581.323 km maxY: minGyroY: -0.002 ° 0.002° maxGyroY: 0 km minZ: 10.563 km maxZ: 0° minGyroZ: 0.4° maxGyroZ: **Wheel Car Control CAN Bus** [Simulator.Sensors.CanBusSensor] [Simulator.Sensors.WheelControlSensor]

GearUsed: MaxSteer: 0 (user input) 11.505 m/s MaxAccel: 0 (user input) MaxSpeed: MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input) MaxSteering: GPS [Simulator.Sensors.GpsSensor] **GPS INS Status** [Simulator.Sensors.GpsInsSensor] Start Latitude: 37.788° Status: 3 misc 56 misc Start Position Type: -122.4° Longitude:

Start Altitude: 0.352 m Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.793° Latitude: Longitude: -122.393° 10.556 m Altitude: 4,182,971.038 m East Northing: 553,475.846 m North Easting: open Google Maps Map Url:

Clock Sensor [Simulator.Sensors.ClockSensor] **Keyboard Car Control** [Simulator.Sensors.KeyboardControlSensor] 0 (user input) SimulationDura MaxSteer: 120 seconds tion: MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 120.023 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor]

MaxSteer:

0.227 (user input)

MaxAccel: 1 (user input)
MaxBrake: 0 (user input)
IsControlReceiv ed: true misc

GPS Odometry

Start Latitude: 37.788 °
Start Longitude: -122.4 °
Start Altitude: 0.352 m

Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: Longitude: -122.393° 10.556 m Altitude: Northing: 4,182,971.038 m East Easting: 553,475.846 m North open Google Maps Map Url:

Callbacks

MaxTracked:

2 counts