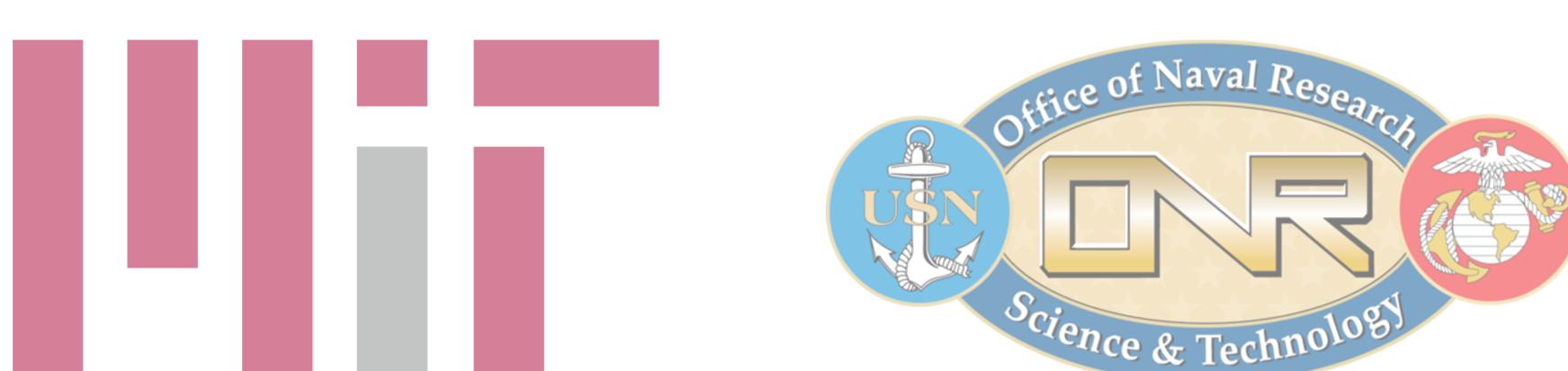
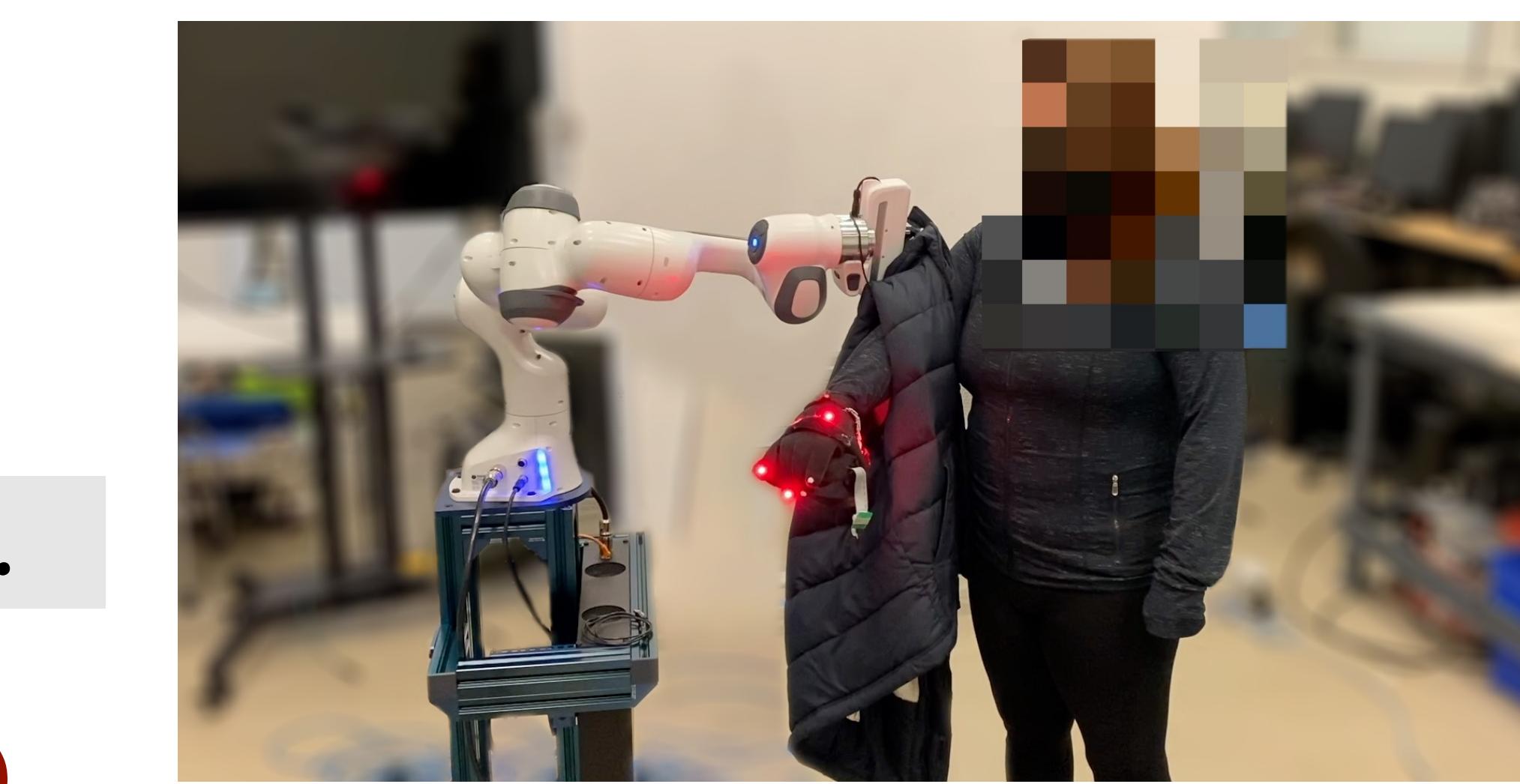


Provably Safe and Efficient Motion Planning with Uncertain Human Dynamics

Shen Li, Nadia Figueiro Ankit Shah, Julie A. Shah



Motivation: (1) Ensure human physical safety & (2) without unnecessarily impacting task efficiency

