## Class Tree Based Model





Topic

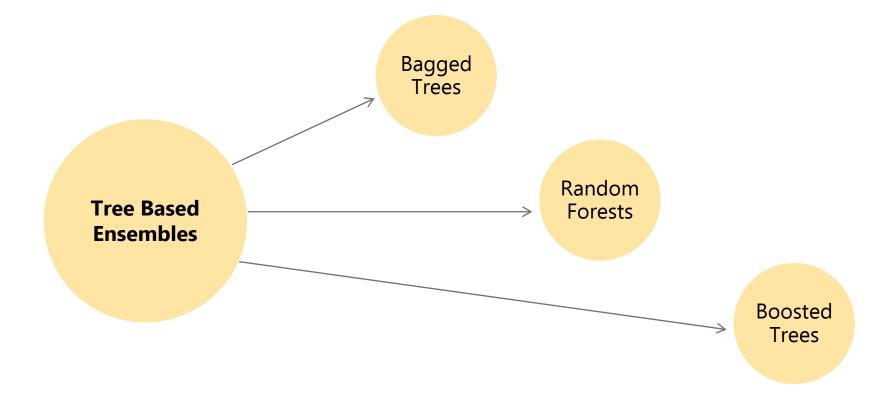
Tree Based Ensembles: Bagged Trees and Random Forests

## **Agenda**

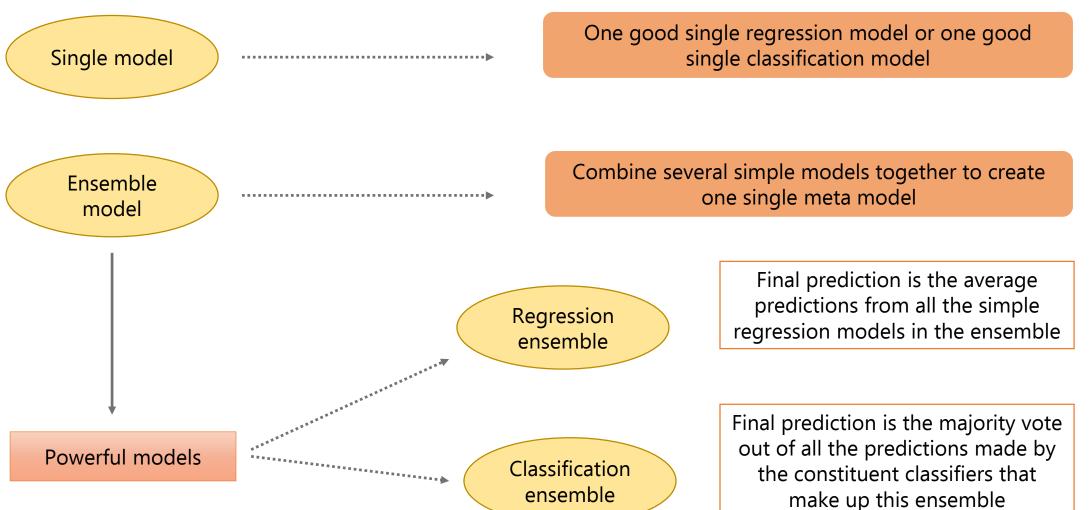


Another category of machine learning models Ensemb

**Ensemble Models** 

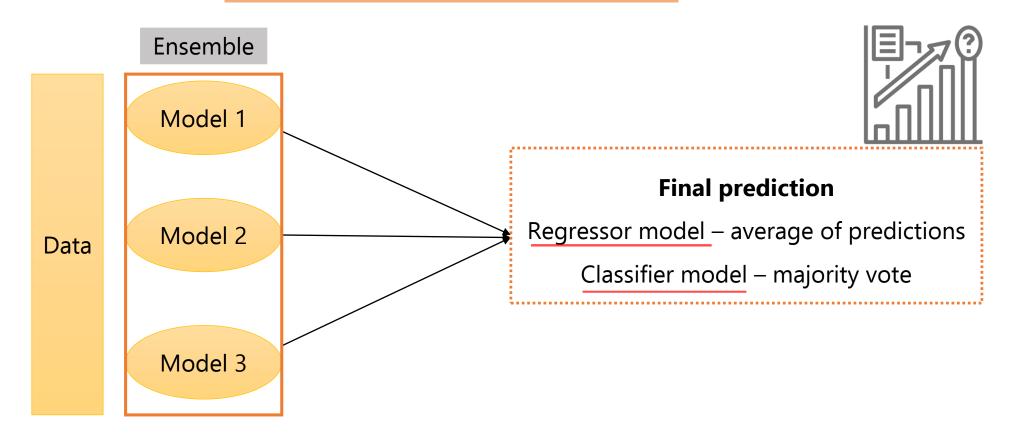


#### **Tree Based Ensembles Overview**

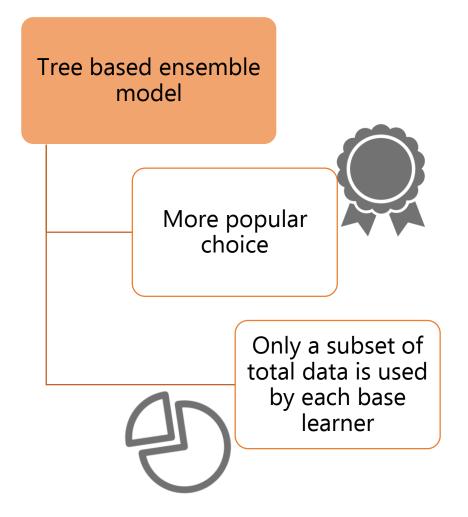


#### **Tree Based Ensembles Overview**

Schematic working of ensembles



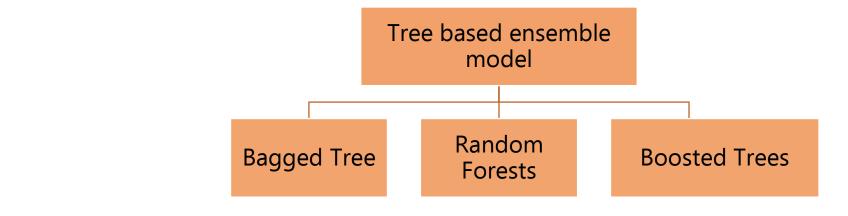
#### **Tree Based Ensembles Overview**



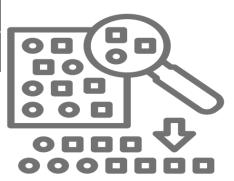
The way this data set is fed into each of the base learners is based on a data sampling scheme

Different sampling schemes give rise to different types of tree based ensembles

#### **Tree Based Ensemble Models**



Sampling Scheme	Bootstrap Sampling	Bootstrap Sampling + Feature Sampling	Data Reweighing
Base Learner	Tree	Tree	Tree





The total error due to any machine learning algorithm

In-sample error ÷

Out-ofsample error

Good predictions on

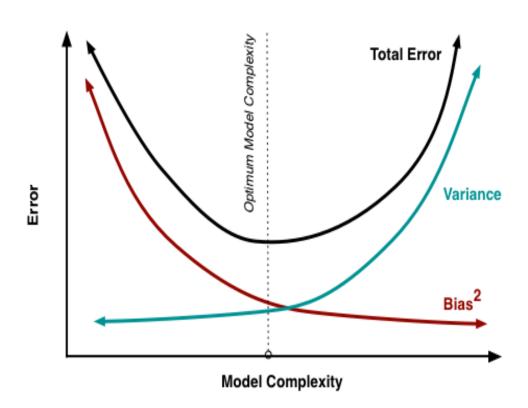
training data but is unable

to do so on unseen data

Inability of an ML algorithm to fit the training data well

Inability of a model to generalize well





Error = Bias + Variance = In-sample Error + Out-of-sample Error Trade offs between the model complexity and the error in models

More complicated models have very **low in-sample error but have a high out-of-sample error** 

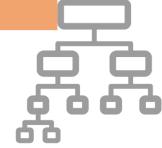
Simpler models have **low out-of-sample error but high in-sample error** 

Theoretically, there is a limit to minimum error that can be achieved

Reduce error further by decreasing insample error and out-of-sample error simultaneously



Use tree based models as base learners to reduce in-sample error



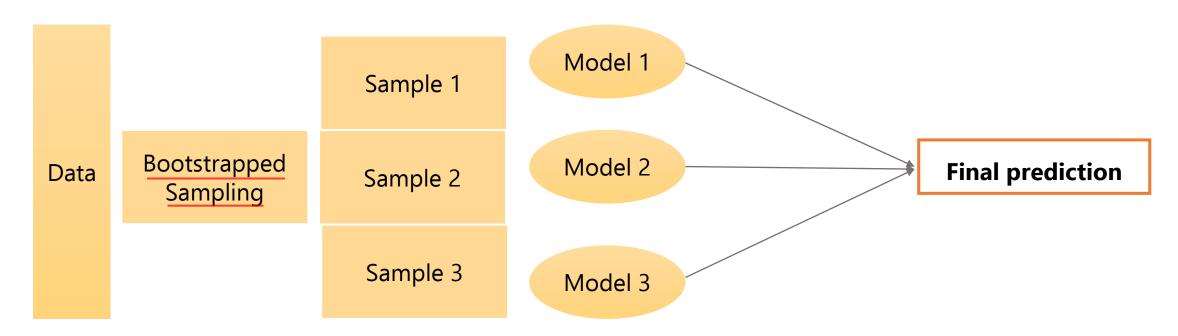
While training a tree based ensemble the constituent tree models are allowed to grow many levels deep



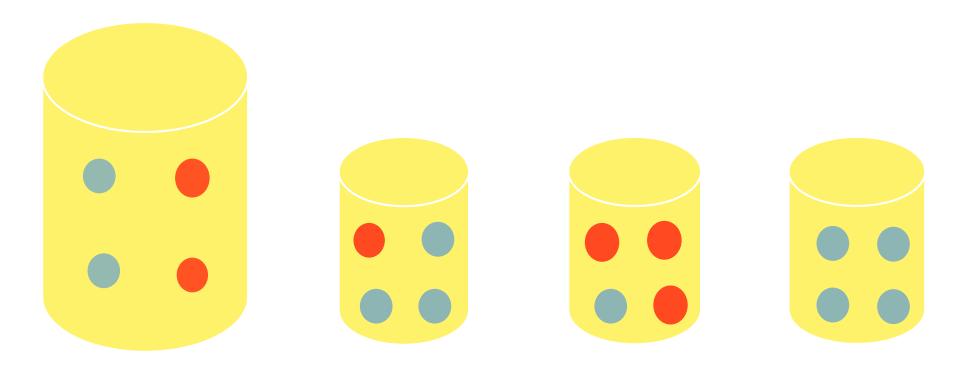
The intricacies of training data are captured intimately, thereby reducing the in-sample error



In the case of **Bagged trees** each of the unpruned trees are fed bootstrapped samples of original data set



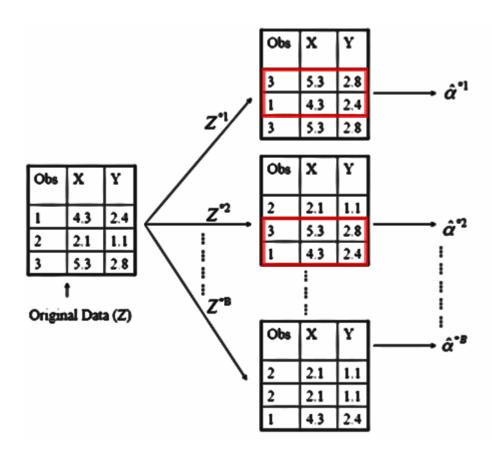
Bootstrapped sampling simply refers to sampling by replacement



Blue and red dots are repeated more often in the samples than they are present in the original data



Bootstrapped Sampling at the data level



Bootstrapped Sampling helps in reducing out of sample error

If an unpruned decision tree is fit into any data set then the model will have very high out-of-sample error

Why?



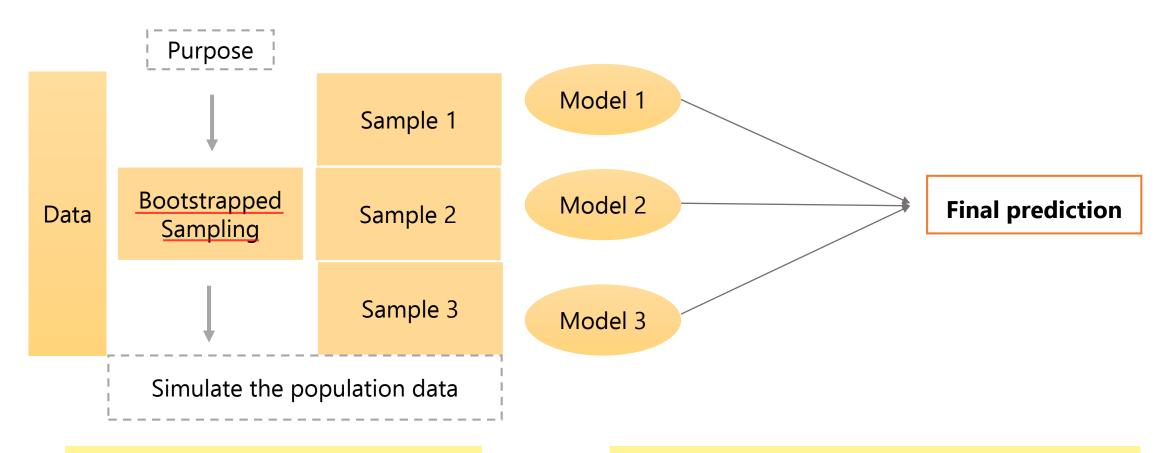
The test data can be very different from training data

Since tree model is being overfitted on training data, the **out-of-sample error will be high** 

Hypothetically, if unpruned tree model is being fitted on total population data the error will be very low

Low error due to all the variation and variety in data has been already seen by the model as the population data has been used to train the model





Realistic view of the data generation process

Synthetically generate variation and variety in the training data itself



Characteristics of Bagged Model

Using unpruned decision trees as base learners

Using **Bootstrapped Sampling** to create samples that are fed to each of the base learners

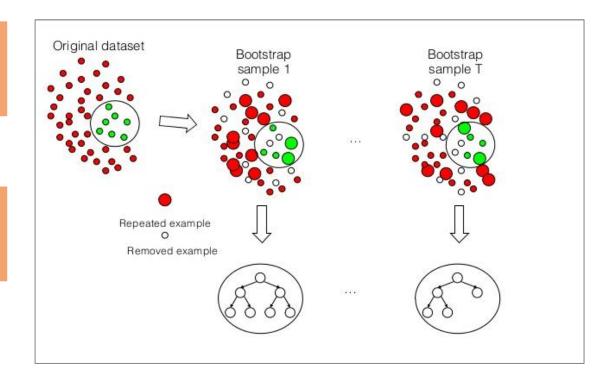




## **Peculiarities of Bagged Trees**

Bagged tree ensemble is comprised of multiple decision trees

Not interpretable as a linear model or simple decision tree



Qualitative statement on ensemble models

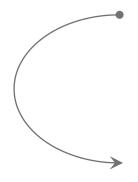


Identify the important predictors by looking at Variable Importance

## **Variable Importance**

Variable Importance - Averaging or summing the improvement in **Gini or Entropy for a classification model** and **RSS for a regression model** for all the variables





Bagged tree ensemble model contains many tree models

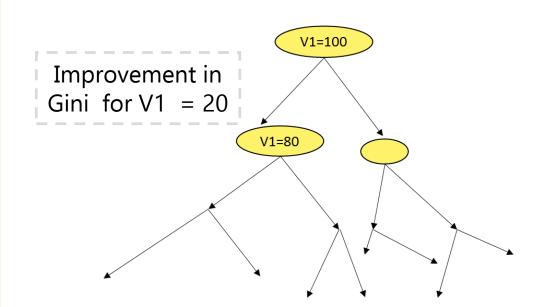
**Feature importance** of each variable in each of the constituent trees

Tracking the decrease in Gini metric and weighing this decrease appropriately

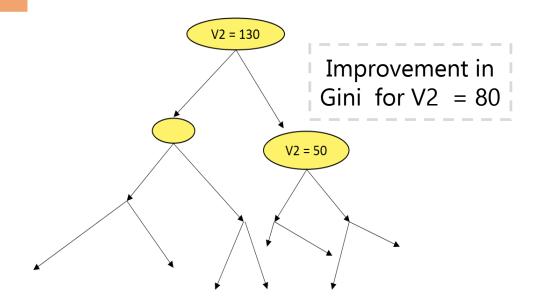




## **Variable Importance**



Tree 1 Gini Measure for each split Example



Tree 2
Gini Measure for each split

Computing variable importance for all the variables used in the split



## **Variable Importance**

#### Ensemble has N trees

Improvement in Gini/RSS Across Splits

Variable	Tree 1	Tree 2	Tree 3	••••	Tree N
V1	300	30	12	••••	0
V2	600	0	200	••••	150
				••••	
$V_k$	120	450	30	••••	19

Variable	Variable Importance
V1	$\frac{(300+30+12+\cdots+0)}{N}$
V2	$\frac{(600 + 0 + 200 + \dots + 150)}{N}$
•••	•••
$V_k$	$\frac{(120 + 450 + 30 + \dots + 19)}{N}$

The average values of importance measures per variable will produce a consolidated number



## **Parameters of Bagged Trees**

What could be the user specified parameters while building a bagged tree model?

Number of tree used to build an ensemble

Depth of the tree

Number of observations per node of a tree



User specified parameters or **Hyperparameters** 

## **Parameters of Bagged Trees**

User specified parameters have an implication

Different ensemble model depending on different parameters

Model 1: Trees = 100Depth of Tree = 4

Which among the three model?

Model 2: Trees = 150Depth of Tree = 3

**K-Fold CV** to get an estimate of out of sample error

Expensive

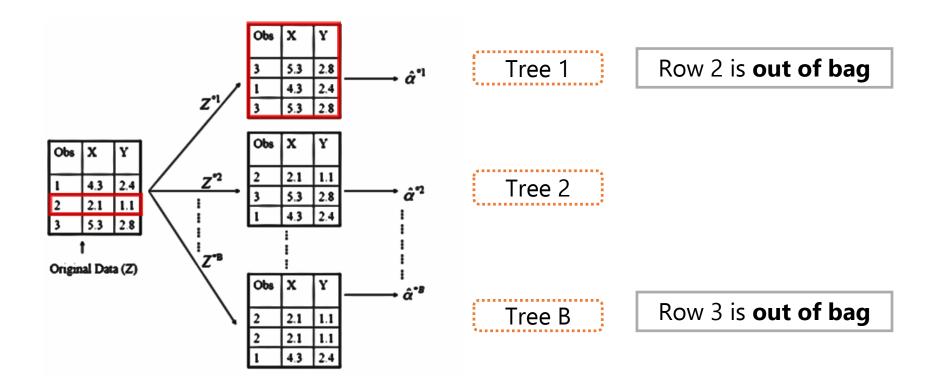
Model 3: Trees = 500Depth of Tree = 4

Out of Bag Error is generally used in most tree based models



## **Out Of Bag Error (OOB)**

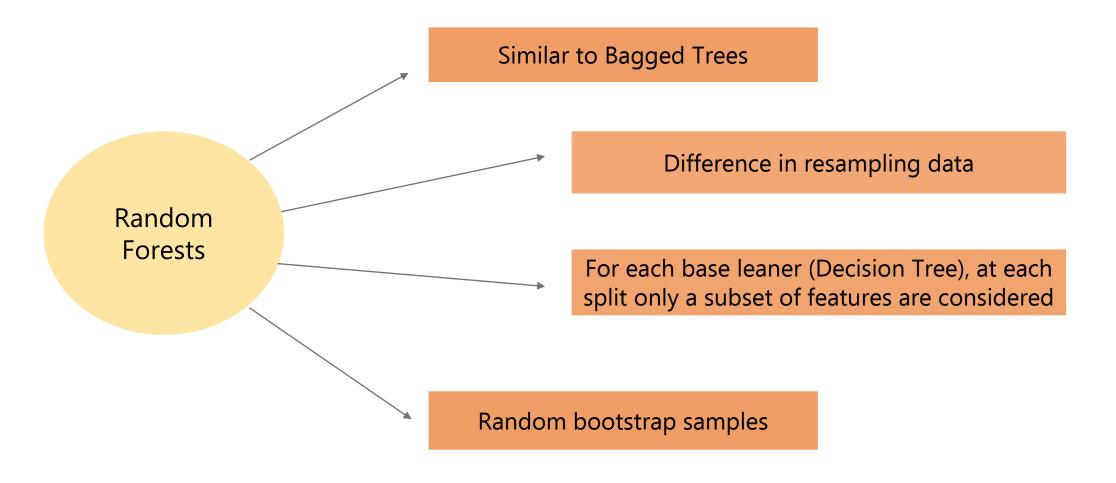
In Bootstrap Sampling, some observation gets left out from the original data



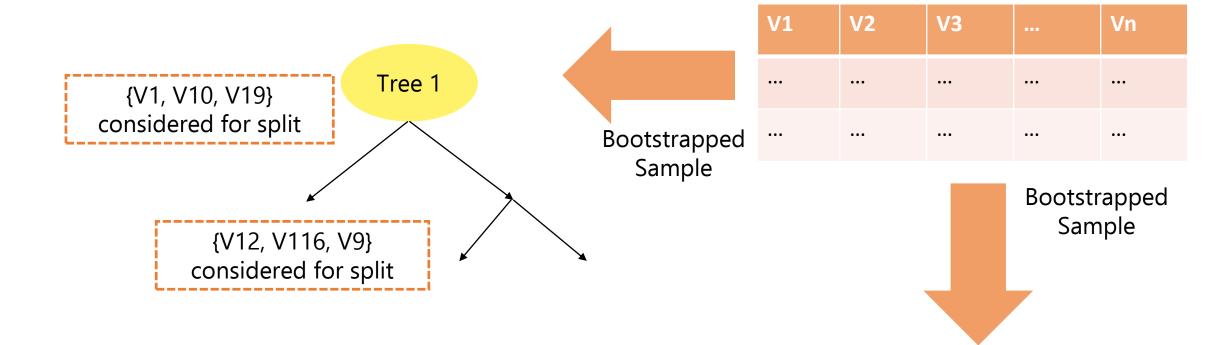
Average Out of Bag observations in Bootstrapped Sampling is around **33**%



#### **Random Forests**

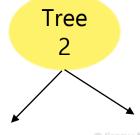


#### **Random Forests**



Number of random sample features for splitting can vary and is usually a **hyperparameter** that the user of the algorithm specifies

{V10, V1, V18} considered for split





#### **Random Forests**

Random Forests uses tree models as base learner

Extract Variable Importance or compute Out-of-bag Error to get an estimate of out of sample model performance for parameter tuning

Number of features considered for each split

Number of trees

**Parameters** of Radom Forests

Number of observations in root node

Depth of tree models



## Recap

- Tree based ensembles overview
- Tree based ensembles models Bagged Tree and Random Forests
- Bootstrapped sampling
- Variable importance
- Out of bag error (OOB error)
- Random Forests
- Code Demo

# MACHINE LEARNING Algorithms



#### Class

### **Tree Based Models**





Topic

Tree Based Ensembles: Adaboost and Gradient Boosting

#### **Adaboost**



Boosting – Another ensemble technique built using decision trees as base learners

Boosted trees works differently than Bagged trees and Random forests

	Boosted Trees	Bagged Trees	Random Forests
Used to build an ensemble	Data re-weighing strategy	Bootstrapped samples	
Depth of tree	Not large (2 to 3 levels)	As many required	





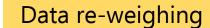
Adaboost is a popular technique



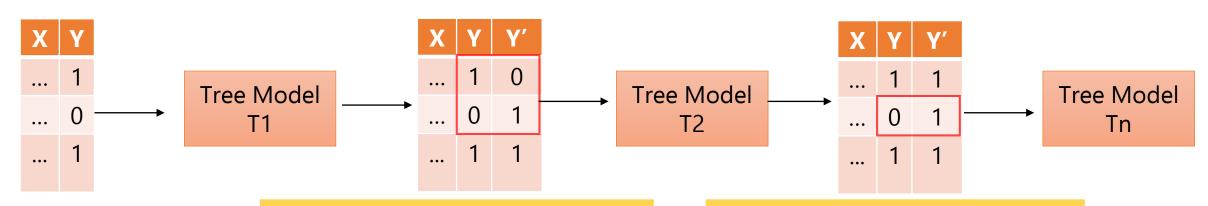
## **Data Re-weighing Strategy**

Classification task using a data set

Wherever the model makes a mistake, that row is given more importance

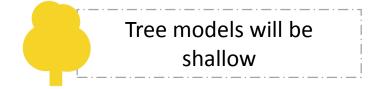


Data re-weighing



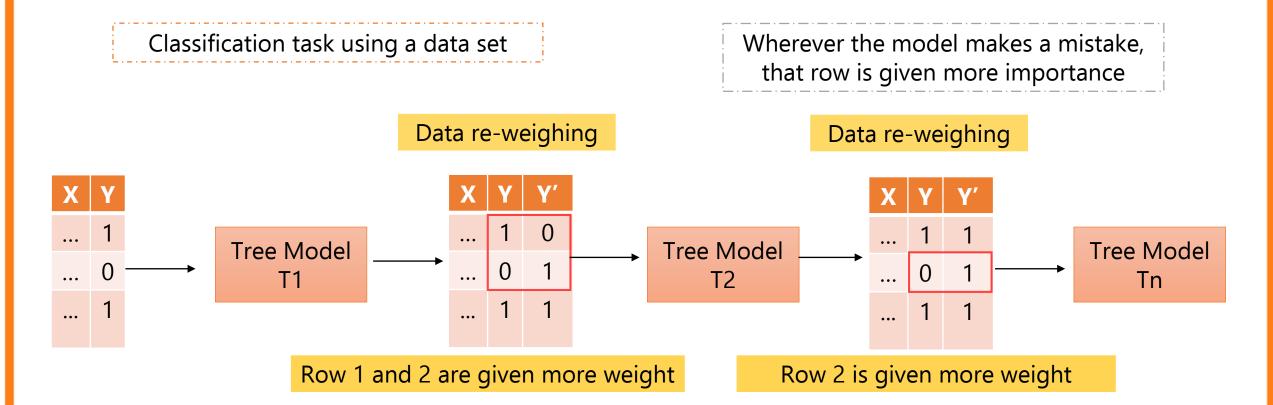
Row 1 and 2 are given more weight

Row 2 is given more weight



Final model is a combination of these trees (T1, T2,... Tn)

## **Data Re-weighing Strategy**



Re-weighing strategy - each successive tree pays more attention to the parts of the data that preceding trees have failed to correctly predict

Successive trees try to improve the error rate



## **Gradient Boosting**

Gradient Boosting is another popular boosting technique



Gradient boosting is an iterative algorithm

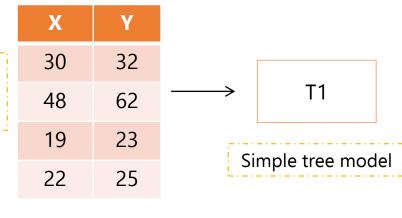
Regression task using a dataset

Yet, the mechanics of the discussions are valid in a classification task

## **Gradient Boosting**

#### Step 1

Data set with 1 predictor and 1 target variable



**Predictions** 

	X	Y	Y'	Residual
	30	32	31	1
	48	62	60	2
-;	19	23	24	-1
j	22	25	26	-1
				Error

T2

Error – difference between the actual variable and predicted variable

#### Step 2

X	Υ		
30	32		
48	62	$\longrightarrow$	T1+T2
19	23	ļ	
22	25	Co	ombination of 2 tree models

X	Y	Y'	Residual
30	32	92.5	0.9
48	62	61	1
19	23	23.5	-0.5
22	25	25.5	-0.5

T3



## **Gradient Boosting**



Keep on repeating this process quite a few times and eventually end up with an ensemble of trees

Gradient boosting is a general ensemble framework





Boosting trees can use other base learner other than decision tree



## **Partial Dependence Plot**

Not as interpretable as simple models like decision trees or linear models

Ensembles provide a list of important predictors by computing variable importance measures

Able to calculate the variables that are important predictors

What is the direction of impact a given predictor has on the dependent variable?

Is the given predictor positively or negatively impacting the dependant variable?



## **Partial Dependence Plot**

Partial Dependence Plot – helps in understanding relationships between a dependent variable and an independent variable

Help in establishing the direction of impact of a predictor on target variable

Depending on which machine learning framework is being used, partial dependence plots for the ensembles may or may not be supported

#### **Drawbacks**

Only bivariate relationships can be understood but unearthing interaction effects can be difficult

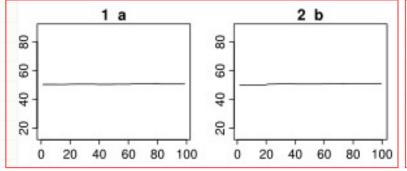
Creating partial dependence plot is computationally expensive

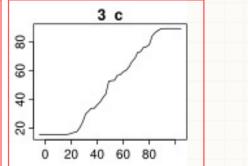


## **Partial Dependence Plot**

Partial dependence plots helps identifying the relationship between value of target and the value of a predictor variable after considering the effect of all the other variables

Y axis = values of target variable





3 partial dependence plots

X axis = values of a predictor

Plot 1 and 2 - Value of target variable doesn't change

Plot 3 - Positive relationship between the target variable and the predictor variable



## **Code Demo**

## Recap

- Adaboost
- Data re-weighing strategy
- Gradient boosting
- Partial dependence plot
- Code demo