GearUsed: MaxSteer: 0 (user input) 11.77 m/s MaxAccel: 0 (user input) MaxSpeed: MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input) MaxSteering: GPS [Simulator.Sensors.GpsSensor] **GPS INS Status** [Simulator.Sensors.GpsInsSensor] Start Latitude: 37.788° Status: 3 misc 56 misc Position Type:

Start -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.785° Latitude: Longitude: -122.406° 10.558 m Altitude: 4,182,158.706 m East Northing: 552,293.575 m North Easting: Map Url: open Google Maps

0 (user input) SimulationDura MaxSteer: 120 seconds tion: MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 120.021 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor] MaxTracked: MaxSteer: 0.447 (user input) 3 counts

Keyboard Car Control

MaxAccel:

MaxBrake:

1 (user input)

0 (user input)

[Simulator.Sensors.KeyboardControlSensor]

IsControlReceiv true misc ed: **GPS Odometry** [Simulator.Sensors.GpsOdometrySensor] Start Latitude: 37.788° Start -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: Longitude: -122.406°

[Simulator.Sensors.ClockSensor]

Callbacks

Altitude:

Northing:

Easting:

Map Url:

10.558 m

4,182,158.706 m East

552,293.575 m North

open Google Maps

Clock Sensor