SEIJI SHAW

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EDUCATION	Ph.D. in Electrical Engineering and Computer Science Massachusetts Institute of Technology, Cambridge, MA Advisor: Prof. Nicholas Roy	2022-
	M.S. in Electrical Engineering and Computer Science Massachusetts Institute of Technology, Cambridge, MA Advisor: Prof. Nicholas Roy	2022-
	Sc.B., with Honors, in Mathematics-Computer Science Brown University, Providence, RI Advisor: Prof. George Konidaris Thesis: Towards Safe Learning in Robotic Manipulation	2018-2022
EMPLOYMENT	Graduate Researcher Computer Science and Artifical Intelligence Lab, MIT Robust Robotics Group (PI: Nicholas Roy)	2022 - Present
	Undergraduate Researcher Department of Computer Science, Brown University Intelligent Robot Lab (PI: George Konidaris)	2020 - 2022
	Research Intern Mitsubishi Electric Research Laboratories, Cambridge, MA Data Analytics Group (PI: Daniel Nikovski)	Summer 2021
	Research Intern Cedars-Sinai Medical Center Hong Lab (PI: TingTing Hong)	Summers 2015, 2019
AWARDS AND HONORS	Senior Prize, Brown University Dept. of Computer Science Sigma Xi, inducted Outstanding Winner, COMAP Mathematical Contest in Mode Rachel Carson Award, COMAP Mathematical Contest in Mode	_

PUBLICATIONS

- 4. Seiji Shaw, Ben Abbatematteo, and George Konidaris. Rmps for safe impedance control in contact-rich manipulation. In 2022 International Conference on Robotics and Automation, pages 2707–2713. IEEE, 2022
- 3. Tiffany Ding*, Soryan Kumar*, and Seiji Shaw*. A seabird population model to evaluate plastic pollution policies. *UMAP Journal of Undergraduate Mathematics and its Applications*, 41(3), 2020
- 2. Yan Liu, Kang Zhou, Jing Li, Sosse Agvanian, Ana-Maria Caldaruse, Seiji Shaw, Tara C Hitzeman, Robin M Shaw, and TingTing Hong. In mice subjected to chronic stress, exogenous cbin1 preserves calcium-handling machinery and cardiac function. *Basic to Translational Science*, 5(6):561–578, 2020

1. Ying Fu, Seiji A Shaw, Robert Naami, Caresse L Vuong, Wassim A Basheer, Xiuqing Guo, and TingTing Hong. Isoproterenol promotes rapid ryanodine receptor movement to bridging integrator 1 (bin1)—organized dyads. *Circulation*, 133(4):388–397, 2016

GRANTS AND	National Science Foundation Graduate Research Fellowship	2022-2025
FELLOWSHIPS	Ford Foundation Fellowship, Honorable Mention	2022
	Karen T. Romer Undergraduate Research and Teaching Award	2019

TEACHING Head Teaching Assistant, CSCI 1951R: Introduction to Robotics Fall 2020

Dept. Computer Science, Brown University

Instructor: Stefanie Tellex

OUTREACH Choreorobotics Controls Engineer and Mentor Spring, Summer 2022

Dept. Theatre and Performance Studies, Brown University

Workshop Instructor 2019-2020

Brown Design Workshop, Dept. of Engineering, Brown University

Mentor, Team 5987 Galaxia Fall 2017-Spring 2018

Reali Hebrew Day School, Haifa, Israel

Mentor, Team 6000 Firehawk Robotics 2018-2019

Shalhevet High School, Los Angeles, California

REFEREEING IEEE International Conference on Robotics and Automation (ICRA) 2023

OTHER Shabbat Program Coordinator, MIT GradHillel 2023-Orthodox Student Community Liaison, Brown-RISD Hillel 2019-2021

Blacher Outstanding New Student Initiatives Award, Brown-RISD Hillel 2019