10.562 km maxZ: 0° minGyroZ: maxGyroZ: 0.696° **Wheel Car Control CAN Bus** [Simulator.Sensors.CanBusSensor] [Simulator.Sensors.WheelControlSensor]

GearUsed: MaxSteer: 0 (user input) 10.967 m/s MaxAccel: 0 (user input) MaxSpeed: MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input) MaxSteering: GPS [Simulator.Sensors.GpsSensor] **GPS INS Status** [Simulator.Sensors.GpsInsSensor] Start Latitude: 37.788° Status: 3 misc Start Position Type: 56 misc -122.4° Longitude: Start Altitude: 0.352 m

Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.782° Latitude: Longitude: -122.393° 10.557 m Altitude: 4,181,767.015 m East Northing: 553,434.967 m North Easting: open Google Maps Map Url:

**Clock Sensor** [Simulator.Sensors.ClockSensor] **Keyboard Car Control** [Simulator.Sensors.KeyboardControlSensor] 0 (user input) SimulationDura MaxSteer: 120 seconds tion: MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 120.024 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor]

0.003 (user input) MaxTracked: MaxSteer: 2 counts MaxAccel: 1 (user input) MaxBrake: 0 (user input) IsControlReceiv true misc ed: **GPS Odometry** [Simulator.Sensors.GpsOdometrySensor] Start Latitude: 37.788° Start -122.4° Longitude: 0.352 m

Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: Longitude: -122.393° 10.557 m Altitude: Northing: 4,181,767.015 m East Easting: 553,434.967 m North open Google Maps Map Url:

## Callbacks