0.002° maxGyroY: 0 km minZ: 10.565 km maxZ: 0° minGyroZ: maxGyroZ: 0.715° **Wheel Car Control CAN Bus** [Simulator.Sensors.CanBusSensor] [Simulator.Sensors.WheelControlSensor]

GearUsed: MaxSteer: 0 (user input) 12.871 m/s MaxAccel: 0 (user input) MaxSpeed: MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input) MaxSteering: GPS [Simulator.Sensors.GpsSensor] **GPS INS Status** [Simulator.Sensors.GpsInsSensor] Start Latitude: 37.788° Status: 3 misc 56 misc Start Position Type: -122.4° Longitude: 0.352 m Start Altitude:

Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.79° Latitude: Longitude: -122.403° 10.556 m Altitude: 4,182,634.236 m East Northing: 552,574.589 m North Easting: open Google Maps Map Url:

Clock Sensor [Simulator.Sensors.ClockSensor] **Keyboard Car Control** [Simulator.Sensors.KeyboardControlSensor] 0 (user input) SimulationDura MaxSteer: 120 seconds tion: MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 120.061 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor]

MaxTracked: MaxSteer: 0.023 (user input) 14 counts MaxAccel: 1 (user input) MaxBrake: 0 (user input) IsControlReceiv true misc ed: **GPS Odometry** [Simulator.Sensors.GpsOdometrySensor] Start Latitude: 37.788° Start -122.4° Longitude: 0.352 m

Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: Longitude: -122.403° 10.556 m Altitude: Northing: 4,182,634.236 m East Easting: 552,574.589 m North open Google Maps Map Url:

Callbacks