maxGyroZ: 0.716° **Wheel Car Control CAN Bus** [Simulator.Sensors.CanBusSensor] [Simulator.Sensors.WheelControlSensor] GearUsed: MaxSteer: 0 (user input) 11.743 m/s MaxAccel: 0 (user input) MaxSpeed: MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxBrake: 0 (user input) MaxSteering: GPS [Simulator.Sensors.GpsSensor] **GPS INS Status** [Simulator.Sensors.GpsInsSensor]

Start Latitude: 37.788° Status: 3 misc 56 misc Start Position Type: -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps 37.792° Latitude: Longitude: -122.401° 10.558 m Altitude: 4,182,918.953 m East Northing: 552,752.225 m North Easting: open Google Maps Map Url:

[Simulator.Sensors.ClockSensor]

RealtimeDurati MaxBrake: 0 (user input) 120.056 seconds on: 3D Ground Truth [Simulator.Sensors.PerceptionSensor3D] **Apollo Car Control** [Simulator.Sensors.ApolloControlSensor] MaxTracked: MaxSteer: 0.169 (user input) 20 counts MaxAccel: 1 (user input) MaxBrake: 0 (user input) IsControlReceiv true misc ed:

**Keyboard Car Control** 

MaxSteer:

MaxAccel:

0 (user input)

0 (user input)

[Simulator.Sensors.KeyboardControlSensor]

**GPS Odometry** [Simulator.Sensors.GpsOdometrySensor] Start Latitude: 37.788° Start -122.4° Longitude: 0.352 m Start Altitude: Start Northing: 4,182,486.02 m East Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: Longitude: -122.401° 10.558 m Altitude: Northing: 4,182,918.953 m East Easting: 552,752.225 m North open Google Maps Map Url:

## Callbacks

**Clock Sensor** 

tion:

SimulationDura

120 seconds