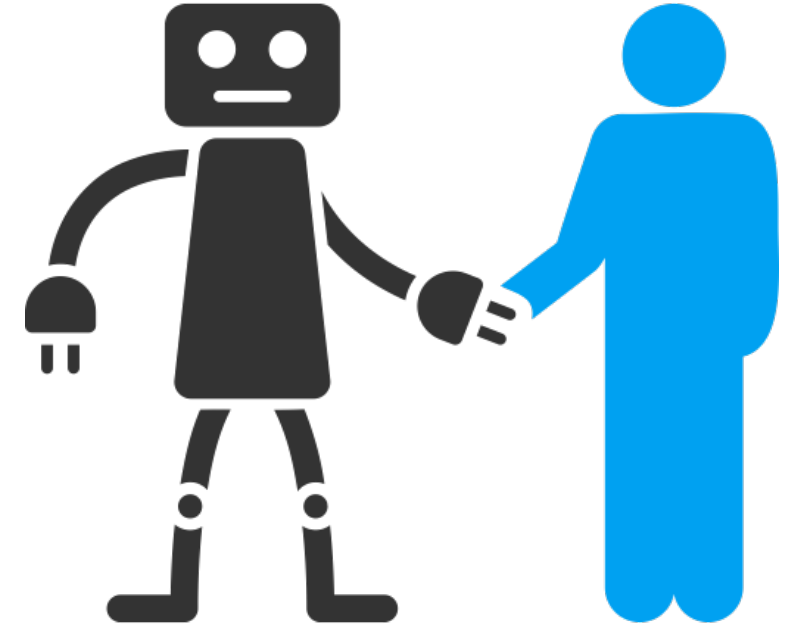
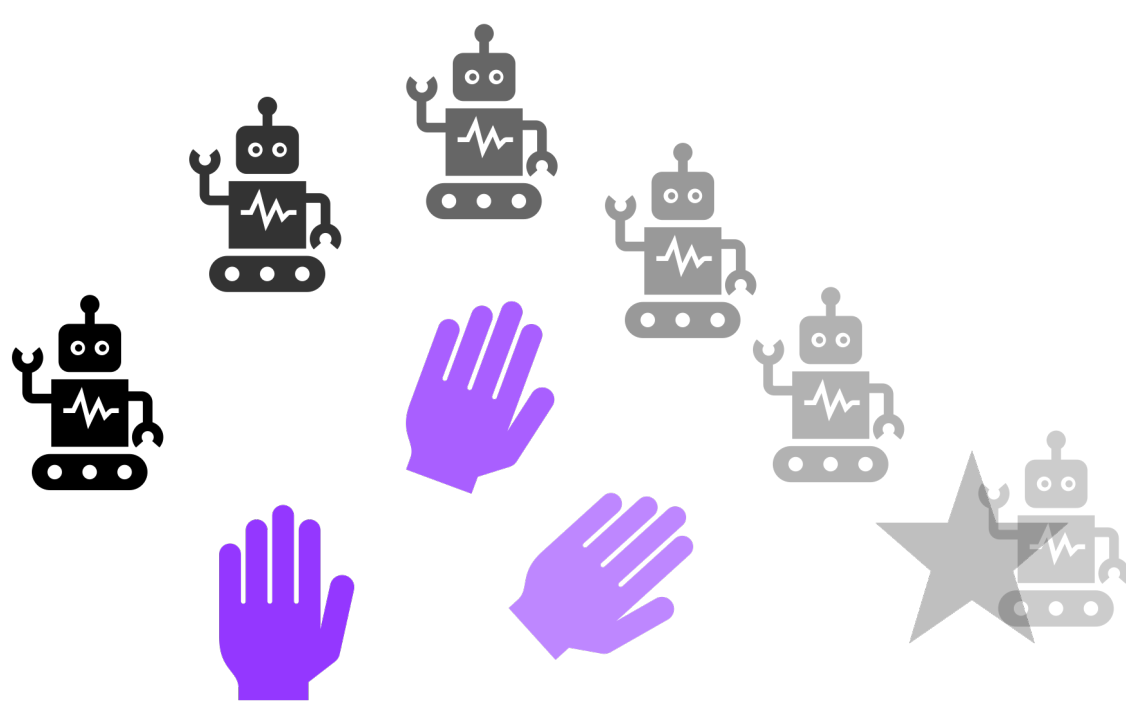


Human-aware motion planners
Safety = collision avoidance

Compliant controllers
Safety = low contact force



Collision avoidance **OR** safe impact