

Making Third Person Techniques Recognize First-Person Actions in Egocentric Videos

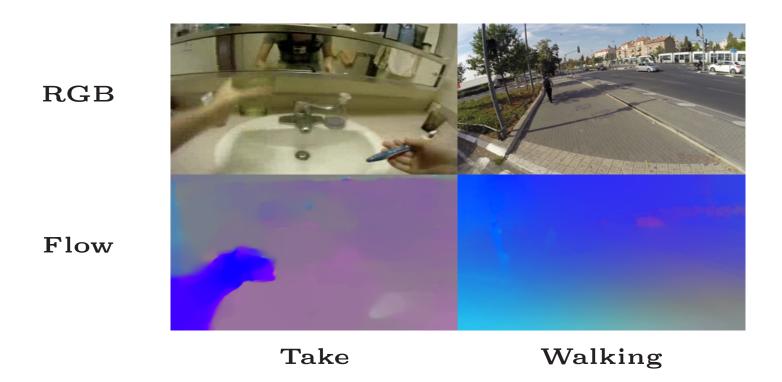


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PROBLEM STATEMENT

DNN trained on third-person actions do not adapt to egocentric actions due to a large difference in size of visible objects. Another complexity is multiple action categories. This work unifies the feature learning for multiple action categories using a generic two-stream architecture.



Actions with hand-object interaction(take) and without(walking) in two different view streams.

CONTRIBUTIONS

1. Deep neural network trained on third person videos do not adapt to egocentric action due to large difference in size of the visible objects.



After cropping and resizing the objects become comparable to the objects in third person videos.

- 2. We propose curriculum learning by merging similar but opposite actions while training CNN.
- 3. Proposed framework is generic to all categories of egocentric actions.

Related Work

Earlier works on first-person action recognition use hands and objects as important cues.[1, 2] On the other end many works only use motion information for first-person action recognition. [3, 4] State of the art (SoTA) techniques focus only on one specific category of action classes.

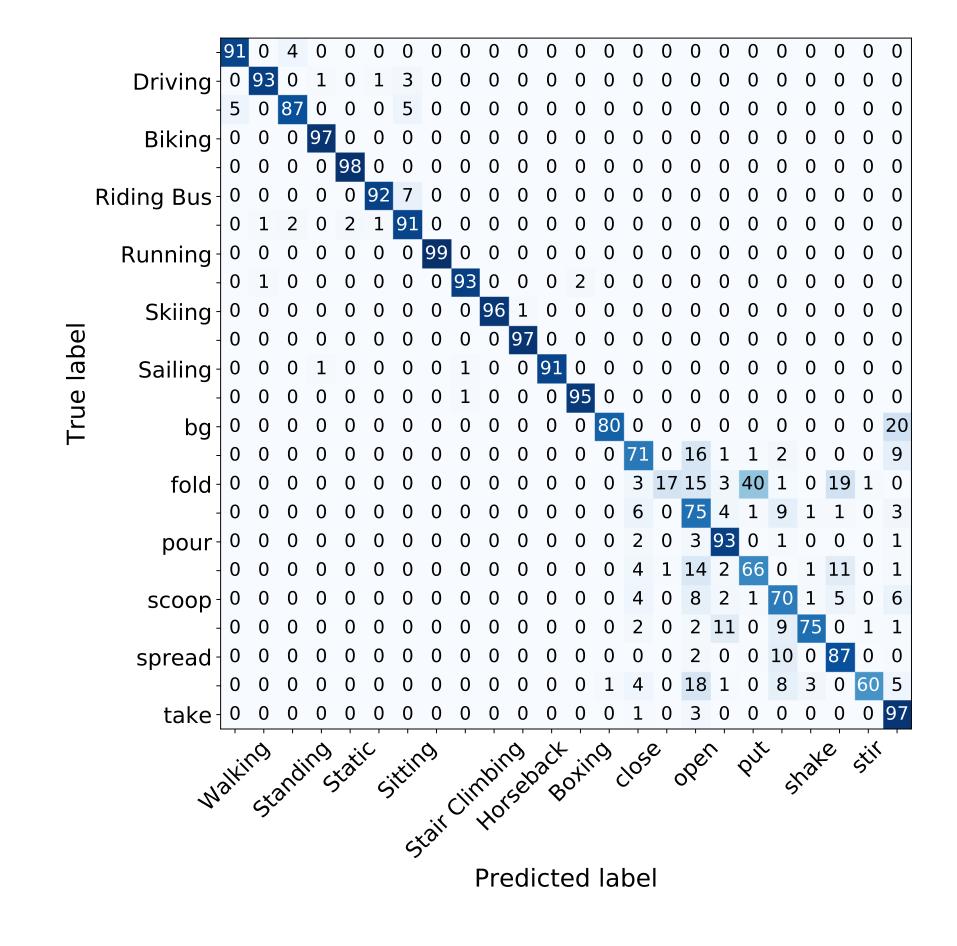
Proposed Architecture Resize (300x300) LSTM₁ SoftMax₁ ResNet50 LSTM SoftMax SoftMax Random Crop 224x224) RGB Stream LSTM₁ SoftMax₁ Central Crop (MxN) ResNet50 LSTM SoftMax SoftMax Flow Long/Short term actions Flow Stream

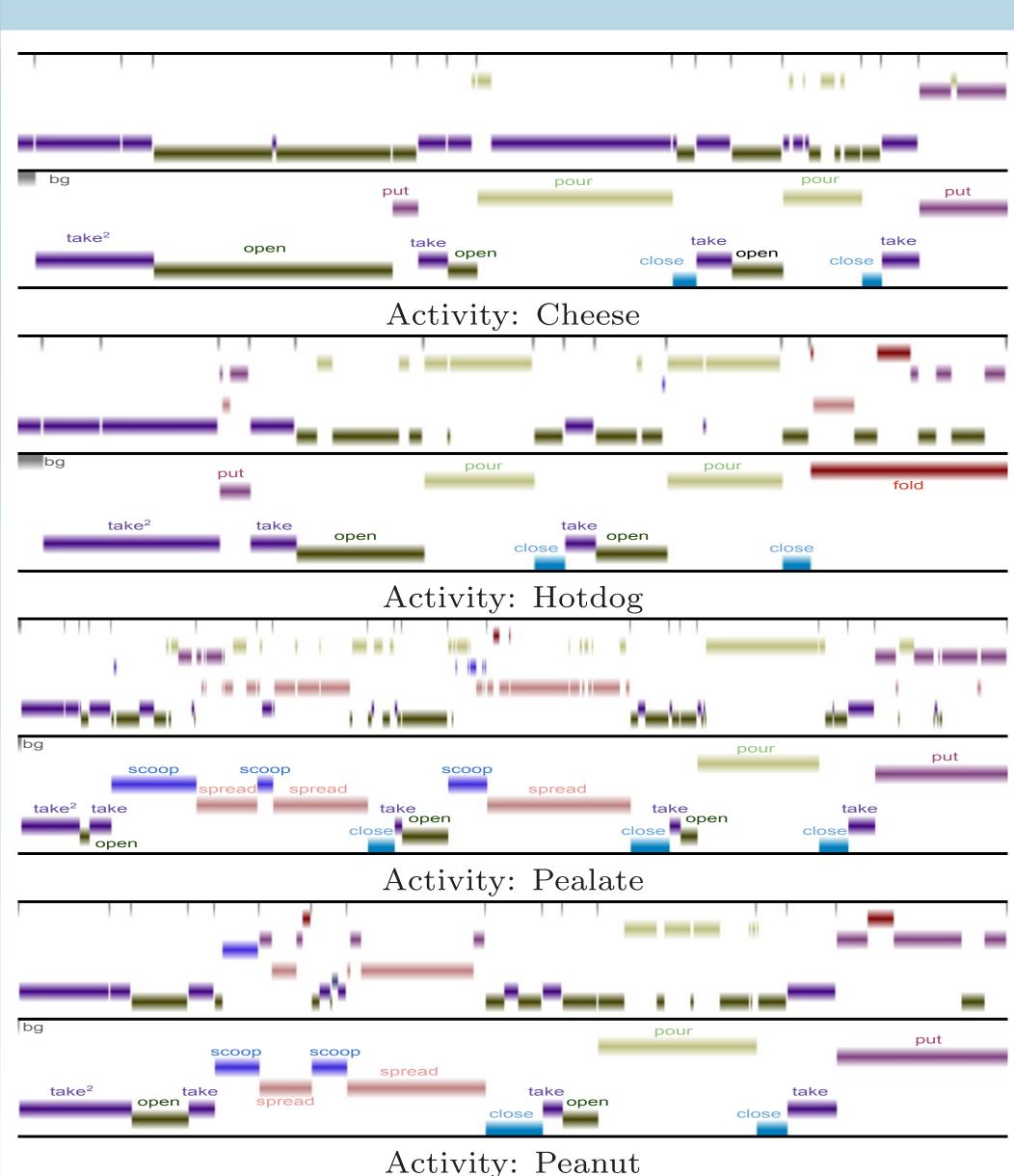
RESULTS AND DISCUSSION

Dataset	Subjects	Frames	Classes	Accuracy		
				Current	Ours	Accuracy comparison
GTEA [1]	4	31,253	11	68.50[5]	82.71	of our method with
EGTEA+[1]	32	$1,\!055,\!937$	19	NA	66	SoTA and statistics of
Kitchen [6]	7	$48,\!117$	29	66.23[5]	71.92	egocentric video
ADL [2]	5	$93,\!293$	21	37.58[5]	44.13	datasets
$\mathrm{UTE} \ [7]$	2	$208,\!230$	21	60.17[5]	65.12	
HUJI [8]	NA	1,338,606	14	86[8]	93.92	

Applicability in real life setting where different action categories are present

To validate the applicability of our method, we use mixed samples from GTEA [1] and HUJI [8] dataset. From the confusion matrix it is evident that the proposed network does not seem to have any confusion in the different category of actions.





Top and bottom of each subfigure shows predicted and ground truth sequence respectively.

REFERENCES

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