#### Samir Yitzhak Gadre

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#### Research interests

Pre-training: datasets, language and multimodal modeling, scaling

#### Research summary

I study large-scale dataset construction and model training with an emphasis on understanding how model performance improves predictably with better datasets and bigger models. Nowadays, I investigate these interests in the context of multimodal models (e.g., DataComp) and language models (e.g., OpenLM).

#### Education

Sept 2020–Present Columbia University, Computer Science Ph.D. candidate, GPA: 4.0,

Advisor: Professor Shuran Song (now @ Stanford)

Sept 2014–May 2018 Brown University, Computer Science Sc.B. w/ Honors, CS GPA: 3.94,

Advisors: Professors George Konidaris & Stefanie Tellex Thesis: Teaching Robots Using Mixed Reality. [pdf] [video]

### Awards and grants

Mar 2022–Present NSF graduate research fellow

Sept 2020–Present Presidential fellow, Columbia University

May 2022 CS departmental service award, Columbia University

May 2018 Sigma Xi honors society inductee, Brown University

June 2016 Undergraduate teaching and research award, Brown University

## Publications and technical reports

(\* denotes equal contribution)

Pre-print 2024 Language models scale reliably with over-training and on downstream

tasks.

S. Y. Gadre, G. Smyrnis, V. Shankar, S. Gururangan, M. Wortsman, R. Shao, J. Mercat, A. Fang, J. Li, S. Keh, R. Xin, M. Nezhurina, I. Vasiljevic, J. Jitsev, A. G. Dimakis, G. Ilharco, S. Song, T. Kollar, Y. Carmon\*, A. Dave\*, R. Heckel\*, N. Muennighoff\*, L. Schmidt\*. [arXiv]

[code]

NeurIPS 2023 (oral) DataComp: In search of the next generation of multimodal datasets.

S. Y. Gadre\*, G. Ilharco\*, A. Fang\*, J. Hayase, G. Smyrnis, T. Nguyen,

R. Marten, M. Wortsman, D. Ghosh, J. Zhang, E. Orgad, R. Entezari, G. Daras, S. Pratt, V. Ramanujan, Y. Bitton, K. Marathe, S. Mussmann, R. Vencu, M. Cherti, R. Krishna, P. W. Koh, O. Saukh, A. Ratner, S. Song, H. Hajishirzi, A. Farhadi, R. Beaumont, S. Oh, A. Dimakis, J. Jitsev, Y. Carmon, V. Shankar, L. Schmidt. [arXiv] [website] [code]

NeurIPS 2023 Multimodal C4: An open, billion-scale corpus of images interleaved with text.

W. Zhu\*, J. Hessel\*, A. Awadalla, S. Y. Gadre, J. Dodge, A. Fang, Y. Yu, L. Schmidt, W. Y. Wang, Y. Choi. [arXiv] [code]

NeurIPS 2023 Objaverse-XL: A wniverse of 10M+ 3D objects.

M. Deitke, R. Liu, M. Wallingford, H. Ngo, O. Michel, A. Kusupati, A. Fan, C. Laforte, V. Voleti, S. Y. Gadre, E. VanderBilt, A. Kembhavi, C. Vondrick, G. Gkioxari, K. Ehsani, L. Schmidt\*, A. Farhadi\*. [arXiv] [website] [code]

NeurIPS 2023 Improving multimodal datasets with image captioning.
T. Nguyen, S. Y. Gadre, G. Ilharco, S. Oh, L. Schmidt. [arXiv]

Tech Report 2023 OpenFlamingo: An open-source framework for training large autoregressive vision-language models.

A. Awadalla\*, I. Gao\*, J. Gardner, J. Hessel, Y. Hanafy, W. Zhu, K. Marathe, Y. Bitton, S. Y. Gadre, S. Sagawa, J. Jitsev, S. Kornblith, P. W. Koh, G. Ilharco, M. Wortsman, L. Schmidt. [arXiv] [code]

Tech Report 2023 OpenLM: a minimal but performative language modeling repository.

S. Gururangan\*, M. Wortsman\*, S. Y. Gadre\*, A. Dave\*, M. Kilian, W. Shi, J. Mercat, G. Smyrnis, G. Ilharco, M. Jordan, R. Heckel, A. Dimakis, A. Farhadi, V. Shankar\*, L. Schmidt. [blog] [code]

IROS 2023 Structure From Action: Learning interactions for articulated object 3D structure discovery.

N. Nie, S. Y. Gadre, K. Ehsani, S. Song. [arXiv] [website]

CVPR 2023 CoWs on Pasture: Baselines and benchmarks for language-driven zeroshot object navigation.

S. Y. Gadre, M. Wortsman, G. Ilharco, L. Schmidt, S. Song. [arXiv] [website] [code]

NeurIPS 2022 Patching open-vocabulary models by interpolating weights.

G. Ilharco\*, M. Wortsman\*, S. Y. Gadre\*, S. Song, H. Hajishirzi, S. Kornblith, A. Farhadi, L. Schmidt. [arXiv] [website] [code]

ICML 2022 Model soups: Averaging weights of multiple fine-tuned models improves accuracy without increasing inference time.

M. Wortsman, G. Illharco, S. Y. Gadre, R. Roelofs, R. Gontijo-Lopes, A. S. Morcos, H. Namkoong, A. Farhadi, Y. Carmon\*, S. Kornblith\*, L. Schmidt\*. [arXiv] [code]

CVPR 2022 Continuous scene representations for embodied AI.

S. Y. Gadre, K. Ehsani, S. Song, R. Mottaghi. [arXiv] [website] [code]

ICCV 2021 Act the Part: Learning interaction strategies for articulated object part

discovery.

S. Y. Gadre, K. Ehsani, S. Song. [arXiv] [website]

ICRA 2019 End-user robot programming using mixed reality.

S. Y. Gadre, E. Rosen, G. Chien, E. Phillips, S. Tellex, G. Konidaris.

[pdf] [video]

### Research experience

Sept 2020–Present Columbia University, Graduate researcher

Advisor: Professor Shuran Song

Multimodal computer vision, natural language processing, and robotics.

May-Aug 2022 Allen Institute for Artificial Intelligence (AI2), Research intern

Advisors: Professor Roozbeh Mottaghi & Dr. Kiana Ehsani

How can open-vocabulary models bridge the simulation to reality gap?

June–Dec 2021 Allen Institute for Artificial Intelligence (AI2), Research intern

Advisors: Professor Roozbeh Mottaghi & Dr. Kiana Ehsani

Worked on learning scene representations to support a wide range of

downstream embodied and vision tasks.

Sept 2017–July 2018 Brown University, Robotics researcher & honors candidate

Advisors: Professors George Konidaris & Stefanie Tellex

Investigated mixed reality interfaces to allow novice users to use holo-

grams to program and teach robots.

May-Aug 2016 Brown University, Computer Vision researcher

Advisor: Professor Benjamin Kimia

Worked on visual odometry and camera pose estimation.

### Industry experience

Feb 2019–Aug 2020 Microsoft HoloLens, Software Engineer II

Manager: Dr. Harpreet Sawhney

Worked on object detection and 6DoF object pose estimation for Azure

Object Anchors, which I helped to ship.

# Teaching experience

Jan–May 2021	Robot Learning, Columbia University, Graduate TA
Sept-Dec 2020	Computational Robotics, Columbia University, Graduate TA
Jan–May 2018	Algorithms & Data Structures, Brown University, TA
Sept-Dec 2016	Object Oriented Programming, Brown University, TA

#### **Invited Talks**

IBM Research, Zurich April 2024 The pre-trainer's toolkit: Dataset construction, model training, & scaling Data, intelligence, and computation in engineering lab @ NYU Oct 2023 DataComp: In search of the next generation of multimodal datasets June 2023 CVPR 2023 workshop on 3D scene understanding for vision, graphics, and robotics CoWs on Pasture: Baselines and benchmarks for language-driven zeroshot object navigation. [slides] [website] CVPR 2022 tutorial on vision-based robot learning. June 2022 No Training? Towards Adapting Zero-Shot Models to Robotics Tasks [slides] [website] University of Washington robotics colloquium Oct 2018 Virtual and Mixed Reality Interfaces for Human-Robot Interaction. [website] Service Reviewer, ECCV (2020), CVPR (2023), ICLR (2023), ICML (2022, July 2020-Present 2023, 2024), IROS (2022), ICRA (2023), NeurIPS (2023) CVPR diversity, equity, and inclusion (DEI) committee, Member April–June 2022 Reviewed CVPR registration fee waivers with an emphasis on improving CVPR's accessibility to underrepresented groups. Sept-Dec 2021 Columbia Pre-submission Application Review (PAR), Co-organizer In charge of outreach efforts with a focus on recruiting underrepresented applicants. Women in Science at Columbia (WiSC), Mentor Sept 2020-May 2021 Met weekly with mentee to provide academic advise and help prepare for internship interviews. Sept-Dec 2020 Columbia Pre-submission Application Review (PAR), Reader Provided comments on statement of purpose materials submitted by students intending to apply for Ph.D. admission. Microsoft HoloLens Intern Co-Mentor, Research mentor June-Aug 2020 Provided mentorship for a then incoming Princeton PhD student. Outdoor Leadership and Environmental Education, Mentor Sept 2014-May 2016 Mentored 3-5 high school students per year on topics related to college

admissions and internships. Taught science workshops and led field trips.

# Other interests

In addition to research, I enjoy running, climbing mountains, and singing with my pop/rock choir: Here to Sing.