

Q1 c)

<< Notation`

Symbolize[ $\mathbf{x}_{t+\Delta t}$ ]

Symbolize[ $\dot{\mathbf{x}}_{t+\Delta t}$ ]

Symbolize[ $\ddot{\mathbf{x}}_{t+\Delta t}$ ]

Symbolize[ $\mathbf{x}_{t+\gamma\Delta t}$ ]

Symbolize[ $\dot{\mathbf{x}}_{t+\gamma\Delta t}$ ]

Symbolize[ $\ddot{\mathbf{x}}_{t+\gamma\Delta t}$ ]

Symbolize[ $\mathbf{x}_t$ ]

Symbolize[ $\dot{\mathbf{x}}_t$ ]

Symbolize[ $\ddot{\mathbf{x}}_t$ ]

Symbolize[ $\mathbf{r}_{t+\Delta t}$ ]

Symbolize[ $\mathbf{r}_{t+\gamma\Delta t}$ ]

Symbolize[ $\Omega_o$ ]

Symbolize[ $\overline{\Omega_d}$ ]

Symbolize[ $\overline{\xi}$ ]

Symbolize[ $\beta_1$ ]

Symbolize[ $\beta_2$ ]

Symbolize[ $\mathbf{X}_t$ ]

ClearAll["Global`\*"]

(\*

Writing in the modal form

\*)

$\xi = 0;$

Solve[

$$\ddot{x}_{t+\gamma\Delta t} + 2\xi\omega\dot{x}_{t+\gamma\Delta t} + \omega^2 x_{t+\gamma\Delta t} == r_{t+\gamma\Delta t} \&\&$$

$$x_{t+\gamma\Delta t} == x_t + \frac{\gamma\Delta t}{2} (\dot{x}_t + \dot{x}_{t+\gamma\Delta t}) \&\&$$

$$\dot{x}_{t+\gamma\Delta t} == \dot{x}_t + \frac{\gamma\Delta t}{2} (\ddot{x}_t + \ddot{x}_{t+\gamma\Delta t}),$$

$$\{\ddot{x}_{t+\gamma\Delta t}, \dot{x}_{t+\gamma\Delta t}, x_{t+\gamma\Delta t}\}]$$

$$\left\{ \left\{ \begin{aligned} x_{t+\gamma\Delta t} &\rightarrow -\left(\left(-4r_{t+\gamma\Delta t} + 4x_t\omega^2 + 4\dot{x}_t\gamma\Delta t\omega^2 + x_t\gamma^2\Delta t^2\omega^2\right) / \left(4 + \gamma^2\Delta t^2\omega^2\right)\right), \\ \dot{x}_{t+\gamma\Delta t} &\rightarrow -\left(\left(-4\dot{x}_t - 2r_{t+\gamma\Delta t}\gamma\Delta t - 2x_t\gamma\Delta t + 2x_t\gamma\Delta t\omega^2 + \dot{x}_t\gamma^2\Delta t^2\omega^2\right) / \left(4 + \gamma^2\Delta t^2\omega^2\right)\right), \\ x_{t+\gamma\Delta t} &\rightarrow -\left(\left(-4x_t - 4\dot{x}_t\gamma\Delta t - r_{t+\gamma\Delta t}\gamma^2\Delta t^2 - x_t\gamma^2\Delta t^2\right) / \left(4 + \gamma^2\Delta t^2\omega^2\right)\right) \end{aligned} \right\} \right\}$$

ClearAll["Global`\*"]

$$\begin{aligned} \ddot{x}_{t+\gamma\Delta t} = & -\left(\left(-4r_{t+\gamma\Delta t} + 4x_t\omega^2 + 4\dot{x}_t\gamma\Delta t\omega^2 + x_t\gamma^2\Delta t^2\omega^2\right) / \left(4 + \gamma^2\Delta t^2\omega^2\right)\right) \\ & -\left(\left(-4r_{t+\gamma\Delta t} + 4x_t\omega^2 + 4\dot{x}_t\gamma\Delta t\omega^2 + x_t\gamma^2\Delta t^2\omega^2\right) / \left(4 + \gamma^2\Delta t^2\omega^2\right)\right) \end{aligned}$$

$$\begin{aligned} \dot{x}_{t+\gamma\Delta t} = & -\left(\left(-4\dot{x}_t - 2r_{t+\gamma\Delta t}\gamma\Delta t - 2x_t\gamma\Delta t + 2x_t\gamma\Delta t\omega^2 + \dot{x}_t\gamma^2\Delta t^2\omega^2\right) / \left(4 + \gamma^2\Delta t^2\omega^2\right)\right) \\ & -\left(\left(-4\dot{x}_t - 2r_{t+\gamma\Delta t}\gamma\Delta t - 2x_t\gamma\Delta t + 2x_t\gamma\Delta t\omega^2 + \dot{x}_t\gamma^2\Delta t^2\omega^2\right) / \left(4 + \gamma^2\Delta t^2\omega^2\right)\right) \end{aligned}$$

$$\begin{aligned} x_{t+\gamma\Delta t} = & -\frac{-4x_t - 4\dot{x}_t\gamma\Delta t - r_{t+\gamma\Delta t}\gamma^2\Delta t^2 - x_t\gamma^2\Delta t^2}{4 + \gamma^2\Delta t^2\omega^2} \\ & -\frac{-4x_t - 4\dot{x}_t\gamma\Delta t - r_{t+\gamma\Delta t}\gamma^2\Delta t^2 - x_t\gamma^2\Delta t^2}{4 + \gamma^2\Delta t^2\omega^2} \end{aligned}$$

Solve[  $\ddot{\mathbf{x}}_{t+\Delta t} + 2 \xi \omega \dot{\mathbf{x}}_{t+\Delta t} + \omega^2 \mathbf{x}_{t+\Delta t} == \mathbf{r}_{t+\Delta t}$  &&

$\mathbf{x}_{t+\Delta t} == \mathbf{x}_t + \gamma \Delta t \left( (1 - \beta_1) \dot{\mathbf{x}}_t + \beta_1 \dot{\mathbf{x}}_{t+\gamma \Delta t} \right) + (1 - \gamma) \Delta t \left( (1 - \beta_2) \ddot{\mathbf{x}}_{t+\gamma \Delta t} + \beta_2 \ddot{\mathbf{x}}_{t+\Delta t} \right)$  &&

$\dot{\mathbf{x}}_{t+\Delta t} == \dot{\mathbf{x}}_t + \gamma \Delta t \left( (1 - \beta_1) \ddot{\mathbf{x}}_t + \beta_1 \ddot{\mathbf{x}}_{t+\gamma \Delta t} \right) + (1 - \gamma) \Delta t \left( (1 - \beta_2) \ddot{\mathbf{x}}_{t+\gamma \Delta t} + \beta_2 \ddot{\mathbf{x}}_{t+\Delta t} \right),$

$\{\ddot{\mathbf{x}}_{t+\Delta t}, \dot{\mathbf{x}}_{t+\Delta t}, \mathbf{x}_{t+\Delta t}\}$  ]

{ {  $\mathbf{x}_{t+\Delta t} \rightarrow$

$$- \frac{1}{-1 - \beta_2^2 (1 - \gamma)^2 \Delta t^2 \omega^2} \left( \mathbf{r}_{t+\Delta t} + \beta_2 (1 - \gamma) \Delta t \omega^2 \left( -\dot{\mathbf{x}}_t + \left( (1 - \beta_2) (1 - \gamma) \Delta t \left( -4 \mathbf{r}_{t+\gamma \Delta t} + 4 \mathbf{x}_t \right. \right. \right. \right. \\ \left. \left. \left. \omega^2 + 4 \dot{\mathbf{x}}_t \gamma \Delta t \omega^2 + \mathbf{x}_t \gamma^2 \Delta t^2 \omega^2 \right) \right) / \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) - \gamma \Delta t \left( \mathbf{x}_t (1 - \beta_1) - \right. \right. \\ \left. \left. \left( \beta_1 \left( -4 \mathbf{r}_{t+\gamma \Delta t} + 4 \mathbf{x}_t \omega^2 + 4 \dot{\mathbf{x}}_t \gamma \Delta t \omega^2 + \mathbf{x}_t \gamma^2 \Delta t^2 \omega^2 \right) \right) / \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) \right) \right) + \\ \omega^2 \left( -\mathbf{x}_t + \left( (1 - \beta_2) (1 - \gamma) \Delta t \left( -4 \dot{\mathbf{x}}_t - 2 \mathbf{r}_{t+\gamma \Delta t} \gamma \Delta t - 2 \mathbf{x}_t \gamma \Delta t + 2 \mathbf{x}_t \gamma \Delta t \omega^2 + \dot{\mathbf{x}}_t \right. \right. \right. \right. \\ \left. \left. \left. \gamma^2 \Delta t^2 \omega^2 \right) \right) / \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) - \gamma \Delta t \left( \mathbf{x}_t (1 - \beta_1) - \left( \beta_1 \left( -4 \dot{\mathbf{x}}_t - 2 \mathbf{r}_{t+\gamma \Delta t} \gamma \Delta t - \right. \right. \right. \right. \\ \left. \left. \left. 2 \mathbf{x}_t \gamma \Delta t + 2 \mathbf{x}_t \gamma \Delta t \omega^2 + \dot{\mathbf{x}}_t \gamma^2 \Delta t^2 \omega^2 \right) \right) / \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) \right) \right) \right),$$

$$\ddot{\mathbf{x}}_{t+\Delta t} \rightarrow - \left( \left( -4 \dot{\mathbf{x}}_t - 4 \mathbf{r}_{t+\gamma \Delta t} \Delta t + 4 \mathbf{r}_{t+\gamma \Delta t} \beta_2 \Delta t - 4 \mathbf{r}_{t+\Delta t} \beta_2 \Delta t + 4 \mathbf{r}_{t+\gamma \Delta t} \gamma \Delta t - \right. \right. \\ 4 \mathbf{x}_t \gamma \Delta t - 4 \mathbf{r}_{t+\gamma \Delta t} \beta_1 \gamma \Delta t + 4 \mathbf{x}_t \beta_1 \gamma \Delta t - 4 \mathbf{r}_{t+\gamma \Delta t} \beta_2 \gamma \Delta t + 4 \mathbf{r}_{t+\Delta t} \beta_2 \gamma \Delta t + \\ 4 \mathbf{x}_t \Delta t \omega^2 - 4 \mathbf{x}_t \gamma \Delta t \omega^2 + 4 \mathbf{x}_t \beta_1 \gamma \Delta t \omega^2 + 4 \dot{\mathbf{x}}_t \beta_2 \Delta t^2 \omega^2 - 4 \dot{\mathbf{x}}_t \beta_2^2 \Delta t^2 \omega^2 + \\ 4 \dot{\mathbf{x}}_t \gamma \Delta t^2 \omega^2 - 8 \dot{\mathbf{x}}_t \beta_2 \gamma \Delta t^2 \omega^2 + 8 \dot{\mathbf{x}}_t \beta_2^2 \gamma \Delta t^2 \omega^2 - 5 \dot{\mathbf{x}}_t \gamma^2 \Delta t^2 \omega^2 + \\ 4 \dot{\mathbf{x}}_t \beta_1 \gamma^2 \Delta t^2 \omega^2 + 4 \dot{\mathbf{x}}_t \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 \dot{\mathbf{x}}_t \beta_2^2 \gamma^2 \Delta t^2 \omega^2 + 2 \mathbf{r}_{t+\gamma \Delta t} \beta_2 \gamma \Delta t^3 \omega^2 + \\ 2 \mathbf{x}_t \beta_2 \gamma \Delta t^3 \omega^2 - 2 \mathbf{r}_{t+\gamma \Delta t} \beta_2^2 \gamma \Delta t^3 \omega^2 - 2 \mathbf{x}_t \beta_2^2 \gamma \Delta t^3 \omega^2 + \mathbf{x}_t \gamma^2 \Delta t^3 \omega^2 - \\ 4 \mathbf{r}_{t+\gamma \Delta t} \beta_2 \gamma^2 \Delta t^3 \omega^2 - \mathbf{r}_{t+\Delta t} \beta_2 \gamma^2 \Delta t^3 \omega^2 - 5 \mathbf{x}_t \beta_2 \gamma^2 \Delta t^3 \omega^2 + \\ 2 \mathbf{r}_{t+\gamma \Delta t} \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^2 + 2 \mathbf{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^2 + 4 \mathbf{r}_{t+\gamma \Delta t} \beta_2^2 \gamma^2 \Delta t^3 \omega^2 + \\ 4 \mathbf{x}_t \beta_2^2 \gamma^2 \Delta t^3 \omega^2 - 2 \mathbf{x}_t \gamma^3 \Delta t^3 \omega^2 + 2 \mathbf{x}_t \beta_1 \gamma^3 \Delta t^3 \omega^2 + 2 \mathbf{r}_{t+\gamma \Delta t} \beta_2 \gamma^3 \Delta t^3 \omega^2 + \\ \mathbf{r}_{t+\Delta t} \beta_2 \gamma^3 \Delta t^3 \omega^2 + 3 \mathbf{x}_t \beta_2 \gamma^3 \Delta t^3 \omega^2 - 2 \mathbf{r}_{t+\gamma \Delta t} \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^2 - \\ 2 \mathbf{x}_t \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^2 - 2 \mathbf{r}_{t+\gamma \Delta t} \beta_2^2 \gamma^3 \Delta t^3 \omega^2 - 2 \mathbf{x}_t \beta_2^2 \gamma^3 \Delta t^3 \omega^2 - \\ 2 \mathbf{x}_t \beta_2 \gamma \Delta t^3 \omega^4 + 2 \mathbf{x}_t \beta_2^2 \gamma \Delta t^3 \omega^4 + 5 \mathbf{x}_t \beta_2 \gamma^2 \Delta t^3 \omega^4 - 2 \mathbf{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^4 - \\ 4 \mathbf{x}_t \beta_2^2 \gamma^2 \Delta t^3 \omega^4 - 3 \mathbf{x}_t \beta_2 \gamma^3 \Delta t^3 \omega^4 + 2 \mathbf{x}_t \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^4 + 2 \mathbf{x}_t \beta_2^2 \gamma^3 \Delta t^3 \omega^4 - \\ \dot{\mathbf{x}}_t \beta_2 \gamma^2 \Delta t^4 \omega^4 + \dot{\mathbf{x}}_t \beta_2^2 \gamma^2 \Delta t^4 \omega^4 + 3 \dot{\mathbf{x}}_t \beta_2 \gamma^3 \Delta t^4 \omega^4 - 2 \dot{\mathbf{x}}_t \beta_1 \beta_2 \gamma^3 \Delta t^4 \omega^4 - \\ 2 \dot{\mathbf{x}}_t \beta_2^2 \gamma^3 \Delta t^4 \omega^4 - 2 \dot{\mathbf{x}}_t \beta_2 \gamma^4 \Delta t^4 \omega^4 + 2 \dot{\mathbf{x}}_t \beta_1 \beta_2 \gamma^4 \Delta t^4 \omega^4 + \dot{\mathbf{x}}_t \beta_2^2 \gamma^4 \Delta t^4 \omega^4 \left. \right) / \\ \left( \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) \left( 1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \right) \right) \right),$$

$$\mathbf{x}_{t+\Delta t} \rightarrow - \left( \left( -4 \mathbf{x}_t - 4 \dot{\mathbf{x}}_t \Delta t - 4 \mathbf{r}_{t+\gamma \Delta t} \beta_2 \Delta t^2 + 4 \mathbf{r}_{t+\gamma \Delta t} \beta_2^2 \Delta t^2 - 4 \mathbf{r}_{t+\Delta t} \beta_2^2 \Delta t^2 - \right. \right. \\ 2 \mathbf{r}_{t+\gamma \Delta t} \gamma \Delta t^2 - 2 \mathbf{x}_t \gamma \Delta t^2 + 10 \mathbf{r}_{t+\gamma \Delta t} \beta_2 \gamma \Delta t^2 - 2 \mathbf{x}_t \beta_2 \gamma \Delta t^2 - 4 \mathbf{r}_{t+\gamma \Delta t} \beta_1 \beta_2 \gamma \Delta t^2 + \\ 4 \mathbf{x}_t \beta_1 \beta_2 \gamma \Delta t^2 - 8 \mathbf{r}_{t+\gamma \Delta t} \beta_2^2 \gamma \Delta t^2 + 8 \mathbf{r}_{t+\Delta t} \beta_2^2 \gamma \Delta t^2 + 2 \mathbf{r}_{t+\gamma \Delta t} \gamma^2 \Delta t^2 + 2 \mathbf{x}_t \gamma^2 \Delta t^2 - \\ 2 \mathbf{r}_{t+\gamma \Delta t} \beta_1 \gamma^2 \Delta t^2 - 2 \mathbf{x}_t \beta_1 \gamma^2 \Delta t^2 - 6 \mathbf{r}_{t+\gamma \Delta t} \beta_2 \gamma^2 \Delta t^2 + 2 \mathbf{x}_t \beta_2 \gamma^2 \Delta t^2 + \\ 4 \mathbf{r}_{t+\gamma \Delta t} \beta_1 \beta_2 \gamma^2 \Delta t^2 - 4 \mathbf{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^2 + 4 \mathbf{r}_{t+\gamma \Delta t} \beta_2^2 \gamma^2 \Delta t^2 - 4 \mathbf{r}_{t+\Delta t} \beta_2^2 \gamma^2 \Delta t^2 + \\ 4 \mathbf{x}_t \beta_2 \Delta t^2 \omega^2 - 4 \mathbf{x}_t \beta_2^2 \Delta t^2 \omega^2 + 2 \mathbf{x}_t \gamma \Delta t^2 \omega^2 - 10 \mathbf{x}_t \beta_2 \gamma \Delta t^2 \omega^2 + 4 \mathbf{x}_t \beta_1 \beta_2 \gamma \Delta t^2 \omega^2 + \\ 8 \mathbf{x}_t \beta_2^2 \gamma \Delta t^2 \omega^2 - 3 \mathbf{x}_t \gamma^2 \Delta t^2 \omega^2 + 2 \mathbf{x}_t \beta_1 \gamma^2 \Delta t^2 \omega^2 + 6 \mathbf{x}_t \beta_2 \gamma^2 \Delta t^2 \omega^2 - \\ 4 \mathbf{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 \mathbf{x}_t \beta_2^2 \gamma^2 \Delta t^2 \omega^2 + 4 \dot{\mathbf{x}}_t \beta_2 \gamma \Delta t^3 \omega^2 - 4 \dot{\mathbf{x}}_t \beta_2^2 \gamma \Delta t^3 \omega^2 + \\ \dot{\mathbf{x}}_t \gamma^2 \Delta t^3 \omega^2 - 10 \dot{\mathbf{x}}_t \beta_2 \gamma^2 \Delta t^3 \omega^2 + 4 \dot{\mathbf{x}}_t \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^2 + 8 \dot{\mathbf{x}}_t \beta_2^2 \gamma^2 \Delta t^3 \omega^2 - \\ 2 \dot{\mathbf{x}}_t \gamma^3 \Delta t^3 \omega^2 + 2 \dot{\mathbf{x}}_t \beta_1 \gamma^3 \Delta t^3 \omega^2 + 6 \dot{\mathbf{x}}_t \beta_2 \gamma^3 \Delta t^3 \omega^2 - 4 \dot{\mathbf{x}}_t \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^2 - \\ 4 \dot{\mathbf{x}}_t \beta_2^2 \gamma^3 \Delta t^3 \omega^2 + \mathbf{x}_t \beta_2 \gamma^2 \Delta t^4 \omega^2 - \mathbf{r}_{t+\Delta t} \beta_2^2 \gamma^2 \Delta t^4 \omega^2 - \mathbf{x}_t \beta_2^2 \gamma^2 \Delta t^4 \omega^2 - \\ 3 \mathbf{x}_t \beta_2 \gamma^3 \Delta t^4 \omega^2 + 2 \mathbf{x}_t \beta_1 \beta_2 \gamma^3 \Delta t^4 \omega^2 + 2 \mathbf{r}_{t+\Delta t} \beta_2^2 \gamma^3 \Delta t^4 \omega^2 + 2 \mathbf{x}_t \beta_2^2 \gamma^3 \Delta t^4 \omega^2 + \\ 2 \mathbf{x}_t \beta_2 \gamma^4 \Delta t^4 \omega^2 - 2 \mathbf{x}_t \beta_1 \beta_2 \gamma^4 \Delta t^4 \omega^2 - \mathbf{r}_{t+\Delta t} \beta_2^2 \gamma^4 \Delta t^4 \omega^2 - \mathbf{x}_t \beta_2^2 \gamma^4 \Delta t^4 \omega^2 \left. \right) / \\ \left( \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) \left( 1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \right) \right) \right) \} \}$$

recursive =

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{
  Collect[ $\ddot{x}_{t+\Delta t} -$ 
     $\left( -\frac{1}{-1 - \beta_2^2 (1 - \gamma)^2 \Delta t^2 \omega^2} \left( r_{t+\Delta t} + \beta_2 (1 - \gamma) \Delta t \omega^2 (-\dot{x}_t + ((1 - \beta_2) (1 - \gamma) \Delta t (-4 r_{t+\gamma \Delta t} + \right.\right.$ 
       $4 x_t \omega^2 + 4 \dot{x}_t \gamma \Delta t \omega^2 + \ddot{x}_t \gamma^2 \Delta t^2 \omega^2)) / (4 + \gamma^2 \Delta t^2 \omega^2) - \gamma \Delta t (\dot{x}_t (1 - \beta_1) -$ 
       $(\beta_1 (-4 r_{t+\gamma \Delta t} + 4 x_t \omega^2 + 4 \dot{x}_t \gamma \Delta t \omega^2 + \ddot{x}_t \gamma^2 \Delta t^2 \omega^2)) / (4 + \gamma^2 \Delta t^2 \omega^2)) +$ 
       $\omega^2 (-x_t + ((1 - \beta_2) (1 - \gamma) \Delta t (-4 \dot{x}_t - 2 r_{t+\gamma \Delta t} \gamma \Delta t - 2 \ddot{x}_t \gamma \Delta t +$ 
       $2 x_t \gamma \Delta t \omega^2 + \ddot{x}_t \gamma^2 \Delta t^2 \omega^2)) / (4 + \gamma^2 \Delta t^2 \omega^2) -$ 
       $\gamma \Delta t (\dot{x}_t (1 - \beta_1) - (\beta_1 (-4 \dot{x}_t - 2 r_{t+\gamma \Delta t} \gamma \Delta t - 2 \ddot{x}_t \gamma \Delta t + 2 x_t \gamma \Delta t \omega^2 +$ 
       $\ddot{x}_t \gamma^2 \Delta t^2 \omega^2)) / (4 + \gamma^2 \Delta t^2 \omega^2))) \right), \{ \ddot{x}_t, \dot{x}_t, x_t, r_{t+\Delta t}, r_{t+\gamma \Delta t} \}],$ 
    Collect[ $\ddot{x}_{t+\Delta t} - (-(( -4 \dot{x}_t - 4 r_{t+\gamma \Delta t} \Delta t + 4 r_{t+\gamma \Delta t} \beta_2 \Delta t - 4 r_{t+\Delta t} \beta_2 \Delta t + 4 r_{t+\gamma \Delta t} \gamma \Delta t -$ 
       $4 \ddot{x}_t \gamma \Delta t - 4 r_{t+\gamma \Delta t} \beta_1 \gamma \Delta t + 4 \ddot{x}_t \beta_1 \gamma \Delta t - 4 r_{t+\gamma \Delta t} \beta_2 \gamma \Delta t + 4 r_{t+\Delta t} \beta_2 \gamma \Delta t +$ 
       $4 x_t \Delta t \omega^2 - 4 x_t \gamma \Delta t \omega^2 + 4 x_t \beta_1 \gamma \Delta t \omega^2 + 4 \dot{x}_t \beta_2 \Delta t^2 \omega^2 - 4 \ddot{x}_t \beta_2^2 \Delta t^2 \omega^2 +$ 
       $4 \dot{x}_t \gamma \Delta t^2 \omega^2 - 8 \dot{x}_t \beta_2 \gamma \Delta t^2 \omega^2 + 8 \dot{x}_t \beta_2^2 \gamma \Delta t^2 \omega^2 - 5 \dot{x}_t \gamma^2 \Delta t^2 \omega^2 + 4 \dot{x}_t \beta_1 \gamma^2 \Delta t^2 \omega^2 +$ 
       $4 \dot{x}_t \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 \dot{x}_t \beta_2^2 \gamma^2 \Delta t^2 \omega^2 + 2 r_{t+\gamma \Delta t} \beta_2 \gamma \Delta t^3 \omega^2 + 2 \ddot{x}_t \beta_2 \gamma \Delta t^3 \omega^2 -$ 
       $2 r_{t+\gamma \Delta t} \beta_2^2 \gamma \Delta t^3 \omega^2 - 2 \ddot{x}_t \beta_2^2 \gamma \Delta t^3 \omega^2 + \ddot{x}_t \gamma^2 \Delta t^3 \omega^2 - 4 r_{t+\gamma \Delta t} \beta_2 \gamma^2 \Delta t^3 \omega^2 -$ 
       $r_{t+\Delta t} \beta_2 \gamma^2 \Delta t^3 \omega^2 - 5 \ddot{x}_t \beta_2 \gamma^2 \Delta t^3 \omega^2 + 2 r_{t+\gamma \Delta t} \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^2 + 2 \ddot{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^2 +$ 
       $4 r_{t+\gamma \Delta t} \beta_2^2 \gamma^2 \Delta t^3 \omega^2 + 4 \ddot{x}_t \beta_2^2 \gamma^2 \Delta t^3 \omega^2 - 2 \ddot{x}_t \gamma^3 \Delta t^3 \omega^2 + 2 \ddot{x}_t \beta_1 \gamma^3 \Delta t^3 \omega^2 +$ 
       $2 r_{t+\gamma \Delta t} \beta_2 \gamma^3 \Delta t^3 \omega^2 + r_{t+\Delta t} \beta_2 \gamma^3 \Delta t^3 \omega^2 + 3 \ddot{x}_t \beta_2 \gamma^3 \Delta t^3 \omega^2 - 2 r_{t+\gamma \Delta t} \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^2 -$ 
       $2 \ddot{x}_t \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^2 - 2 r_{t+\gamma \Delta t} \beta_2^2 \gamma^3 \Delta t^3 \omega^2 - 2 \ddot{x}_t \beta_2^2 \gamma^3 \Delta t^3 \omega^2 -$ 
       $2 x_t \beta_2 \gamma \Delta t^3 \omega^4 + 2 x_t \beta_2^2 \gamma \Delta t^3 \omega^4 + 5 x_t \beta_2 \gamma^2 \Delta t^3 \omega^4 - 2 x_t \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^4 -$ 
       $4 x_t \beta_2^2 \gamma^2 \Delta t^3 \omega^4 - 3 x_t \beta_2 \gamma^3 \Delta t^3 \omega^4 + 2 x_t \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^4 + 2 x_t \beta_2^2 \gamma^3 \Delta t^3 \omega^4 -$ 
       $\dot{x}_t \beta_2 \gamma^2 \Delta t^4 \omega^4 + \dot{x}_t \beta_2^2 \gamma^2 \Delta t^4 \omega^4 + 3 \dot{x}_t \beta_2 \gamma^3 \Delta t^4 \omega^4 - 2 \ddot{x}_t \beta_1 \beta_2 \gamma^3 \Delta t^4 \omega^4 -$ 
       $2 \ddot{x}_t \beta_2^2 \gamma^3 \Delta t^4 \omega^4 - 2 \ddot{x}_t \beta_2 \gamma^4 \Delta t^4 \omega^4 + 2 \ddot{x}_t \beta_1 \beta_2 \gamma^4 \Delta t^4 \omega^4 + \ddot{x}_t \beta_2^2 \gamma^4 \Delta t^4 \omega^4) /$ 
       $((4 + \gamma^2 \Delta t^2 \omega^2) (1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2))) \right),$ 
      { $\ddot{x}_t, \dot{x}_t, x_t, r_{t+\Delta t}, r_{t+\gamma \Delta t}$ }],
    Collect[ $x_{t+\Delta t} - (-(( -4 x_t - 4 \dot{x}_t \Delta t - 4 r_{t+\gamma \Delta t} \beta_2 \Delta t^2 + 4 r_{t+\gamma \Delta t} \beta_2^2 \Delta t^2 - 4 r_{t+\Delta t} \beta_2^2 \Delta t^2 -$ 
       $2 r_{t+\gamma \Delta t} \gamma \Delta t^2 - 2 \ddot{x}_t \gamma \Delta t^2 + 10 r_{t+\gamma \Delta t} \beta_2 \gamma \Delta t^2 - 2 \ddot{x}_t \beta_2 \gamma \Delta t^2 - 4 r_{t+\gamma \Delta t} \beta_1 \beta_2 \gamma \Delta t^2 +$ 
       $4 \ddot{x}_t \beta_1 \beta_2 \gamma \Delta t^2 - 8 r_{t+\gamma \Delta t} \beta_2^2 \gamma \Delta t^2 + 8 r_{t+\Delta t} \beta_2^2 \gamma \Delta t^2 + 2 r_{t+\gamma \Delta t} \gamma^2 \Delta t^2 + 2 \ddot{x}_t \gamma^2 \Delta t^2 -$ 
       $2 r_{t+\gamma \Delta t} \beta_1 \gamma^2 \Delta t^2 - 2 \ddot{x}_t \beta_1 \gamma^2 \Delta t^2 - 6 r_{t+\gamma \Delta t} \beta_2 \gamma^2 \Delta t^2 + 2 \ddot{x}_t \beta_2 \gamma^2 \Delta t^2 +$ 
       $4 r_{t+\gamma \Delta t} \beta_1 \beta_2 \gamma^2 \Delta t^2 - 4 \ddot{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^2 + 4 r_{t+\gamma \Delta t} \beta_2^2 \gamma^2 \Delta t^2 - 4 r_{t+\Delta t} \beta_2^2 \gamma^2 \Delta t^2 +$ 
       $4 x_t \beta_2 \Delta t^2 \omega^2 - 4 x_t \beta_2^2 \Delta t^2 \omega^2 + 2 x_t \gamma \Delta t^2 \omega^2 - 10 x_t \beta_2 \gamma \Delta t^2 \omega^2 + 4 x_t \beta_1 \beta_2 \gamma \Delta t^2 \omega^2 +$ 
       $8 x_t \beta_2^2 \gamma \Delta t^2 \omega^2 - 3 x_t \gamma^2 \Delta t^2 \omega^2 + 2 x_t \beta_1 \gamma^2 \Delta t^2 \omega^2 + 6 x_t \beta_2 \gamma^2 \Delta t^2 \omega^2 -$ 
       $4 x_t \beta_1 \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 x_t \beta_2^2 \gamma^2 \Delta t^2 \omega^2 + 4 \dot{x}_t \beta_2 \gamma \Delta t^3 \omega^2 - 4 \ddot{x}_t \beta_2^2 \gamma \Delta t^3 \omega^2 +$ 
       $\dot{x}_t \gamma^2 \Delta t^3 \omega^2 - 10 \dot{x}_t \beta_2 \gamma^2 \Delta t^3 \omega^2 + 4 \dot{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^2 + 8 \dot{x}_t \beta_2^2 \gamma^2 \Delta t^3 \omega^2 -$ 
       $2 \ddot{x}_t \gamma^3 \Delta t^3 \omega^2 + 2 \ddot{x}_t \beta_1 \gamma^3 \Delta t^3 \omega^2 + 6 \ddot{x}_t \beta_2 \gamma^3 \Delta t^3 \omega^2 - 4 \ddot{x}_t \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^2 -$ 
       $4 \ddot{x}_t \beta_2^2 \gamma^3 \Delta t^3 \omega^2 + \ddot{x}_t \beta_2 \gamma^2 \Delta t^4 \omega^2 - r_{t+\Delta t} \beta_2^2 \gamma^2 \Delta t^4 \omega^2 - \ddot{x}_t \beta_2^2 \gamma^2 \Delta t^4 \omega^2 -$ 
       $3 \ddot{x}_t \beta_2 \gamma^3 \Delta t^4 \omega^2 + 2 \ddot{x}_t \beta_1 \beta_2 \gamma^3 \Delta t^4 \omega^2 + 2 r_{t+\Delta t} \beta_2^2 \gamma^3 \Delta t^4 \omega^2 + 2 \ddot{x}_t \beta_2^2 \gamma^3 \Delta t^4 \omega^2 +$ 
       $2 \ddot{x}_t \beta_2 \gamma^4 \Delta t^4 \omega^2 - 2 \ddot{x}_t \beta_1 \beta_2 \gamma^4 \Delta t^4 \omega^2 - r_{t+\Delta t} \beta_2^2 \gamma^4 \Delta t^4 \omega^2 - \ddot{x}_t \beta_2^2 \gamma^4 \Delta t^4 \omega^2) /$ 
       $((4 + \gamma^2 \Delta t^2 \omega^2) (1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2))) \right),$ 
      { $\ddot{x}_t, \dot{x}_t, x_t, r_{t+\gamma \Delta t}, r_{t+\Delta t}$ }],
    (* /. { $-1 - \beta_2^2 (1 - \gamma)^2 \Delta t^2 \omega^2 \rightarrow \eta_1$ ,  $4 + \gamma^2 \Delta t^2 \omega^2 \rightarrow \eta_2$ ,
       $1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \rightarrow \eta_3$ } *)
  }

```

[illegible]



[illegible]

$$\begin{aligned} & \left( \beta_2^2 \gamma^2 \Delta t^4 \omega^2 \right) / \left( \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) \left( 1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \right) \right) - \\ & \left( 3 \beta_2 \gamma^3 \Delta t^4 \omega^2 \right) / \left( \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) \left( 1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \right) \right) + \\ & \left( 2 \beta_1 \beta_2 \gamma^3 \Delta t^4 \omega^2 \right) / \left( \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) \left( 1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \right) \right) + \\ & \left( 2 \beta_2^2 \gamma^3 \Delta t^4 \omega^2 \right) / \left( \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) \left( 1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \right) \right) + \\ & \left( 2 \beta_2 \gamma^4 \Delta t^4 \omega^2 \right) / \left( \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) \left( 1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \right) \right) - \\ & \left( 2 \beta_1 \beta_2 \gamma^4 \Delta t^4 \omega^2 \right) / \left( \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) \left( 1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \right) \right) - \\ & \left( \beta_2^2 \gamma^4 \Delta t^4 \omega^2 \right) / \left( \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) \left( 1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \right) \right) \} \end{aligned}$$

**a =**

$$- \begin{pmatrix} \text{Coefficient}[\text{Part}[\text{recursive}, 1], \dot{\mathbf{x}}_t] & \text{Coefficient}[\text{Part}[\text{recursive}, 1], \dot{\mathbf{x}}_t] & \text{Coeff} \\ \text{Coefficient}[\text{Part}[\text{recursive}, 2], \dot{\mathbf{x}}_t] & \text{Coefficient}[\text{Part}[\text{recursive}, 2], \dot{\mathbf{x}}_t] & \text{Coeff} \\ \text{Coefficient}[\text{Part}[\text{recursive}, 3], \dot{\mathbf{x}}_t] & \text{Coefficient}[\text{Part}[\text{recursive}, 3], \dot{\mathbf{x}}_t] & \text{Coeff} \end{pmatrix};$$

**a // MatrixForm // Simplify**

$$\begin{pmatrix} \frac{2(-1-3\beta_1+4\beta_1^2)\Delta t^2\omega^2}{(16+\Delta t^2\omega^2)(1+\beta_1^2\Delta t^2\omega^2)} & \frac{-16\Delta t\omega^2+(3-4\beta_1)\beta_1\Delta t^3\omega^4}{(16+\Delta t^2\omega^2)(1+\beta_1^2\Delta t^2\omega^2)} & \frac{-16\omega^2+(1+6\beta_1-8\beta_1^2)\Delta t^2\omega^4}{(16+\Delta t^2\omega^2)(1+\beta_1^2\Delta t^2\omega^2)} \\ \frac{2\Delta t(4+\beta_1^2\Delta t^2\omega^2-\beta_1(4+\Delta t^2\omega^2))}{(16+\Delta t^2\omega^2)(1+\beta_1^2\Delta t^2\omega^2)} & \frac{16+(-3-12\beta_1+16\beta_1^2)\Delta t^2\omega^2}{(16+\Delta t^2\omega^2)(1+\beta_1^2\Delta t^2\omega^2)} & \frac{\Delta t\omega^2(-8-2\beta_1^2\Delta t^2\omega^2+\beta_1(-8+\Delta t^2\omega^2))}{(16+\Delta t^2\omega^2)(1+\beta_1^2\Delta t^2\omega^2)} \\ \frac{2(1+3\beta_1-4\beta_1^2)\Delta t^2}{(16+\Delta t^2\omega^2)(1+\beta_1^2\Delta t^2\omega^2)} & \frac{\Delta t(16-3\beta_1\Delta t^2\omega^2+4\beta_1^2\Delta t^2\omega^2)}{(16+\Delta t^2\omega^2)(1+\beta_1^2\Delta t^2\omega^2)} & \frac{16+(-1-6\beta_1+8\beta_1^2)\Delta t^2\omega^2}{(16+\Delta t^2\omega^2)(1+\beta_1^2\Delta t^2\omega^2)} \end{pmatrix}$$

**ClearAll["Global`\*"]**

$$\mathbf{1a} = - \begin{pmatrix} \text{Coefficient}[\text{Part}[\text{recursive}, 1], \mathbf{r}_{t+\gamma\Delta t}] \\ \text{Coefficient}[\text{Part}[\text{recursive}, 2], \mathbf{r}_{t+\gamma\Delta t}] \\ \text{Coefficient}[\text{Part}[\text{recursive}, 3], \mathbf{r}_{t+\gamma\Delta t}] \end{pmatrix};$$

**1a // MatrixForm // Simplify**

$$\begin{pmatrix} \frac{2(-1-3\beta_1+4\beta_1^2)\Delta t^2\omega^2}{(16+\Delta t^2\omega^2)(1+\beta_1^2\Delta t^2\omega^2)} \\ \frac{2\Delta t(4+\beta_1^2\Delta t^2\omega^2-\beta_1(4+\Delta t^2\omega^2))}{(16+\Delta t^2\omega^2)(1+\beta_1^2\Delta t^2\omega^2)} \\ \frac{2(1+3\beta_1-4\beta_1^2)\Delta t^2}{(16+\Delta t^2\omega^2)(1+\beta_1^2\Delta t^2\omega^2)} \end{pmatrix}$$

$$\mathbf{1b} = - \begin{pmatrix} \text{Coefficient}[\text{Part}[\text{recursive}, 1], \mathbf{r}_{t+\Delta t}] \\ \text{Coefficient}[\text{Part}[\text{recursive}, 2], \mathbf{r}_{t+\Delta t}] \\ \text{Coefficient}[\text{Part}[\text{recursive}, 3], \mathbf{r}_{t+\Delta t}] \end{pmatrix};$$

**1b // MatrixForm // Simplify**

$$\begin{pmatrix} \frac{1}{1+\beta_1^2\Delta t^2\omega^2} \\ \frac{\beta_1\Delta t}{1+\beta_1^2\Delta t^2\omega^2} \\ \frac{\beta_1^2\Delta t^2}{1+\beta_1^2\Delta t^2\omega^2} \end{pmatrix}$$

**eigA = Eigenvalues[a] /. Δt → p T // Expand // Simplify // Cancel;**

**eigA // MatrixForm**

$$\begin{pmatrix} 0 \\ \frac{4T^4-3p^2\pi^2T^4-12p^2\pi^2T^4\beta_1+16p^2\pi^2T^4\beta_1^2-2\pi\sqrt{-p^2T^8(4-3p^2\pi^2\beta_1+4p^2\pi^2\beta_1^2)^2}}{(4+p^2\pi^2)T^4(1+4p^2\pi^2\beta_1^2)} \\ \frac{4T^4-3p^2\pi^2T^4-12p^2\pi^2T^4\beta_1+16p^2\pi^2T^4\beta_1^2+2\pi\sqrt{-p^2T^8(4-3p^2\pi^2\beta_1+4p^2\pi^2\beta_1^2)^2}}{(4+p^2\pi^2)T^4(1+4p^2\pi^2\beta_1^2)} \end{pmatrix}$$



$$\gamma = \frac{1}{2}; \beta_2 = 2 \beta_1;$$

$$\xi = 0;$$

$$\omega = 2 \text{ Pi} / \text{T};$$

$$\lambda 1 = \text{Part}[\text{eigA}, 2] /. \text{T} \rightarrow 1 // \text{Simplify} // \text{Expand}$$

$$\frac{4}{(4 + p^2 \pi^2) (1 + 4 p^2 \pi^2 \beta_1^2)} - \frac{3 p^2 \pi^2}{(4 + p^2 \pi^2) (1 + 4 p^2 \pi^2 \beta_1^2)} - \frac{12 p^2 \pi^2 \beta_1}{(4 + p^2 \pi^2) (1 + 4 p^2 \pi^2 \beta_1^2)} +$$

$$\frac{16 p^2 \pi^2 \beta_1^2}{(4 + p^2 \pi^2) (1 + 4 p^2 \pi^2 \beta_1^2)} - \frac{2 \pi \sqrt{-p^2 (4 + p^2 \pi^2 \beta_1 (-3 + 4 \beta_1))^2}}{(4 + p^2 \pi^2) (1 + 4 p^2 \pi^2 \beta_1^2)}$$

$$\text{pe} = \frac{\Omega_o}{\bar{\Omega}_d} - 1$$

$$-1 + \frac{\Omega_o}{\bar{\Omega}_d}$$

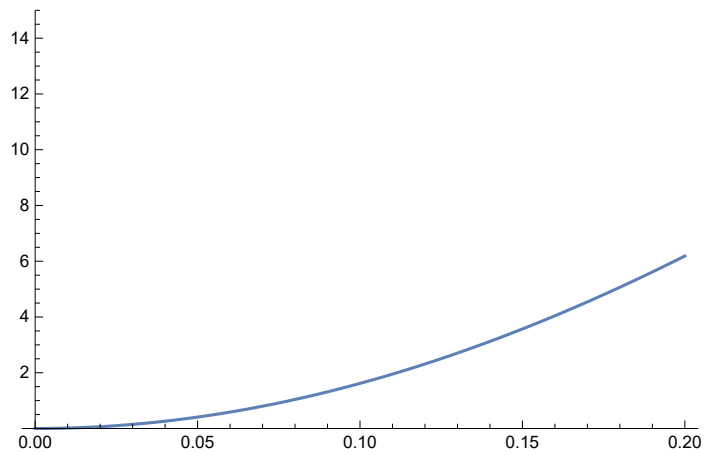
$$\Omega_o = \omega \Delta t /. \frac{\Delta t}{\text{T}} \rightarrow p$$

$$2 p \pi$$

$$\bar{\Omega}_d = \text{ArcTan}\left[\frac{2 \pi \sqrt{p^2 (-36 + 5 p^2 \pi^2)^2}}{36 - 47 p^2 \pi^2}\right] (*\text{simply copy paste this from above}*)$$

$$\text{ArcTan}\left[\frac{2 \pi \sqrt{p^2 (-36 + 5 p^2 \pi^2)^2}}{36 - 47 p^2 \pi^2}\right]$$

$$\text{Plot}[(\text{pe}) * 100, \{p, 0, .2\}, \text{PlotRange} \rightarrow \{0, 20\}]$$



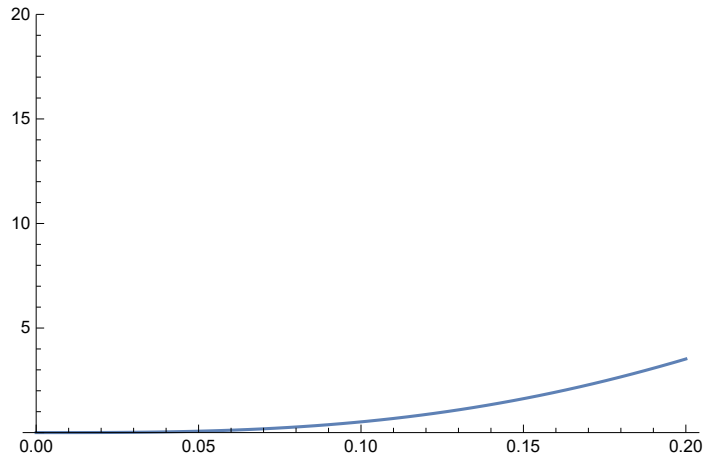
$$\text{AD} = 1 - \text{Exp}\left[-2 \text{ Pi} \bar{\xi} \frac{\Omega_o}{\bar{\Omega}_d}\right]$$

$$1 - \text{Abs}\left[\frac{36 - 47 p^2 \pi^2 - 2 \pi \sqrt{-p^2 (-36 + 5 p^2 \pi^2)^2}}{(4 + p^2 \pi^2) (9 + 4 p^2 \pi^2)}\right] \frac{2 \pi}{\text{ArcTan}\left[\frac{2 \pi \sqrt{p^2 (-36 + 5 p^2 \pi^2)^2}}{36 - 47 p^2 \pi^2}\right]}$$

$$\bar{\xi} = -\frac{1}{\Omega_0} \text{Log}[\text{Abs}[\lambda_1]]$$

$$-\frac{\text{Log}\left[\text{Abs}\left[\frac{36-47 p^2 \pi^2-2 \pi \sqrt{-p^2 (-36+5 p^2 \pi^2)^2}}{(4+p^2 \pi^2) (9+4 p^2 \pi^2)}\right]\right]}{2 p \pi}$$

`Plot[(AD) * 100, {p, 0, .2}, PlotRange -> {0, 20}]`



$$\begin{aligned} \text{aNot} = & -\left( \frac{\text{Coefficient}[\text{Part}[\text{recursive}, 2], \mathbf{x_t}]}{\text{Coefficient}[\text{Part}[\text{recursive}, 3], \mathbf{x_t}]} \frac{\text{Coefficient}[\text{Part}[\text{recursive}, 2], \mathbf{x_t}]}{\text{Coefficient}[\text{Part}[\text{recursive}, 3], \mathbf{x_t}]} \right) \\ & \left\{ \left\{ \frac{144}{\left(9 + \frac{4 \pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4 \pi^2 \Delta t^2}{T^2}\right)} - \frac{188 \pi^2 \Delta t^2}{T^2 \left(9 + \frac{4 \pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4 \pi^2 \Delta t^2}{T^2}\right)}, \right. \right. \\ & - \frac{384 \pi^2 \Delta t}{T^2 \left(9 + \frac{4 \pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4 \pi^2 \Delta t^2}{T^2}\right)} + \frac{16 \pi^4 \Delta t^3}{T^4 \left(9 + \frac{4 \pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4 \pi^2 \Delta t^2}{T^2}\right)} \left. \right\}, \\ & \left\{ \frac{144 \Delta t}{\left(9 + \frac{4 \pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4 \pi^2 \Delta t^2}{T^2}\right)} - \frac{20 \pi^2 \Delta t^3}{T^2 \left(9 + \frac{4 \pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4 \pi^2 \Delta t^2}{T^2}\right)}, \right. \\ & \left. \frac{144}{\left(9 + \frac{4 \pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4 \pi^2 \Delta t^2}{T^2}\right)} - \frac{76 \pi^2 \Delta t^2}{T^2 \left(9 + \frac{4 \pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4 \pi^2 \Delta t^2}{T^2}\right)} \right\} \end{aligned}$$

`eigaNot = Eigenvalues[aNot] /. Δt -> p T // Expand // Simplify // Cancel;`

`ppp = {0, Part[eigaNot, 1], Part[eigaNot, 2]}`

$$\begin{aligned} & \{0, \\ & \left( 36 T^4 - 33 p^2 \pi^2 T^4 - 2 \pi \sqrt{-p^2 (864 - 205 p^2 \pi^2 + 5 p^4 \pi^4) T^8} \right) / \left( (4 + p^2 \pi^2) (9 + 4 p^2 \pi^2) T^4 \right), \\ & \left( 36 T^4 - 33 p^2 \pi^2 T^4 + 2 \pi \sqrt{-p^2 (864 - 205 p^2 \pi^2 + 5 p^4 \pi^4) T^8} \right) / \left( (4 + p^2 \pi^2) (9 + 4 p^2 \pi^2) T^4 \right) \} \end{aligned}$$

`qqq = eiga`

$$\begin{aligned} & \{0, \left( 36 T^4 - 47 p^2 \pi^2 T^4 - 2 \pi \sqrt{-p^2 (-36 + 5 p^2 \pi^2)^2 T^8} \right) / \left( (4 + p^2 \pi^2) (9 + 4 p^2 \pi^2) T^4 \right), \\ & \left( 36 T^4 - 47 p^2 \pi^2 T^4 + 2 \pi \sqrt{-p^2 (-36 + 5 p^2 \pi^2)^2 T^8} \right) / \left( (4 + p^2 \pi^2) (9 + 4 p^2 \pi^2) T^4 \right) \} \end{aligned}$$

**ppp - qqg // Simplify**

$$\left\{ 0, \frac{\left( 2 \pi \left( 7 p^2 \pi T^4 + \sqrt{-p^2 (-36 + 5 p^2 \pi^2)^2 T^8} - \sqrt{-p^2 (864 - 205 p^2 \pi^2 + 5 p^4 \pi^4) T^8} \right) \right)}{\left( (4 + p^2 \pi^2) (9 + 4 p^2 \pi^2) T^4 \right)}, \right. \\ \left. \frac{\left( 2 \pi \left( 7 p^2 \pi T^4 - \sqrt{-p^2 (-36 + 5 p^2 \pi^2)^2 T^8} + \sqrt{-p^2 (864 - 205 p^2 \pi^2 + 5 p^4 \pi^4) T^8} \right) \right)}{\left( (4 + p^2 \pi^2) (9 + 4 p^2 \pi^2) T^4 \right)} \right\}$$