CAN Bus

[Simulator.Sensors.CanBusSensor]

Wheel Car Control

[MaxSteer: 0 (user input)

MaxSpeed: 12.684 m/s

MaxSteering: 0 (user input)

MaxBrake: 0 (user input)

MaxSteering: 0 °

**GPS INS Status** 

[Simulator.Sensors.GpsInsSensor]

[Simulator.Sensors.GpsSensor]

Start Latitude: 37.788° Status: 3 misc 56 misc Start Position Type: -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.783° Latitude: Longitude: -122.391° 10.556 m Altitude: 4,181,892.877 m East Northing: 553,651.474 m North Easting: Map Url: open Google Maps

[Simulator.Sensors.KeyboardControlSensor] **Clock Sensor** [Simulator.Sensors.ClockSensor] **Keyboard Car Control** SimulationDura MaxSteer: 0 (user input) 120 seconds tion: MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 120.04 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor]

MaxSteer:

0.822 (user input)

MaxAccel: 1 (user input) MaxBrake: 0 (user input) IsControlReceiv true misc ed: **GPS Odometry** [Simulator.Sensors.GpsOdometrySensor] Start Latitude: 37.788° Start -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East

Callbacks

552,872.635 m North

open Google Maps

4,181,892.877 m East

553,651.474 m North

open Google Maps

-122.391°

10.556 m

GPS

MaxTracked:

Start Easting:

Start Map Url:

Latitude:

Longitude:

Altitude:

Northing:

Easting:

Map Url:

4 counts