-0.725 ° minGyroZ: 0.264° maxGyroZ: **Wheel Car Control CAN Bus** [Simulator.Sensors.CanBusSensor] [Simulator.Sensors.WheelControlSensor]

GearUsed: MaxSteer: 0 (user input) 11.422 m/s MaxAccel: 0 (user input) MaxSpeed: MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input) MaxSteering: GPS [Simulator.Sensors.GpsSensor] **GPS INS Status** [Simulator.Sensors.GpsInsSensor] Start Latitude: 37.788° Status: 3 misc 56 misc Start Position Type: -122.4° Longitude: 0.352 m Start Altitude:

Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.787° Latitude: Longitude: -122.397° 10.556 m Altitude: 4,182,323.081 m East Northing: 553,112.801 m North Easting: open Google Maps Map Url: **Clock Sensor** [Simulator.Sensors.ClockSensor] **Keyboard Car Control** [Simulator.Sensors.KeyboardControlSensor]

0 (user input) SimulationDura MaxSteer: 120 seconds tion: MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 120.051 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor] MaxTracked: 4 counts MaxSteer: 0.714 (user input)

MaxAccel:

MaxBrake:

1 (user input)

0 (user input) IsControlReceiv true misc ed: **GPS Odometry** [Simulator.Sensors.GpsOdometrySensor] Start Latitude: 37.788° Start -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: Longitude: -122.397°

## Callbacks

Altitude:

Northing:

Easting:

Map Url:

10.556 m

4,182,323.081 m East

553,112.801 m North

open Google Maps