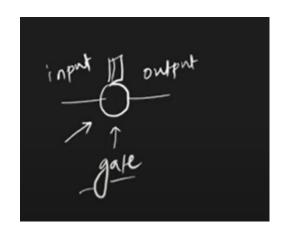
## **Activation Function**

• In artificial neural networks, each neuron forms a weighted sum of its inputs and passes the resulting scalar value through a function referred to as an activation function or transfer function. If a neuron has n inputs then the output or activation of a neuron is

$$a = g(w_1x_1 + w_2x_2 + w_3x_3 + \dots w_nx_n + b)$$

This function g is referred to as the activation function."



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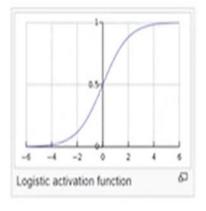
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#### Activation function

From Wikipedia, the free encyclopedia

For the formalism used to approximate the influence of an extracellular electrical field on neurons, see activating function. For a linear system's transfer function, see transfer function.

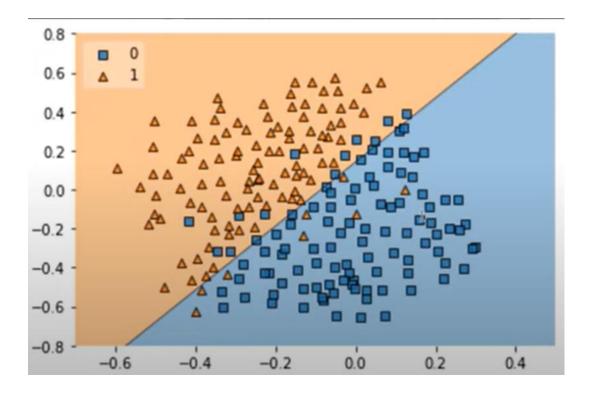
in artificial neural networks, each neuron forms a weighted sum of its inputs and passes the resulting scalar value through a function referred to as an activation function or transfer function. If a neuron has n inputs  $x_1, x_2, \dots x_n$  then the output or activation of a neuron is  $a = g(w_1x_1 + w_2x_2 + w_3x_3 + \dots + w_nx_n + b)$ . This function gis referred to as the activation function. If the function g is taken as the linear function g(z) = z then the neuron performs linear regression or classification. In general g is taken to be a nonlinear function to do nonlinear regression and solve classification problems that are not linearly separable. When g is taken to be a sigmoidal or 's' shaped function varying from 0 to 1 or -1 to 1, the output value of the neuron can be interpreted as a YES/NO answer or binary decision. However saturating activation function can cause the vanishing gradient problem in deep networks. Replacing saturating sigmoidal activation functions with activation functions like ReLU that have larger derivative values allowed deeper networks to be trained for the first time. Non-monotonic and oscillating activation functions that significantly outperform ReLU have since been found.[1] In particular oscillating activation functions improve gradient flow, speedup training and allow single neurons to learn the XOR function like certain human cerebral neurons. [2][3]

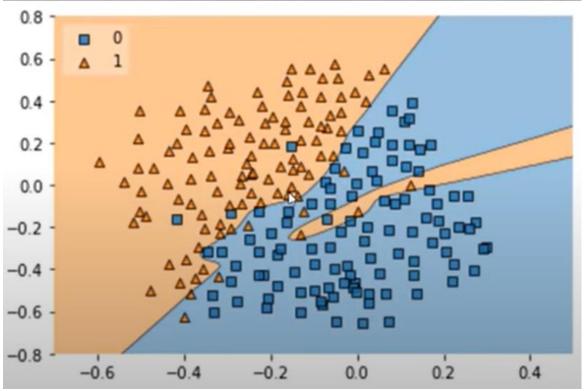


#### Contents [hide]

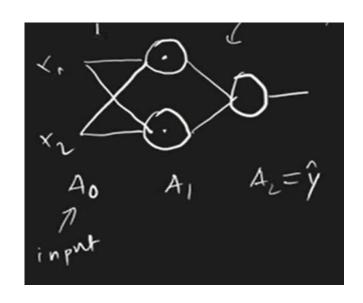
- Classification of activation functions
  - 1.1 Ridge activation functions
  - 1.2 Radial activation functions
  - 1.3 Folding activation functions
- 2 Comparison of activation functions
  - 2.1 Table of activation functions
- 3 See also
- 4 References

Print/export





# Why activation function needed?



Non linear

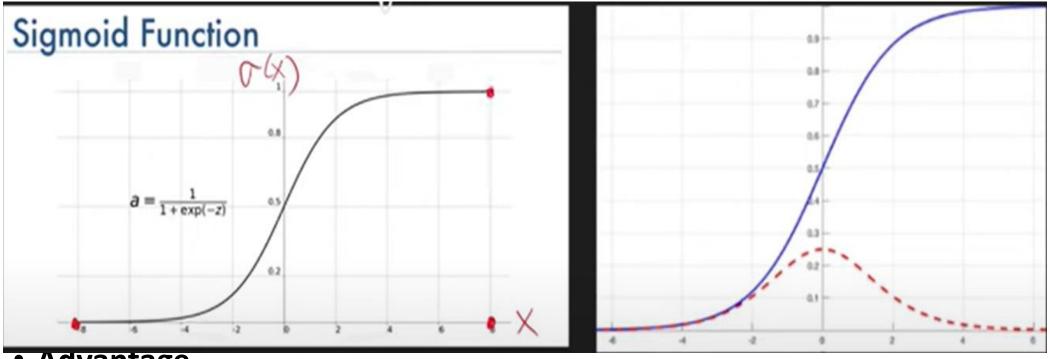
• Differentiable

Computationaly inexpensive

Zero-centerd (Normalized)

- None Saturating
  - Vanishing gardient

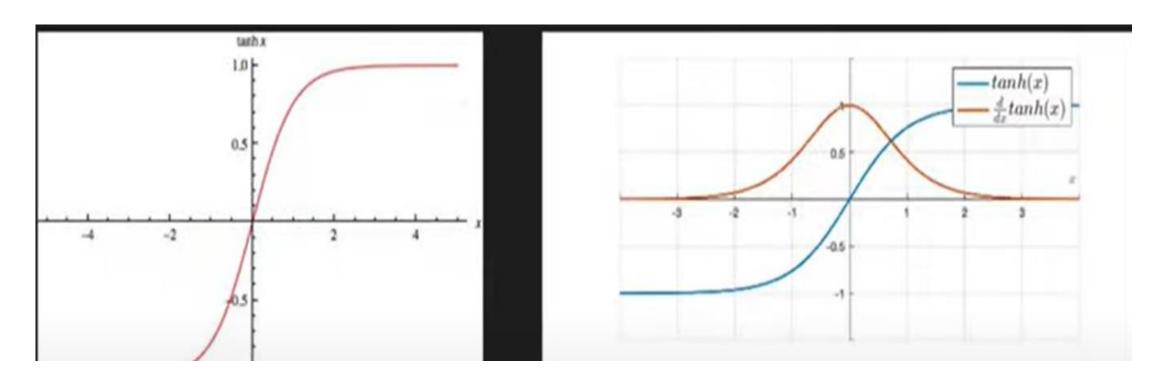
## Sigmoid Activation Function



- Advantage
- [0,1], non linear function, differentiable
- Disadvantage
- Saturating function, Not used in hidden layers, used in output layer
- None zero centerd → slow convergence
- Computationaly expensive



## Tanh Activation Function



$$f(x) = \frac{(e^{x} - e^{-x})}{e^{x} + e^{-x}}$$

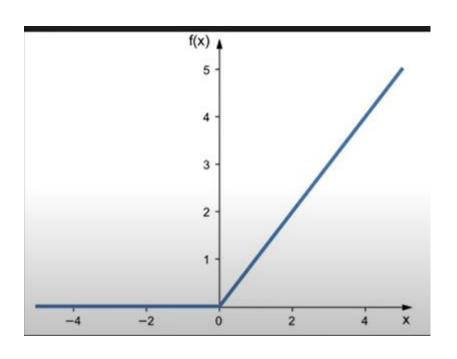
### Advantages:

- Non Linear
- Differentiable
- Zreo-centered

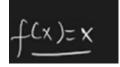
## • Disadvantages:

- Saturating function → vanishing Gradient problem
- Computationally Expensive → slow

## Relu Activation Function







#### Advantage:

- Non Linear
- Non saturated in +ve region
- Computationally Inexpensive
- Convergence → faster

Disadvantabe

Not completely differentiable

 $X<0 \rightarrow 0$ 

 $X>0 \rightarrow 1$ 

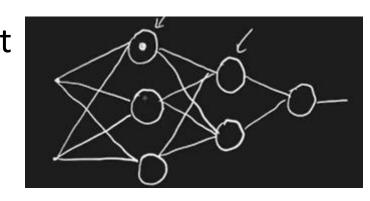
Not zero centered → batch normalization

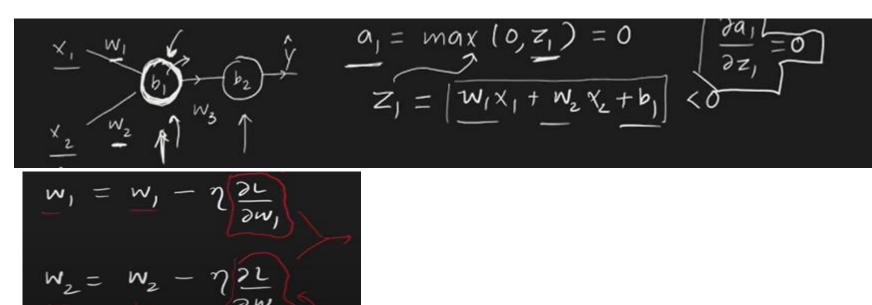
Dying relu problem

Best choice for hidden Layers

# Dying Relu Problem

Relu → vanishing Gradient problem → ouput
 Of some neuron become zero, whatever the
 Input is → Dead Neuron





$$\frac{\partial L}{\partial w_1} = \frac{\partial L}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial q_1} \frac{\partial q_1}{\partial z_1} \frac{\partial z_1}{\partial w_1}$$

$$\frac{\partial L}{\partial w_2} = \frac{\partial L}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial q_1} \frac{\partial q_1}{\partial z_1} \frac{\partial z_1}{\partial w_2}$$

$$\frac{\partial L}{\partial w_2} = \frac{\partial L}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial q_1} \frac{\partial q_1}{\partial z_1} \frac{\partial z_1}{\partial w_2}$$

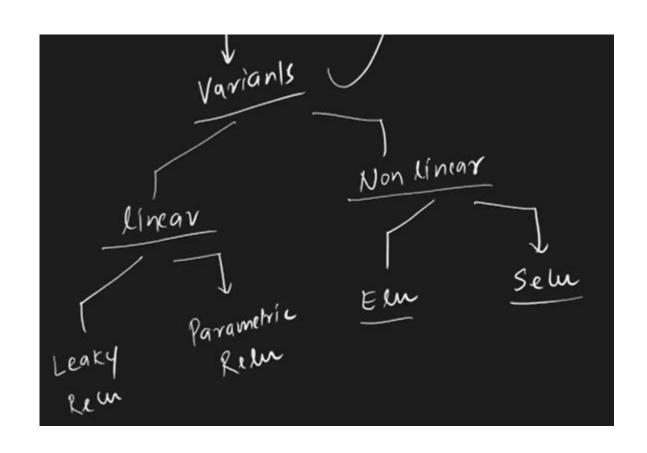
$$z_1 = W_1 X_1 + W_2 X_2 + b_1 < 0$$

- Reason of become negative
  - Learning Rate become very high
  - High negative bias

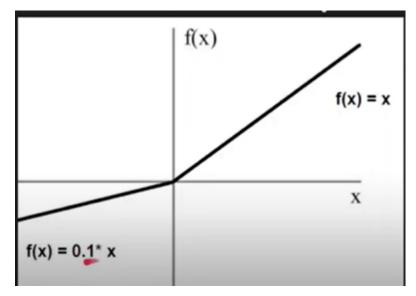
## Solutions:

- Set Low learning rate
- Set +ve value of bias → 0.01
- Don't use Relu > use its variants

•



## Leaky Relu



$$f(z) = \max(0.0|z,z)$$

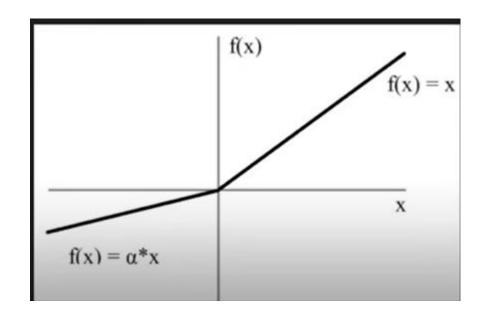
$$f'(z) = \sum_{z \neq 0} \sqrt{1}$$

Non saturated

#### Easily computed

- No dying
- Close to zero

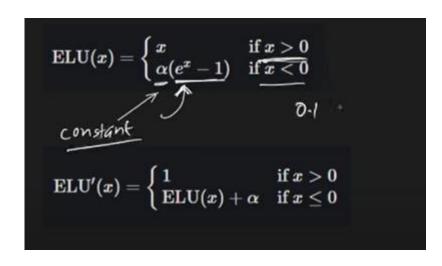
## Parmetric Relu



$$f(x) = \begin{cases} x & \text{if } x > 0 \\ \underline{ax} & \text{otherwise} \\ 0.01x \end{cases}$$

a is traninable parameter

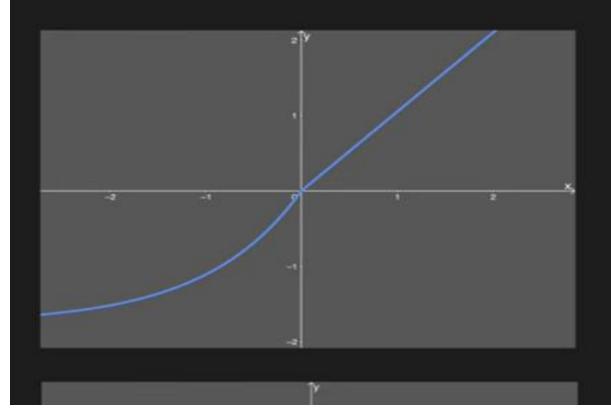
# Elu - Exponential Linear Unit



- Close to zero center faster
- Always continues and differentiable
- Computationally inexpensive

#### Selu - Scaled Exponential Linear Unit

09 June 2022 0



$$ext{SELU}(x) = \lambda egin{cases} x & ext{if } x > 0 \ lpha e^x - lpha & ext{if } x \leq 0 \end{cases}$$

 $a \approx 1.6732632423543772848170429916717$ 

 $\lambda \approx 1.0507009873554804934193349852946$ 

$$ext{SELU}'(x) = \lambda \left\{ egin{array}{ll} 1 & ext{if } x > 0 \ lpha e^x & ext{if } x \leq 0 \end{array} 
ight.$$

- Self normalize
- Mean → zero standard deviation =1