

# Classical Physics

**Module A: Classical Mechanics**

**Module B: Classical Electrodynamics**

Exam. type	Module - A	Module - B
Two Combined Quizzes	5%	5%
Midterm Examination	20%	20%
End term Examination	25%	25%
Total	50%	50%

- **Mathematical Tools** 5 lectures
- **Electrostatics** 3 lectures
- **Special techniques** 3 lectures
- **Concepts of Multipole Expansion** 2 lectures
- **Electric Field in Materials** 3 lectures
- **Magnetostatics** 2 lectures
- **Magnetic Field in Materials** 2 lectures
- **Electrodynamics** 1 lectures
- **Maxwell's Equation** 1 lectures

## **Reference Books**

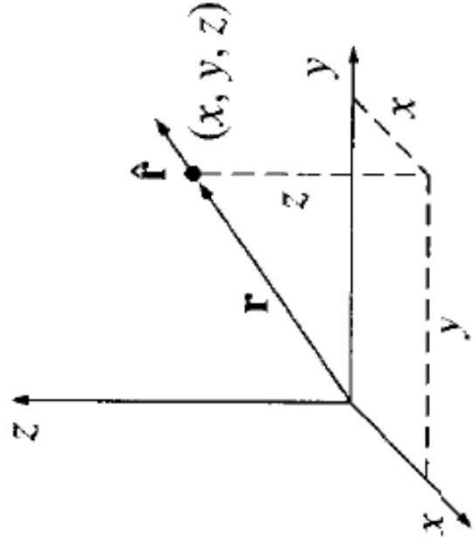
- 1. Introduction to Electrodynamics by David. J. Griffiths**
- 2. Classical Electrodynamics by John David Jackson**
- 3. Electricity and Magnetism by Edward M. Purcell**

# Mathematical Tools

1. **Vector Calculus**
2. **Cylindrical Co-ordinate System**
3. **Spherical Co-ordinate System**
4. **Delta Function**

# Vector Calculus

# Position Vector, Separation Vector and Infinitesimal Displacement vector

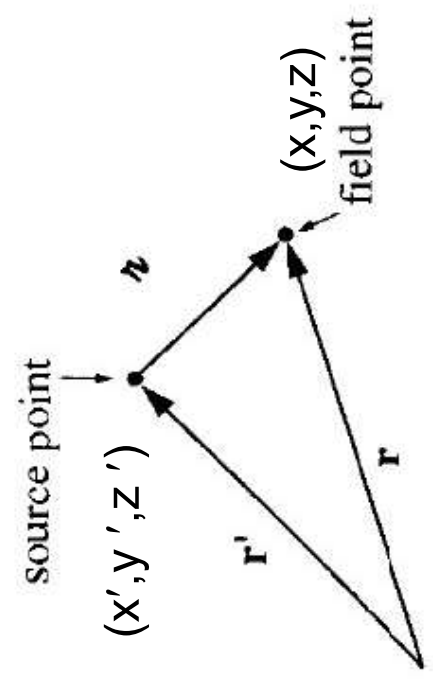


$$\mathbf{r} \equiv x \hat{\mathbf{x}} + y \hat{\mathbf{y}} + z \hat{\mathbf{z}}.$$

$$r = \sqrt{x^2 + y^2 + z^2};$$

$$\hat{\mathbf{r}} = \frac{\mathbf{r}}{r} = \frac{x \hat{\mathbf{x}} + y \hat{\mathbf{y}} + z \hat{\mathbf{z}}}{\sqrt{x^2 + y^2 + z^2}}$$

$$\begin{aligned} \mathbf{r} &\equiv \mathbf{r} - \mathbf{r}' \\ r &= |\mathbf{r} - \mathbf{r}'| \\ \hat{\mathbf{r}} &= \frac{\mathbf{r} - \mathbf{r}'}{r} = \frac{\mathbf{r} - \mathbf{r}'}{|\mathbf{r} - \mathbf{r}'|} \\ r &= (x - x')\hat{\mathbf{x}} + (y - y')\hat{\mathbf{y}} + (z - z')\hat{\mathbf{z}}, \\ r &= \sqrt{(x - x')^2 + (y - y')^2 + (z - z')^2}, \\ \hat{\mathbf{r}} &= \frac{(x - x')\hat{\mathbf{x}} + (y - y')\hat{\mathbf{y}} + (z - z')\hat{\mathbf{z}}}{\sqrt{(x - x')^2 + (y - y')^2 + (z - z')^2}} \end{aligned}$$



## infinitesimal displacement vector

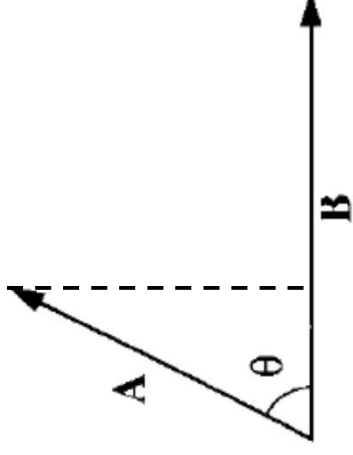
$(x, y, z)$  to  $(x + dx, y + dy, z + dz)$ ,

$$d\mathbf{l} = dx \hat{\mathbf{x}} + dy \hat{\mathbf{y}} + dz \hat{\mathbf{z}}$$

## Dot product of two vectors

$$\mathbf{A} \cdot \mathbf{B} \equiv AB \cos \theta$$

$$\vec{A} \bullet \vec{B} = |\vec{A}| \cos \theta$$



$$\begin{aligned} \mathbf{A} \cdot \mathbf{B} &= (A_x \hat{\mathbf{x}} + A_y \hat{\mathbf{y}} + A_z \hat{\mathbf{z}}) \cdot (B_x \hat{\mathbf{x}} + B_y \hat{\mathbf{y}} + B_z \hat{\mathbf{z}}) \\ &= A_x B_x + A_y B_y + A_z B_z. \end{aligned}$$

$$\mathbf{A} \cdot \mathbf{B} = \mathbf{B} \cdot \mathbf{A}$$

$$\hat{\mathbf{x}} \cdot \hat{\mathbf{x}} = \hat{\mathbf{y}} \cdot \hat{\mathbf{y}} = \hat{\mathbf{z}} \cdot \hat{\mathbf{z}} = 1; \quad \hat{\mathbf{x}} \cdot \hat{\mathbf{y}} = \hat{\mathbf{x}} \cdot \hat{\mathbf{z}} = \hat{\mathbf{y}} \cdot \hat{\mathbf{z}} = 0$$



## Cross product of two vectors.

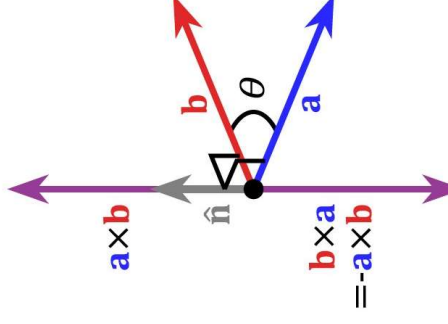
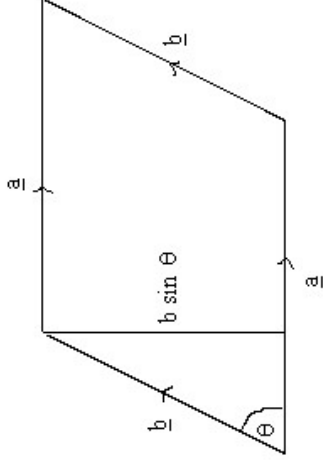
$$\mathbf{A} \times \mathbf{B} \equiv AB \sin \theta \hat{\mathbf{n}}$$

$$\mathbf{A} \times \mathbf{B} = (A_x \hat{\mathbf{x}} + A_y \hat{\mathbf{y}} + A_z \hat{\mathbf{z}}) \times (B_x \hat{\mathbf{x}} + B_y \hat{\mathbf{y}} + B_z \hat{\mathbf{z}})$$

$$\mathbf{A} \times \mathbf{B} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

$$= (A_y B_z - A_z B_y) \hat{\mathbf{x}} + (A_z B_x - A_x B_z) \hat{\mathbf{y}} + (A_x B_y - A_y B_x) \hat{\mathbf{z}}$$

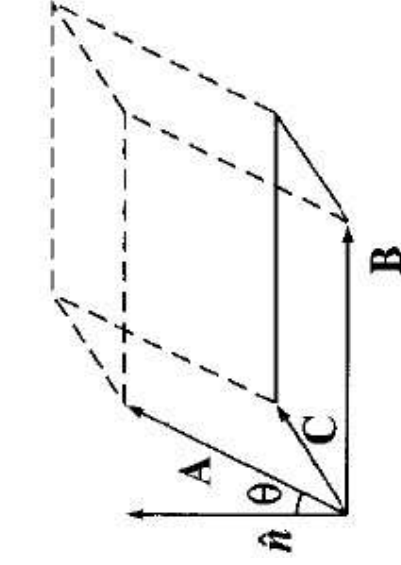
$$(\mathbf{B} \times \mathbf{A}) = -(\mathbf{A} \times \mathbf{B})$$



$$\begin{aligned} \hat{\mathbf{x}} \times \hat{\mathbf{x}} &= \hat{\mathbf{y}} \times \hat{\mathbf{y}} &= \hat{\mathbf{z}} \times \hat{\mathbf{z}} &= 0, \\ \hat{\mathbf{x}} \times \hat{\mathbf{y}} &= -\hat{\mathbf{y}} \times \hat{\mathbf{x}} &= \hat{\mathbf{z}}, \\ \hat{\mathbf{y}} \times \hat{\mathbf{z}} &= -\hat{\mathbf{z}} \times \hat{\mathbf{y}} &= \hat{\mathbf{x}}, \\ \hat{\mathbf{z}} \times \hat{\mathbf{x}} &= -\hat{\mathbf{x}} \times \hat{\mathbf{z}} &= \hat{\mathbf{y}}. \end{aligned}$$

## Triple Products

**Scalar triple product:**  $\mathbf{A} \cdot (\mathbf{B} \times \mathbf{C})$



$|\mathbf{B} \times \mathbf{C}|$  is the area of the base

$|\mathbf{A} \cos \theta|$  is the altitude

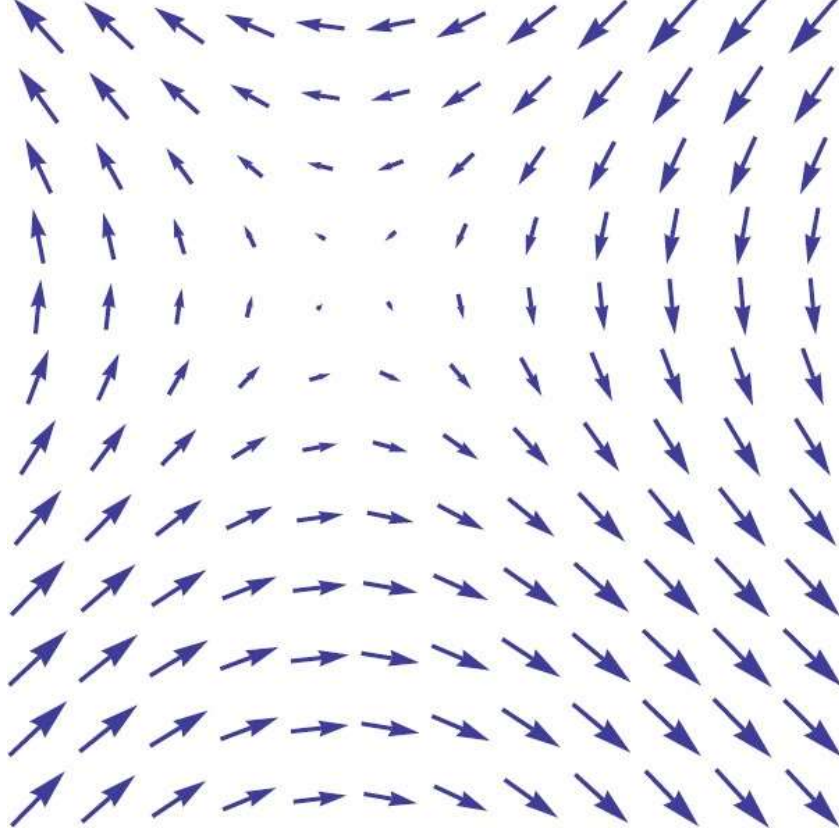
$$\mathbf{A} \cdot (\mathbf{B} \times \mathbf{C}) = \mathbf{B} \cdot (\mathbf{C} \times \mathbf{A}) = \mathbf{C} \cdot (\mathbf{A} \times \mathbf{B})$$

$$\mathbf{A} \times (\mathbf{B} \times \mathbf{C}) = \mathbf{B}(\mathbf{A} \cdot \mathbf{C}) - \mathbf{C}(\mathbf{A} \cdot \mathbf{B})$$

# Vector calculus

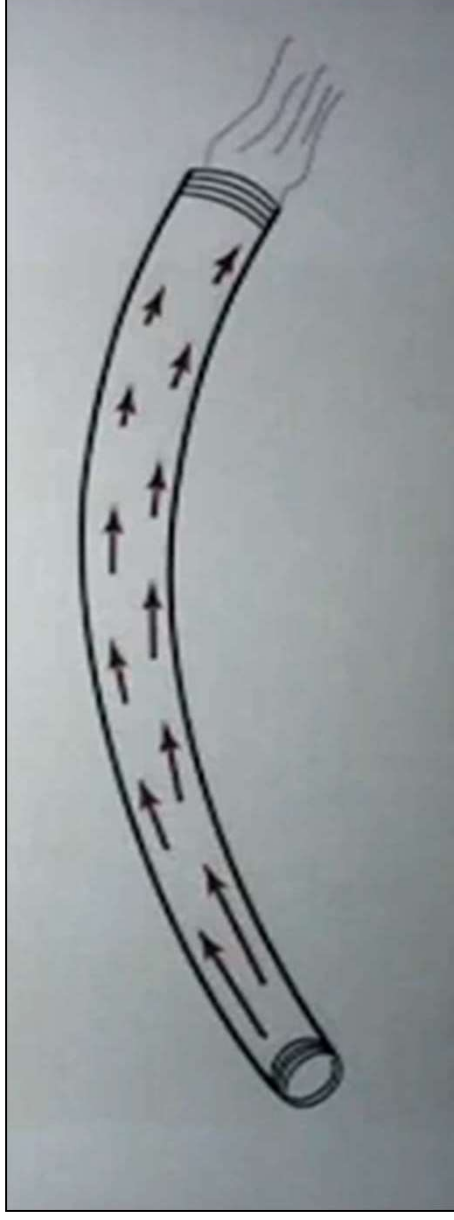
Scalar Function / Scalar Field

Vector Function / Vector Field



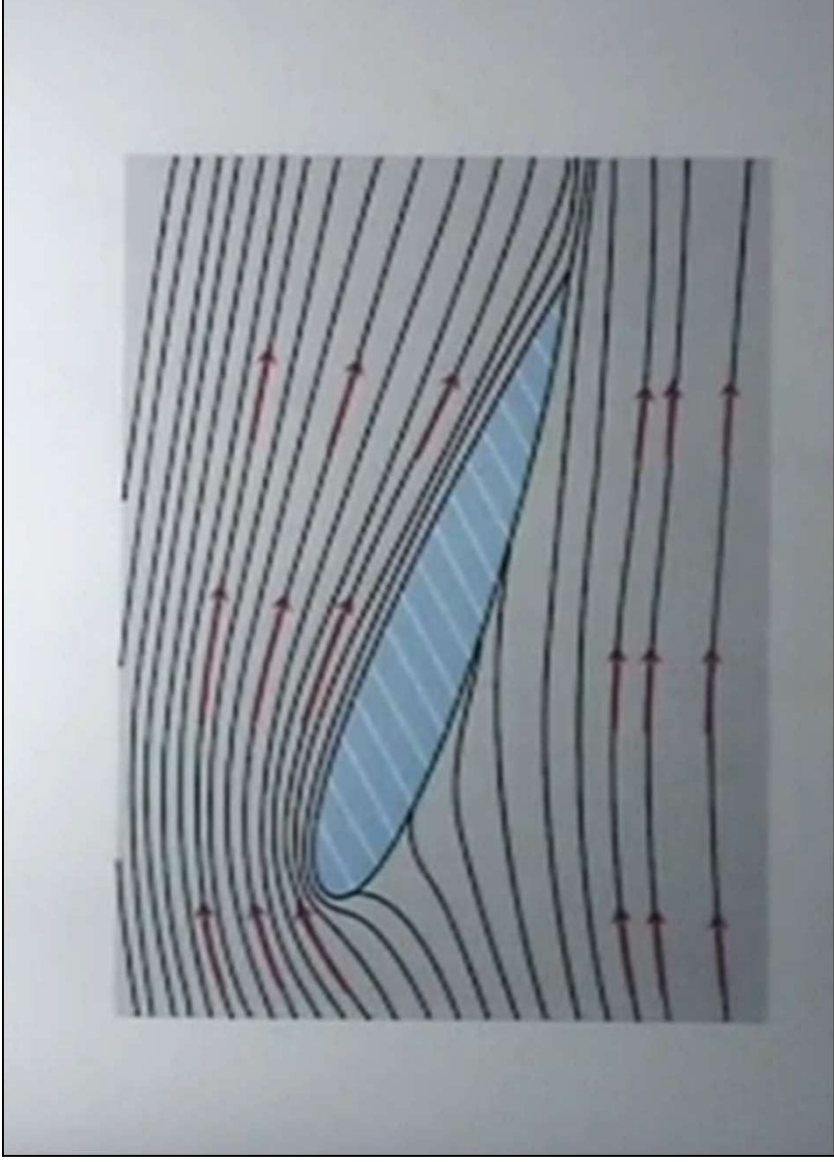
$$\vec{F} = \sin y \hat{i} + \sin x \hat{j}$$

[http://en.wikipedia.org/wiki/Vector\\_field](http://en.wikipedia.org/wiki/Vector_field)

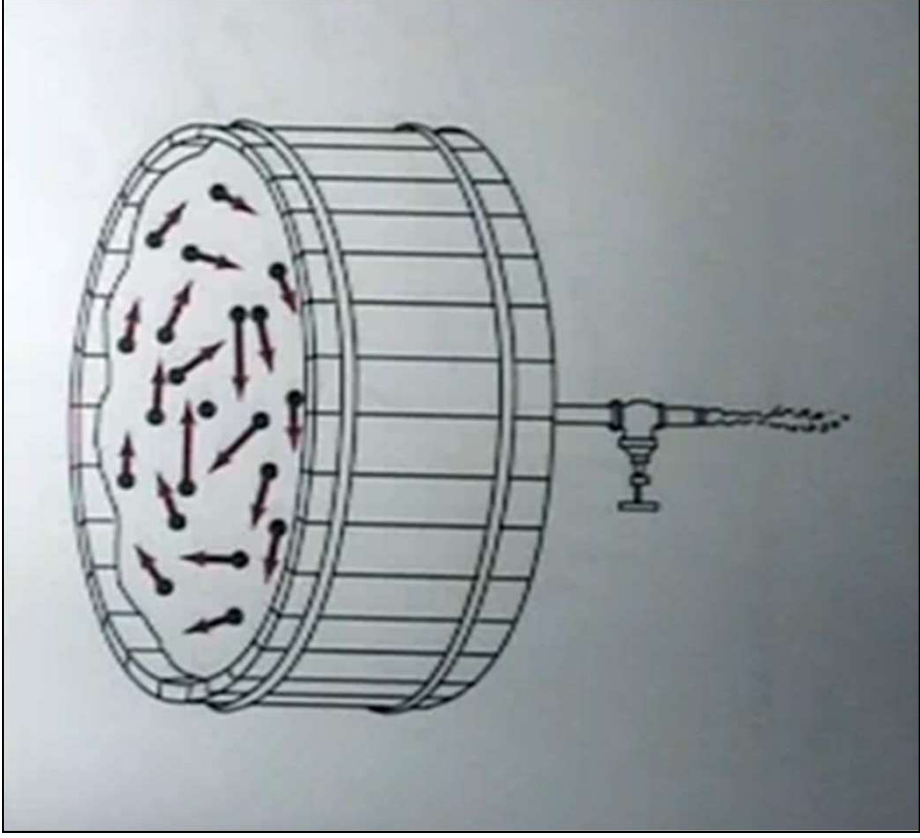


A vector field describing the velocity of a flow in a pipe

*Note: All the figures related of vector field has been taken from a lecture series given by Dr. Chris Tisdell, UNSW*

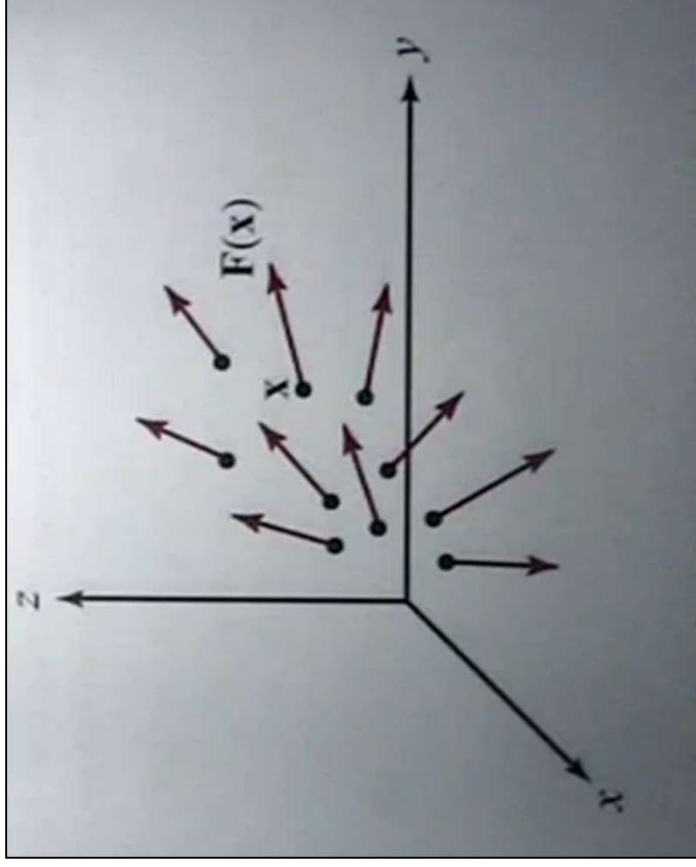


Velocity vector field of a flow around a aircraft wing



Circular flow in a tub

# Vector Field or Vector function



$$\vec{F}(x, y, z) = F_1(x, y, z)\hat{i} + F_2(x, y, z)\hat{j} + F_3(x, y, z)\hat{k}$$

$$\vec{F}(x, y, z) = xyz\hat{i} - x^2z^4\hat{j} + x\hat{k}$$

# Sketching of Vector Function/Field

$$\vec{V} = x\hat{i}$$

$$\vec{V} = x^2\hat{i}$$

$$\vec{V} = -y\hat{i} + x\hat{j}$$

$$\vec{V} = (x+y)\hat{i} + (x-y)\hat{j}$$



# Gradient Operator ( $\nabla$ )

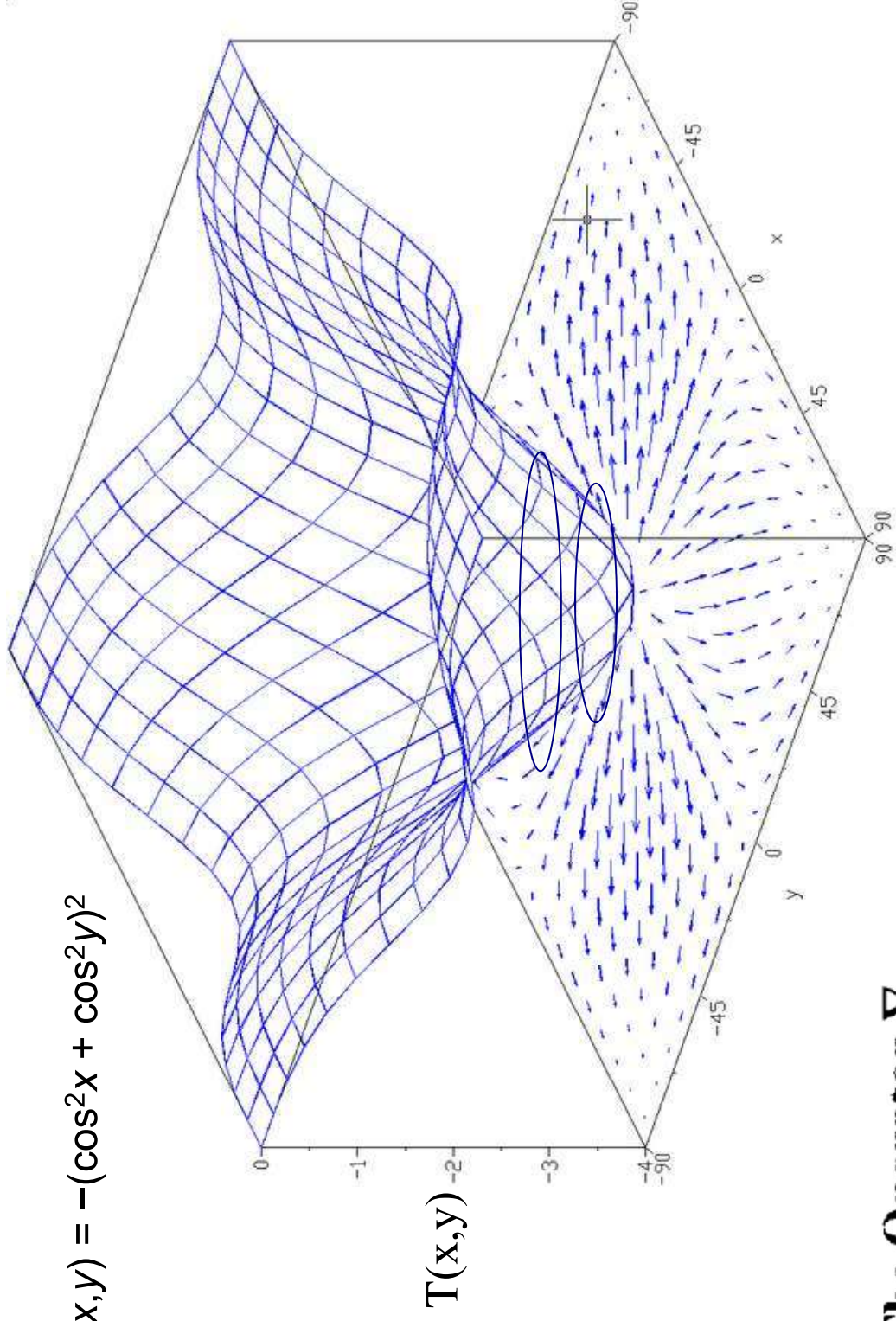
In Cartesian Coordinate

$$\vec{\nabla} = \left( \frac{\partial}{\partial x} \right) \hat{i} + \left( \frac{\partial}{\partial y} \right) \hat{j} + \left( \frac{\partial}{\partial z} \right) \hat{k}$$

Find out gradient of the following function

$$T(x,y) = -(\cos^2 x + \cos^2 y)^2$$

$$T(x,y) = -(\cos^2 x + \cos^2 y)^2$$



## The Operator $\nabla$

$$\nabla = \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z}.$$

$$\nabla T = \underbrace{\left( \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right)}_{\text{Vector Field}} T$$

Scalar Field

<http://en.wikipedia.org/wiki/Gradient>

$$T=T(x,y,z)$$

$$dT = \left(\frac{\partial T}{\partial x}\right)dx + \left(\frac{\partial T}{\partial y}\right)dy + \left(\frac{\partial T}{\partial z}\right)dz.$$

$$\begin{aligned} dT &= \left(\frac{\partial T}{\partial x}\hat{\mathbf{x}} + \frac{\partial T}{\partial y}\hat{\mathbf{y}} + \frac{\partial T}{\partial z}\hat{\mathbf{z}}\right) \cdot (dx\hat{\mathbf{x}} + dy\hat{\mathbf{y}} + dz\hat{\mathbf{z}}) \\ &= (\nabla T) \cdot (d\mathbf{l}), \end{aligned}$$

$$\nabla T \equiv \frac{\partial T}{\partial x}\hat{\mathbf{x}} + \frac{\partial T}{\partial y}\hat{\mathbf{y}} + \frac{\partial T}{\partial z}\hat{\mathbf{z}}$$

*Geometrical Interpretation of the Gradient.*

$$dT = \nabla T \cdot d\mathbf{l} = |\nabla T| |d\mathbf{l}| \cos \theta$$

when  $\theta = 0$  (for then  $\cos \theta = 1$ ),

*The gradient  $\nabla T$  points in the direction of maximum increase of the function  $T$ .*

*The magnitude  $|\nabla T|$  gives the slope (rate of increase) along this maximal direction.*

## The Divergence

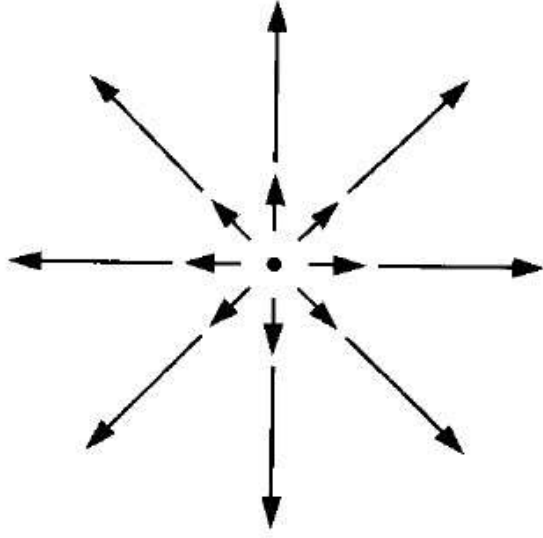
$$\begin{aligned}\nabla \cdot \mathbf{v} &= \left( \hat{\mathbf{x}} \frac{\partial}{\partial x} + \hat{\mathbf{y}} \frac{\partial}{\partial y} + \hat{\mathbf{z}} \frac{\partial}{\partial z} \right) \cdot (v_x \hat{\mathbf{x}} + v_y \hat{\mathbf{y}} + v_z \hat{\mathbf{z}}) \\ &= \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \\ &\quad \nabla \cdot \vec{V} \neq \vec{V} \cdot \nabla\end{aligned}$$

$$\text{(a) } \mathbf{v}_a = x^2 \hat{\mathbf{x}} + 3xz^2 \hat{\mathbf{y}} - 2xz \hat{\mathbf{z}},$$

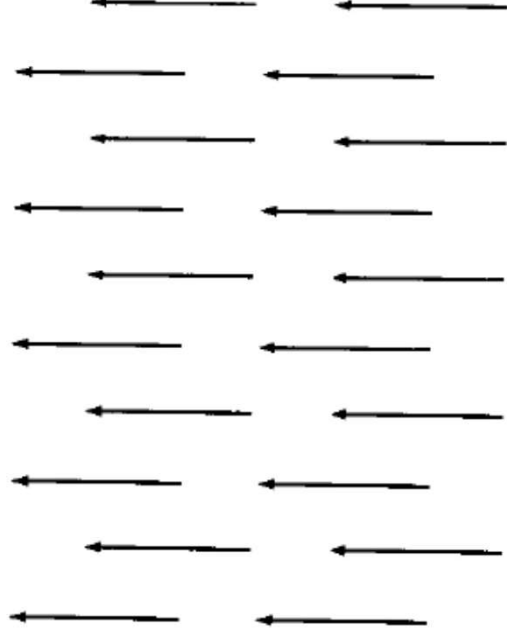
$$\text{(b) } \mathbf{v}_b = xy \hat{\mathbf{x}} + 2yz \hat{\mathbf{y}} + 3zx \hat{\mathbf{z}},$$

$$\text{(c) } \mathbf{v}_c = y^2 \hat{\mathbf{x}} + (2xy + z^2) \hat{\mathbf{y}} + 2yz \hat{\mathbf{z}}.$$

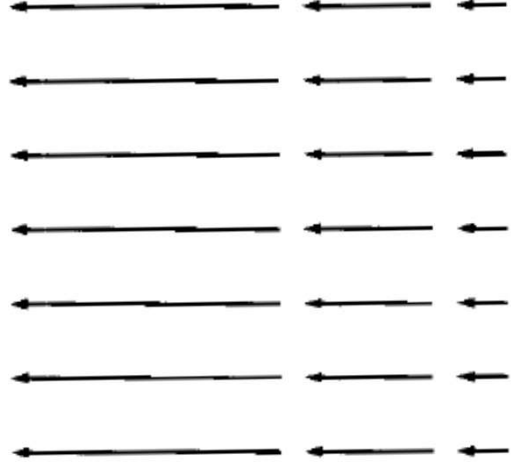
$$\mathbf{v}_a = \mathbf{r} = x \hat{\mathbf{x}} + y \hat{\mathbf{y}} + z \hat{\mathbf{z}}$$



$$\mathbf{v}_b = \hat{\mathbf{z}}$$

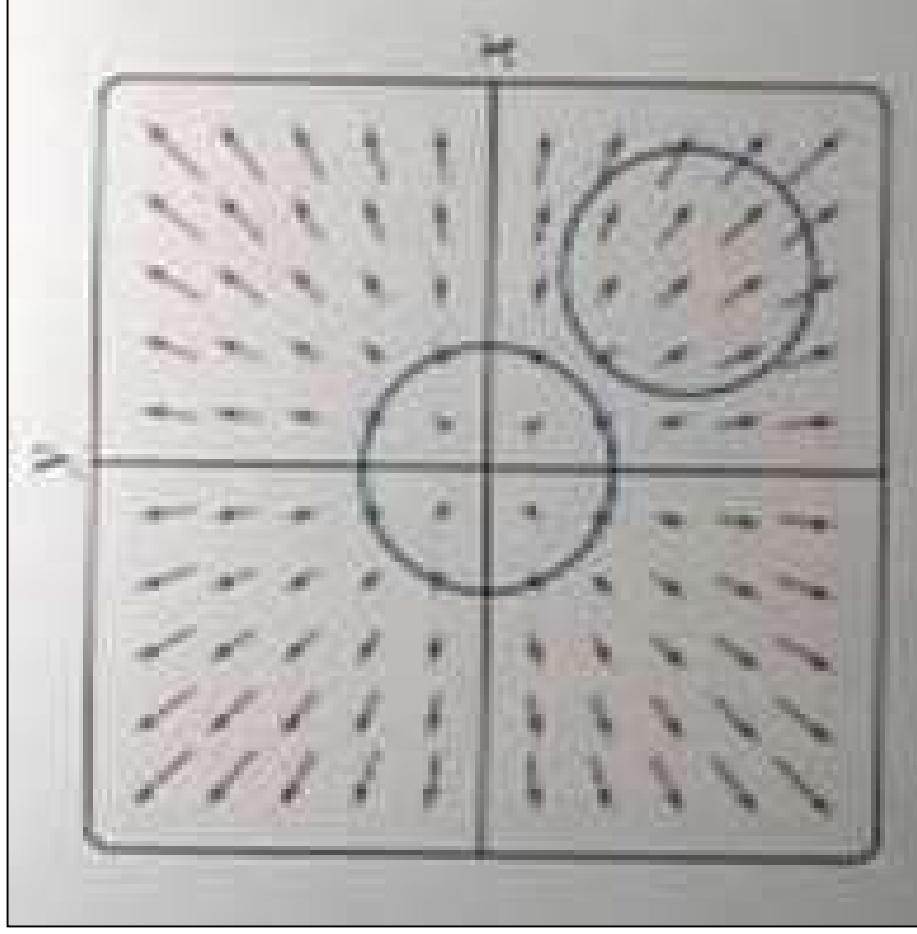


$$\mathbf{v}_c = z \hat{\mathbf{z}}$$



In many cases, the divergence of a vector function at point P may be predicted by considering a closed surface surrounding P and analyzing the flow over the boundary, keeping in mind that at P:

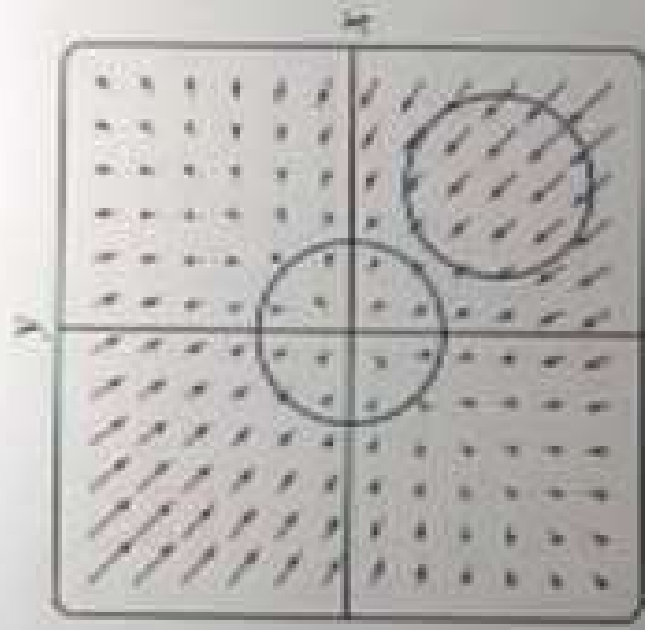
$$\vec{\nabla} \cdot \vec{F} = \text{outflow} - \text{inflow}$$



$$\vec{V} = x\hat{i} + y\hat{j}$$

$$\vec{\nabla} \cdot \vec{V} = 2$$

In 3-D, divergence is a measure of change of flux per unit volume

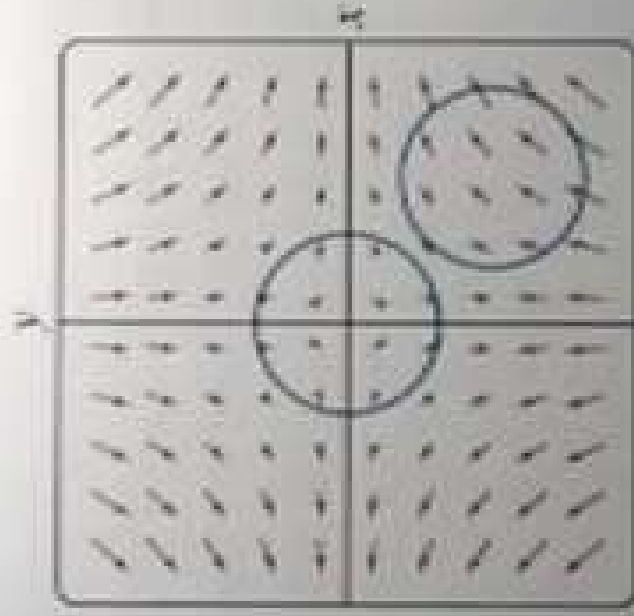


(B) The force field

$$\mathbf{F} = \langle y - 2x, x - 2y \rangle$$

with  $\text{div}(\mathbf{F}) = -4$ .

There is a net inflow  
into every circle.

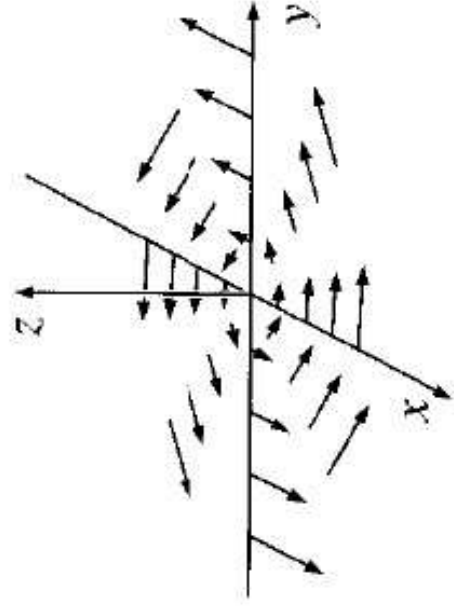


(C) The force field  $\mathbf{F} = \langle x, -y \rangle$  with  $\text{div}(\mathbf{F}) = 0$ . The flux through every circle is zero.

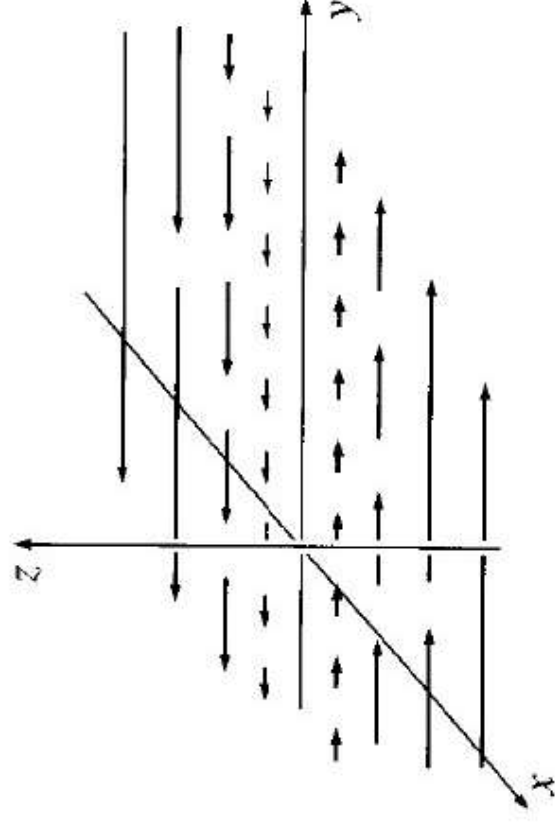


# The Curl

$$\begin{aligned}\nabla \times \mathbf{v} &= \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ v_x & v_y & v_z \end{vmatrix} \\ &= \hat{\mathbf{x}} \left( \frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) + \hat{\mathbf{y}} \left( \frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) + \hat{\mathbf{z}} \left( \frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right)\end{aligned}$$

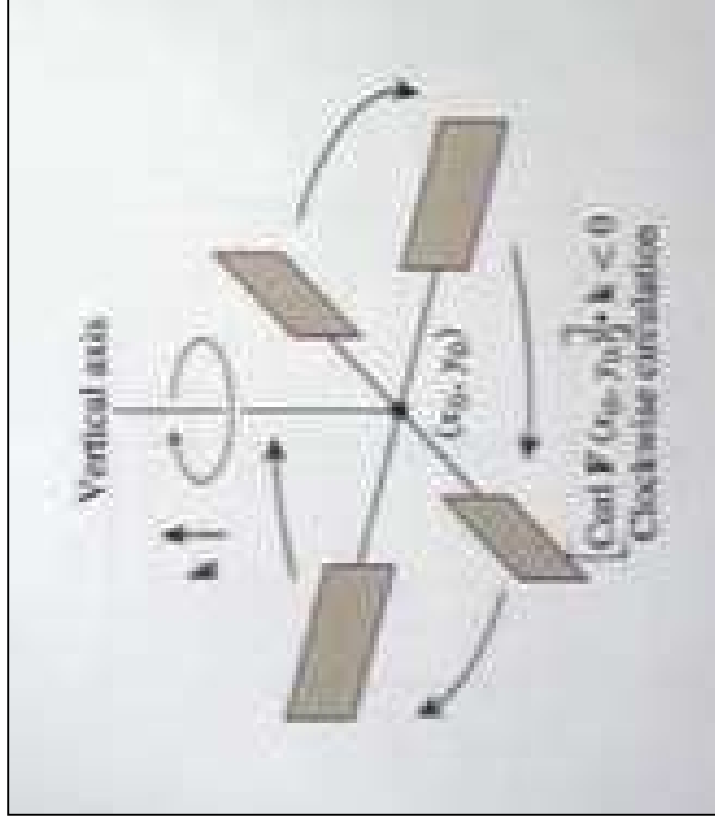


$$\mathbf{v}_a = -y\hat{\mathbf{x}} + x\hat{\mathbf{y}}$$



$$\mathbf{v}_b = x\hat{\mathbf{y}}$$

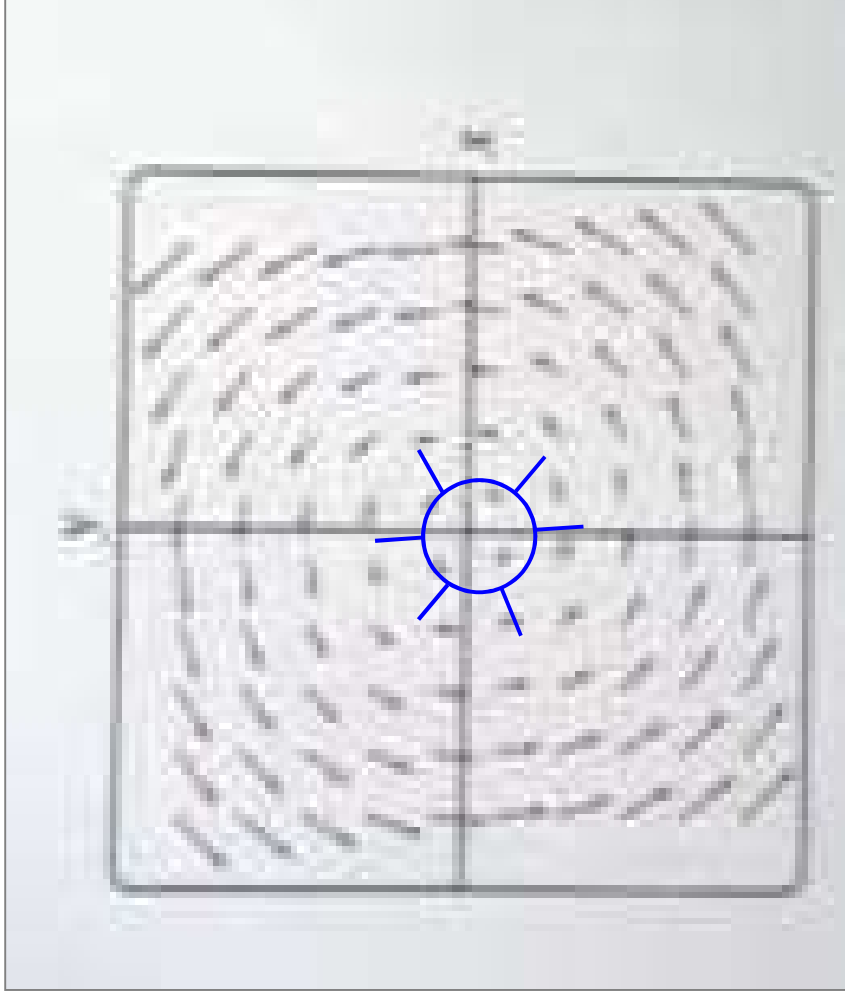
## Paddle wheel analysis



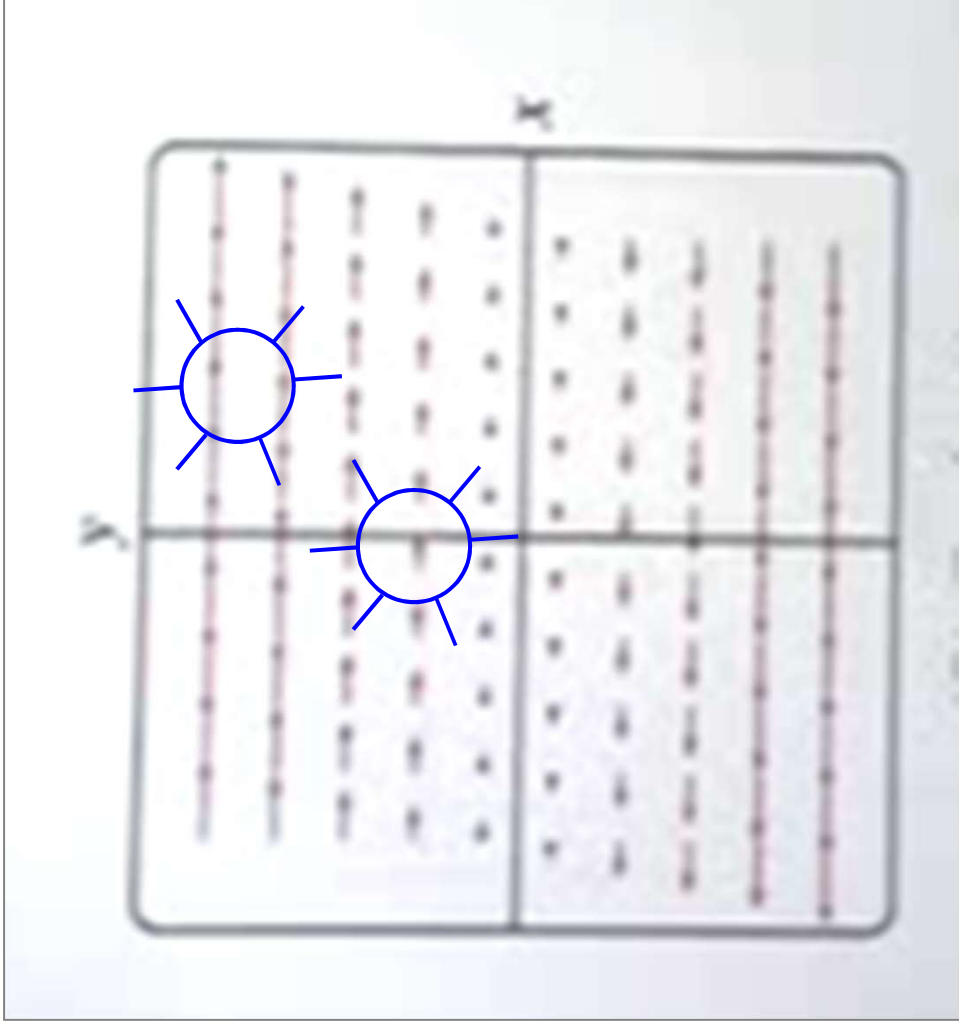
$$[\nabla \times \vec{F}(x_0, y_0)] \cdot \hat{\mathbf{k}} < 0$$

$$\vec{F}(x, y) = -y\hat{i} + x\hat{j}$$

$$(\vec{\nabla} \times \vec{F}) \cdot \hat{k} = 2$$

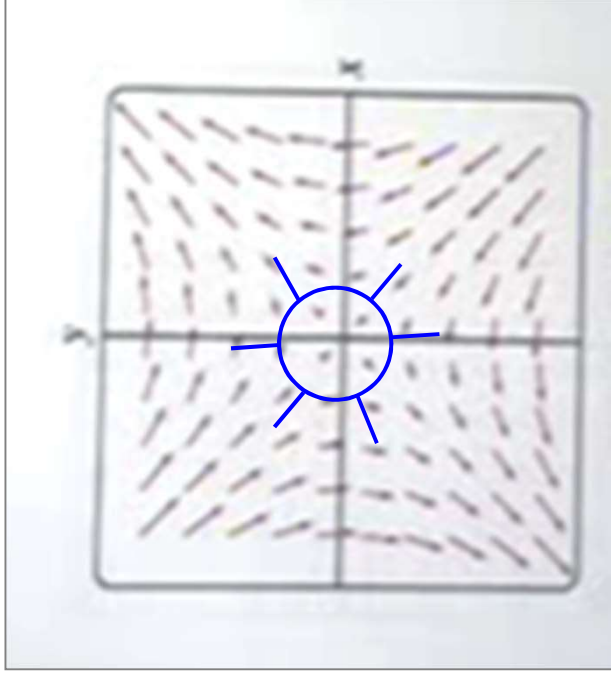


$$\vec{F}(x,y) = y\hat{i}$$

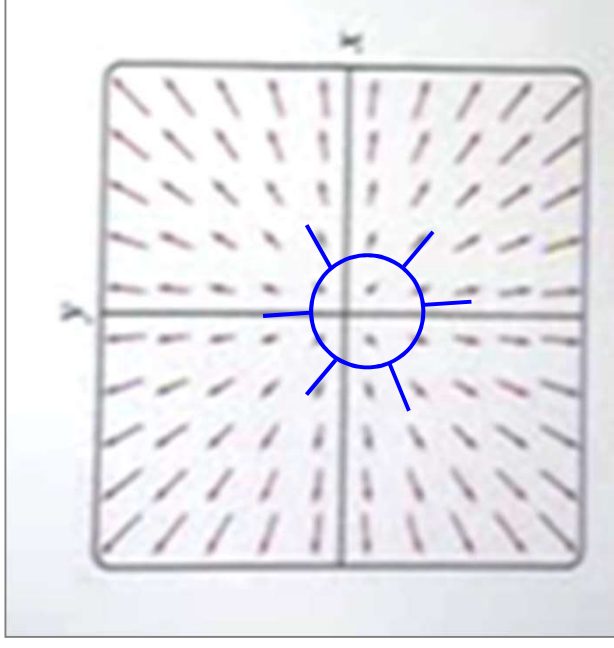


$$(\nabla \times \vec{F}) \cdot \hat{k} = -1$$

$$\vec{F}(x, y) = y\hat{i} + x\hat{j}$$



$$\vec{F}(x, y) = x\hat{i} + y\hat{j}$$



$$\nabla \times \vec{F} = 0$$

# Summary

**Gradient of a Scalar Field**  $\longrightarrow$  **Vector Field**

$$\nabla T = \left( \hat{\mathbf{x}} \frac{\partial}{\partial x} + \hat{\mathbf{y}} \frac{\partial}{\partial y} + \hat{\mathbf{z}} \frac{\partial}{\partial z} \right) T$$

$\uparrow$  Scalar Field       $\underbrace{\hspace{10em}}$  Vector Field

**Divergence of a Vector Field**  $\longrightarrow$  **Measure of Change of flux per unit volume**

**Curl of a Vector Field**  $\longrightarrow$  **Measure of degree of rotation of the field**