Wheel Car Control CAN Bus [Simulator.Sensors.CanBusSensor] [Simulator.Sensors.WheelControlSensor] GearUsed: MaxSteer: 0 (user input) 11.764 m/s MaxAccel: 0 (user input) MaxSpeed: MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input) MaxSteering: GPS [Simulator.Sensors.GpsSensor] **GPS INS Status** [Simulator.Sensors.GpsInsSensor]

Start Latitude: 37.788° Status: 3 misc 56 misc Start Position Type: -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.786° Latitude: Longitude: -122.397° 10.556 m Altitude: 4,182,297.319 m East Northing: 553,107.648 m North Easting: open Google Maps Map Url:

MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 120.025 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor] 0.626 (user input) MaxTracked: MaxSteer: 3 counts MaxAccel: 1 (user input) MaxBrake: 0 (user input) IsControlReceiv

ed:

Keyboard Car Control

MaxSteer:

0 (user input)

true misc

[Simulator.Sensors.KeyboardControlSensor]

[Simulator.Sensors.ClockSensor]

GPS Odometry [Simulator.Sensors.GpsOdometrySensor] Start Latitude: 37.788° Start -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: Longitude: -122.397° 10.556 m Altitude: Northing: 4,182,297.319 m East 553,107.648 m North Easting: open Google Maps Map Url:

Callbacks

Clock Sensor

tion:

SimulationDura

120 seconds