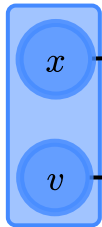


input

$$* = \sigma(w_*^T * + b_*)$$

output

ζ_x



x

v

$+$

z_1

$\times d$
 \dots

z_d

$$s_x = \alpha_s \tanh(w_s^T z_d + b_s)$$

$$t_x = w_t^T z_d + b_t$$

$$q_x = \alpha_q \tanh(w_q^T z_d + b_q)$$