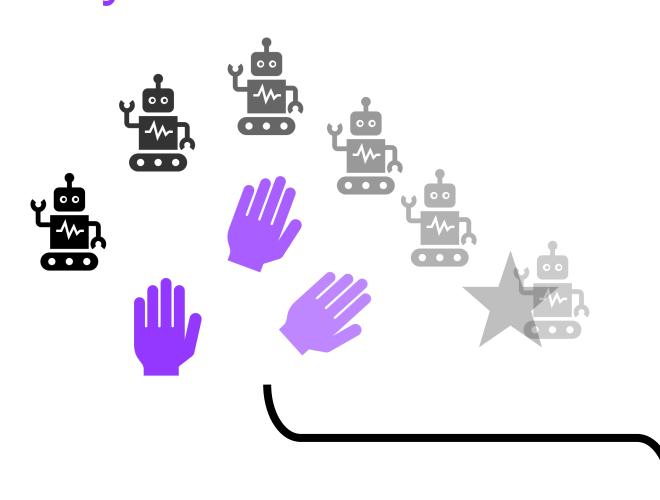
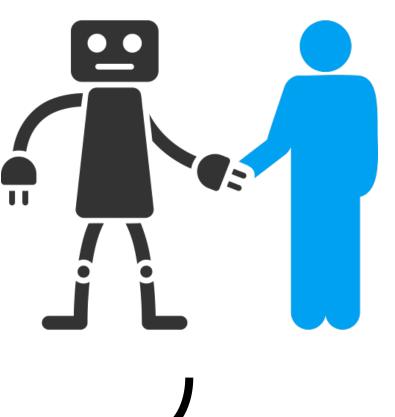
Human-aware motion planners Safety = collision avoidance

Compliant controllers Safety = low contact force





Collision avoidance OR safe impact