0.002° maxGyroY: 0 km minZ: 10.56 km maxZ: 0° minGyroZ: maxGyroZ: 0.724° **Wheel Car Control CAN Bus** [Simulator.Sensors.CanBusSensor] [Simulator.Sensors.WheelControlSensor]

GearUsed: MaxSteer: 0 (user input) 11.089 m/s MaxAccel: 0 (user input) MaxSpeed: MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input) MaxSteering: GPS [Simulator.Sensors.GpsSensor] **GPS INS Status** [Simulator.Sensors.GpsInsSensor] Start Latitude: 37.788° Status: 3 misc Position Type: 56 misc -122.4°

Start Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.788° Latitude: Longitude: -122.397° 10.556 m Altitude: Northing: 4,182,504.444 m East 553,116.295 m North Easting: open Google Maps Map Url:

Clock Sensor [Simulator.Sensors.ClockSensor] **Keyboard Car Control** [Simulator.Sensors.KeyboardControlSensor] 0 (user input) SimulationDura MaxSteer: 120 seconds tion: MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 120.053 seconds on:

Apollo Car Control

[Simulator.Sensors.ApolloControlSensor]

[Simulator.Sensors.PerceptionSensor3D]

MaxTracked: MaxSteer: 0.081 (user input) 2 counts MaxAccel: 0.992 (user input) MaxBrake: 0 (user input) IsControlReceiv true misc ed: **GPS Odometry** [Simulator.Sensors.GpsOdometrySensor] Start Latitude: 37.788°

Start -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: Longitude: -122.397° 10.556 m Altitude: Northing: 4,182,504.444 m East Easting: 553,116.295 m North open Google Maps Map Url:

Callbacks

3D Ground Truth