

Simulation Details

Iterations

110

1

Status:Failed

Cause:Stuck

Start time:7/13/2021, 3:51:34 PM

Real time duration:00 : 02 : 23.000

Simulation time duration:00 : 02 : 0.000

Lincoln2017MKZ

Bridge type:CyberRT

Connection:N/A

Analysis

Visualization

Sensors

IMU[Simulator.Sensors.ImuSensor]

minX:0 km

maxX:727.851 km

minGyroX:-0.004 °

maxGyroX:0.041 °

minY:0 km

maxY:581.323 km

minGyroY:-0.061 °

maxGyroY:0.011 °

minZ:0 km

maxZ:10.665 km

minGyroZ:0 °

maxGyroZ:0.984 °

Signal Sensor[Simulator.Sensors.SignalSensor]

SignalsDetected:0 counts

DetectedStates:green,yellow,red misc

CAN Bus[Simulator.Sensors.CanBusSensor]

GearUsed:1

MaxSpeed:11.736 m/s

MaxThrottle:0 (user input)

MaxBrake:0 (user input)

MaxSteering:0 °

Wheel Car Control[Simulator.Sensors.WheelControlSensor]

MaxSteer:0 (user input)

MaxAccel:0 (user input)

MaxBrake:0 (user input)

GPS[Simulator.Sensors.GpsSensor]

Start Latitude:37.788 °

Start Longitude:-122.4 °

Start Altitude:0.352 m

Start Northing:4,182,486.02 m East

Start Easting:552,872.635 m North

Start Map Url:[open Google Maps](#)

Latitude:37.79 °

Longitude:-122.392 °

Altitude:10.556 m

Northing:4,182,744.616 m East

Easting:553,495.524 m North

Map Url:[open Google Maps](#)

GPS INS Status[Simulator.Sensors.GpsInsSensor]

Status:3 misc

Position Type:56 misc

Clock Sensor[Simulator.Sensors.ClockSensor]

SimulationDuration:120 seconds

RealtimeDuration:120.021 seconds

Keyboard Car Control[Simulator.Sensors.KeyboardControlSensor]

MaxSteer:0 (user input)

MaxAccel:0 (user input)

MaxBrake:0 (user input)

3D Ground Truth[Simulator.Sensors.PerceptionSensor3D]

MaxTracked:0 counts

Apollo Car Control[Simulator.Sensors.ApolloControlSensor]

MaxSteer:0.463 (user input)

MaxAccel:1 (user input)

MaxBrake:0 (user input)

IsControlReceived:true misc

GPS Odometry[Simulator.Sensors.GpsOdometrySensor]

Start Latitude:37.788 °

Start Longitude:-122.4 °

Start Altitude:0.352 m

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Callbacks

00:02:00

Stuck

Show event