Wheel Car Control CAN Bus [Simulator.Sensors.CanBusSensor] [Simulator.Sensors.WheelControlSensor] GearUsed: MaxSteer: 0 (user input) 11.327 m/s MaxAccel: 0 (user input) MaxSpeed: MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input) MaxSteering: GPS [Simulator.Sensors.GpsSensor] **GPS INS Status** [Simulator.Sensors.GpsInsSensor]

Start Latitude: 37.788° Status: 3 misc 56 misc Start Position Type: -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.785° Latitude: Longitude: -122.4° 10.556 m Altitude: 4,182,110.742 m East Northing: 552,850.554 m North Easting: open Google Maps Map Url:

0 (user input) SimulationDura 120 seconds tion: MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 120.043 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor] MaxTracked: MaxSteer: 0.01 (user input) 0 counts 1 (user input) MaxAccel: MaxBrake: 0 (user input)

Keyboard Car Control

MaxSteer:

IsControlReceiv

ed:

true misc

[Simulator.Sensors.KeyboardControlSensor]

[Simulator.Sensors.ClockSensor]

GPS Odometry [Simulator.Sensors.GpsOdometrySensor] Start Latitude: 37.788° Start -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: -122.4° Longitude: 10.556 m Altitude: Northing: 4,182,110.742 m East Easting: 552,850.554 m North open Google Maps Map Url:

Callbacks

Clock Sensor