrite('Output
image/AveragekernelThreeByThreeHouse2.jpg',result2)
```

Output:



*Figure 4 AveragekernelThreeByThreeHouse1.jpg*



*Figure 4 AveragekernelThreeByThreeHouse2.jpg*



*Figure 4 averagekernelfiveByfiveHouse1.jpg*



*Figure 4AveragekernelfiveByfiveHouse2.jpg*

- B. Gaussian Kernel ( $\sigma = 1, 2, 3$ ). Use  $(2\sigma + 1) \times (2\sigma + 1)$  as size of Kernel (You may write a separate function to generate Gaussian Kernels for different values of  $\sigma$ .)

```
import cv2
from skimage import io, color
import matplotlib.pyplot as plt
import numpy as np

#input image
img1=cv2.imread('House1.jpg', cv2.CV_8UC1)
img1 = color.rgb2gray(img1)

img2=cv2.imread('House2.jpg', cv2.CV_8UC1)
img2 = color.rgb2gray(img2)

def convolve2d(image, kernel, kernel_height, kernel_width):
    output = np.zeros_like(image)
    for x in range(image.shape[1]-kernel_width+1):
        for y in range(image.shape[0]-kernel_height+1):
            output[y,x]=(kernel*image[y:y+kernel_height,x:x+kernel_width]).sum()/(kernel_width*kernel_height)
    return output

def gussiankern(sigma):
    x, y = np.meshgrid(np.linspace(-1,1,2*sigma+1),
np.linspace(-1,1,2*sigma+1))
    d = np.sqrt(x*x+y*y)
    g = np.exp(-( d**2 / ( 2.0 * sigma**2 ) ) )
    return g

#gaussian kernel

sigma = 1
kernel = gussiankern(sigma)
result1 = convolve2d(img1,kernel,2*sigma+1,2*sigma+1)
result2 = convolve2d(img2,kernel,2*sigma+1,2*sigma+1)
```

```
cv2.imwrite('Output
image/gussiankernelHouse1.jpg',result1)
cv2.imwrite('Output
image/gussiankernelHouse2.jpg',result2)
```

Output:



*Figure 6gussiankernelHouse1.jpg*



*Figure 6 GussiankernelHouse2.jpg*

### C. Sobel Edge Operators.

```
import cv2
from skimage import io, color
import matplotlib.pyplot as plt
import numpy as np

#input image
img1=cv2.imread('House1.jpg', cv2.CV_8UC1)
img1 = color.rgb2gray(img1)

img2=cv2.imread('House2.jpg', cv2.CV_8UC1)
img2 = color.rgb2gray(img2)

def convolve2d(image,
kernel,kernel_height,kernel_width):
    output = np.zeros_like(image)
    for x in range(image.shape[1]-kernel_width+1):
```

```

        for y in range(image.shape[0]-kernel_height+1):
output[y,x]=(kernel*image[y:y+kernel_height,x:x+kernel_
width]).sum()/(kernel_width*kernel_height)
        return output

#Sobel Edge Operator

# Sobel Edge ---> x <----
kernel = np.array([[-1,0,1],[-2,0,2],[-1,0,1]])
result1 = convolve2d(img1,kernel,3,3)
result2 = convolve2d(img2,kernel,3,3)

cv2.imwrite('Output
image/sobel_edge_X_House1.jpg',result1)
cv2.imwrite('Output
image/sobel_edge_X_House2.jpg',result2)

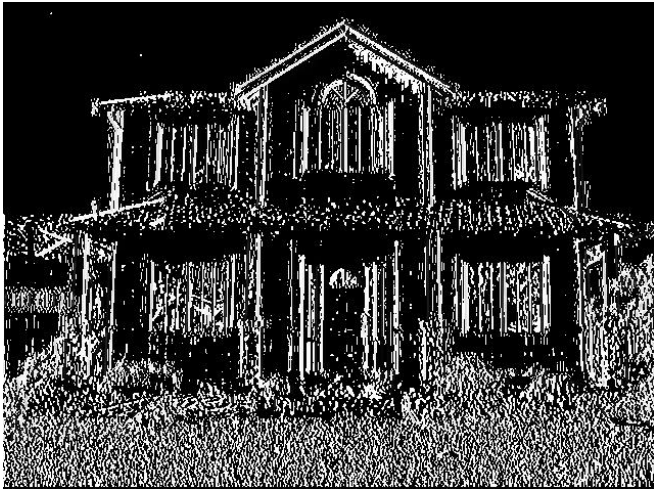
# Sobel Edge ---> y <---
kernel = np.array([[-1,-2,-1],[0,0,0],[1,2,1]])
result1 = convolve2d(img1,kernel,3,3)
result2 = convolve2d(img2,kernel,3,3)

cv2.imwrite('Output
image/sobel_edge_Y_House1.jpg',result1)
cv2.imwrite('Output
image/sobel_edge_Y_House2.jpg',result2)

```



Output:



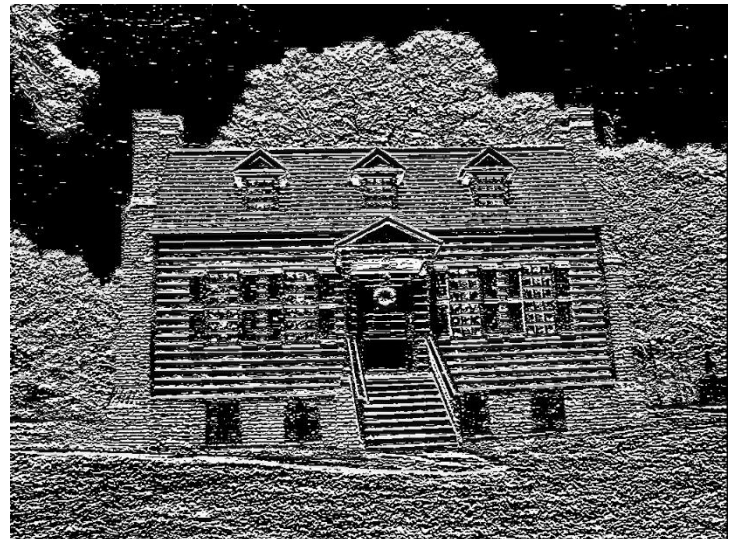
*Figure 10 Sobel\_edge\_X\_House1.jpg*



*Figure 10 Sobel\_edge\_Y\_House1.jpg*



*Figure 10 Sobel\_edge\_X\_House2.jpg*



*Figure 10 Sobel\_edge\_Y\_House2.jpg*

#### D. Prewitt Edge Operators.

```
import cv2
from skimage import io, color

import matplotlib.pyplot as plt
import numpy as np

#input image
img1=cv2.imread('House1.jpg', cv2.CV_8UC1)
img1 = color.rgb2gray(img1)

img2=cv2.imread('House2.jpg', cv2.CV_8UC1)
img2 = color.rgb2gray(img2)

def convolve2d(image,
kernel,kernel_height,kernel_width):
    output = np.zeros_like(image)
    for x in range(image.shape[1]-kernel_width+1):
        for y in range(image.shape[0]-kernel_height+1):
            output[y,x]=(kernel*image[y:y+kernel_height,x:x+kernel_
width]).sum()/(kernel_width*kernel_height)
    return output

# Prewitt edge operator

# Prewitt Edge Operator ----> x <----
kernel = np.array([[+1,0,-1],[+1,0,-1],[1,0,-1]])
result1 = convolve2d(img1,kernel,3,3)
result2 = convolve2d(img2,kernel,3,3)

cv2.imwrite('Output
image/Prewitt_edge_X_house1.jpg',result1)
cv2.imwrite('Output
image/Prewitt_edge_X_house2.jpg',result2)
```



```
# Prewitt Edge Operator ---> y <----  
kernel = np.array([[+1,+1,+1],[0,0,0],[-1,-1,11]])  
result1 = convolve2d(img1,kernel,3,3)  
result2 = convolve2d(img2,kernel,3,3)  
  
cv2.imwrite('Output  
image/Prewitt_edge_Y_house1.jpg',result1)  
cv2.imwrite('Output  
image/Prewitt_edge_Y_house2.jpg',result2)
```

Output:

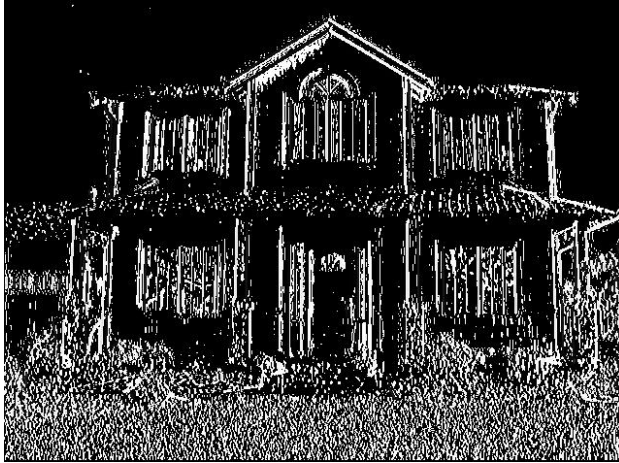


Figure 14 Prewiit\_edge\_X\_house1.jpg



Figure 14 Prewiit\_edge\_Y\_house1.jpg



Figure 14 Prewiit\_edge\_X\_house2.jpg



Figure 14 Prewiit\_edge\_Y\_house2.jpg

- 2 Attached 'Noisy image1' and 'Noisy image2' are corrupted by salt and paper noise. Apply 5 by 5 Averaging and Median filter and show your outputs.

```
import cv2
from skimage import io, color
import numpy as np

#input image
img1=cv2.imread('Noisyimage1.jpg', cv2.CV_8UC1)
img1 = color.rgb2gray(img1)
```

```

img2=cv2.imread('Noisyimage2.jpg', cv2.CV_8UC1)
img2 = color.rgb2gray(img2)

def convolve2d(image,
kernel,kernel_height,kernel_width):
    output = np.zeros_like(image)
    for x in range(image.shape[1]-kernel_width+1):
        for y in range(image.shape[0]-
kernel_height+1):
output[y,x]=(kernel*image[y:y+kernel_height,x:x+kernel_width]).sum()/(kernel_width*kernel_height)
    return output

def median_filter(data, filter_size):
    temp = []
    indexer = filter_size // 2
    data_final = []
    data_final = np.zeros((len(data), len(data[0])))
    for i in range(len(data)):

        for j in range(len(data[0])):

            for z in range(filter_size):
                if i + z - indexer < 0 or i + z -
indexer > len(data) - 1:
                    for c in range(filter_size):
                        temp.append(0)
                else:
                    if j + z - indexer < 0 or j +
indexer > len(data[0]) - 1:
                        temp.append(0)
                    else:
                        for k in range(filter_size):
                            temp.append(data[i + z -
indexer][j + k - indexer])

            temp.sort()

```

```

        data_final[i][j] = temp[len(temp) // 2]
        temp = []
    return data_final

#average jernel 5 by 5

kernel =
np.array([[1,1,0,0,1],[1,1,1,1,0],[0,0,0,0,0],[0,1,1,
1,1],[1,0,1,1,0]])
result1 = convolve2d(img1,kernel,5,5)
result2 = convolve2d(img2,kernel,5,5)

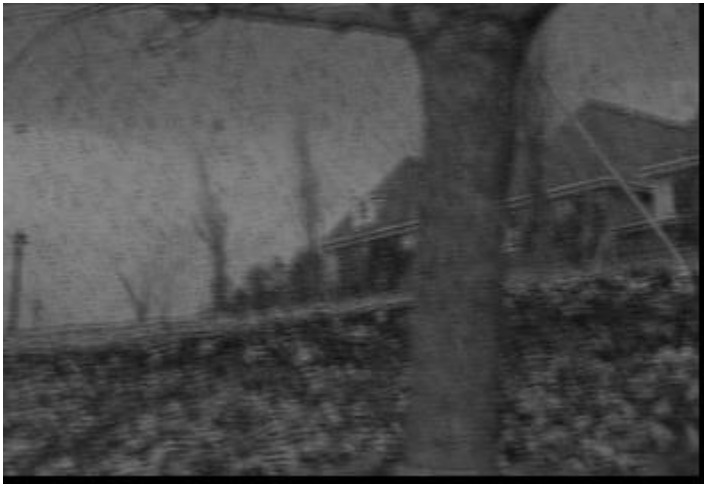
cv2.imwrite('Output
image/noiseRemove1Byaveragefilter.jpg',result1)
cv2.imwrite('Output
image/noiseRemove2Byaveragefilter.jpg',result2)

result1 = median_filter(img1,3)
result2 = median_filter(img2,3)

cv2.imwrite('Output
image/noiseremoveByMedian1.jpg',result1)
cv2.imwrite('Output
image/noiseremoveByMedian2.jpg',result2)

```

Output:



*Figure 18 NoiseRemove1Byaveragefilter.jpg*



*Figure 18 noiseremoveByMedian1.jpg*



*Figure 18 NoiseRemove2Byaveragefilter.jpg*



*Figure 18 noiseremoveByMedian2.jpg*

- 4 Load *walk\_1.jpg* and *walk\_2.jpg* images in openCV. Convert them to gray scale and subtract *walk\_2.jpg* from *walk\_1.jpg*. What is the result? Why?

```
import cv2

image_one = cv2.imread('walk_1.jpg')
image_two = cv2.imread('walk_2.jpg')

gray_image_one =
cv2.cvtColor(image_one,cv2.COLOR_RGB2GRAY)
gray_image_two =
cv2.cvtColor(image_two,cv2.COLOR_RGB2GRAY)

subtract_image = gray_image_one.copy()

for i in range(subtract_image.shape[0]):
    for j in range(subtract_image.shape[1]):

subtract_image.itemset((i,j),abs(int(gray_image_one[i][j]
) - int(gray_image_two[i][j])))

cv2.imwrite('output
image/subtract_image.jpg',subtract_image)
```



Output:



*Figure 19 subtract\_image.jpg*

This result has been come because two images background are same but their objects are difference so one background subtract by another that's why our result every time come like this.

