0 km minZ: 10.561 km maxZ: 0° minGyroZ: maxGyroZ: 0.71 ° **Wheel Car Control CAN Bus** [Simulator.Sensors.CanBusSensor] [Simulator.Sensors.WheelControlSensor] GearUsed: MaxSteer: 0 (user input) 9.442 m/s MaxAccel: 0 (user input) MaxSpeed:

MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input) MaxSteering: GPS [Simulator.Sensors.GpsSensor] **GPS INS Status** [Simulator.Sensors.GpsInsSensor] Start Latitude: 37.788° Status: 3 misc 56 misc Start Position Type: -122.4° Longitude: 0.352 m Start Altitude:

Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.788° Latitude: Longitude: -122.397° 10.556 m Altitude: 4,182,504.167 m East Northing: 553,115.698 m North Easting: open Google Maps Map Url:

Clock Sensor [Simulator.Sensors.ClockSensor] **Keyboard Car Control** [Simulator.Sensors.KeyboardControlSensor] SimulationDura 0 (user input) MaxSteer: 120 seconds tion: MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 120.048 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor]

MaxTracked: 1 counts

MaxSteer: 0.001 (user input)

MaxAccel: 0.992 (user input)

MaxBrake: 0 (user input)

MaxBrake: ved:

Ved:

Ved:

SControlReceiv ed:

Ved:

Start Latitude: 37.788 °

Start Latitude: 37.788 °

Start Latitude: 122.4 °

Start -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: Longitude: -122.397° 10.556 m Altitude: Northing: 4,182,504.167 m East Easting: 553,115.698 m North open Google Maps Map Url:

Callbacks