maxGyroZ: 0.71 ° **Wheel Car Control CAN Bus** [Simulator.Sensors.CanBusSensor] [Simulator.Sensors.WheelControlSensor] GearUsed: MaxSteer: 0 (user input) 12.684 m/s MaxAccel: 0 (user input) MaxSpeed: MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input) MaxSteering:

GPS [Simulator.Sensors.GpsSensor] **GPS INS Status** [Simulator.Sensors.GpsInsSensor] Start Latitude: 37.788° Status: 3 misc 56 misc Start Position Type: -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.782° Latitude: Longitude: -122.394° 10.556 m Altitude: 4,181,754.046 m East Northing: 553,341.068 m North Easting: open Google Maps Map Url:

Clock Sensor [Simulator.Sensors.ClockSensor] **Keyboard Car Control** [Simulator.Sensors.KeyboardControlSensor] 0 (user input) SimulationDura MaxSteer: 120 seconds tion: MaxAccel: 0 (user input) RealtimeDurati MaxBrake: 0 (user input) 120.027 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor] 0.005 (user input) MaxTracked: 4 counts MaxSteer:

0.868 (user input) MaxAccel: MaxBrake: 0 (user input) IsControlReceiv true misc ed: **GPS Odometry** [Simulator.Sensors.GpsOdometrySensor] Start Latitude: 37.788° Start -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East

Callbacks

552,872.635 m North

open Google Maps

4,181,754.046 m East

553,341.068 m North

open Google Maps

-122.394°

10.556 m

Start Easting:

Start Map Url:

Latitude:

Longitude:

Altitude:

Northing:

Easting:

Map Url: