Wheel Car Control CAN Bus [Simulator.Sensors.CanBusSensor] [Simulator.Sensors.WheelControlSensor] GearUsed: MaxSteer: 0 (user input) 11.725 m/s MaxAccel: 0 (user input) MaxSpeed: MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input) MaxSteering:

GPS INS Status

Keyboard Car Control

MaxAccel:

MaxBrake:

1 (user input)

0 (user input)

[Simulator.Sensors.GpsInsSensor]

[Simulator.Sensors.KeyboardControlSensor]

[Simulator.Sensors.GpsSensor]

[Simulator.Sensors.ClockSensor]

Start Latitude: 37.788° Status: 3 misc 56 misc Start Position Type: -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.792° Latitude: Longitude: -122.401° 10.559 m Altitude: 4,182,905.933 m East Northing: 552,747.808 m North Easting: Map Url: open Google Maps

0 (user input) SimulationDura MaxSteer: 120 seconds tion: MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 120.045 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor] MaxTracked: MaxSteer: 0.088 (user input) 8 counts

IsControlReceiv true misc ed: **GPS Odometry** [Simulator.Sensors.GpsOdometrySensor] Start Latitude: 37.788° Start -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: Longitude: -122.401° 10.559 m Altitude:

Callbacks

Northing:

Easting:

Map Url:

4,182,905.933 m East

552,747.808 m North

open Google Maps

GPS

Clock Sensor