**Wheel Car Control CAN Bus** [Simulator.Sensors.CanBusSensor] [Simulator.Sensors.WheelControlSensor] GearUsed: MaxSteer: 0 (user input) 8.45 m/s MaxAccel: 0 (user input) MaxSpeed: MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input) MaxSteering: GPS [Simulator.Sensors.GpsSensor] **GPS INS Status** [Simulator.Sensors.GpsInsSensor] Start Latitude: 37.788° Status: 3 misc

56 misc Start Position Type: -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.788° Latitude: Longitude: -122.394° 10.556 m Altitude: 4,182,483.867 m East Northing: 553,315.375 m North Easting: Map Url: open Google Maps

**Clock Sensor** [Simulator.Sensors.ClockSensor] **Keyboard Car Control** [Simulator.Sensors.KeyboardControlSensor] 0 (user input) SimulationDura MaxSteer: 51.72 seconds tion: MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 51.742 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor]

MaxSteer:

0.059 (user input)

MaxAccel: 1 (user input)
MaxBrake: 0 (user input)

IsControlReceiv ed: true misc

GPS Odometry

Start Latitude: 37.788 °

Start Longitude: 1-122.4 °
Start Altitude: 0.352 m

MaxAccel: 1 (user input)
MaxBrake: 0 (user input)

Frue misc

True misc

Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: Longitude: -122.394° 10.556 m Altitude: 4,182,483.867 m East Northing: Easting: 553,315.375 m North open Google Maps Map Url:

## Callbacks

MaxTracked:

4 counts