**Wheel Car Control CAN Bus** [Simulator.Sensors.CanBusSensor] [Simulator.Sensors.WheelControlSensor] GearUsed: MaxSteer: 0 (user input) 10.272 m/s MaxAccel: 0 (user input) MaxSpeed: MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input)

Start Latitude: 37.788° Status: 3 misc Start Position Type: 56 misc -122.4° Longitude: Start Altitude: 0.352 m Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.788° Latitude: Longitude: -122.397° 10.556 m Altitude: 4,182,512.382 m East Northing: 553,108.186 m North Easting: open Google Maps Map Url:

**GPS INS Status** 

**Keyboard Car Control** 

IsControlReceiv

ed:

true misc

[Simulator.Sensors.GpsInsSensor]

[Simulator.Sensors.KeyboardControlSensor]

[Simulator.Sensors.GpsSensor]

[Simulator.Sensors.ClockSensor]

0 (user input) SimulationDura MaxSteer: 120 seconds tion: MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 120.045 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor] MaxTracked: 4 counts MaxSteer: 0.481 (user input) 1 (user input) MaxAccel: MaxBrake: 0 (user input)

**GPS Odometry** [Simulator.Sensors.GpsOdometrySensor] Start Latitude: 37.788° Start -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: Longitude: -122.397° 10.556 m Altitude: 4,182,512.382 m East Northing: Easting: 553,108.186 m North open Google Maps Map Url:

## Callbacks

MaxSteering:

**Clock Sensor** 

GPS