Autonomous Navigation for Mobile Robots

Sagar Khadse
Department of Computer Science
Golisano College of Computing and Information Sciences
Rochester Institute of Technology
Rochester, NY 14586
sk9877@rit.edu

Abstract—The abstract goes here.
Index Terms—Keyword1; Keyword2; Keyword3

- I. Introduction
- II. BACKGROUND
- III. CONCLUSION

REFERENCES

- I. Z. Ibragimov and I. M. Afanasyev, "Comparison of ros-based visual slam methods in homogeneous indoor environment," 2017 14th Workshop on Positioning, Navigation and Communications (WPNC), pp. 1–6, 2017.
- [2] M. Labbé, "Rtab-map as an open-source lidar and visual slam library for large-scale and long-term online operation," 2018.
- [3] S. Das, "Simultaneous localization and mapping (slam) using rtab-map," 2018. [Online]. Available: https://arxiv.org/abs/1809.02989