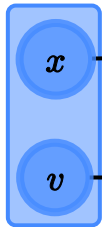


*input*

$$* = \sigma(w_*^T * + b_*)$$

*output*

$\zeta_x$



$\times d$   
 $\dots$



$$s_x = \alpha_s \tanh(w_s^T z_d + b_s)$$

$$t_x = w_t^T z_d + b_t$$

$$q_x = \alpha_q \tanh(w_q^T z_d + b_q)$$