#LifeKoKaroLift

Data Science Certification Program

upGrad

Course : Data Science

Lecture On :Intro of NN

Instructor : Shivam Garg

upGrad

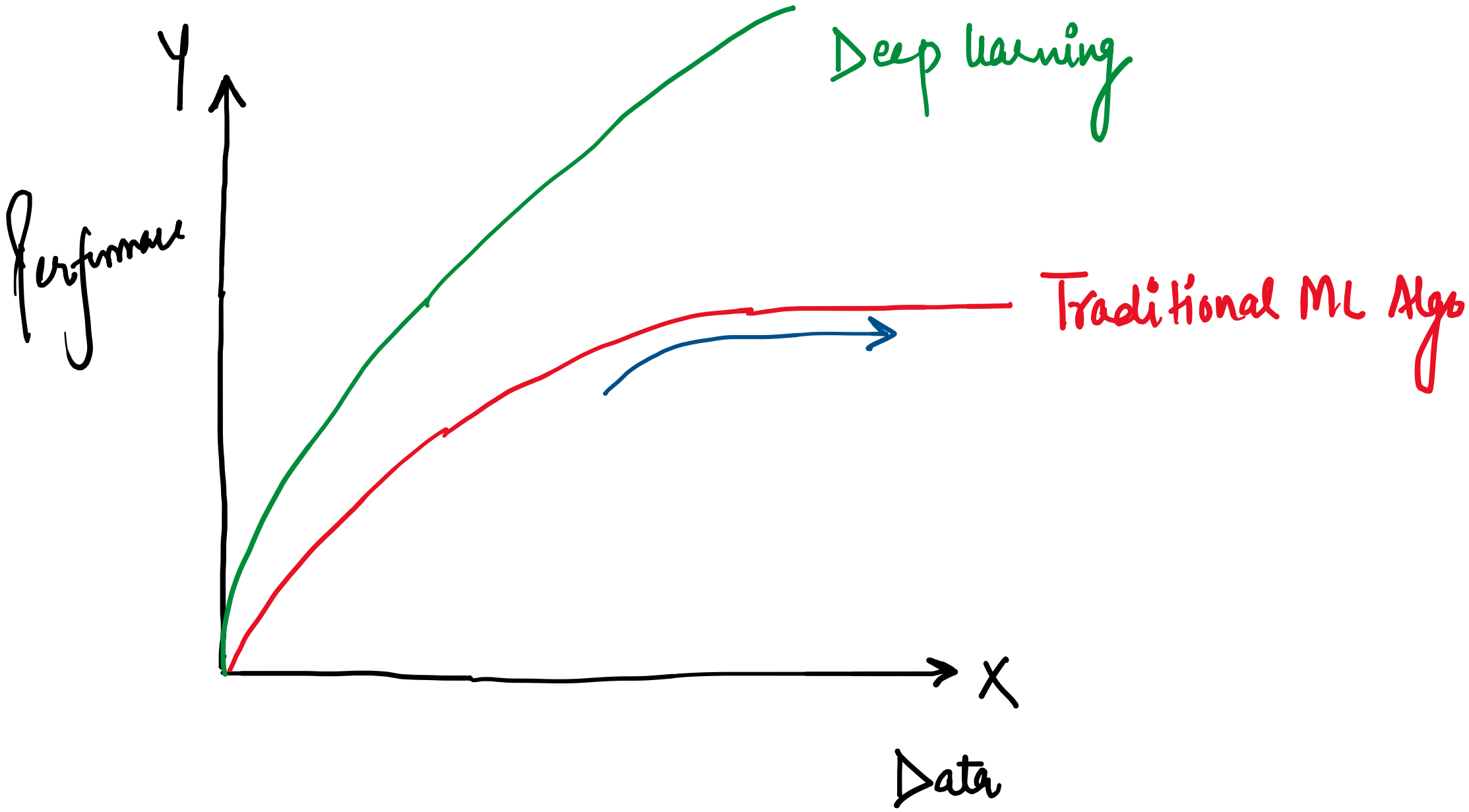
Today's Agenda

Need of neural network

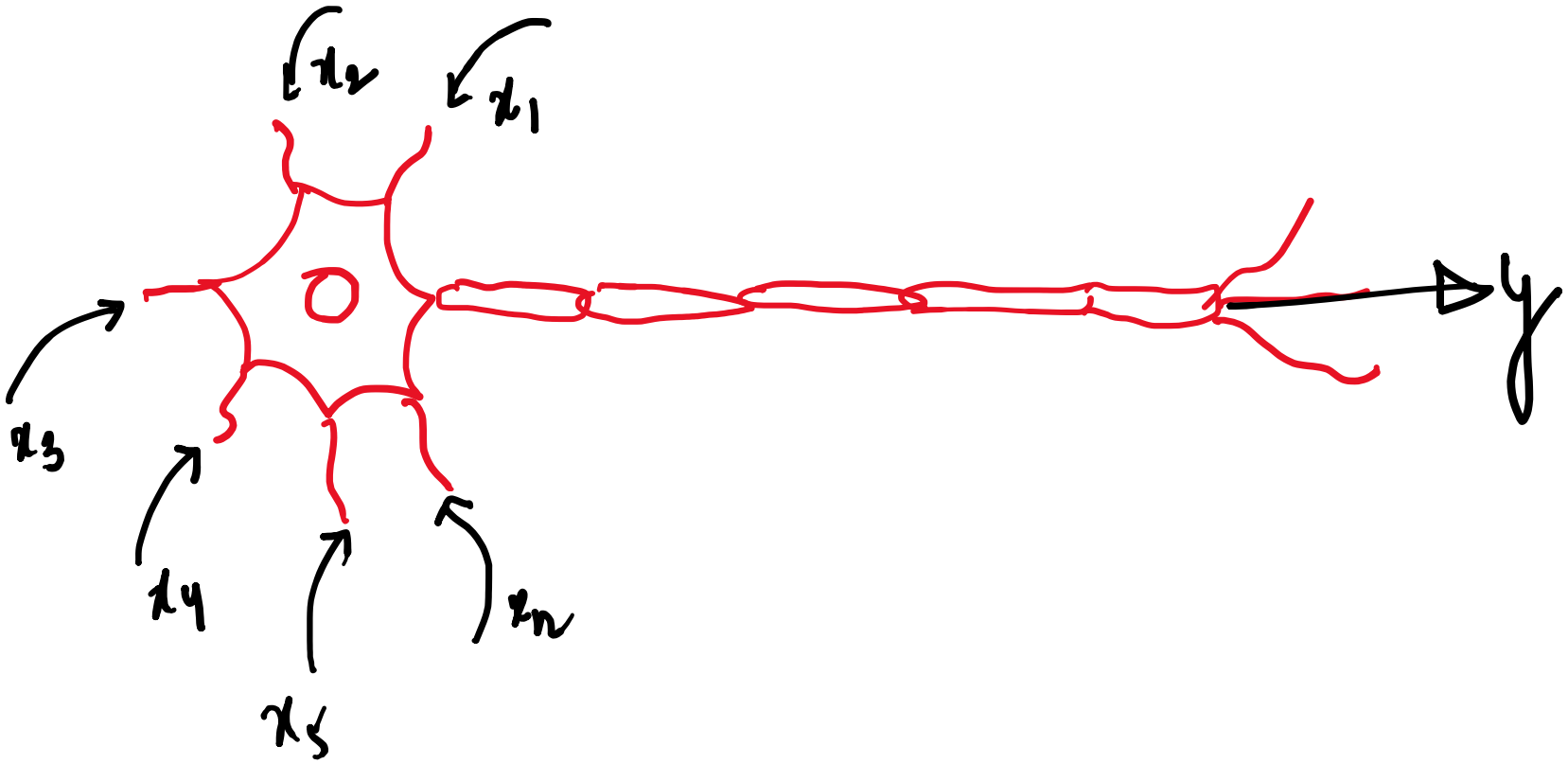
1. Basics of Neural Network
2. Activation Function

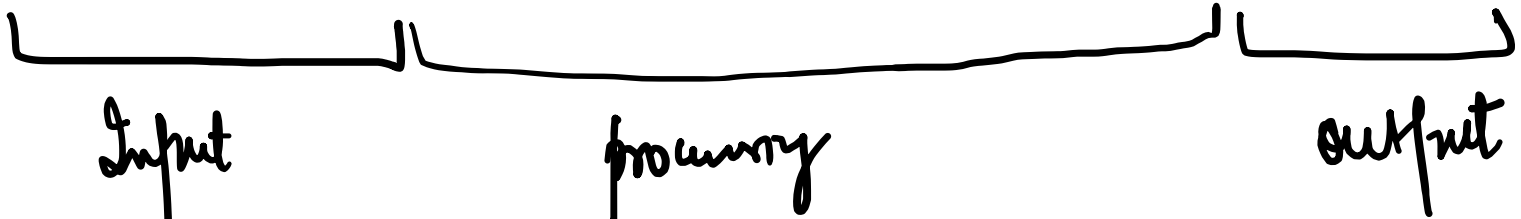
} Training

3. Forward Pass
4. Back Propagation


Y
Performance
Deep learning
Traditional ML Algo
X
Data

→ Human Neuron :-





Neural networks

→ Connection (b/w neurons)

↓ Neuron (Basic entity of NN)

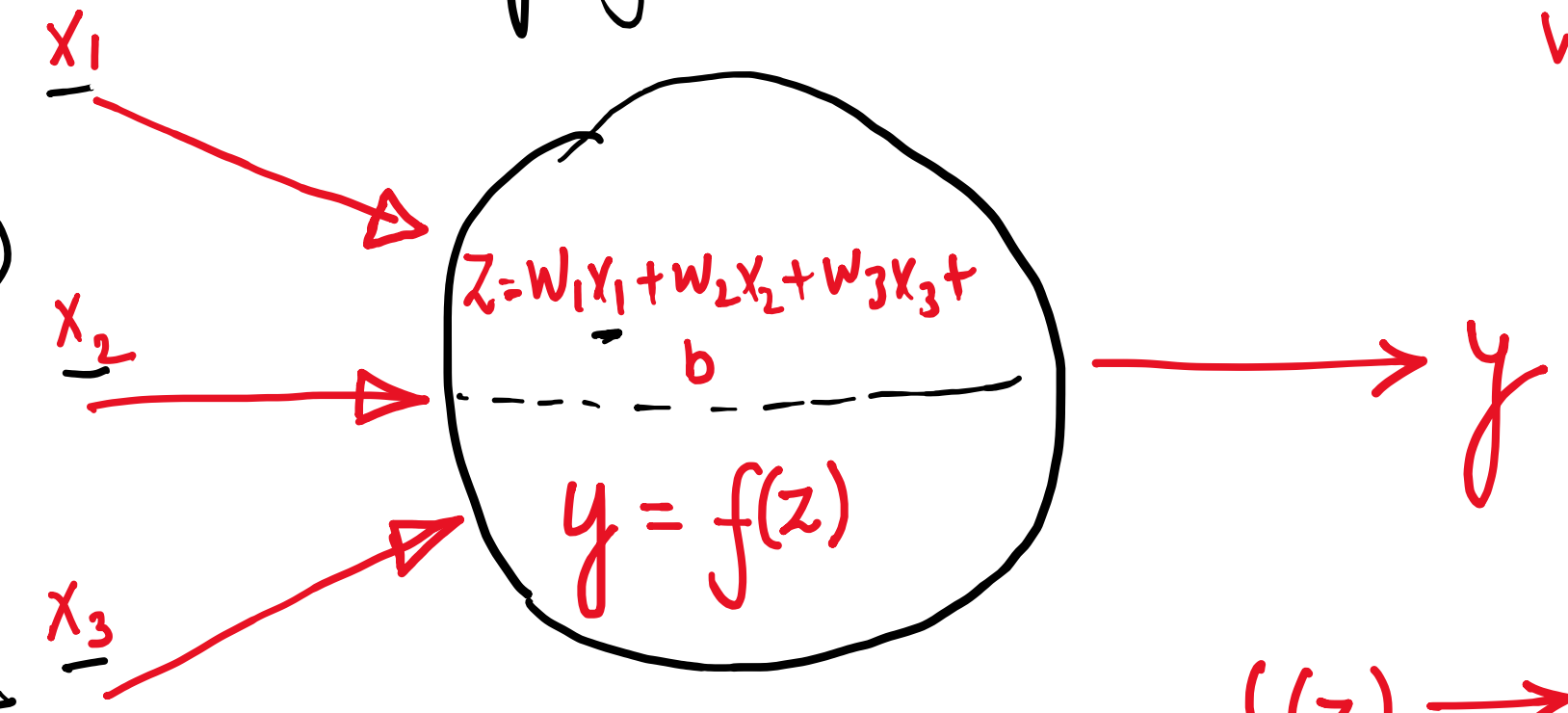
* Capability to learn non-linear patterns
* Neural network is "Universal function Approximator"

→ Working of Neuron :-

$y = m_1x_1 + m_2x_2 + m_3x_3 + \dots + c$

m_i → weights

c → b_i → bias



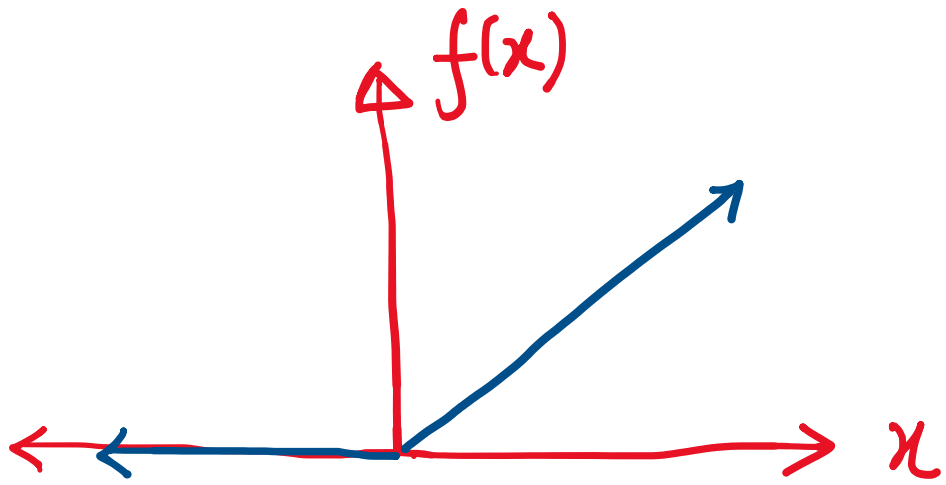
$f(z)$ → Activation function

(Non-linear transformation)

Activation function :- These are non-linear mathematical function which are responsible in NN to learn non-linear patterns.

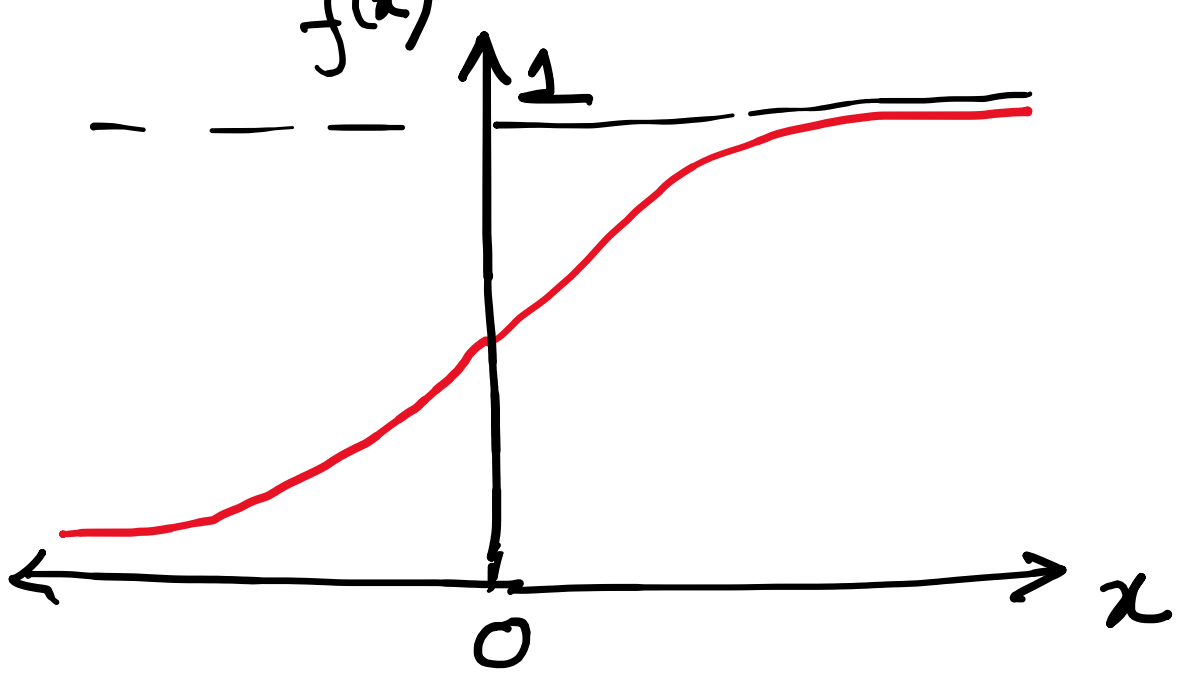
* **ReLU f^n :-** (Rectified Linear Unit)

$$f(x) = \begin{cases} x & x > 0 \\ 0 & x \leq 0 \end{cases}$$



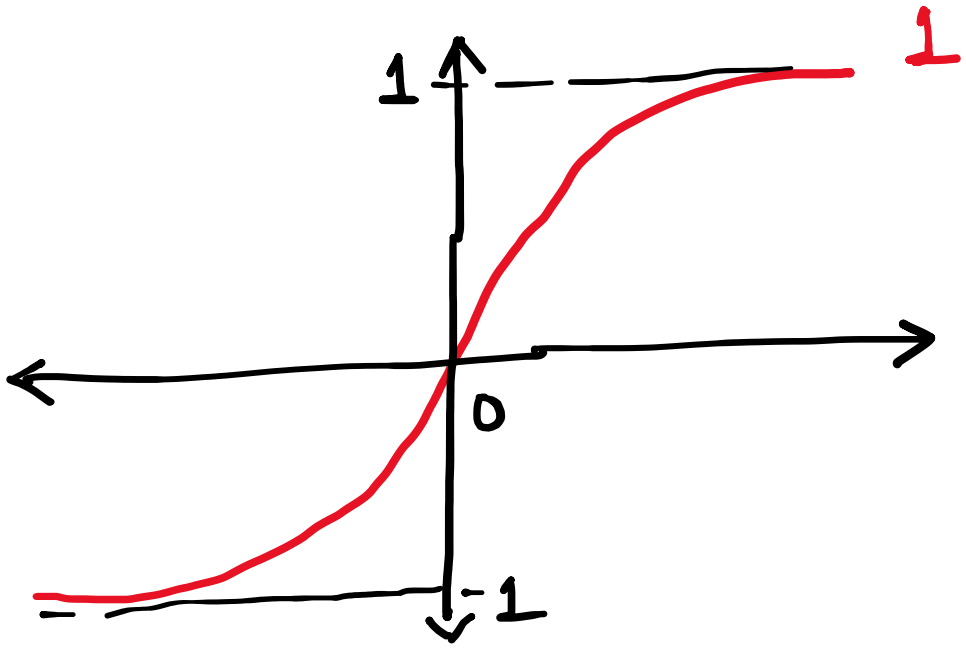
* Sigmoid function :-

$$f(x) = \frac{1}{1 + e^{-x}}$$

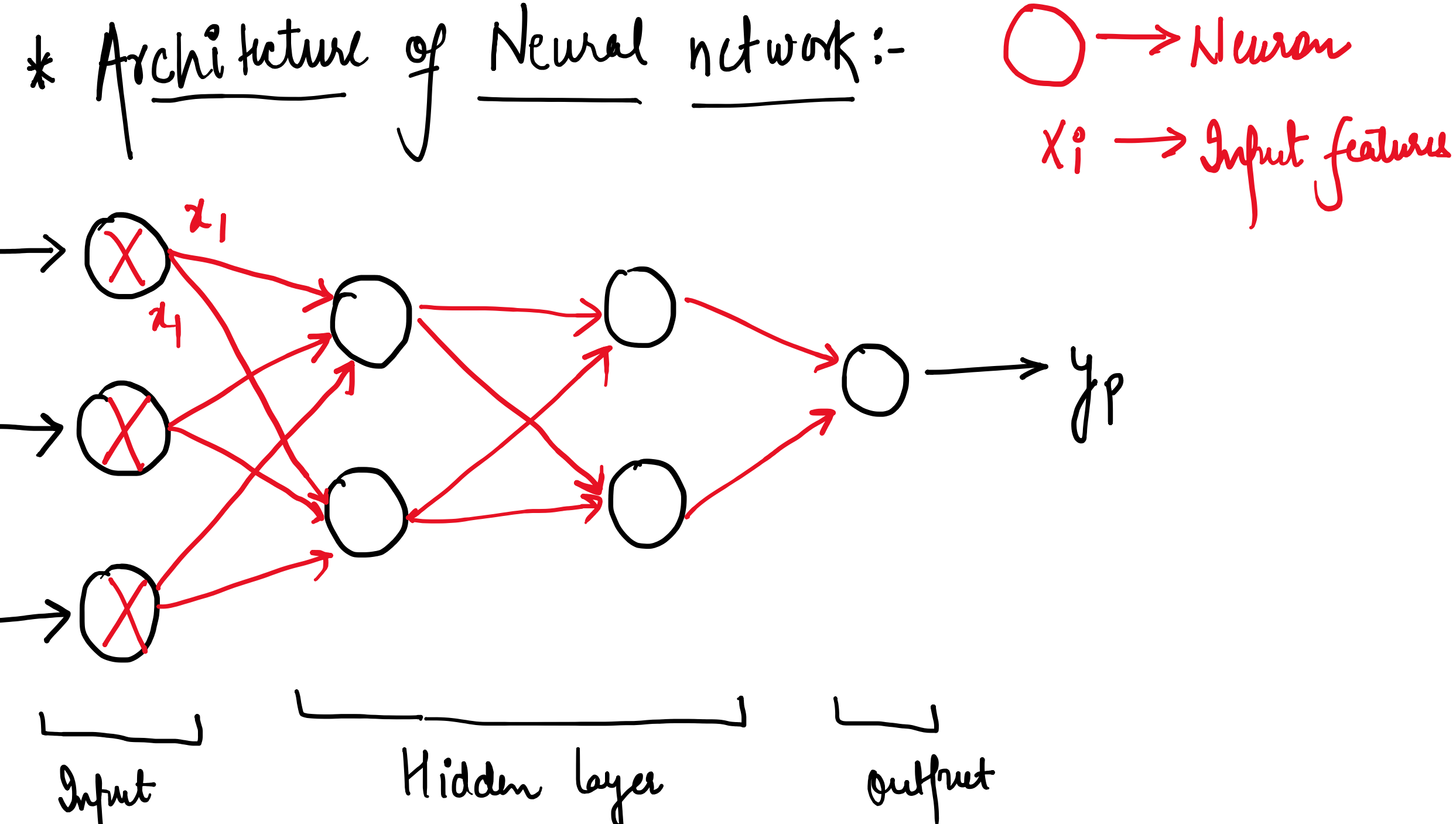


* Tanh function :-

$$f(x) = \frac{e^{x} - e^{-x}}{e^{x} + e^{-x}}$$



* Architecture of Neural network :-



→ Input layer :- (1)

* pass through layer. (no calculation)
* No activation f^n
* No. of neurons is equal to no. of input. (features)

* Output layer :- (1)

* No. of neurons & Activation f^n depends on use case

Use Case	No. of neurons	Activation f^n
Regression	1	ReLU
Binary Classif^n	1	Sigmoid / tanh
Multiclass classif^n (n)	n (no. of classes)	Softmax

→ Hidden layers :- (n)

* Activation f^n : ReLU

No. of hidden layers

No. of neurons in each layer } hyperparameter

→ Disadvantages of NN :-

① Black box (Non-Interpretable) } *

② Need to huge amount of data. }

③ Need of Good Infra Structure }

→ Advantages of NN :-

* Very good on Unstructured data

Training

feed forward

(to generate the output from input to output layer)

Back propagation

(to update weights & bias in order to reduce the error)

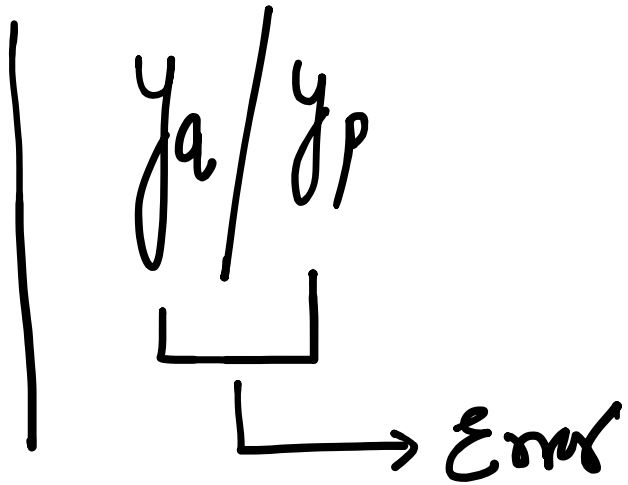
① Random Weights & Bias Initialization.

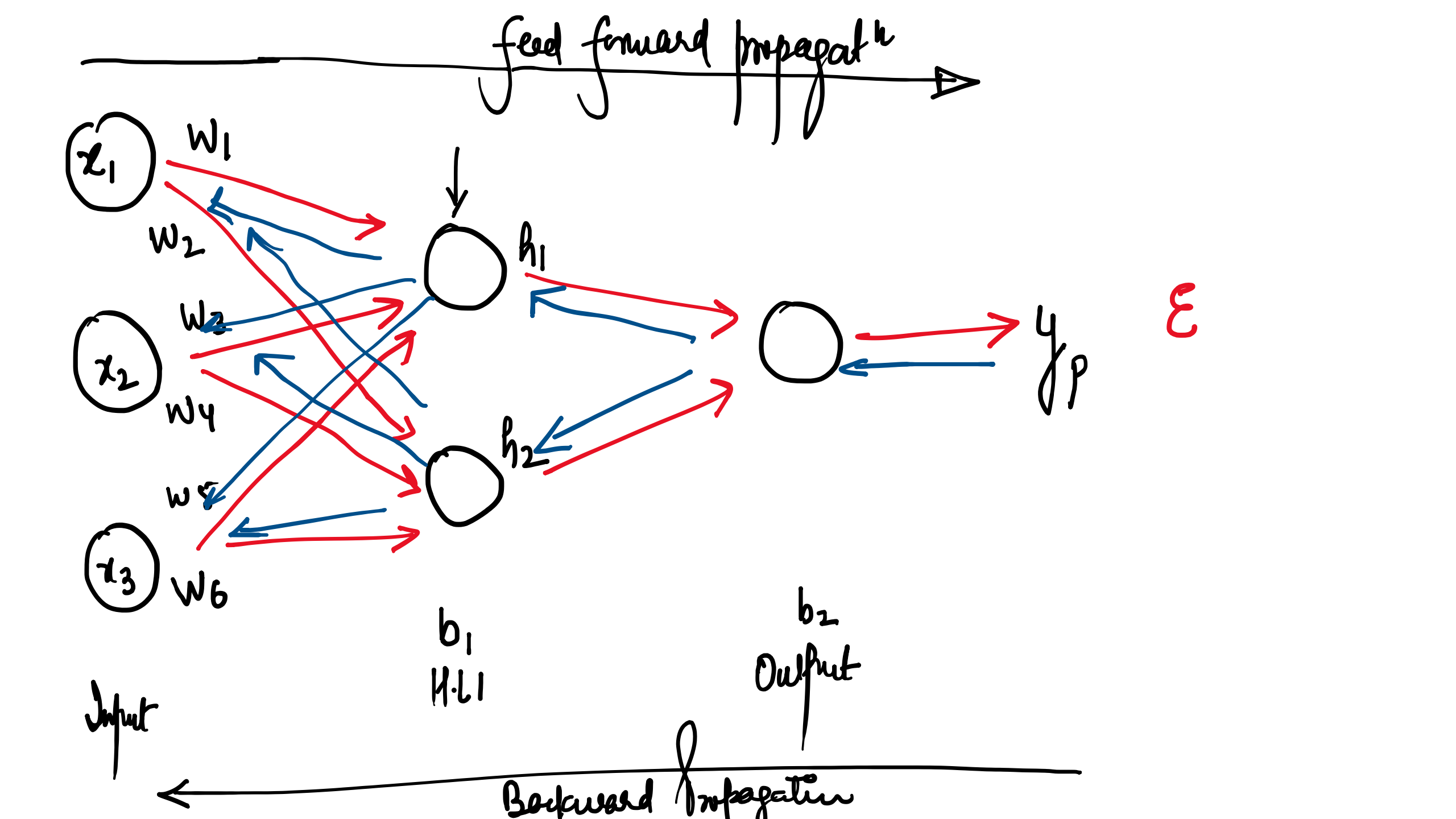
② feed forward propagation (y_p)

③ Error f^n ($\mathcal{E}$)

④ Back ward propagation (W_i & b_i get updated)

⑤ Repeat ②, ③ & ④ untill convergence.




feed forward propagation
x_1
x_2
x_3
w_1
w_2
w_3
w_4
w_5
w_6
h_1
h_2
y_p
ε
b_1
H.L1
b_2
Output
Input
Backward propagation

$$m_i' = m_i - \alpha \frac{\partial \varepsilon}{\partial m_i}$$

} Gradient Descent

$\alpha \rightarrow$ learning rate

(Hyperparameter)

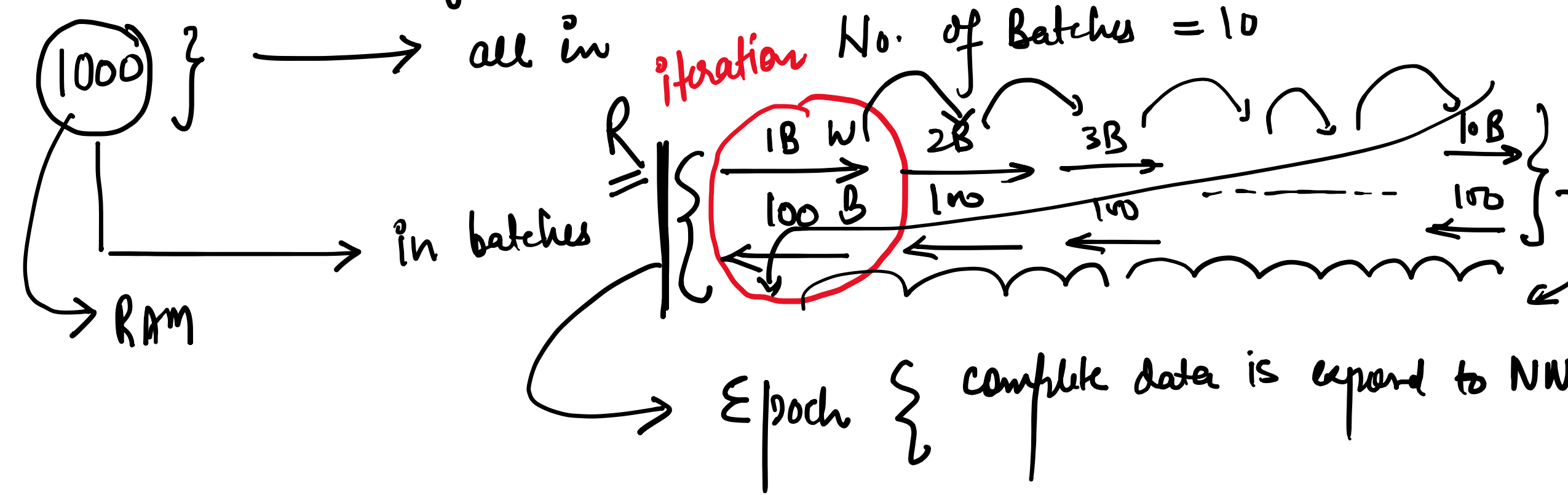
$$W_i' = W_i - \alpha \frac{\partial \varepsilon}{\partial W_i}$$

$$b_i' = b_i - \alpha \frac{\partial \varepsilon}{\partial b_i}$$

}

→ Batch Training :-

Batch size = 100



Total Data points = 1,00,000

Epochs = 10

Batch size = 50

No. of Batches = $\frac{10000}{50} = 2000$ (1 time only)

No. of iteration (1 Epoch) = No. of batches = 2000

Total no. of iterations = 2000 × 10 = 20000 } Ans