

Q1 a)

<< Notation`

Symbolize[$x_{t+\Delta t}$]

Symbolize::bsymbexs :

Warning: The box structure attempting to be symbolized has a similar or identical symbol already defined, possibly overriding previously symbolized box structure. >>

Symbolize[$\dot{x}_{t+\Delta t}$]

Symbolize[$\ddot{x}_{t+\Delta t}$]

Symbolize[$x_{t+\gamma\Delta t}$]

Symbolize[$\dot{x}_{t+\gamma\Delta t}$]

Symbolize[$\ddot{x}_{t+\gamma\Delta t}$]

Symbolize[x_t]

Symbolize[\dot{x}_t]

Symbolize[\ddot{x}_t]

Symbolize[$r_{t+\Delta t}$]

Symbolize[$r_{t+\gamma\Delta t}$]

Symbolize[Ω_o]

Symbolize[$\overline{\Omega}_d$]

Symbolize[$\overline{\xi}$]

Symbolize[β_1]

Symbolize[β_2]

ClearAll["Global`*"]

$\xi = 0;$

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Column[Collect[{ $\ddot{x}_{t+\gamma\Delta t} + 2 \xi \omega \dot{x}_{t+\gamma\Delta t} + \omega^2 x_{t+\gamma\Delta t} == r_{t+\gamma\Delta t}$  ,
 $x_{t+\gamma\Delta t} == x_t + \frac{\gamma \Delta t}{2} (\dot{x}_t + \dot{x}_{t+\gamma\Delta t})$  ,
 $\dot{x}_{t+\gamma\Delta t} == \dot{x}_t + \frac{\gamma \Delta t}{2} (\ddot{x}_t + \ddot{x}_{t+\gamma\Delta t})$  ,
 $\ddot{x}_{t+\Delta t} + 2 \xi \omega \dot{x}_{t+\Delta t} + \omega^2 x_{t+\Delta t} == r_{t+\Delta t}$  ,
 $x_{t+\Delta t} == x_t + \gamma \Delta t ((1 - \beta_1) \dot{x}_t + \beta_1 \dot{x}_{t+\gamma\Delta t}) + (1 - \gamma) \Delta t ((1 - \beta_2) \dot{x}_{t+\gamma\Delta t} + \beta_2 \dot{x}_{t+\Delta t})$  ,
 $\dot{x}_{t+\Delta t} == \dot{x}_t + \gamma \Delta t ((1 - \beta_1) \ddot{x}_t + \beta_1 \ddot{x}_{t+\gamma\Delta t}) + (1 - \gamma) \Delta t ((1 - \beta_2) \ddot{x}_{t+\gamma\Delta t} + \beta_2 \ddot{x}_{t+\Delta t})$  } ,
{ $\ddot{x}_{t+\gamma\Delta t}$ ,  $\dot{x}_{t+\gamma\Delta t}$ ,  $x_{t+\gamma\Delta t}$ ,  $\ddot{x}_{t+\Delta t}$ ,  $\dot{x}_{t+\Delta t}$ ,  $x_{t+\Delta t}$  }]]

 $x_{t+\gamma\Delta t} + 2 \dot{x}_{t+\gamma\Delta t} \xi \omega + x_{t+\gamma\Delta t} \omega^2 == r_{t+\gamma\Delta t}$ 
 $x_{t+\gamma\Delta t} == x_t + \frac{1}{2} \dot{x}_t \gamma \Delta t + \frac{1}{2} \dot{x}_{t+\gamma\Delta t} \gamma \Delta t$ 
 $\dot{x}_{t+\gamma\Delta t} == \dot{x}_t + \frac{1}{2} \ddot{x}_t \gamma \Delta t + \frac{1}{2} \ddot{x}_{t+\gamma\Delta t} \gamma \Delta t$ 
 $x_{t+\Delta t} + 2 \dot{x}_{t+\Delta t} \xi \omega + x_{t+\Delta t} \omega^2 == r_{t+\Delta t}$ 
 $x_{t+\Delta t} == x_t + \dot{x}_{t+\Delta t} \beta_2 (1 - \gamma) \Delta t + \dot{x}_t (1 - \beta_1) \gamma \Delta t + \dot{x}_{t+\gamma\Delta t} ((1 - \beta_2) (1 - \gamma) \Delta t + \beta_1 \gamma \Delta t)$ 
 $\dot{x}_{t+\Delta t} == \dot{x}_t + \ddot{x}_{t+\Delta t} \beta_2 (1 - \gamma) \Delta t + \ddot{x}_t (1 - \beta_1) \gamma \Delta t + \ddot{x}_{t+\gamma\Delta t} ((1 - \beta_2) (1 - \gamma) \Delta t + \beta_1 \gamma \Delta t)$ 

Collect[ $x_{t+\Delta t} - \dot{x}_{t+\Delta t} \beta_2 (1 - \gamma) \Delta t - \dot{x}_{t+\gamma\Delta t} ((1 - \beta_2) (1 - \gamma) \Delta t + \beta_1 \gamma \Delta t) == x_t + \dot{x}_t (1 - \beta_1) \gamma \Delta t$  ,
{ $\ddot{x}_{t+\gamma\Delta t}$ ,  $\dot{x}_{t+\gamma\Delta t}$ ,  $x_{t+\gamma\Delta t}$ ,  $\ddot{x}_{t+\Delta t}$ ,  $\dot{x}_{t+\Delta t}$ ,  $x_{t+\Delta t}$  }]]

 $x_{t+\Delta t} - \dot{x}_{t+\Delta t} \beta_2 (1 - \gamma) \Delta t + \dot{x}_{t+\gamma\Delta t} (- (1 - \beta_2) (1 - \gamma) \Delta t - \beta_1 \gamma \Delta t) == x_t + \dot{x}_t (1 - \beta_1) \gamma \Delta t$ 

Collect[ $\dot{x}_{t+\Delta t} - \ddot{x}_{t+\Delta t} \beta_2 (1 - \gamma) \Delta t - \ddot{x}_{t+\gamma\Delta t} ((1 - \beta_2) (1 - \gamma) \Delta t + \beta_1 \gamma \Delta t) ==$ 
 $\dot{x}_t + \ddot{x}_t (1 - \beta_1) \gamma \Delta t$  , { $\ddot{x}_{t+\gamma\Delta t}$ ,  $\dot{x}_{t+\gamma\Delta t}$ ,  $x_{t+\gamma\Delta t}$ ,  $\ddot{x}_{t+\Delta t}$ ,  $\dot{x}_{t+\Delta t}$ ,  $x_{t+\Delta t}$  }]]

 $\dot{x}_{t+\Delta t} - \ddot{x}_{t+\Delta t} \beta_2 (1 - \gamma) \Delta t + \ddot{x}_{t+\gamma\Delta t} (- (1 - \beta_2) (1 - \gamma) \Delta t - \beta_1 \gamma \Delta t) == \dot{x}_t + \ddot{x}_t (1 - \beta_1) \gamma \Delta t$ 

Solve[
 $\ddot{x}_{t+\gamma\Delta t} + 2 \xi \omega \dot{x}_{t+\gamma\Delta t} + \omega^2 x_{t+\gamma\Delta t} == r_{t+\gamma\Delta t}$  &&
 $x_{t+\gamma\Delta t} == x_t + \frac{\gamma \Delta t}{2} (\dot{x}_t + \dot{x}_{t+\gamma\Delta t})$  &&
 $\dot{x}_{t+\gamma\Delta t} == \dot{x}_t + \frac{\gamma \Delta t}{2} (\ddot{x}_t + \ddot{x}_{t+\gamma\Delta t})$  &&
 $\ddot{x}_{t+\Delta t} + 2 \xi \omega \dot{x}_{t+\Delta t} + \omega^2 x_{t+\Delta t} == r_{t+\Delta t}$  &&
 $x_{t+\Delta t} == x_t + \gamma \Delta t ((1 - \beta_1) \dot{x}_t + \beta_1 \dot{x}_{t+\gamma\Delta t}) + (1 - \gamma) \Delta t ((1 - \beta_2) \dot{x}_{t+\gamma\Delta t} + \beta_2 \dot{x}_{t+\Delta t})$  &&
 $\dot{x}_{t+\Delta t} == \dot{x}_t + \gamma \Delta t ((1 - \beta_1) \ddot{x}_t + \beta_1 \ddot{x}_{t+\gamma\Delta t}) + (1 - \gamma) \Delta t ((1 - \beta_2) \ddot{x}_{t+\gamma\Delta t} + \beta_2 \ddot{x}_{t+\Delta t})$  ,
{ $\ddot{x}_{t+\gamma\Delta t}$ ,  $\dot{x}_{t+\gamma\Delta t}$ ,  $x_{t+\gamma\Delta t}$ ,  $\ddot{x}_{t+\Delta t}$ ,  $\dot{x}_{t+\Delta t}$ ,  $x_{t+\Delta t}$  }]]

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$$\begin{aligned} & \left\{ \dot{\mathbf{x}}_{t+\gamma\Delta t} \rightarrow - \left(\left(-4 \mathbf{r}_{t+\gamma\Delta t} + 4 \mathbf{x}_t \omega^2 + 4 \dot{\mathbf{x}}_t \gamma \Delta t \omega^2 + \mathbf{x}_t \gamma^2 \Delta t^2 \omega^2 \right) / \left(4 + \gamma^2 \Delta t^2 \omega^2 \right) \right), \right. \\ & \dot{\mathbf{x}}_{t+\gamma\Delta t} \rightarrow - \left(\left(-4 \dot{\mathbf{x}}_t - 2 \mathbf{r}_{t+\gamma\Delta t} \gamma \Delta t - 2 \mathbf{x}_t \gamma \Delta t + 2 \mathbf{x}_t \gamma \Delta t \omega^2 + \dot{\mathbf{x}}_t \gamma^2 \Delta t^2 \omega^2 \right) / \left(4 + \gamma^2 \Delta t^2 \omega^2 \right) \right), \\ & \mathbf{x}_{t+\gamma\Delta t} \rightarrow - \left(\left(-4 \mathbf{x}_t - 4 \dot{\mathbf{x}}_t \gamma \Delta t - \mathbf{r}_{t+\gamma\Delta t} \gamma^2 \Delta t^2 - \mathbf{x}_t \gamma^2 \Delta t^2 \right) / \left(4 + \gamma^2 \Delta t^2 \omega^2 \right) \right), \quad \mathbf{x}_{t+\Delta t} \rightarrow \\ & - \left(\left(-4 \mathbf{r}_{t+\Delta t} + 4 \mathbf{x}_t \omega^2 + 4 \dot{\mathbf{x}}_t \Delta t \omega^2 + 4 \mathbf{r}_{t+\gamma\Delta t} \beta_2 \Delta t^2 \omega^2 - 4 \mathbf{r}_{t+\gamma\Delta t} \beta_2^2 \Delta t^2 \omega^2 + 2 \mathbf{r}_{t+\gamma\Delta t} \gamma \Delta t^2 \omega^2 + \right. \right. \\ & 2 \mathbf{x}_t \gamma \Delta t^2 \omega^2 - 10 \mathbf{r}_{t+\gamma\Delta t} \beta_2 \gamma \Delta t^2 \omega^2 + 2 \mathbf{x}_t \beta_2 \gamma \Delta t^2 \omega^2 + 4 \mathbf{r}_{t+\gamma\Delta t} \beta_1 \beta_2 \gamma \Delta t^2 \omega^2 - \\ & 4 \mathbf{x}_t \beta_1 \beta_2 \gamma \Delta t^2 \omega^2 + 8 \mathbf{r}_{t+\gamma\Delta t} \beta_2^2 \gamma \Delta t^2 \omega^2 - 2 \mathbf{r}_{t+\gamma\Delta t} \gamma^2 \Delta t^2 \omega^2 - \mathbf{r}_{t+\Delta t} \gamma^2 \Delta t^2 \omega^2 - \\ & 2 \mathbf{x}_t \gamma^2 \Delta t^2 \omega^2 + 2 \mathbf{r}_{t+\gamma\Delta t} \beta_1 \gamma^2 \Delta t^2 \omega^2 + 2 \mathbf{x}_t \beta_1 \gamma^2 \Delta t^2 \omega^2 + 6 \mathbf{r}_{t+\gamma\Delta t} \beta_2 \gamma^2 \Delta t^2 \omega^2 - \\ & 2 \mathbf{x}_t \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 \mathbf{r}_{t+\gamma\Delta t} \beta_1 \beta_2 \gamma^2 \Delta t^2 \omega^2 + 4 \mathbf{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 \mathbf{r}_{t+\gamma\Delta t} \beta_2^2 \gamma^2 \Delta t^2 \omega^2 - \\ & 4 \mathbf{x}_t \beta_2 \Delta t^2 \omega^4 + 4 \mathbf{x}_t \beta_2^2 \Delta t^2 \omega^4 - 2 \mathbf{x}_t \gamma \Delta t^2 \omega^4 + 10 \mathbf{x}_t \beta_2 \gamma \Delta t^2 \omega^4 - 4 \mathbf{x}_t \beta_1 \beta_2 \gamma \Delta t^2 \omega^4 - \\ & 8 \mathbf{x}_t \beta_2^2 \gamma \Delta t^2 \omega^4 + 3 \mathbf{x}_t \gamma^2 \Delta t^2 \omega^4 - 2 \mathbf{x}_t \beta_1 \gamma^2 \Delta t^2 \omega^4 - 6 \mathbf{x}_t \beta_2 \gamma^2 \Delta t^2 \omega^4 + \\ & 4 \mathbf{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^2 \omega^4 + 4 \mathbf{x}_t \beta_2^2 \gamma^2 \Delta t^2 \omega^4 - 4 \dot{\mathbf{x}}_t \beta_2 \gamma \Delta t^3 \omega^4 + 4 \dot{\mathbf{x}}_t \beta_2^2 \gamma \Delta t^3 \omega^4 - \dot{\mathbf{x}}_t \gamma^2 \Delta t^3 \omega^4 + \\ & 10 \dot{\mathbf{x}}_t \beta_2 \gamma^2 \Delta t^3 \omega^4 - 4 \dot{\mathbf{x}}_t \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^4 - 8 \dot{\mathbf{x}}_t \beta_2^2 \gamma^2 \Delta t^3 \omega^4 + 2 \dot{\mathbf{x}}_t \gamma^3 \Delta t^3 \omega^4 - \\ & 2 \dot{\mathbf{x}}_t \beta_1 \gamma^3 \Delta t^3 \omega^4 - 6 \dot{\mathbf{x}}_t \beta_2 \gamma^3 \Delta t^3 \omega^4 + 4 \dot{\mathbf{x}}_t \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^4 + 4 \dot{\mathbf{x}}_t \beta_2^2 \gamma^3 \Delta t^3 \omega^4 - \\ & \mathbf{x}_t \beta_2 \gamma^2 \Delta t^4 \omega^4 + \mathbf{x}_t \beta_2^2 \gamma^2 \Delta t^4 \omega^4 + 3 \mathbf{x}_t \beta_2 \gamma^3 \Delta t^4 \omega^4 - 2 \mathbf{x}_t \beta_1 \beta_2 \gamma^3 \Delta t^4 \omega^4 - \\ & 2 \mathbf{x}_t \beta_2^2 \gamma^3 \Delta t^4 \omega^4 - 2 \mathbf{x}_t \beta_2 \gamma^4 \Delta t^4 \omega^4 + 2 \mathbf{x}_t \beta_1 \beta_2 \gamma^4 \Delta t^4 \omega^4 + \mathbf{x}_t \beta_2^2 \gamma^4 \Delta t^4 \omega^4 \Big) / \\ & \left. \left(\left(4 + \gamma^2 \Delta t^2 \omega^2 \right) \left(1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \right) \right) \right), \\ & \dot{\mathbf{x}}_{t+\Delta t} \rightarrow - \left(\left(-4 \dot{\mathbf{x}}_t - 4 \mathbf{r}_{t+\gamma\Delta t} \Delta t + 4 \mathbf{r}_{t+\gamma\Delta t} \beta_2 \Delta t - 4 \mathbf{r}_{t+\Delta t} \beta_2 \Delta t + 4 \mathbf{r}_{t+\gamma\Delta t} \gamma \Delta t - 4 \mathbf{x}_t \gamma \Delta t - \right. \right. \\ & 4 \mathbf{r}_{t+\gamma\Delta t} \beta_1 \gamma \Delta t + 4 \mathbf{x}_t \beta_1 \gamma \Delta t - 4 \mathbf{r}_{t+\gamma\Delta t} \beta_2 \gamma \Delta t + 4 \mathbf{r}_{t+\Delta t} \beta_2 \gamma \Delta t + 4 \mathbf{x}_t \Delta t \omega^2 - \\ & 4 \mathbf{x}_t \gamma \Delta t \omega^2 + 4 \mathbf{x}_t \beta_1 \gamma \Delta t \omega^2 + 4 \dot{\mathbf{x}}_t \beta_2 \Delta t^2 \omega^2 - 4 \dot{\mathbf{x}}_t \beta_2^2 \Delta t^2 \omega^2 + 4 \dot{\mathbf{x}}_t \gamma \Delta t^2 \omega^2 - \\ & 8 \dot{\mathbf{x}}_t \beta_2 \gamma \Delta t^2 \omega^2 + 8 \dot{\mathbf{x}}_t \beta_2^2 \gamma \Delta t^2 \omega^2 - 5 \dot{\mathbf{x}}_t \gamma^2 \Delta t^2 \omega^2 + 4 \dot{\mathbf{x}}_t \beta_1 \gamma^2 \Delta t^2 \omega^2 + \\ & 4 \dot{\mathbf{x}}_t \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 \dot{\mathbf{x}}_t \beta_2^2 \gamma^2 \Delta t^2 \omega^2 + 2 \mathbf{r}_{t+\gamma\Delta t} \beta_2 \gamma \Delta t^3 \omega^2 + 2 \mathbf{x}_t \beta_2 \gamma \Delta t^3 \omega^2 - \\ & 2 \mathbf{r}_{t+\gamma\Delta t} \beta_2^2 \gamma \Delta t^3 \omega^2 - 2 \mathbf{x}_t \beta_2^2 \gamma \Delta t^3 \omega^2 + \mathbf{x}_t \gamma^2 \Delta t^3 \omega^2 - 4 \mathbf{r}_{t+\gamma\Delta t} \beta_2 \gamma^2 \Delta t^3 \omega^2 - \\ & \mathbf{r}_{t+\Delta t} \beta_2 \gamma^2 \Delta t^3 \omega^2 - 5 \mathbf{x}_t \beta_2 \gamma^2 \Delta t^3 \omega^2 + 2 \mathbf{r}_{t+\gamma\Delta t} \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^2 + \\ & 2 \mathbf{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^2 + 4 \mathbf{r}_{t+\gamma\Delta t} \beta_2^2 \gamma^2 \Delta t^3 \omega^2 + 4 \mathbf{x}_t \beta_2^2 \gamma^2 \Delta t^3 \omega^2 - 2 \mathbf{x}_t \gamma^3 \Delta t^3 \omega^2 + \\ & 2 \mathbf{x}_t \beta_1 \gamma^3 \Delta t^3 \omega^2 + 2 \mathbf{r}_{t+\gamma\Delta t} \beta_2 \gamma^3 \Delta t^3 \omega^2 + \mathbf{r}_{t+\Delta t} \beta_2 \gamma^3 \Delta t^3 \omega^2 + 3 \mathbf{x}_t \beta_2 \gamma^3 \Delta t^3 \omega^2 - \\ & 2 \mathbf{r}_{t+\gamma\Delta t} \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^2 - 2 \mathbf{x}_t \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^2 - 2 \mathbf{r}_{t+\gamma\Delta t} \beta_2^2 \gamma^3 \Delta t^3 \omega^2 - 2 \mathbf{x}_t \beta_2^2 \gamma^3 \Delta t^3 \omega^2 - \\ & 2 \mathbf{x}_t \beta_2 \gamma \Delta t^3 \omega^4 + 2 \mathbf{x}_t \beta_2^2 \gamma \Delta t^3 \omega^4 + 5 \mathbf{x}_t \beta_2 \gamma^2 \Delta t^3 \omega^4 - 2 \mathbf{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^4 - \\ & 4 \mathbf{x}_t \beta_2^2 \gamma^2 \Delta t^3 \omega^4 - 3 \mathbf{x}_t \beta_2 \gamma^3 \Delta t^3 \omega^4 + 2 \mathbf{x}_t \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^4 + 2 \mathbf{x}_t \beta_2^2 \gamma^3 \Delta t^3 \omega^4 - \\ & \dot{\mathbf{x}}_t \beta_2 \gamma^2 \Delta t^4 \omega^4 + \dot{\mathbf{x}}_t \beta_2^2 \gamma^2 \Delta t^4 \omega^4 + 3 \dot{\mathbf{x}}_t \beta_2 \gamma^3 \Delta t^4 \omega^4 - 2 \dot{\mathbf{x}}_t \beta_1 \beta_2 \gamma^3 \Delta t^4 \omega^4 - \\ & 2 \dot{\mathbf{x}}_t \beta_2^2 \gamma^3 \Delta t^4 \omega^4 - 2 \dot{\mathbf{x}}_t \beta_2 \gamma^4 \Delta t^4 \omega^4 + 2 \dot{\mathbf{x}}_t \beta_1 \beta_2 \gamma^4 \Delta t^4 \omega^4 + \dot{\mathbf{x}}_t \beta_2^2 \gamma^4 \Delta t^4 \omega^4 \Big) / \\ & \left. \left(\left(4 + \gamma^2 \Delta t^2 \omega^2 \right) \left(1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \right) \right) \right), \\ & \mathbf{x}_{t+\Delta t} \rightarrow - \left(\left(-4 \mathbf{x}_t - 4 \dot{\mathbf{x}}_t \Delta t - 4 \mathbf{r}_{t+\gamma\Delta t} \beta_2 \Delta t^2 + 4 \mathbf{r}_{t+\gamma\Delta t} \beta_2^2 \Delta t^2 - 4 \mathbf{r}_{t+\Delta t} \beta_2^2 \Delta t^2 - \right. \right. \\ & 2 \mathbf{r}_{t+\gamma\Delta t} \gamma \Delta t^2 - 2 \mathbf{x}_t \gamma \Delta t^2 + 10 \mathbf{r}_{t+\gamma\Delta t} \beta_2 \gamma \Delta t^2 - 2 \mathbf{x}_t \beta_2 \gamma \Delta t^2 - 4 \mathbf{r}_{t+\gamma\Delta t} \beta_1 \beta_2 \gamma \Delta t^2 + \\ & 4 \mathbf{x}_t \beta_1 \beta_2 \gamma \Delta t^2 - 8 \mathbf{r}_{t+\gamma\Delta t} \beta_2^2 \gamma \Delta t^2 + 8 \mathbf{r}_{t+\Delta t} \beta_2^2 \gamma \$$

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ClearAll["Global`*"]
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```
recursive =
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```
{
  Collect[
    
$$\ddot{x}_{t+\Delta t} - \left( - \left( \left( -4 r_{t+\Delta t} + 4 x_t \omega^2 + 4 \dot{x}_t \Delta t \omega^2 + 4 r_{t+\gamma \Delta t} \beta_2 \Delta t^2 \omega^2 - 4 r_{t+\gamma \Delta t} \beta_2^2 \Delta t^2 \omega^2 + 2 r_{t+\gamma \Delta t} \gamma \Delta t^2 \omega^2 + 2 \dot{x}_t \gamma \Delta t^2 \omega^2 - 10 r_{t+\gamma \Delta t} \beta_2 \gamma \Delta t^2 \omega^2 + 2 \dot{x}_t \beta_2 \gamma \Delta t^2 \omega^2 + 4 r_{t+\gamma \Delta t} \beta_1 \beta_2 \gamma \Delta t^2 \omega^2 - 4 \dot{x}_t \beta_1 \beta_2 \gamma \Delta t^2 \omega^2 + 8 r_{t+\gamma \Delta t} \beta_2^2 \gamma \Delta t^2 \omega^2 - 2 r_{t+\gamma \Delta t} \gamma^2 \Delta t^2 \omega^2 - r_{t+\Delta t} \gamma^2 \Delta t^2 \omega^2 - 2 \dot{x}_t \gamma^2 \Delta t^2 \omega^2 + 2 r_{t+\gamma \Delta t} \beta_1 \gamma^2 \Delta t^2 \omega^2 + 2 \dot{x}_t \beta_1 \gamma^2 \Delta t^2 \omega^2 + 6 r_{t+\gamma \Delta t} \beta_2 \gamma^2 \Delta t^2 \omega^2 - 2 \dot{x}_t \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 r_{t+\gamma \Delta t} \beta_1 \beta_2 \gamma^2 \Delta t^2 \omega^2 + 4 \dot{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 r_{t+\gamma \Delta t} \beta_2^2 \gamma^2 \Delta t^2 \omega^2 - 4 x_t \beta_2 \Delta t^2 \omega^4 + 4 x_t \beta_2^2 \Delta t^2 \omega^4 - 2 x_t \gamma \Delta t^2 \omega^4 + 10 x_t \beta_2 \gamma \Delta t^2 \omega^4 - 4 x_t \beta_1 \beta_2 \gamma \Delta t^2 \omega^4 - 8 x_t \beta_2^2 \gamma \Delta t^2 \omega^4 + 3 x_t \gamma^2 \Delta t^2 \omega^4 - 2 x_t \beta_1 \gamma^2 \Delta t^2 \omega^4 - 6 x_t \beta_2 \gamma^2 \Delta t^2 \omega^4 + 4 x_t \beta_1 \beta_2 \gamma^2 \Delta t^2 \omega^4 + 4 x_t \beta_2^2 \gamma^2 \Delta t^2 \omega^4 - 4 \dot{x}_t \beta_2 \gamma \Delta t^3 \omega^4 + 4 \dot{x}_t \beta_2^2 \gamma \Delta t^3 \omega^4 - \dot{x}_t \gamma^2 \Delta t^3 \omega^4 + 10 \dot{x}_t \beta_2 \gamma^2 \Delta t^3 \omega^4 - 4 \dot{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^4 - 8 \dot{x}_t \beta_2^2 \gamma^2 \Delta t^3 \omega^4 + 2 \dot{x}_t \gamma^3 \Delta t^3 \omega^4 - 2 \dot{x}_t \beta_1 \gamma^3 \Delta t^3 \omega^4 - 6 \dot{x}_t \beta_2 \gamma^3 \Delta t^3 \omega^4 + 4 \dot{x}_t \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^4 + 4 \dot{x}_t \beta_2^2 \gamma^3 \Delta t^3 \omega^4 - \dot{x}_t \beta_2 \gamma^2 \Delta t^4 \omega^4 + \dot{x}_t \beta_2^2 \gamma^2 \Delta t^4 \omega^4 + 3 \dot{x}_t \beta_2 \gamma^3 \Delta t^4 \omega^4 - 2 \dot{x}_t \beta_1 \beta_2 \gamma^3 \Delta t^4 \omega^4 - 2 \dot{x}_t \beta_2^2 \gamma^3 \Delta t^4 \omega^4 - 2 \dot{x}_t \beta_2 \gamma^4 \Delta t^4 \omega^4 + 2 \dot{x}_t \beta_1 \beta_2 \gamma^4 \Delta t^4 \omega^4 + \dot{x}_t \beta_2^2 \gamma^4 \Delta t^4 \omega^4 \right) \right) / \left( \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) \left( 1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \right) \right) \right),$$

    { $\dot{x}_t$ ,  $\ddot{x}_t$ ,  $x_t$ ,  $r_{t+\Delta t}$ ,  $r_{t+\gamma \Delta t}$ }],
    Collect[ $\ddot{x}_{t+\Delta t} - \left( - \left( \left( -4 \dot{x}_t - 4 r_{t+\gamma \Delta t} \Delta t + 4 r_{t+\gamma \Delta t} \beta_2 \Delta t - 4 r_{t+\Delta t} \beta_2 \Delta t + 4 r_{t+\gamma \Delta t} \gamma \Delta t - 4 \dot{x}_t \gamma \Delta t - 4 r_{t+\gamma \Delta t} \beta_1 \gamma \Delta t + 4 \dot{x}_t \beta_1 \gamma \Delta t - 4 r_{t+\gamma \Delta t} \beta_2 \gamma \Delta t + 4 r_{t+\Delta t} \beta_2 \gamma \Delta t + 4 x_t \Delta t \omega^2 - 4 x_t \gamma \Delta t \omega^2 + 4 x_t \beta_1 \gamma \Delta t \omega^2 + 4 \dot{x}_t \beta_2 \Delta t^2 \omega^2 - 4 \dot{x}_t \beta_2^2 \Delta t^2 \omega^2 + 4 \dot{x}_t \gamma \Delta t^2 \omega^2 - 8 \dot{x}_t \beta_2 \gamma \Delta t^2 \omega^2 + 8 \dot{x}_t \beta_2^2 \gamma \Delta t^2 \omega^2 - 5 \dot{x}_t \gamma^2 \Delta t^2 \omega^2 + 4 \dot{x}_t \beta_1 \gamma^2 \Delta t^2 \omega^2 + 4 \dot{x}_t \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 \dot{x}_t \beta_2^2 \gamma^2 \Delta t^2 \omega^2 + 2 r_{t+\gamma \Delta t} \beta_2 \gamma \Delta t^3 \omega^2 + 2 \dot{x}_t \beta_2 \gamma \Delta t^3 \omega^2 - 2 r_{t+\gamma \Delta t} \beta_2^2 \gamma \Delta t^3 \omega^2 - 2 \dot{x}_t \beta_2^2 \gamma \Delta t^3 \omega^2 + \dot{x}_t \gamma^2 \Delta t^3 \omega^2 - 4 r_{t+\gamma \Delta t} \beta_2 \gamma^2 \Delta t^3 \omega^2 - r_{t+\Delta t} \beta_2 \gamma^2 \Delta t^3 \omega^2 - 5 \dot{x}_t \beta_2 \gamma^2 \Delta t^3 \omega^2 + 2 r_{t+\gamma \Delta t} \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^2 + 2 \dot{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^2 + 4 r_{t+\gamma \Delta t} \beta_2^2 \gamma^2 \Delta t^3 \omega^2 + 4 \dot{x}_t \beta_2^2 \gamma^2 \Delta t^3 \omega^2 - 2 \dot{x}_t \gamma^3 \Delta t^3 \omega^2 + 2 \dot{x}_t \beta_1 \gamma^3 \Delta t^3 \omega^2 + 2 r_{t+\gamma \Delta t} \beta_2 \gamma^3 \Delta t^3 \omega^2 + r_{t+\Delta t} \beta_2 \gamma^3 \Delta t^3 \omega^2 + 3 \dot{x}_t \beta_2 \gamma^3 \Delta t^3 \omega^2 - 2 r_{t+\gamma \Delta t} \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^2 - 2 \dot{x}_t \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^2 - 2 r_{t+\gamma \Delta t} \beta_2^2 \gamma^3 \Delta t^3 \omega^2 - 2 \dot{x}_t \beta_2^2 \gamma^3 \Delta t^3 \omega^2 - 2 x_t \beta_2 \gamma \Delta t^3 \omega^4 + 2 x_t \beta_2^2 \gamma \Delta t^3 \omega^4 + 5 x_t \beta_2 \gamma^2 \Delta t^3 \omega^4 - 2 x_t \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^4 - 4 x_t \beta_2^2 \gamma^2 \Delta t^3 \omega^4 - 3 x_t \beta_2 \gamma^3 \Delta t^3 \omega^4 + 2 x_t \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^4 + 2 x_t \beta_2^2 \gamma^3 \Delta t^3 \omega^4 - \dot{x}_t \beta_2 \gamma^2 \Delta t^4 \omega^4 + \dot{x}_t \beta_2^2 \gamma^2 \Delta t^4 \omega^4 + 3 \dot{x}_t \beta_2 \gamma^3 \Delta t^4 \omega^4 - 2 \dot{x}_t \beta_1 \beta_2 \gamma^3 \Delta t^4 \omega^4 - 2 \dot{x}_t \beta_2^2 \gamma^3 \Delta t^4 \omega^4 - 2 \dot{x}_t \beta_2 \gamma^4 \Delta t^4 \omega^4 + 2 \dot{x}_t \beta_1 \beta_2 \gamma^4 \Delta t^4 \omega^4 + \dot{x}_t \beta_2^2 \gamma^4 \Delta t^4 \omega^4 \right) \right) / \left( \left( 4 + \gamma^2 \Delta t^2 \omega^2 \right) \left( 1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \right) \right) \right) //$ 
    Factor, { $\dot{x}_t$ ,  $\ddot{x}_t$ ,  $x_t$ ,  $r_{t+\Delta t}$ ,  $r_{t+\gamma \Delta t}$ }],
    Collect[ $x_{t+\Delta t} - \left( - \left( \left( -4 x_t - 4 \dot{x}_t \Delta t - 4 r_{t+\gamma \Delta t} \beta_2 \Delta t^2 + 4 r_{t+\gamma \Delta t} \beta_2^2 \Delta t^2 - 4 r_{t+\Delta t} \beta_2^2 \Delta t^2 - 2 r_{t+\gamma \Delta t} \gamma \Delta t^2 - 2 \dot{x}_t \gamma \Delta t^2 + 10 r_{t+\gamma \Delta t} \beta_2 \gamma \Delta t^2 - 2 \dot{x}_t \beta_2 \gamma \Delta t^2 - 4 r_{t+\gamma \Delta t} \beta_1 \beta_2 \gamma \Delta t^2 + 4 \dot{x}_t \beta_1 \beta_2 \gamma \Delta t^2 - 8 r_{t+\gamma \Delta t} \beta_2^2 \gamma \Delta t^2 + 8 r_{t+\Delta t} \beta_2^2 \gamma \Delta t^2 + 2 r_{t+\gamma \Delta t} \gamma^2 \Delta t^2 + 2 \dot{x}_t \gamma^2 \Delta t^2 - 2 r_{t+\gamma \Delta t} \beta_1 \gamma^2 \Delta t^2 - 2 \dot{x}_t \beta_1 \gamma^2 \Delta t^2 - 6 r_{t+\gamma \Delta t} \beta_2 \gamma^2 \Delta t^2 + 2 \dot{x}_t \beta_2 \gamma^2 \Delta t^2 + 4 r_{t+\gamma \Delta t} \beta_1 \beta_2 \gamma^2 \Delta t^2 - 4 \dot{x}_t \beta_1 \beta_2 \gamma^2 \Delta t^2 + 4 r_{t+\gamma \Delta t} \beta_2^2 \gamma^2 \Delta t^2 - 4 r_{t+\Delta t} \beta_2^2 \gamma^2 \Delta t^2 + 4 x_t \beta_2 \Delta t^2 \omega^2 - 4 x_t \beta_2^2 \Delta t^2 \omega^2 + 2 x_t \gamma \Delta t^2 \omega^2 - 10 x_t \beta_2 \gamma \Delta t^2 \omega^2 + 4 x_t \beta_1 \beta_2 \gamma \Delta t^2 \omega^2 + 8 x_t \beta_2^2 \gamma \Delta t^2 \omega^2 - 3 x_t \gamma^2 \Delta t^2 \omega^2 + 2 x_t \beta_1 \gamma^2 \Delta t^2 \omega^2 + 6 x_t \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 x_t \beta_1 \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 x_t \beta_2^2 \gamma^2 \Delta t^2 \omega^2 + 4 \dot{x}_t \beta_2 \gamma \Delta t^3 \omega^2 - 4 \dot{x}_t \beta_2^2 \gamma \Delta t^3 \omega^2 + \dot{x}_t \gamma^2 \Delta t^3 \omega^2 - \right) \right)$ 

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$$\begin{aligned}
& 10 \dot{\mathbf{x}}_t \beta_2 \gamma^2 \Delta t^3 \omega^2 + 4 \dot{\mathbf{x}}_t \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^2 + 8 \dot{\mathbf{x}}_t \beta_2^2 \gamma^2 \Delta t^3 \omega^2 - 2 \dot{\mathbf{x}}_t \gamma^3 \Delta t^3 \omega^2 + \\
& 2 \dot{\mathbf{x}}_t \beta_1 \gamma^3 \Delta t^3 \omega^2 + 6 \dot{\mathbf{x}}_t \beta_2 \gamma^3 \Delta t^3 \omega^2 - 4 \dot{\mathbf{x}}_t \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^2 - 4 \dot{\mathbf{x}}_t \beta_2^2 \gamma^3 \Delta t^3 \omega^2 + \\
& \dot{\mathbf{x}}_t \beta_2 \gamma^2 \Delta t^4 \omega^2 - \mathbf{r}_{t+\Delta t} \beta_2^2 \gamma^2 \Delta t^4 \omega^2 - \dot{\mathbf{x}}_t \beta_2^2 \gamma^2 \Delta t^4 \omega^2 - 3 \dot{\mathbf{x}}_t \beta_2 \gamma^3 \Delta t^4 \omega^2 + \\
& 2 \dot{\mathbf{x}}_t \beta_1 \beta_2 \gamma^3 \Delta t^4 \omega^2 + 2 \mathbf{r}_{t+\Delta t} \beta_2^2 \gamma^3 \Delta t^4 \omega^2 + 2 \dot{\mathbf{x}}_t \beta_2^2 \gamma^3 \Delta t^4 \omega^2 + \\
& 2 \dot{\mathbf{x}}_t \beta_2 \gamma^4 \Delta t^4 \omega^2 - 2 \dot{\mathbf{x}}_t \beta_1 \beta_2 \gamma^4 \Delta t^4 \omega^2 - \mathbf{r}_{t+\Delta t} \beta_2^2 \gamma^4 \Delta t^4 \omega^2 - \dot{\mathbf{x}}_t \beta_2^2 \gamma^4 \Delta t^4 \omega^2) / \\
& ((4 + \gamma^2 \Delta t^2 \omega^2) (1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2))) // \\
& \text{Factor, } \{\dot{\mathbf{x}}_t, \ddot{\mathbf{x}}_t, \mathbf{x}_t, \mathbf{r}_{t+\gamma \Delta t}, \mathbf{r}_{t+\Delta t}\} \\
& \} /. \{-1 - \beta_2^2 (1 - \gamma)^2 \Delta t^2 \omega^2 \rightarrow \eta_1, \quad 4 + \gamma^2 \Delta t^2 \omega^2 \rightarrow \eta_2, \\
& 1 + \beta_2^2 \Delta t^2 \omega^2 - 2 \beta_2^2 \gamma \Delta t^2 \omega^2 + \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \rightarrow \eta_3\} \\
& \left\{ \mathbf{x}_{t+\Delta t} + \mathbf{r}_{t+\Delta t} \left(-\frac{4}{\eta_2 \eta_3} - \frac{\gamma^2 \Delta t^2 \omega^2}{\eta_2 \eta_3} \right) + \mathbf{r}_{t+\gamma \Delta t} \right. \\
& \left(\frac{4 \beta_2 \Delta t^2 \omega^2}{\eta_2 \eta_3} - \frac{4 \beta_2^2 \Delta t^2 \omega^2}{\eta_2 \eta_3} + \frac{2 \gamma \Delta t^2 \omega^2}{\eta_2 \eta_3} - \frac{10 \beta_2 \gamma \Delta t^2 \omega^2}{\eta_2 \eta_3} + \frac{4 \beta_1 \beta_2 \gamma \Delta t^2 \omega^2}{\eta_2 \eta_3} + \frac{8 \beta_2^2 \gamma \Delta t^2 \omega^2}{\eta_2 \eta_3} - \right. \\
& \left. \frac{2 \gamma^2 \Delta t^2 \omega^2}{\eta_2 \eta_3} + \frac{2 \beta_1 \gamma^2 \Delta t^2 \omega^2}{\eta_2 \eta_3} + \frac{6 \beta_2 \gamma^2 \Delta t^2 \omega^2}{\eta_2 \eta_3} - \frac{4 \beta_1 \beta_2 \gamma^2 \Delta t^2 \omega^2}{\eta_2 \eta_3} - \frac{4 \beta_2^2 \gamma^2 \Delta t^2 \omega^2}{\eta_2 \eta_3} \right) + \\
& \mathbf{x}_t \left(\frac{4 \omega^2}{\eta_2 \eta_3} - \frac{4 \beta_2 \Delta t^2 \omega^4}{\eta_2 \eta_3} + \frac{4 \beta_2^2 \Delta t^2 \omega^4}{\eta_2 \eta_3} - \frac{2 \gamma \Delta t^2 \omega^4}{\eta_2 \eta_3} + \frac{10 \beta_2 \gamma \Delta t^2 \omega^4}{\eta_2 \eta_3} - \right. \\
& \frac{4 \beta_1 \beta_2 \gamma \Delta t^2 \omega^4}{\eta_2 \eta_3} - \frac{8 \beta_2^2 \gamma \Delta t^2 \omega^4}{\eta_2 \eta_3} + \frac{3 \gamma^2 \Delta t^2 \omega^4}{\eta_2 \eta_3} - \frac{2 \beta_1 \gamma^2 \Delta t^2 \omega^4}{\eta_2 \eta_3} - \\
& \frac{6 \beta_2 \gamma^2 \Delta t^2 \omega^4}{\eta_2 \eta_3} + \frac{4 \beta_1 \beta_2 \gamma^2 \Delta t^2 \omega^4}{\eta_2 \eta_3} + \frac{4 \beta_2^2 \gamma^2 \Delta t^2 \omega^4}{\eta_2 \eta_3} \left. \right) + \\
& \ddot{\mathbf{x}}_t \left(\frac{4 \Delta t \omega^2}{\eta_2 \eta_3} - \frac{4 \beta_2 \gamma \Delta t^3 \omega^4}{\eta_2 \eta_3} + \frac{4 \beta_2^2 \gamma \Delta t^3 \omega^4}{\eta_2 \eta_3} - \frac{\gamma^2 \Delta t^3 \omega^4}{\eta_2 \eta_3} + \frac{10 \beta_2 \gamma^2 \Delta t^3 \omega^4}{\eta_2 \eta_3} - \right. \\
& \frac{4 \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^4}{\eta_2 \eta_3} - \frac{8 \beta_2^2 \gamma^2 \Delta t^3 \omega^4}{\eta_2 \eta_3} + \frac{2 \gamma^3 \Delta t^3 \omega^4}{\eta_2 \eta_3} - \frac{2 \beta_1 \gamma^3 \Delta t^3 \omega^4}{\eta_2 \eta_3} - \\
& \frac{6 \beta_2 \gamma^3 \Delta t^3 \omega^4}{\eta_2 \eta_3} + \frac{4 \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^4}{\eta_2 \eta_3} + \frac{4 \beta_2^2 \gamma^3 \Delta t^3 \omega^4}{\eta_2 \eta_3} \left. \right) + \\
& \mathbf{x}_t \left(\frac{2 \gamma \Delta t^2 \omega^2}{\eta_2 \eta_3} + \frac{2 \beta_2 \gamma \Delta t^2 \omega^2}{\eta_2 \eta_3} - \frac{4 \beta_1 \beta_2 \gamma \Delta t^2 \omega^2}{\eta_2 \eta_3} - \frac{2 \gamma^2 \Delta t^2 \omega^2}{\eta_2 \eta_3} + \frac{2 \beta_1 \gamma^2 \Delta t^2 \omega^2}{\eta_2 \eta_3} - \right. \\
& \frac{2 \beta_2 \gamma^2 \Delta t^2 \omega^2}{\eta_2 \eta_3} + \frac{4 \beta_1 \beta_2 \gamma^2 \Delta t^2 \omega^2}{\eta_2 \eta_3} - \frac{\beta_2 \gamma^2 \Delta t^4 \omega^4}{\eta_2 \eta_3} + \frac{\beta_2^2 \gamma^2 \Delta t^4 \omega^4}{\eta_2 \eta_3} + \frac{3 \beta_2 \gamma^3 \Delta t^4 \omega^4}{\eta_2 \eta_3} - \\
& \frac{2 \beta_1 \beta_2 \gamma^3 \Delta t^4 \omega^4}{\eta_2 \eta_3} - \frac{2 \beta_2^2 \gamma^3 \Delta t^4 \omega^4}{\eta_2 \eta_3} - \frac{2 \beta_2 \gamma^4 \Delta t^4 \omega^4}{\eta_2 \eta_3} + \frac{2 \beta_1 \beta_2 \gamma^4 \Delta t^4 \omega^4}{\eta_2 \eta_3} + \frac{\beta_2^2 \gamma^4 \Delta t^4 \omega^4}{\eta_2 \eta_3} \left. \right), \\
& \frac{1}{\eta_2 \eta_3} \mathbf{r}_{t+\Delta t} (-4 \beta_2 \Delta t + 4 \beta_2 \gamma \Delta t - \beta_2 \gamma^2 \Delta t^3 \omega^2 + \beta_2 \gamma^3 \Delta t^3 \omega^2) + \frac{1}{\eta_2 \eta_3} \mathbf{r}_{t+\gamma \Delta t} \\
& (-4 \Delta t + 4 \beta_2 \Delta t + 4 \gamma \Delta t - 4 \beta_1 \gamma \Delta t - 4 \beta_2 \gamma \Delta t + 2 \beta_2 \gamma \Delta t^3 \omega^2 - 2 \beta_2^2 \gamma \Delta t^3 \omega^2 - 4 \beta_2 \gamma^2 \Delta t^3 \omega^2 + \\
& 2 \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^2 + 4 \beta_2^2 \gamma^2 \Delta t^3 \omega^2 + 2 \beta_2 \gamma^3 \Delta t^3 \omega^2 - 2 \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^2 - 2 \beta_2^2 \gamma^3 \Delta t^3 \omega^2) + \\
& \frac{1}{\eta_2 \eta_3} \mathbf{x}_t (-4 \gamma \Delta t + 4 \beta_1 \gamma \Delta t + 2 \beta_2 \gamma \Delta t^3 \omega^2 - 2 \beta_2^2 \gamma \Delta t^3 \omega^2 + \gamma^2 \Delta t^3 \omega^2 - \\
& 5 \beta_2 \gamma^2 \Delta t^3 \omega^2 + 2 \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^2 + 4 \beta_2^2 \gamma^2 \Delta t^3 \omega^2 - 2 \gamma^3 \Delta t^3 \omega^2 + \\
& 2 \beta_1 \gamma^3 \Delta t^3 \omega^2 + 3 \beta_2 \gamma^3 \Delta t^3 \omega^2 - 2 \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^2 - 2 \beta_2^2 \gamma^3 \Delta t^3 \omega^2) + \\
& \frac{1}{\eta_2 \eta_3} \mathbf{x}_t (4 \Delta t \omega^2 - 4 \gamma \Delta t \omega^2 + 4 \beta_1 \gamma \Delta t \omega^2 - 2 \beta_2 \gamma \Delta t^3 \omega^4 + 2 \beta_2^2 \gamma \Delta t^3 \omega^4 + 5 \beta_2 \gamma^2 \Delta t^3 \omega^4 - \\
& 2 \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^4 - 4 \beta_2^2 \gamma^2 \Delta t^3 \omega^4 - 3 \beta_2 \gamma^3 \Delta t^3 \omega^4 + 2 \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^4 + 2 \beta_2^2 \gamma^3 \Delta t^3 \omega^4) + \\
& \frac{1}{\eta_2 \eta_3} \ddot{\mathbf{x}}_t (-4 + 4 \beta_2 \Delta t^2 \omega^2 - 4 \beta_2^2 \Delta t^2 \omega^2 + 4 \gamma \Delta t^2 \omega^2 - 8 \beta_2 \gamma \Delta t^2 \omega^2 + 8 \beta_2^2 \gamma \Delta t^2 \omega^2 - 5 \gamma^2 \Delta t^2 \omega^2 + \\
& 4 \beta_1 \gamma^2 \Delta t^2 \omega^2 + 4 \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 \beta_2^2 \gamma^2 \Delta t^2 \omega^2 - \beta_2 \gamma^2 \Delta t^4 \omega^4 + \beta_2^2 \gamma^2 \Delta t^4 \omega^4 + 3 \beta_2 \gamma^3 \Delta t^4 \omega^4 -
\end{aligned}$$

$$\begin{aligned}
& 2 \beta_1 \beta_2 \gamma^3 \Delta t^4 \omega^4 - 2 \beta_2^2 \gamma^3 \Delta t^4 \omega^4 - 2 \beta_2 \gamma^4 \Delta t^4 \omega^4 + 2 \beta_1 \beta_2 \gamma^4 \Delta t^4 \omega^4 + \beta_2^2 \gamma^4 \Delta t^4 \omega^4 \Big) + \\
& \frac{1}{\eta_2 \eta_3} \Big(4 \dot{x}_{t+\Delta t} + 4 \dot{x}_{t+\Delta t} \beta_2^2 \Delta t^2 \omega^2 - 8 \dot{x}_{t+\Delta t} \beta_2^2 \gamma \Delta t^2 \omega^2 + \dot{x}_{t+\Delta t} \gamma^2 \Delta t^2 \omega^2 + \\
& 4 \dot{x}_{t+\Delta t} \beta_2^2 \gamma^2 \Delta t^2 \omega^2 + \dot{x}_{t+\Delta t} \beta_2^2 \gamma^2 \Delta t^4 \omega^4 - 2 \dot{x}_{t+\Delta t} \beta_2^2 \gamma^3 \Delta t^4 \omega^4 + \dot{x}_{t+\Delta t} \beta_2^2 \gamma^4 \Delta t^4 \omega^4 \Big), \\
& \frac{1}{\eta_2 \eta_3} r_{t+\gamma \Delta t} \Big(-4 \beta_2 \Delta t^2 + 4 \beta_2^2 \Delta t^2 - 2 \gamma \Delta t^2 + 10 \beta_2 \gamma \Delta t^2 - 4 \beta_1 \beta_2 \gamma \Delta t^2 - 8 \beta_2^2 \gamma \Delta t^2 + \\
& 2 \gamma^2 \Delta t^2 - 2 \beta_1 \gamma^2 \Delta t^2 - 6 \beta_2 \gamma^2 \Delta t^2 + 4 \beta_1 \beta_2 \gamma^2 \Delta t^2 + 4 \beta_2^2 \gamma^2 \Delta t^2 \Big) + \frac{1}{\eta_2 \eta_3} \\
& x_t \Big(-4 + 4 \beta_2 \Delta t^2 \omega^2 - 4 \beta_2^2 \Delta t^2 \omega^2 + 2 \gamma \Delta t^2 \omega^2 - 10 \beta_2 \gamma \Delta t^2 \omega^2 + 4 \beta_1 \beta_2 \gamma \Delta t^2 \omega^2 + 8 \beta_2^2 \gamma \Delta t^2 \omega^2 - \\
& 3 \gamma^2 \Delta t^2 \omega^2 + 2 \beta_1 \gamma^2 \Delta t^2 \omega^2 + 6 \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 \beta_1 \beta_2 \gamma^2 \Delta t^2 \omega^2 - 4 \beta_2^2 \gamma^2 \Delta t^2 \omega^2 \Big) + \\
& \frac{1}{\eta_2 \eta_3} \dot{x}_t \Big(-4 \Delta t + 4 \beta_2 \gamma \Delta t^3 \omega^2 - 4 \beta_2^2 \gamma \Delta t^3 \omega^2 + \gamma^2 \Delta t^3 \omega^2 - 10 \beta_2 \gamma^2 \Delta t^3 \omega^2 + \\
& 4 \beta_1 \beta_2 \gamma^2 \Delta t^3 \omega^2 + 8 \beta_2^2 \gamma^2 \Delta t^3 \omega^2 - 2 \gamma^3 \Delta t^3 \omega^2 + 2 \beta_1 \gamma^3 \Delta t^3 \omega^2 + \\
& 6 \beta_2 \gamma^3 \Delta t^3 \omega^2 - 4 \beta_1 \beta_2 \gamma^3 \Delta t^3 \omega^2 - 4 \beta_2^2 \gamma^3 \Delta t^3 \omega^2 \Big) + \frac{1}{\eta_2 \eta_3} \\
& r_{t+\Delta t} \Big(-4 \beta_2^2 \Delta t^2 + 8 \beta_2^2 \gamma \Delta t^2 - 4 \beta_2^2 \gamma^2 \Delta t^2 - \beta_2^2 \gamma^2 \Delta t^4 \omega^2 + 2 \beta_2^2 \gamma^3 \Delta t^4 \omega^2 - \beta_2^2 \gamma^4 \Delta t^4 \omega^2 \Big) + \\
& \frac{1}{\eta_2 \eta_3} x_t \Big(-2 \gamma \Delta t^2 - 2 \beta_2 \gamma \Delta t^2 + 4 \beta_1 \beta_2 \gamma \Delta t^2 + 2 \gamma^2 \Delta t^2 - 2 \beta_1 \gamma^2 \Delta t^2 + 2 \beta_2 \gamma^2 \Delta t^2 - \\
& 4 \beta_1 \beta_2 \gamma^2 \Delta t^2 + \beta_2 \gamma^2 \Delta t^4 \omega^2 - \beta_2^2 \gamma^2 \Delta t^4 \omega^2 - 3 \beta_2 \gamma^3 \Delta t^4 \omega^2 + 2 \beta_1 \beta_2 \gamma^3 \Delta t^4 \omega^2 + \\
& 2 \beta_2^2 \gamma^3 \Delta t^4 \omega^2 + 2 \beta_2 \gamma^4 \Delta t^4 \omega^2 - 2 \beta_1 \beta_2 \gamma^4 \Delta t^4 \omega^2 - \beta_2^2 \gamma^4 \Delta t^4 \omega^2 \Big) + \frac{1}{\eta_2 \eta_3} \\
& \Big(4 x_{t+\Delta t} + 4 x_{t+\Delta t} \beta_2^2 \Delta t^2 \omega^2 - 8 x_{t+\Delta t} \beta_2^2 \gamma \Delta t^2 \omega^2 + x_{t+\Delta t} \gamma^2 \Delta t^2 \omega^2 + 4 x_{t+\Delta t} \beta_2^2 \gamma^2 \Delta t^2 \omega^2 + \\
& x_{t+\Delta t} \beta_2^2 \gamma^2 \Delta t^4 \omega^4 - 2 x_{t+\Delta t} \beta_2^2 \gamma^3 \Delta t^4 \omega^4 + x_{t+\Delta t} \beta_2^2 \gamma^4 \Delta t^4 \omega^4 \Big) \Big\}
\end{aligned}$$

a =

$$\begin{pmatrix} \text{Coefficient}[\text{Part}[\text{recursive}, 1], \dot{x}_t] & \text{Coefficient}[\text{Part}[\text{recursive}, 1], x_t] & \text{Coeff} \\ \text{Coefficient}[\text{Part}[\text{recursive}, 2], \dot{x}_t] & \text{Coefficient}[\text{Part}[\text{recursive}, 2], x_t] & \text{Coeff} \\ \text{Coefficient}[\text{Part}[\text{recursive}, 3], \dot{x}_t] & \text{Coefficient}[\text{Part}[\text{recursive}, 3], x_t] & \text{Coeff} \end{pmatrix};$$

a // MatrixForm // Simplify

$$\begin{pmatrix} -\frac{\gamma \Delta t^2 \omega^2 (2+2(-1+\beta_1) \gamma + \beta_2^2 (-1+\gamma)^2 \gamma \Delta t^2 \omega^2 + \beta_2 (-1+\gamma) (-2+\gamma \Delta t^2 \omega^2 - 2 \gamma^2 \Delta t^2 \omega^2 + 2 \beta_1 (2+\gamma^2 \Delta t^2 \omega^2)))}{\eta_2 \eta_3} \\ \frac{\gamma \Delta t (4+2 \beta_2^2 (-1+\gamma)^2 \Delta t^2 \omega^2 - \gamma \Delta t^2 \omega^2 + 2 \gamma^2 \Delta t^2 \omega^2 + \beta_2 (-2+5 \gamma - 3 \gamma^2) \Delta t^2 \omega^2 + 2 \beta_1 (-2+\beta_2 (-1+\gamma) \gamma \Delta t^2 \omega^2 - \gamma^2 \Delta t^2 \omega^2))}{\eta_2 \eta_3} & \frac{4-4 \gamma \Delta t^2 \omega^2 + (5-}{\eta_2 \eta_3} \\ \frac{\gamma \Delta t^2 (2+2(-1+\beta_1) \gamma + \beta_2^2 (-1+\gamma)^2 \gamma \Delta t^2 \omega^2 + \beta_2 (-1+\gamma) (-2+\gamma \Delta t^2 \omega^2 - 2 \gamma^2 \Delta t^2 \omega^2 + 2 \beta_1 (2+\gamma^2 \Delta t^2 \omega^2)))}{\eta_2 \eta_3} & \frac{\Delta t}{\eta_2 \eta_3} \end{pmatrix}$$

$$\text{la} = - \begin{pmatrix} \text{Coefficient}[\text{Part}[\text{recursive}, 1], r_{t+\gamma \Delta t}] \\ \text{Coefficient}[\text{Part}[\text{recursive}, 2], r_{t+\gamma \Delta t}] \\ \text{Coefficient}[\text{Part}[\text{recursive}, 3], r_{t+\gamma \Delta t}] \end{pmatrix};$$

la // MatrixForm // Simplify

$$\begin{pmatrix} \frac{2 (2 \beta_2 (-1+\gamma)-\gamma) (1+\beta_2 (-1+\gamma)+(-1+\beta_1) \gamma) \Delta t^2 \omega^2}{(1+\beta_2^2 (-1+\gamma)^2 \Delta t^2 \omega^2) (4+\gamma^2 \Delta t^2 \omega^2)} \\ \frac{2 (1+\beta_2 (-1+\gamma)+(-1+\beta_1) \gamma) \Delta t (2+\beta_2 (-1+\gamma) \gamma \Delta t^2 \omega^2)}{(1+\beta_2^2 (-1+\gamma)^2 \Delta t^2 \omega^2) (4+\gamma^2 \Delta t^2 \omega^2)} \\ - \frac{2 (2 \beta_2 (-1+\gamma)-\gamma) (1+\beta_2 (-1+\gamma)+(-1+\beta_1) \gamma) \Delta t^2}{(1+\beta_2^2 (-1+\gamma)^2 \Delta t^2 \omega^2) (4+\gamma^2 \Delta t^2 \omega^2)} \end{pmatrix}$$

$$\mathbf{lb} = - \begin{pmatrix} \text{Coefficient}[\text{Part}[\text{recursive}, 1], \mathbf{r}_{t+\Delta t}] \\ \text{Coefficient}[\text{Part}[\text{recursive}, 2], \mathbf{r}_{t+\Delta t}] \\ \text{Coefficient}[\text{Part}[\text{recursive}, 3], \mathbf{r}_{t+\Delta t}] \end{pmatrix};$$

lb // MatrixForm // Simplify

$$\begin{pmatrix} \frac{1}{1+\beta_2^2 (-1+\gamma)^2 \Delta t^2 \omega^2} \\ - \frac{\beta_2 (-1+\gamma) \Delta t}{1+\beta_2^2 (-1+\gamma)^2 \Delta t^2 \omega^2} \\ \frac{\beta_2^2 (-1+\gamma)^2 \Delta t^2}{1+\beta_2^2 (-1+\gamma)^2 \Delta t^2 \omega^2} \end{pmatrix}$$

eigA = Eigenvalues[a];

eigA // MatrixForm // Simplify

$$\begin{pmatrix} -4+4 \beta_2 \Delta t^2 \omega^2-4 \beta_2^2 \Delta t^2 \omega^2+4 \gamma \Delta t^2 \omega^2-8 \beta_2 \gamma \Delta t^2 \omega^2+8 \beta_2^2 \gamma \Delta t^2 \omega^2-5 \gamma^2 \Delta t^2 \omega^2+4 \beta_1 \gamma^2 \Delta t^2 \omega^2+4 \beta_2 \gamma^2 \Delta t^2 \omega^2-4 \beta_2^2 \gamma^2 \Delta t^2 \omega^2-\beta_2 \gamma^2 \Delta t^4 \omega^4. \\ 4-4 \beta_2 \Delta t^2 \omega^2+4 \beta_2^2 \Delta t^2 \omega^2-4 \gamma \Delta t^2 \omega^2+8 \beta_2 \gamma \Delta t^2 \omega^2-8 \beta_2^2 \gamma \Delta t^2 \omega^2+5 \gamma^2 \Delta t^2 \omega^2-4 \beta_1 \gamma^2 \Delta t^2 \omega^2-4 \beta_2 \gamma^2 \Delta t^2 \omega^2+4 \beta_2^2 \gamma^2 \Delta t^2 \omega^2+\beta_2 \gamma^2 \Delta t^4 \omega^4-f \end{pmatrix}$$

$\xi = 0;$

$\omega = 2 \text{ Pi} / \mathbf{T};$

$\lambda_1 = \text{Part}[\text{eigA}, 2] /. \mathbf{T} \rightarrow 1 // \text{Simplify} // \text{Apart}$

$$\begin{aligned} & - \frac{1 - \beta_2 - 2 \gamma + 2 \beta_1 \gamma + \beta_2 \gamma}{\beta_2 (-1 + \gamma)} + \frac{4 (1 - \beta_2 - \gamma + \beta_1 \gamma + \beta_2 \gamma)}{(-2 \beta_2 + \gamma + 2 \beta_2 \gamma) (1 + p^2 \pi^2 \gamma^2)} + \\ & \left(2 \beta_2 + \gamma - 4 \beta_2 \gamma - 2 \gamma^2 + 2 \beta_1 \gamma^2 + 2 \beta_2 \gamma^2 \right) / \\ & \left(\beta_2 (-1 + \gamma) (-2 \beta_2 + \gamma + 2 \beta_2 \gamma) (1 + 4 p^2 \pi^2 \beta_2^2 - 8 p^2 \pi^2 \beta_2^2 \gamma + 4 p^2 \pi^2 \beta_2^2 \gamma^2) \right) + \\ & \left(2 \pi \gamma^2 \sqrt{\left(- (p + p^3 \pi^2 \gamma \right. \right.} \right. \\ & \quad \left. \left. \left(4 \beta_2^2 (-1 + \gamma)^2 + \gamma (-1 - 2 (-1 + \beta_1) \gamma) + 2 \beta_2 (-1 + \gamma) (2 + (-3 + 2 \beta_1) \gamma) \right) \right)^2} \right) / \\ & \left((1 + p^2 \pi^2 \gamma^2) (4 \beta_2^2 - 8 \beta_2^2 \gamma - \gamma^2 + 4 \beta_2^2 \gamma^2) \right) - \left(8 \pi \beta_2^2 \sqrt{\left(- (p + p^3 \pi^2 \gamma \right. \right.} \right. \\ & \quad \left. \left. \left(4 \beta_2^2 (-1 + \gamma)^2 + \gamma (-1 - 2 (-1 + \beta_1) \gamma) + 2 \beta_2 (-1 + \gamma) (2 + (-3 + 2 \beta_1) \gamma) \right) \right) \right)^2} \right) / \\ & \left((4 \beta_2^2 - 8 \beta_2^2 \gamma - \gamma^2 + 4 \beta_2^2 \gamma^2) (1 + 4 p^2 \pi^2 \beta_2^2 - 8 p^2 \pi^2 \beta_2^2 \gamma + 4 p^2 \pi^2 \beta_2^2 \gamma^2) \right) + \\ & \left(16 \pi \beta_2^2 \gamma \sqrt{\left(- (p + p^3 \pi^2 \gamma \right. \right.} \right. \\ & \quad \left. \left. \left(4 \beta_2^2 (-1 + \gamma)^2 + \gamma (-1 - 2 (-1 + \beta_1) \gamma) + 2 \beta_2 (-1 + \gamma) (2 + (-3 + 2 \beta_1) \gamma) \right) \right) \right)^2} \right) / \\ & \left((4 \beta_2^2 - 8 \beta_2^2 \gamma - \gamma^2 + 4 \beta_2^2 \gamma^2) (1 + 4 p^2 \pi^2 \beta_2^2 - 8 p^2 \pi^2 \beta_2^2 \gamma + 4 p^2 \pi^2 \beta_2^2 \gamma^2) \right) - \\ & \left(8 \pi \beta_2^2 \gamma^2 \sqrt{\left(- (p + p^3 \pi^2 \gamma \right. \right.} \right. \\ & \quad \left. \left. \left(4 \beta_2^2 (-1 + \gamma)^2 + \gamma (-1 - 2 (-1 + \beta_1) \gamma) + 2 \beta_2 (-1 + \gamma) (2 + (-3 + 2 \beta_1) \gamma) \right) \right) \right)^2} \right) / \\ & \left((4 \beta_2^2 - 8 \beta_2^2 \gamma - \gamma^2 + 4 \beta_2^2 \gamma^2) (1 + 4 p^2 \pi^2 \beta_2^2 - 8 p^2 \pi^2 \beta_2^2 \gamma + 4 p^2 \pi^2 \beta_2^2 \gamma^2) \right) \end{aligned}$$

$$pe = \frac{\Omega_o}{\bar{\Omega}_d} - 1$$

$$-1 + \frac{\Omega_o}{\bar{\Omega}_d}$$

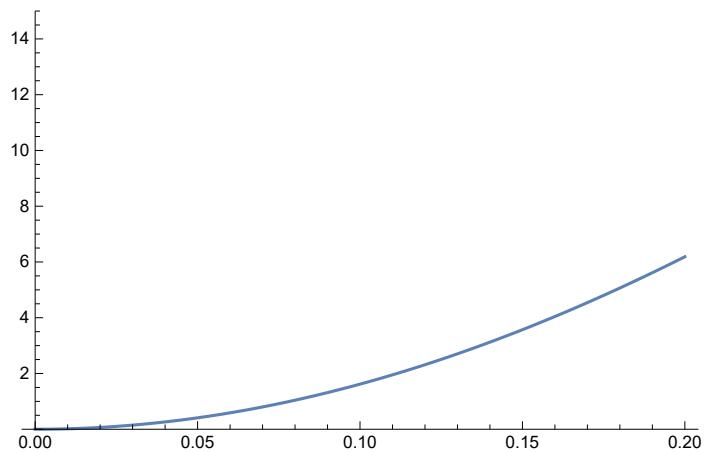
$$\Omega_o = \omega \Delta t /. \frac{\Delta t}{T} \rightarrow p$$

$$2 p \pi$$

$$\bar{\Omega}_d = \text{ArcTan}\left[\frac{2 \pi \sqrt{p^2 (-36 + 5 p^2 \pi^2)^2}}{36 - 47 p^2 \pi^2}\right] \text{ (*simply copy paste this from above*)}$$

$$\text{ArcTan}\left[\frac{2 \pi \sqrt{p^2 (-36 + 5 p^2 \pi^2)^2}}{36 - 47 p^2 \pi^2}\right]$$

`Plot[(pe) * 100, {p, 0, .2}, PlotRange -> {0, 20}]`



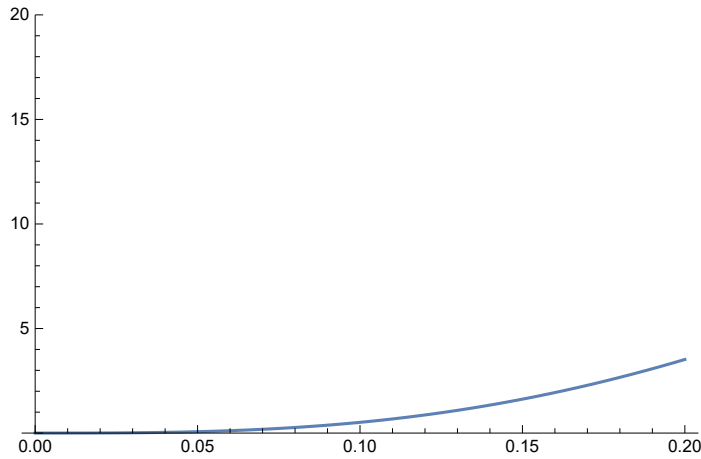
$$AD = 1 - \text{Exp}\left[-2 p i \bar{\xi} \frac{\Omega_o}{\bar{\Omega}_d}\right]$$

$$1 - \text{Abs}\left[\frac{36 - 47 p^2 \pi^2 - 2 \pi \sqrt{-p^2 (-36 + 5 p^2 \pi^2)^2}}{(4 + p^2 \pi^2) (9 + 4 p^2 \pi^2)}\right] \frac{2 \pi}{\text{ArcTan}\left[\frac{2 \pi \sqrt{-p^2 (-36 + 5 p^2 \pi^2)^2}}{36 - 47 p^2 \pi^2}\right]}$$

$$\bar{\xi} = -\frac{1}{\Omega_o} \text{Log}[\text{Abs}[\lambda_1]]$$

$$-\frac{\text{Log}\left[\text{Abs}\left[\frac{36 - 47 p^2 \pi^2 - 2 \pi \sqrt{-p^2 (-36 + 5 p^2 \pi^2)^2}}{(4 + p^2 \pi^2) (9 + 4 p^2 \pi^2)}\right]\right]}{2 p \pi}$$


```
Plot[(AD) * 100, {p, 0, .2}, PlotRange -> {0, 20}]
```



$$\mathbf{aNot} = - \begin{pmatrix} \text{Coefficient}[\text{Part}[\text{recursive}, 2], \dot{\mathbf{x}}_t] & \text{Coefficient}[\text{Part}[\text{recursive}, 2], \mathbf{x}_t] \\ \text{Coefficient}[\text{Part}[\text{recursive}, 3], \dot{\mathbf{x}}_t] & \text{Coefficient}[\text{Part}[\text{recursive}, 3], \mathbf{x}_t] \end{pmatrix}$$

$$\left\{ \left\{ \frac{144}{\left(9 + \frac{4\pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4\pi^2 \Delta t^2}{T^2}\right)} - \frac{188\pi^2 \Delta t^2}{T^2 \left(9 + \frac{4\pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4\pi^2 \Delta t^2}{T^2}\right)}, \right. \right. \\ \left. - \frac{384\pi^2 \Delta t}{T^2 \left(9 + \frac{4\pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4\pi^2 \Delta t^2}{T^2}\right)} + \frac{16\pi^4 \Delta t^3}{T^4 \left(9 + \frac{4\pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4\pi^2 \Delta t^2}{T^2}\right)} \right\}, \\ \left\{ \frac{144 \Delta t}{\left(9 + \frac{4\pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4\pi^2 \Delta t^2}{T^2}\right)} - \frac{20\pi^2 \Delta t^3}{T^2 \left(9 + \frac{4\pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4\pi^2 \Delta t^2}{T^2}\right)}, \right. \\ \left. \frac{144}{\left(9 + \frac{4\pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4\pi^2 \Delta t^2}{T^2}\right)} - \frac{76\pi^2 \Delta t^2}{T^2 \left(9 + \frac{4\pi^2 \Delta t^2}{T^2}\right) \left(16 + \frac{4\pi^2 \Delta t^2}{T^2}\right)} \right\} \right\}$$

```
eigaNot = Eigenvalues[aNot] /. Dt -> p T // Expand // Simplify // Cancel;
```

```
ppp = {0, Part[eigaNot, 1], Part[eigaNot, 2]}
```

$$\left\{ 0, \frac{36 T^4 - 33 p^2 \pi^2 T^4 - 2 \pi \sqrt{-p^2 (864 - 205 p^2 \pi^2 + 5 p^4 \pi^4)} T^8}{(4 + p^2 \pi^2) (9 + 4 p^2 \pi^2) T^4}, \right. \\ \left. \frac{36 T^4 - 33 p^2 \pi^2 T^4 + 2 \pi \sqrt{-p^2 (864 - 205 p^2 \pi^2 + 5 p^4 \pi^4)} T^8}{(4 + p^2 \pi^2) (9 + 4 p^2 \pi^2) T^4} \right\}$$

```
qqq = eiga
```

$$\left\{ 0, \frac{36 T^4 - 47 p^2 \pi^2 T^4 - 2 \pi \sqrt{-p^2 (-36 + 5 p^2 \pi^2)^2} T^8}{(4 + p^2 \pi^2) (9 + 4 p^2 \pi^2) T^4}, \right. \\ \left. \frac{36 T^4 - 47 p^2 \pi^2 T^4 + 2 \pi \sqrt{-p^2 (-36 + 5 p^2 \pi^2)^2} T^8}{(4 + p^2 \pi^2) (9 + 4 p^2 \pi^2) T^4} \right\}$$

ppp - qq q // Simplify

$$\left\{ 0, \frac{2 \pi \left(7 p^2 \pi T^4 + \sqrt{-p^2 \left(-36 + 5 p^2 \pi^2 \right)^2 T^8} - \sqrt{-p^2 \left(864 - 205 p^2 \pi^2 + 5 p^4 \pi^4 \right) T^8} \right)}{\left(4 + p^2 \pi^2 \right) \left(9 + 4 p^2 \pi^2 \right) T^4}, \right. \\ \left. \frac{2 \pi \left(7 p^2 \pi T^4 - \sqrt{-p^2 \left(-36 + 5 p^2 \pi^2 \right)^2 T^8} + \sqrt{-p^2 \left(864 - 205 p^2 \pi^2 + 5 p^4 \pi^4 \right) T^8} \right)}{\left(4 + p^2 \pi^2 \right) \left(9 + 4 p^2 \pi^2 \right) T^4} \right\}$$