maxGyroZ: 0.716° **Wheel Car Control CAN Bus** [Simulator.Sensors.CanBusSensor] [Simulator.Sensors.WheelControlSensor] GearUsed: MaxSteer: 0 (user input) 11.004 m/s MaxAccel: 0 (user input) MaxSpeed: MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input) MaxSteering:

GPS INS Status

Keyboard Car Control

MaxSteer:

0 (user input)

true misc

[Simulator.Sensors.GpsInsSensor]

[Simulator.Sensors.KeyboardControlSensor]

[Simulator.Sensors.GpsSensor]

[Simulator.Sensors.ClockSensor]

Start Latitude: 37.788° Status: 3 misc 56 misc Start Position Type: -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.79° Latitude: Longitude: -122.403° 10.556 m Altitude: 4,182,652.882 m East Northing: 552,580.083 m North Easting: open Google Maps Map Url:

MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 120.028 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor] 0.021 (user input) MaxTracked: MaxSteer: 16 counts MaxAccel: 0.993 (user input) MaxBrake: 0 (user input) IsControlReceiv

ed:

GPS Odometry [Simulator.Sensors.GpsOdometrySensor] Start Latitude: 37.788° Start -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: Longitude: -122.403° 10.556 m Altitude: Northing: 4,182,652.882 m East Easting: 552,580.083 m North open Google Maps Map Url:

0.001°

10.56 km

0 km

0°

maxGyroY:

minGyroZ:

minZ:

maxZ:

GPS

Clock Sensor

tion:

SimulationDura

120 seconds

Callbacks