

# Structure-Aware Manipulation of Images and Videos

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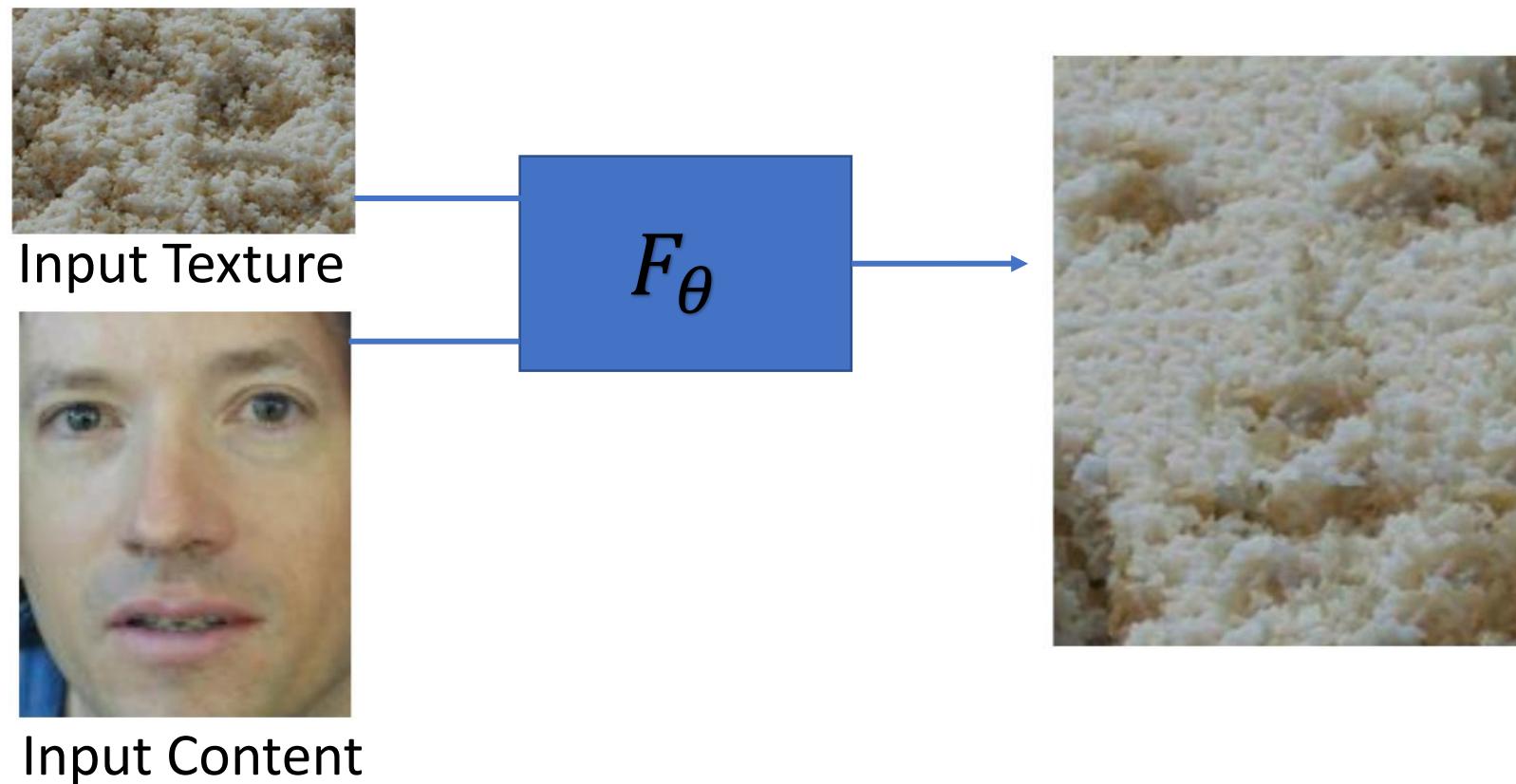
# What is a natural image?

Intelligent  
machines must  
**understand**  
perceived  
content

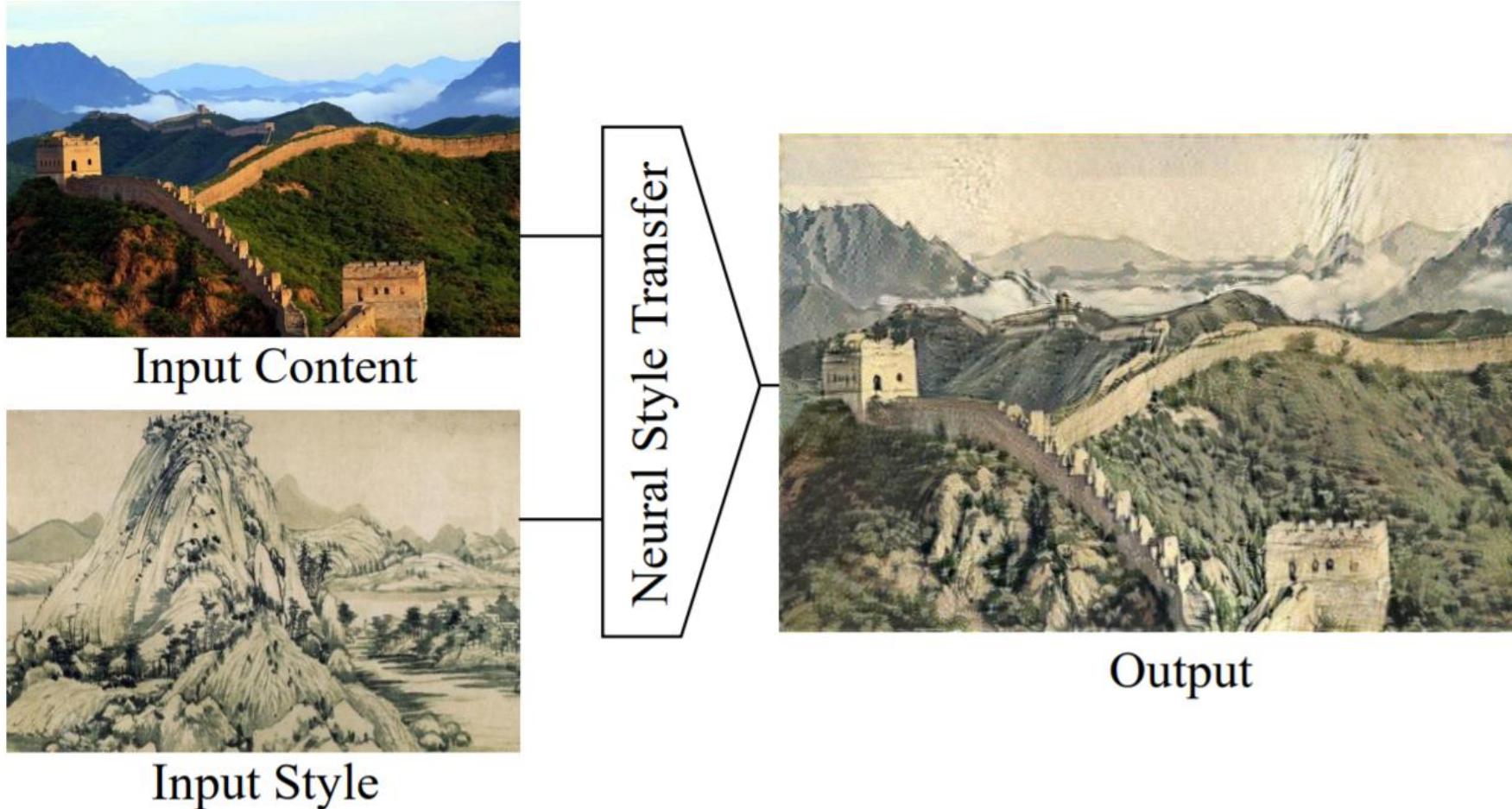


**Understanding by  
creating/manipulating:**  
“What I cannot create,  
I do not understand”  
(Richard Feynman)

# Manipulating Texture



# Manipulating Style



# Image to Image Translation

1.  $F_\theta(x)$  preserves the **structure** of objects of  $x$
2.  $F_\theta(x)$  belongs to  $Y$ 's distribution (changes **style**)

$x \in X$



$$F_\theta$$

$F_\theta(x) \in Y$



$$F_\theta$$



CycleGAN, Zhu et al., ICCV 2017  
DistanceGAN, Benaim et al., NeurIPS 2017  
MUNIT, Huang et al., ECCV 2018  
Many more...

# Manipulating Structure



Target



Source Structure



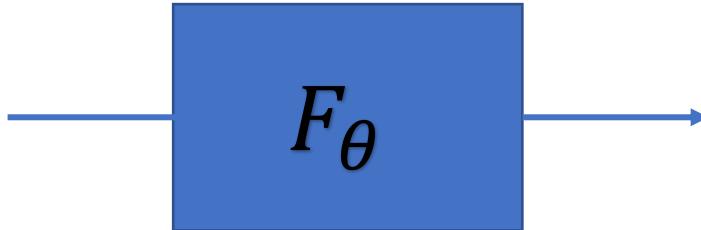
# Manipulating Structure



Target



Source Structure



# Applications

Architecture



Video games



Movies



Advertising



AR/VR



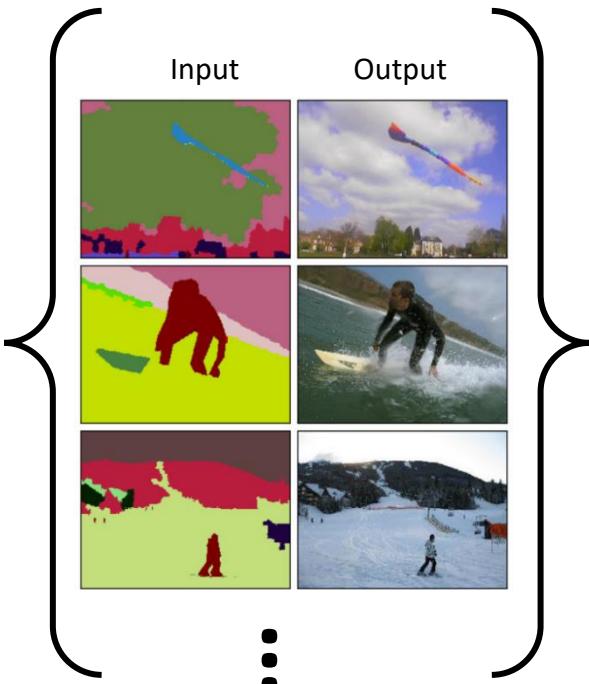
Autonomous Driving Simulations



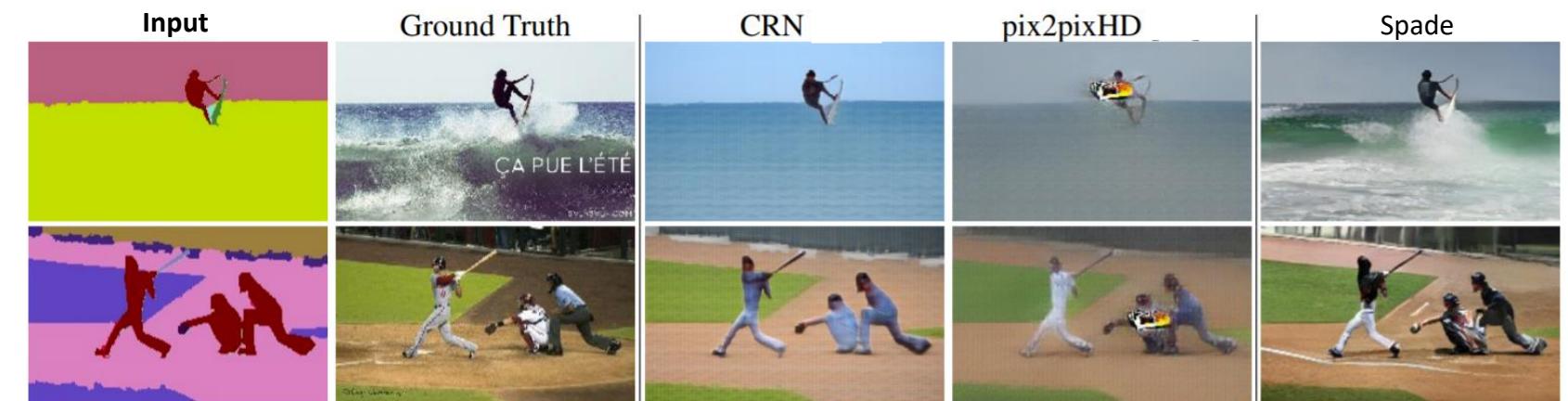
# Multi-Image Approaches

# Supervised (Paired) Setting

Train



Test



# Unsupervised (Unpaired) Setting

**A**



Faces without glasses

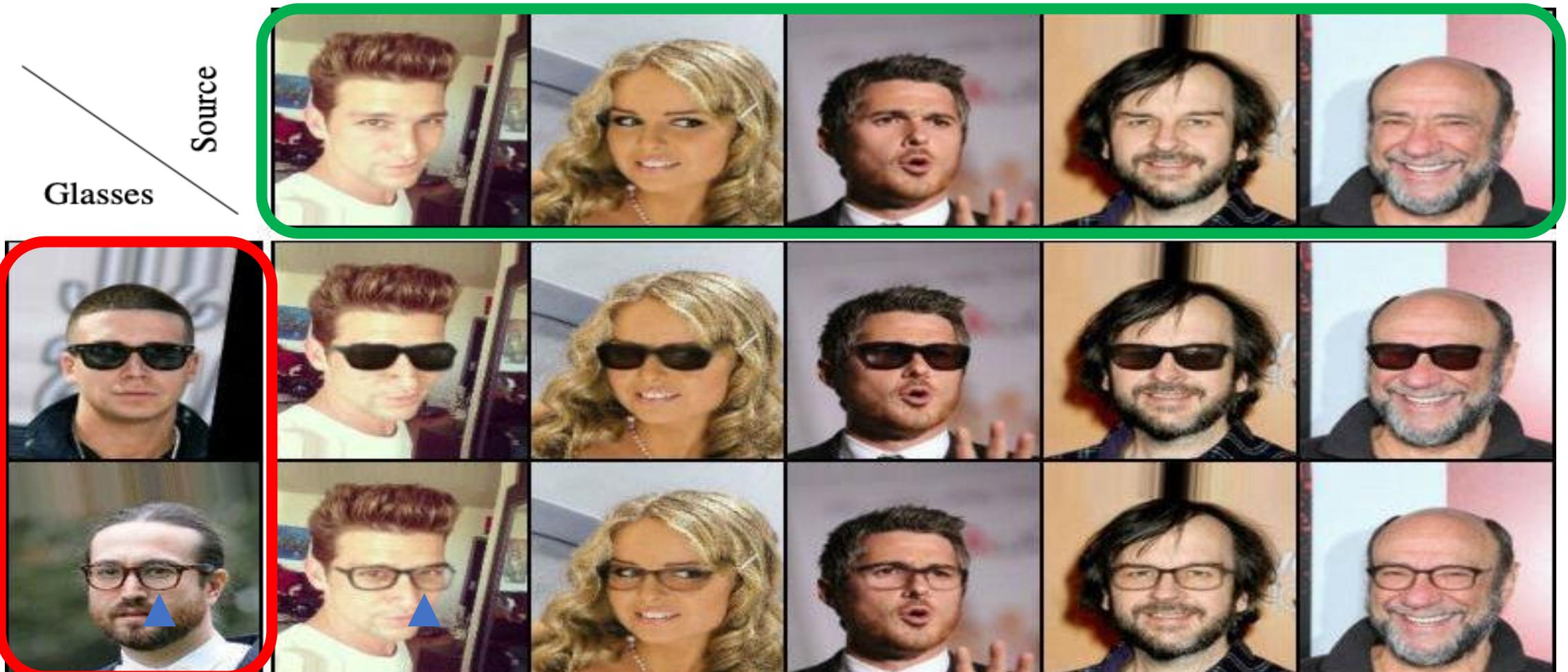
**B**



Faces with glasses

# Control Structure of Generated Faces (Transfer Glasses)

Common



Separate

# Domain Intersection and Domain Difference

**S. Benaim, M. Khaitov, T. Galanti, L. Wolf.** ICCV 2019.

Given two visual domains, disentangle the  
**separate (domain specific)** information and  
**common (domain invariant)** information.

# Unsupervised Content Transfer

A



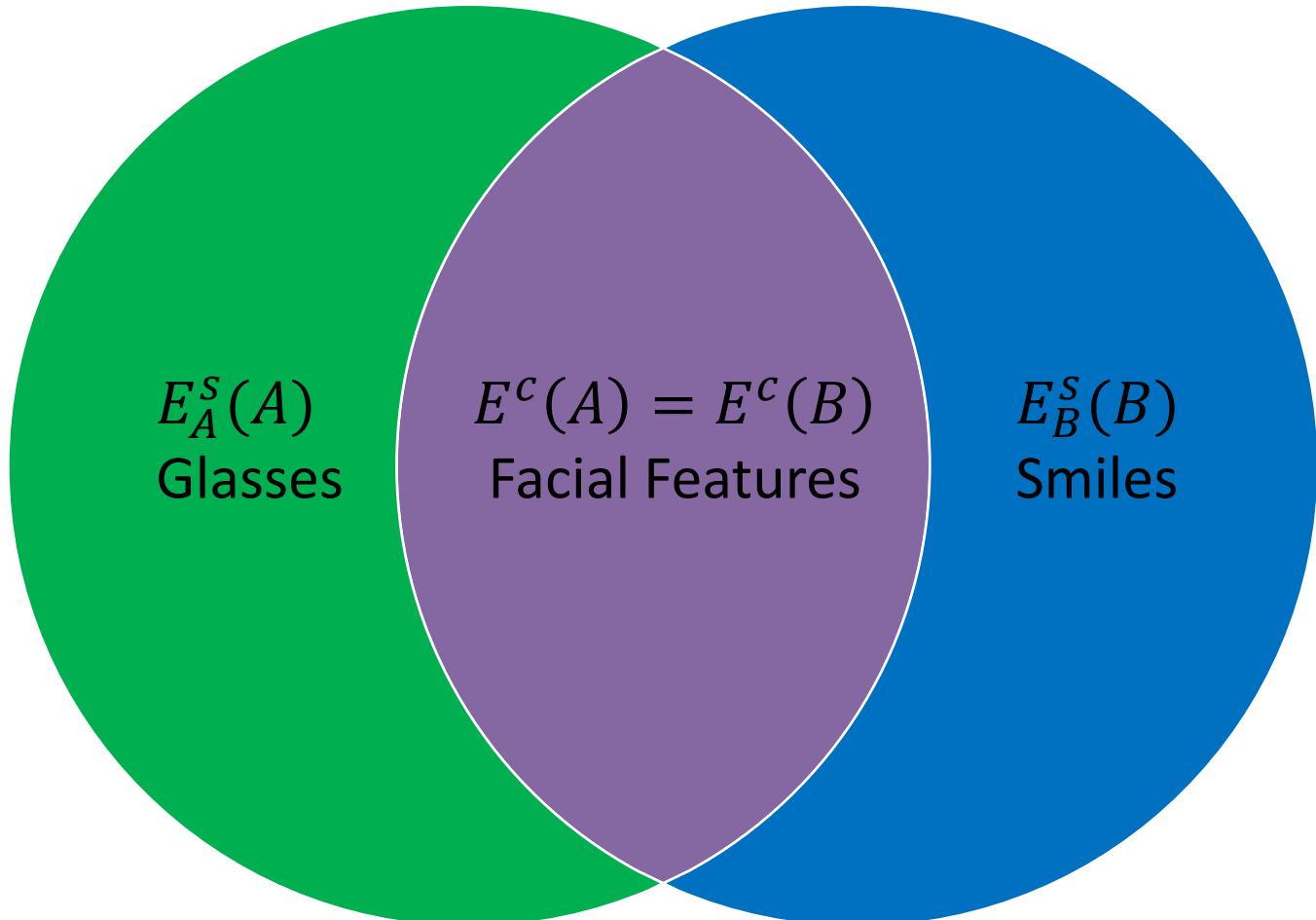
Non-smiling faces with glasses

B



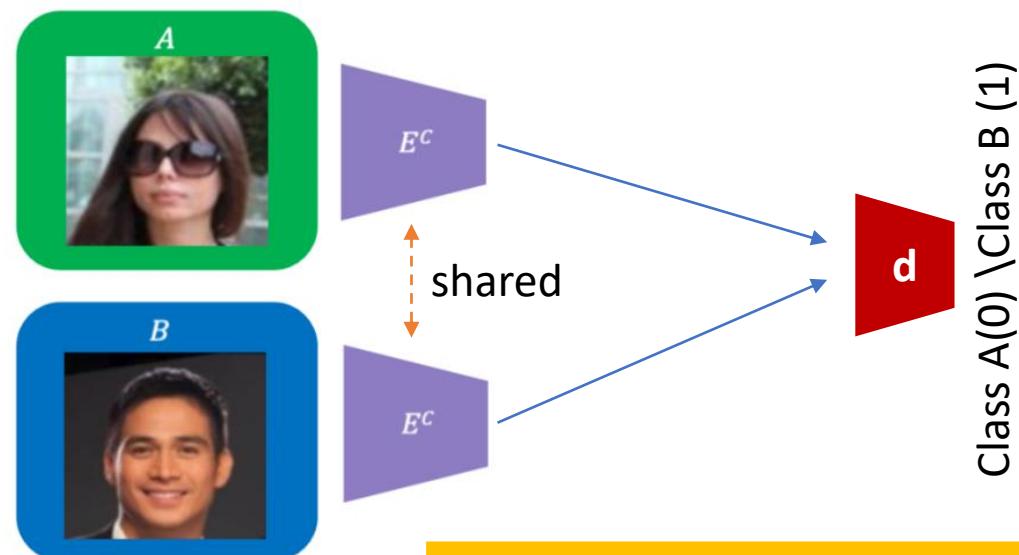
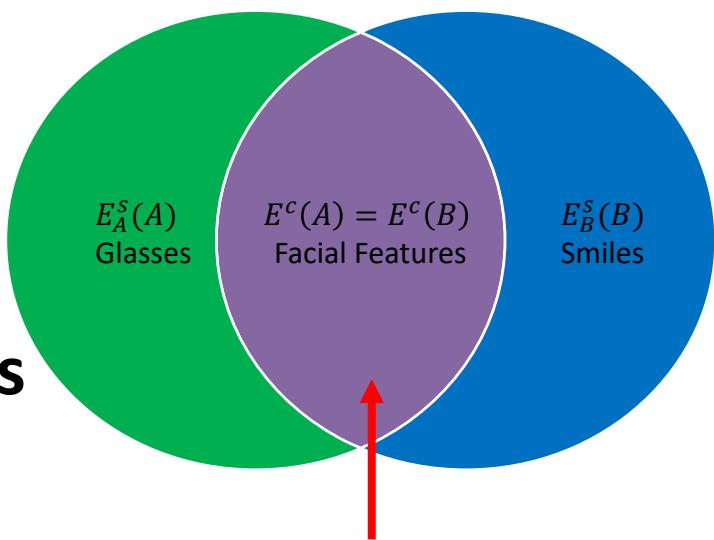
Smiling faces without glasses

1. "Common" latent space,  $E^c(A) = E^c(B)$ . The space of **common facial features**.
2. "Separate" latent space for domain A,  $E_A^s(A)$ . The **space of glasses**.
3. "Separate" latent space for domain B,  $E_B^s(B)$ . The **space of smiles**.



# The "common" Loss

Ensures  $E_c$  encodes information common to both domains



Discriminator  $d$  attempts to separate distributions (classify to correct label):

$$\frac{1}{m_1} \sum_{i=1}^{m_1} l(d(E^c(a_i)), 0) + \frac{1}{m_2} \sum_{j=1}^{m_2} l(d(E^c(b_j)), 1)$$

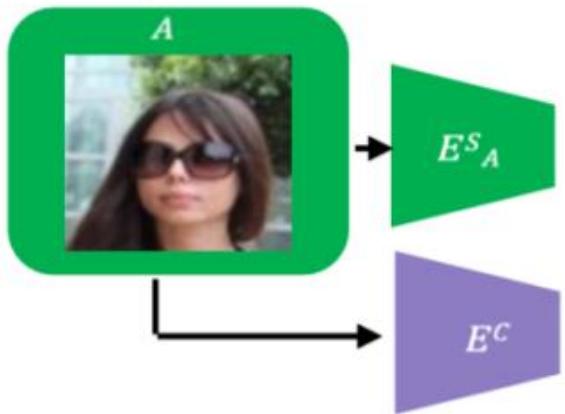
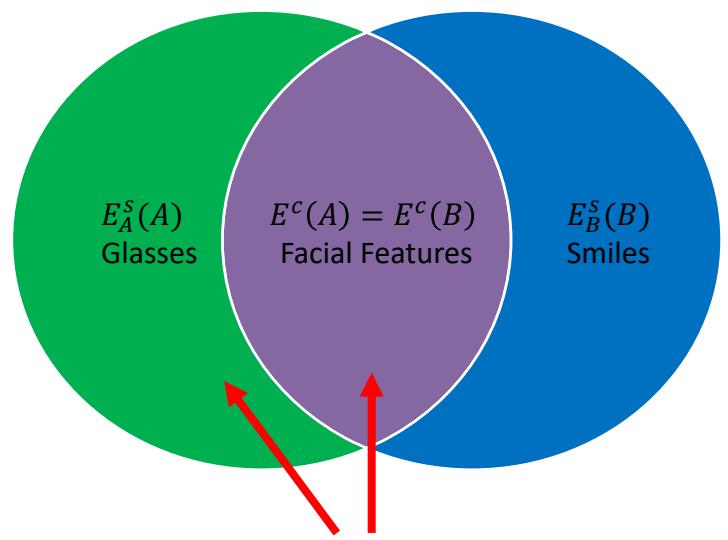
Encoder  $E_c$  attempts to match distributions of  $E_c(A)$  and  $E_c(B)$ :

**$d$  can encode zero information**

$$m_1 \sum_{i=1}^{m_1} l(d(E^c(a_i)), 0) + m_2 \sum_{j=1}^{m_2} l(d(E^c(b_j)), 1)$$

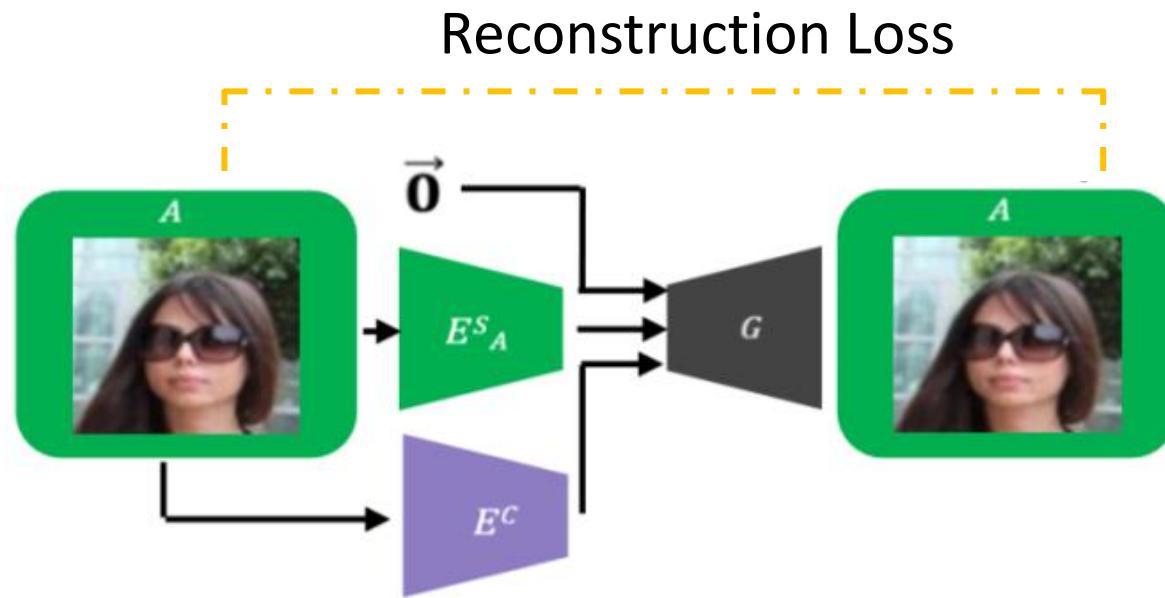
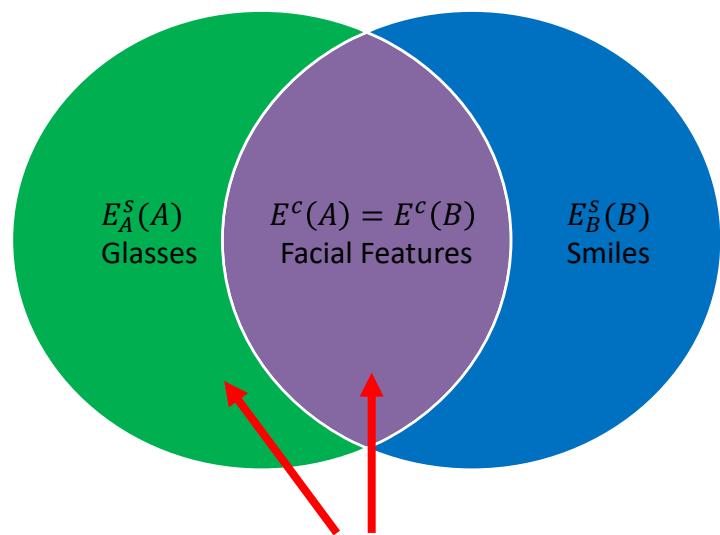
# Reconstruction Losses

Ensures the “common” and  
“separate” encodings contain all  
the information in A



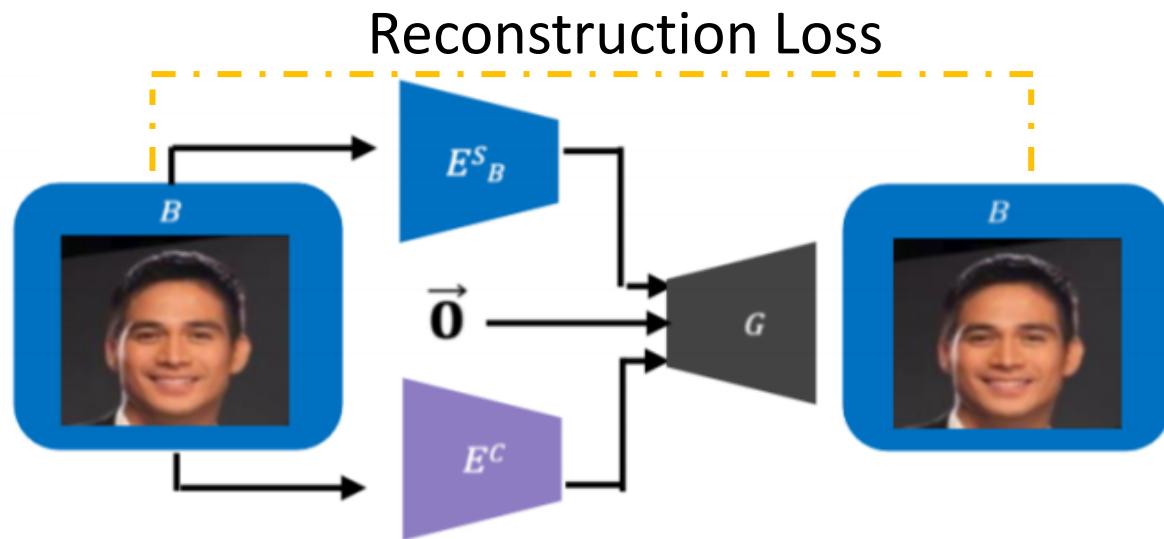
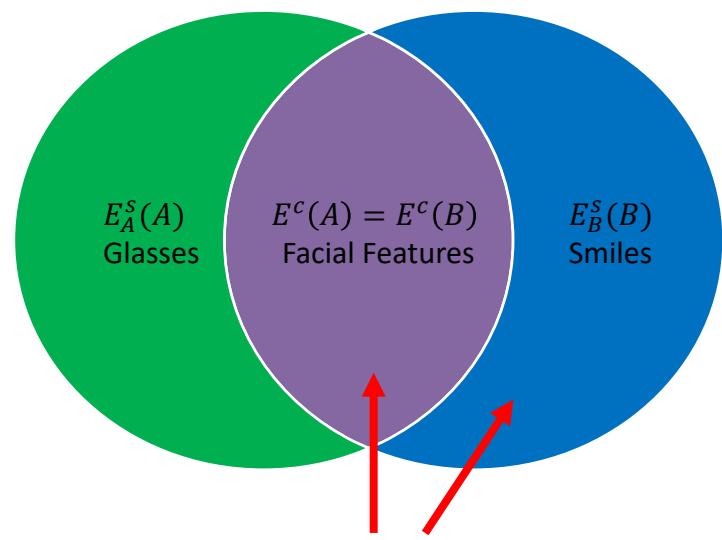
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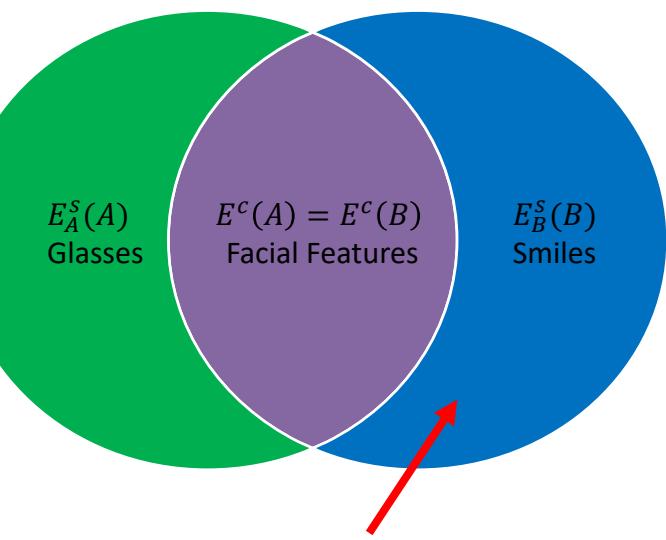
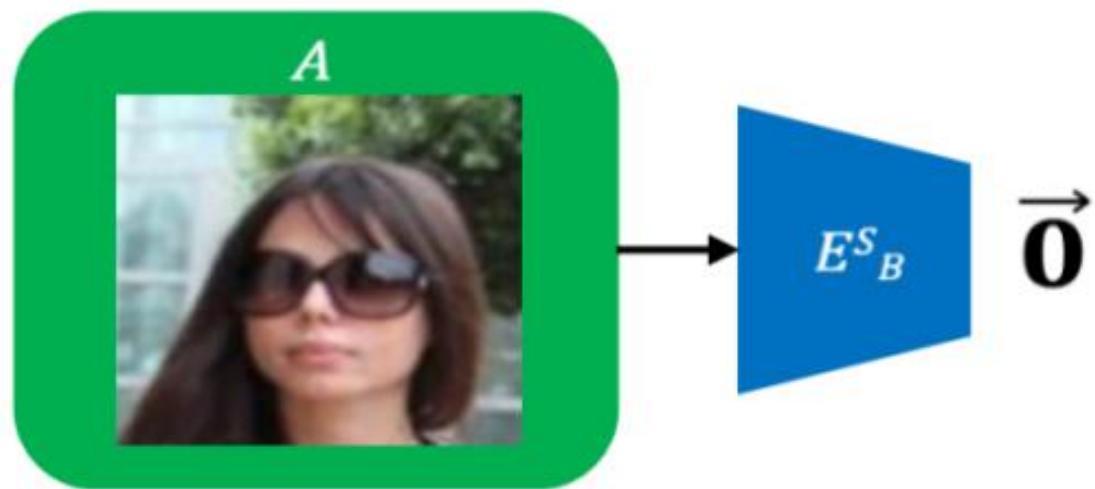


$E_A^S$  ( $E_B^S$ ) can encode all the information of A (B)

# "Zero" LOSS

**Ensures the separate encoder of B  
does not encode information  
about A**

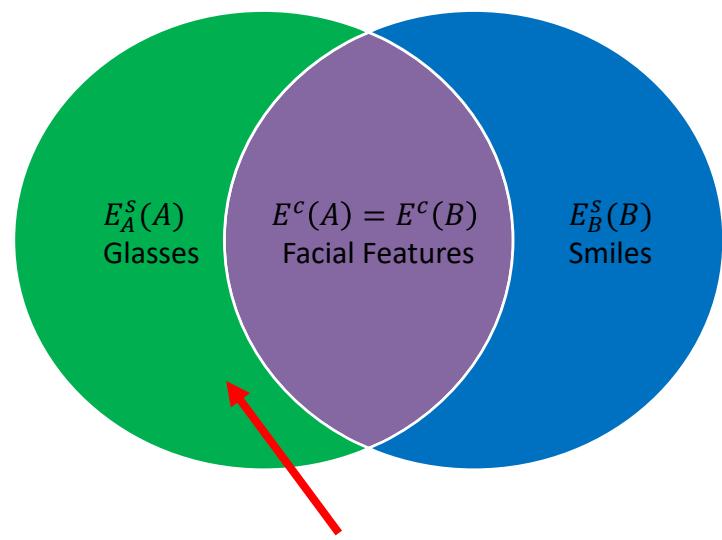
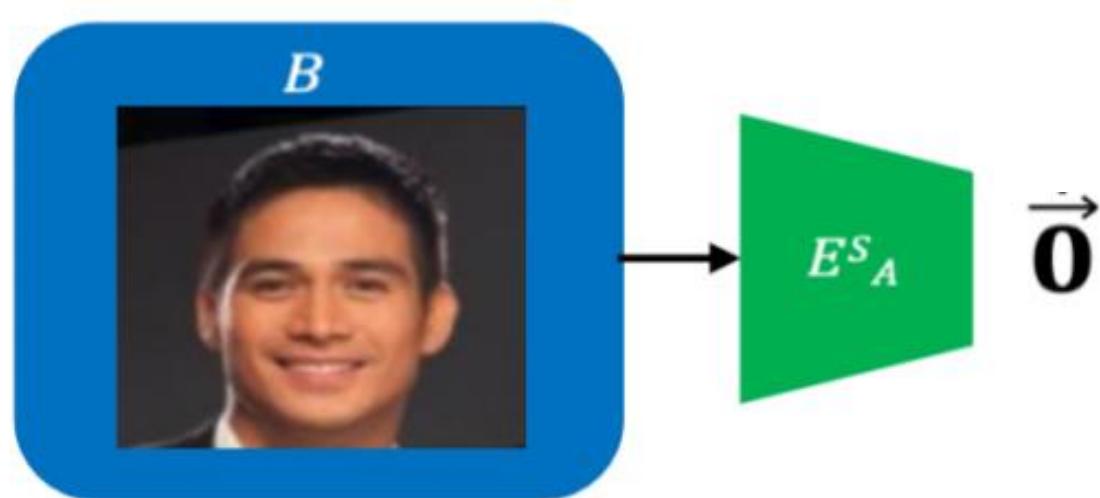
$$\mathcal{L}_{zero}^B := \frac{1}{m_1} \sum_{i=1}^{m_1} \|E_B^s(a_i)\|_1$$



# "Zero" LOSS

**Ensures the separate encoder of B  
does not encode information  
about A**

$$\mathcal{L}_{zero}^A := \frac{1}{m_2} \sum_{j=1}^{m_2} \|E_A^s(b_j)\|_1$$



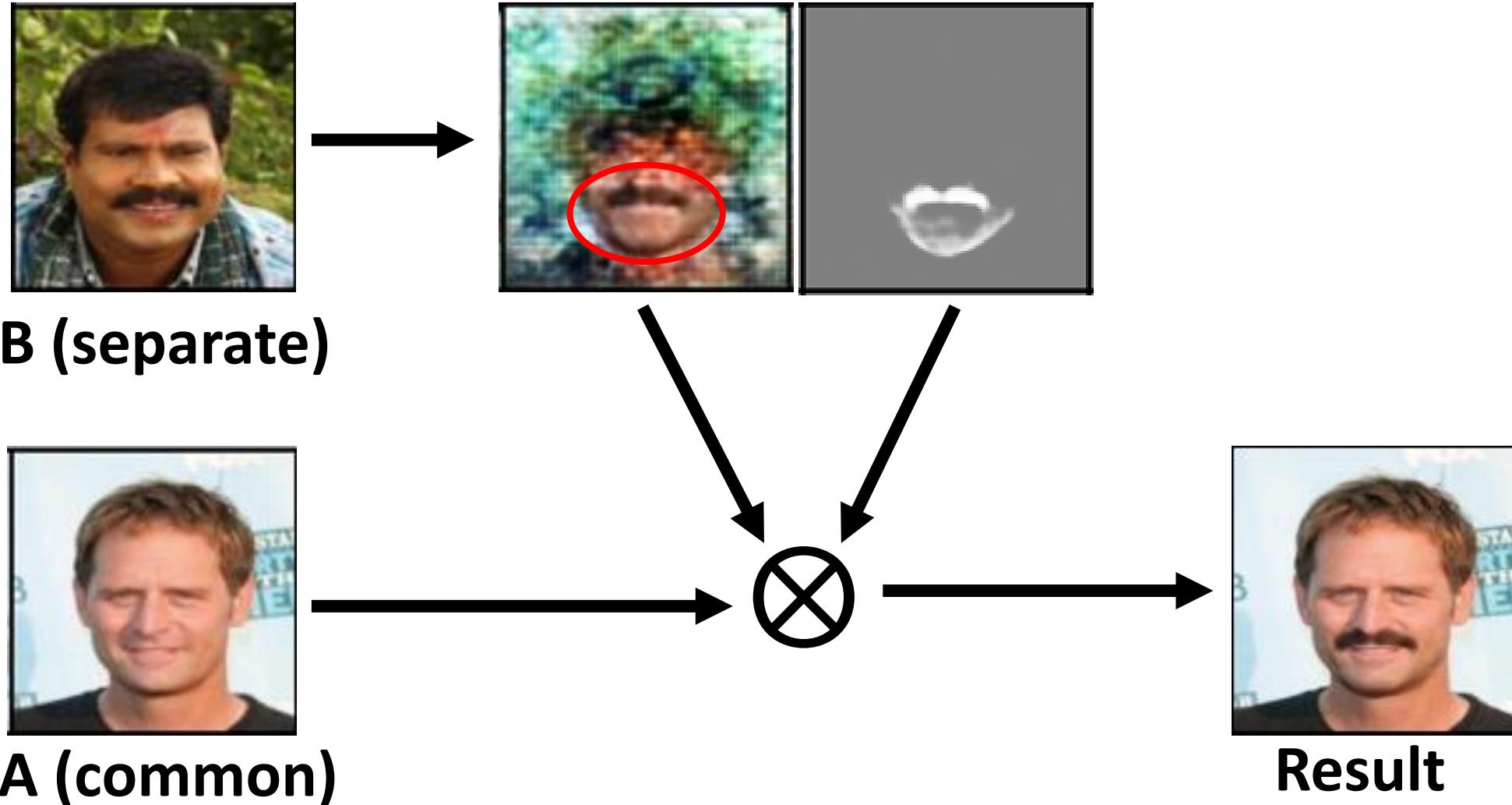
$$G\left(\mathrm{E}_c(c), E_A^S(a), E_B^S(b)\right) \longrightarrow \begin{array}{l} \text{c's face} \\ \text{a's glasses} \\ \text{b's smile} \end{array}$$

c's face      a's glasses    b's smile

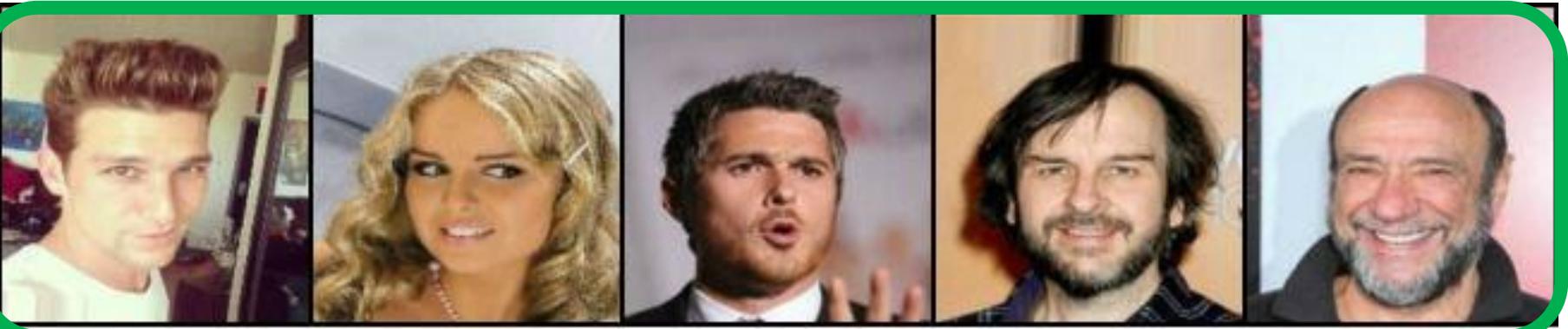
$$G\left(\mathrm{E}_c(\text{}), E_A^S(\text{}), E_A^S(\text{}), E_A^S(\text{<img alt="Portrait of a man wearing sunglasses" data-bbox='473 787 553 900" style="display: block; margin: auto;"/>}), 0 \right) \longrightarrow \text{$$

# Masked Based Unsupervised Content Transfer

R. Mokady, S. Benaim, L. Wolf, A. Bermano. ICLR 2020.



Common



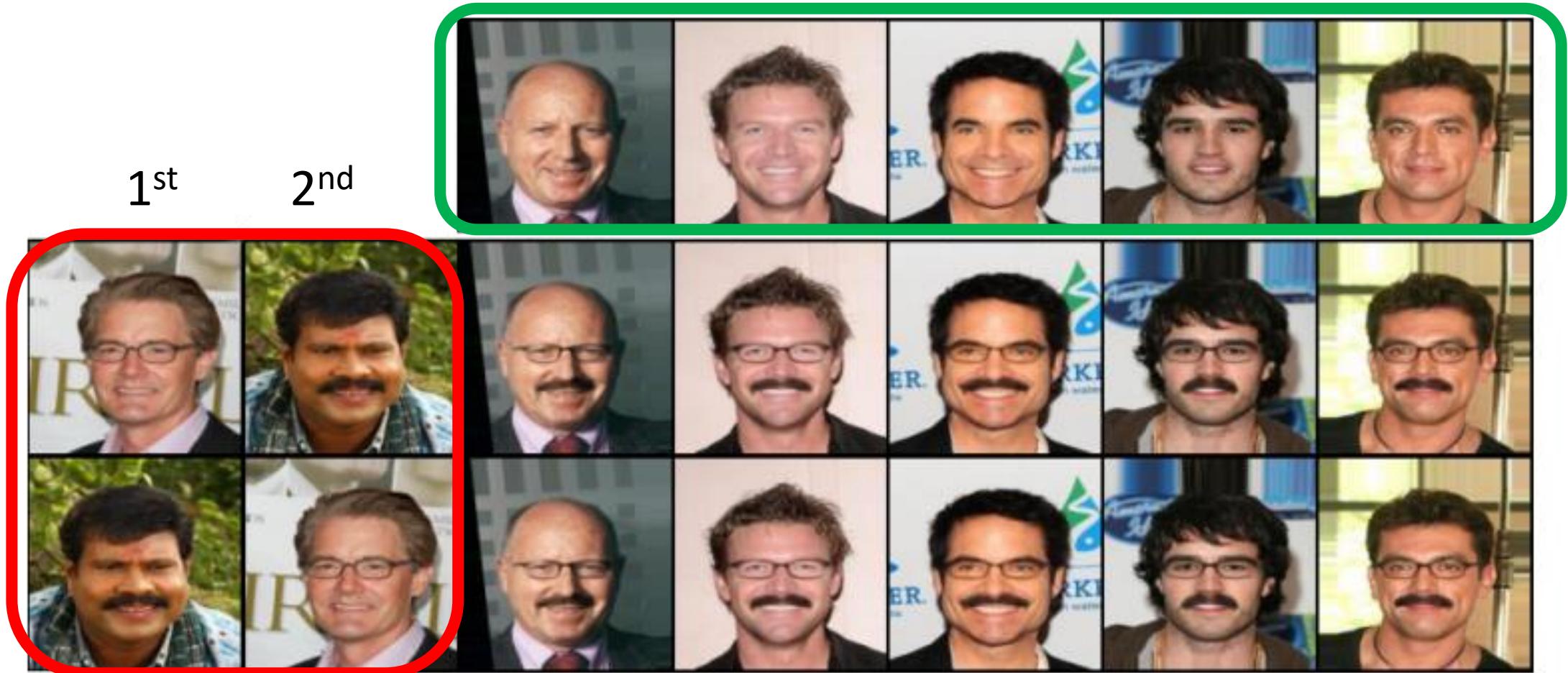
Source

Glasses



Separate

# Two Attributes



# Attribute removal

**Input**

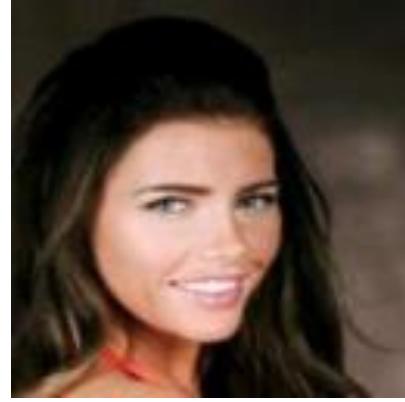


**Result**

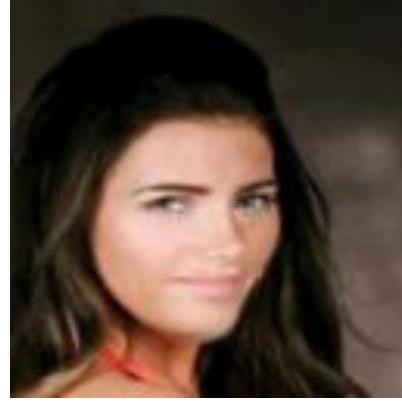


**Facial Hair Removal**

**Input**



**Result**



**Smile Removal**

# Out of Domain Manipulation



# Weakly-Supervised Segmentation

Table 5: Mean and SD IoU for the two hair segmentation benchmarks.

Method	Women's hair	Men's hair
Ours	$0.77 \pm 0.15$	$0.77 \pm 0.13$
Press et al.	$0.67 \pm 0.13$	$0.58 \pm 0.11$
Ahn & Kwak.	$0.54 \pm 0.10$	$0.52 \pm 0.10$
CAM	$0.43 \pm 0.09$	$0.56 \pm 0.07$



GT

Ours

Press  
et al.

Ahn et  
al.

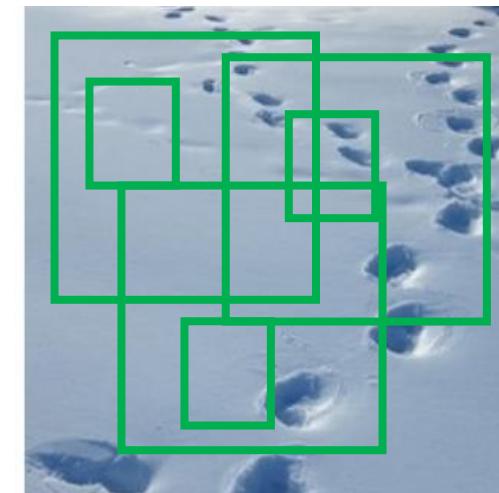
CAM

# Patch-Based Approaches

# Multi-Image Distribution



# Multi-Scale Patch Distribution

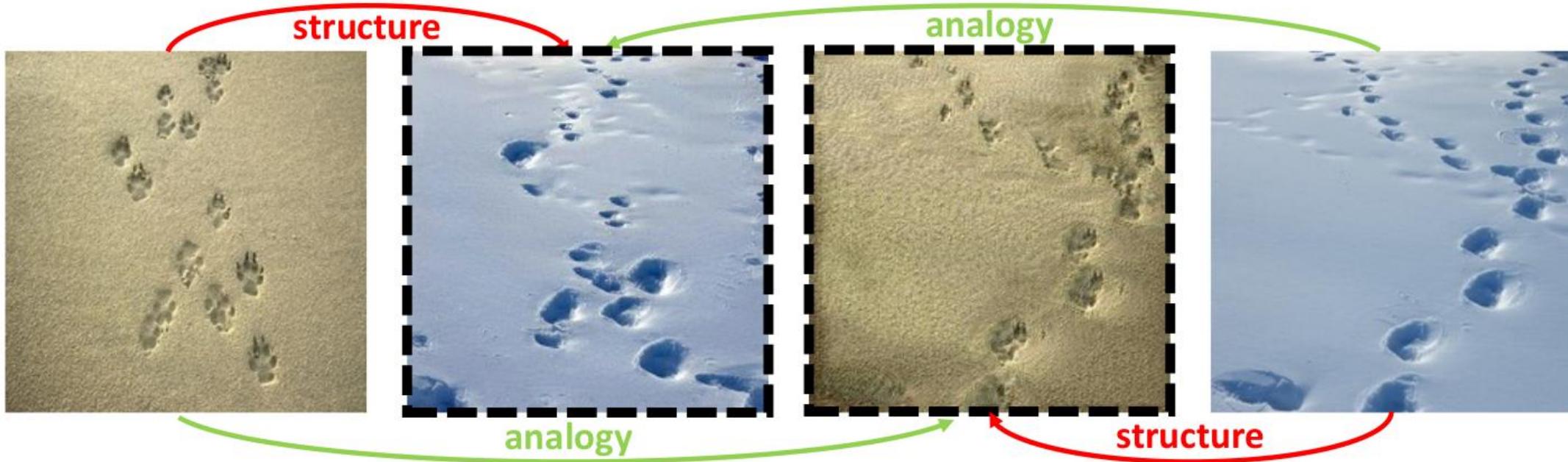


# Structural-analogy from a Single Image Pair

S. Benaim\*, R. Mokady\*, A. Bermano, D Cohen-Or, L. Wolf. CGF 2020. (\*Equal contribution)



Generate an image which is aligned to the source image but depicts structure from a target image



# Structural Analogy

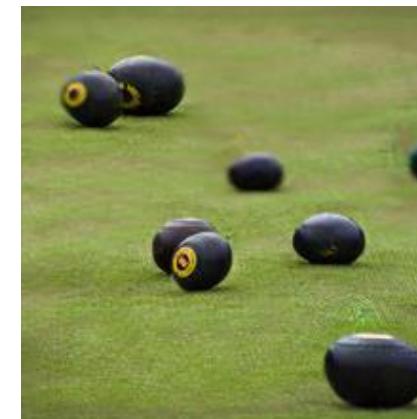
Target



Source

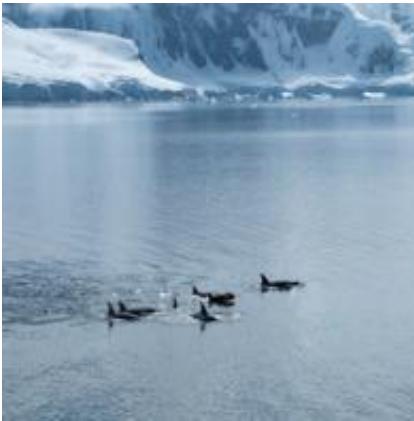


Output



# Structural Analogy

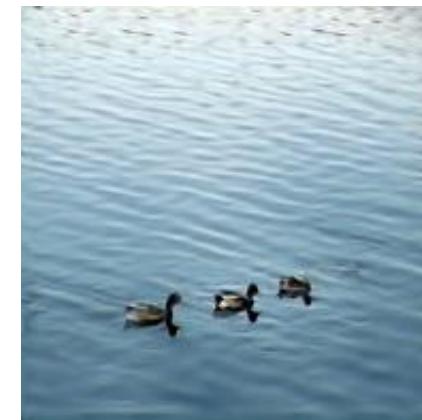
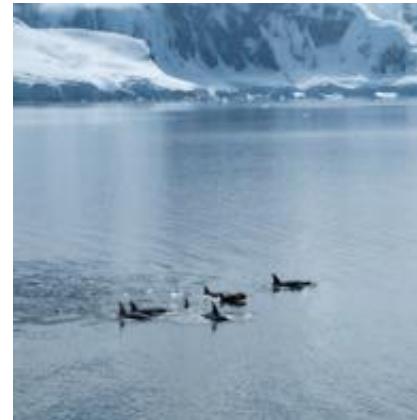
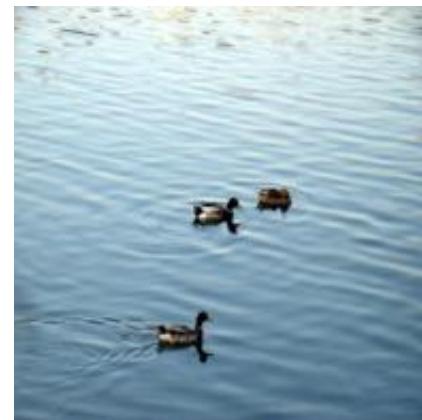
Target



Source



Output



# Structural Analogy

Target



Source



Output



# Style Transfer

# Deep Image Analogy

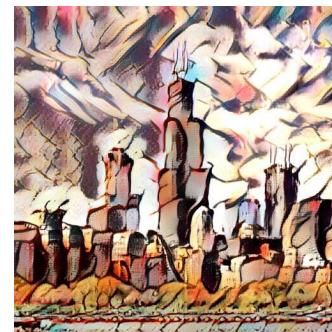
Style



Content



Result



Style



Content

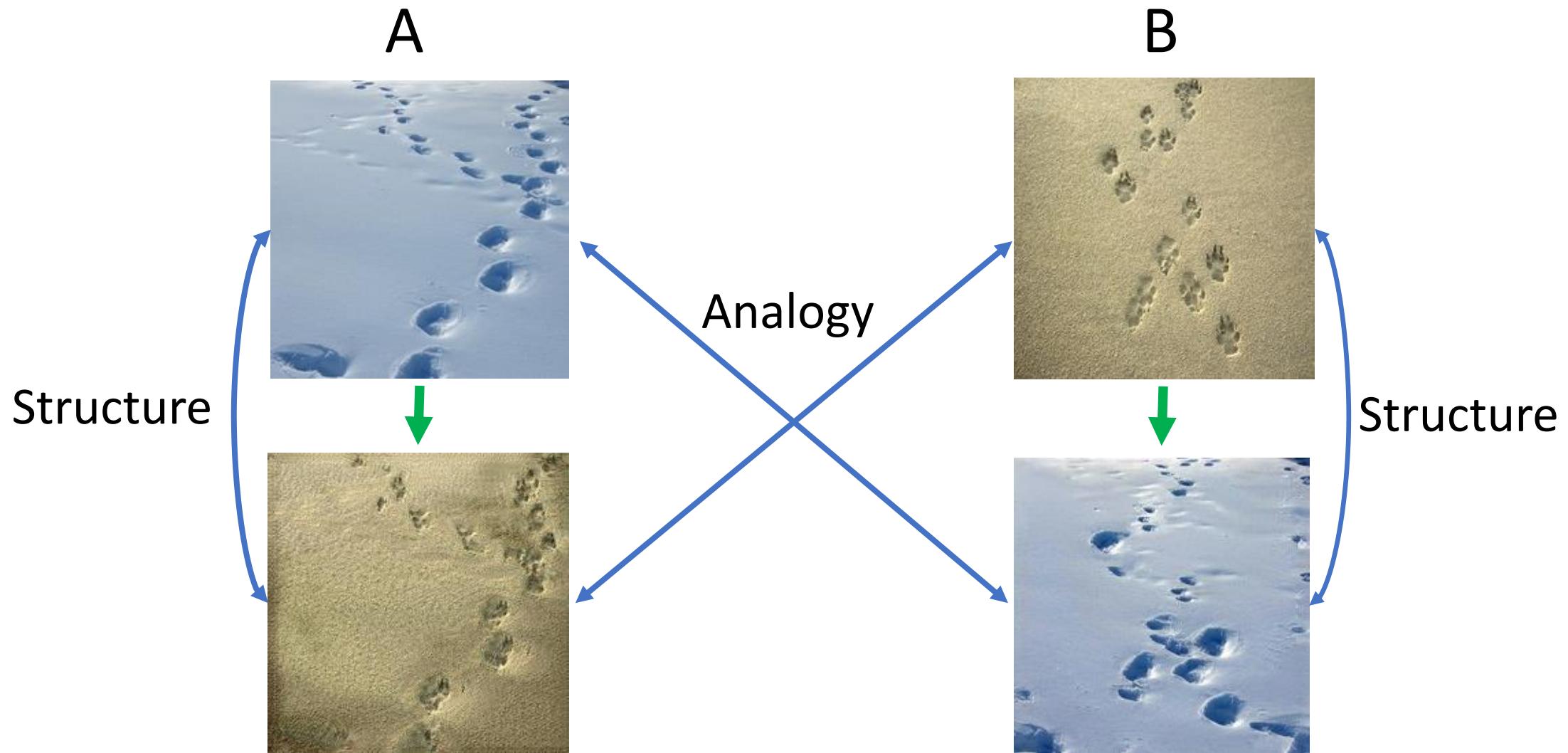


Result



Cannot Change Object Shape

# Structural Analogy



# Motivation

A

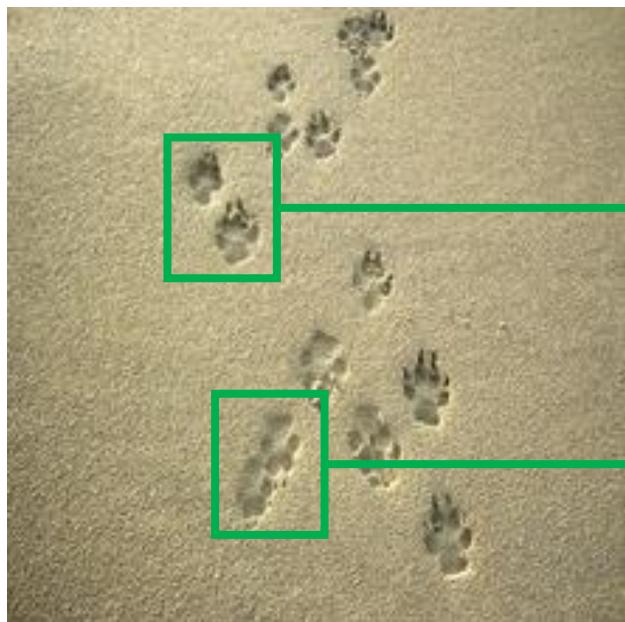


B



# Motivation

A



B



# Motivation

A



B



# Proposed Hierarchical Approach

Coarsest scale:  
**Large Patches**

$\bar{a}^0$ (Unconditional)  
 $\bar{ab}^0$ (Conditional)

LEVEL = 0

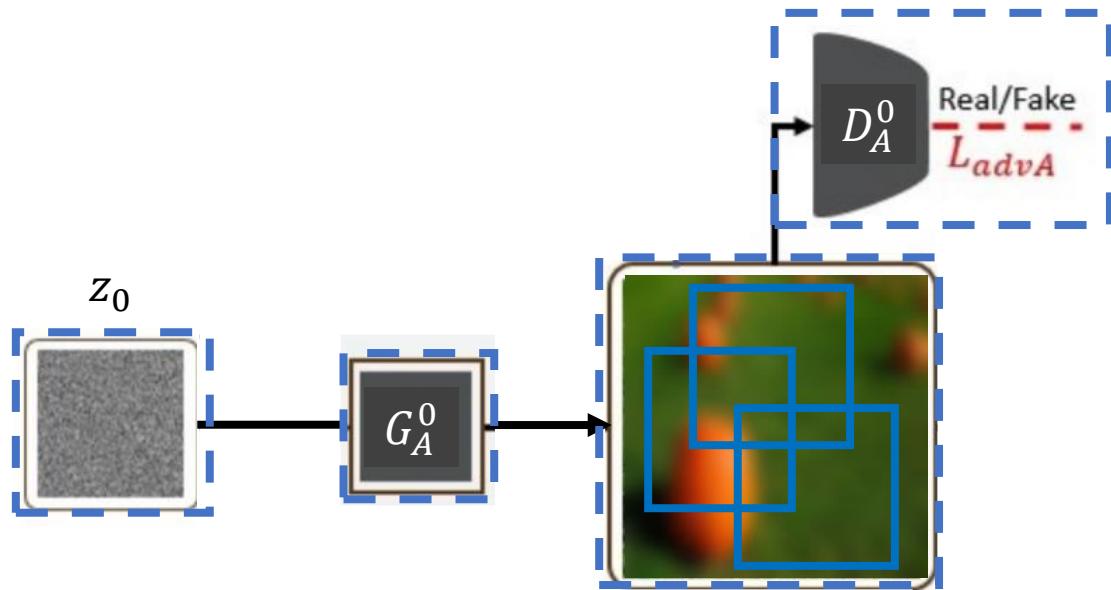
Finest scale:  
**Small Patches**

$\bar{a}^N$ (Unconditional)  
 $\bar{ab}^N$ (Conditional)

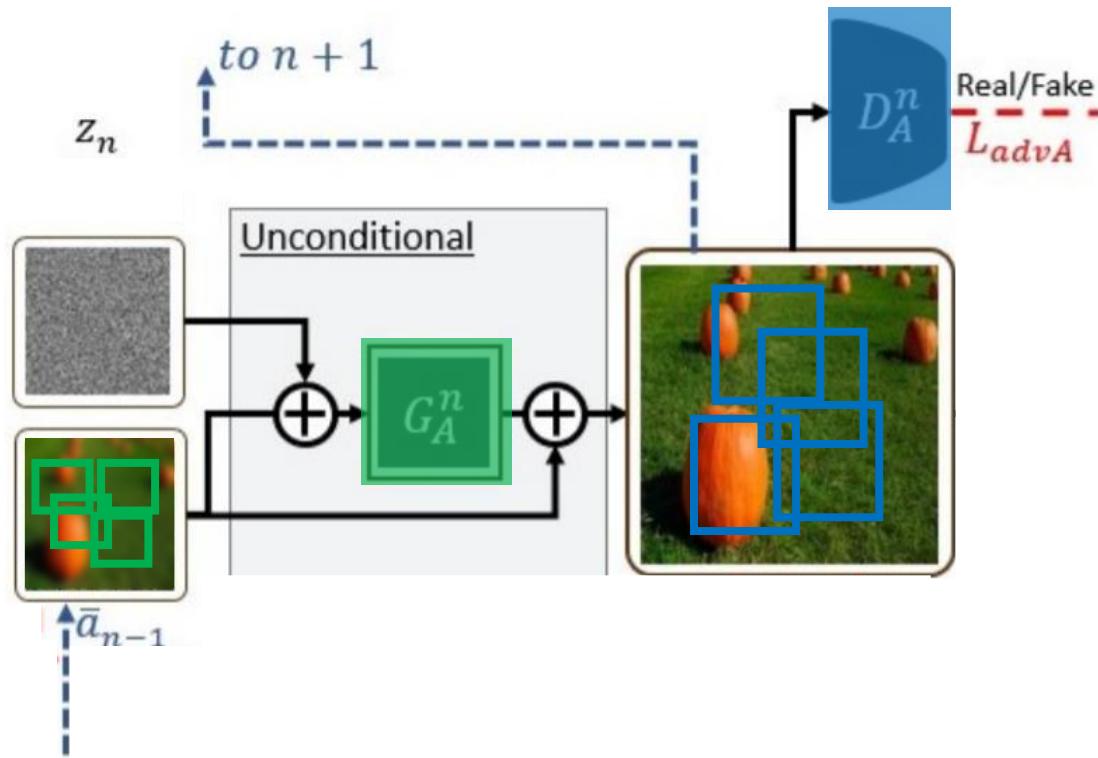
LEVEL = N



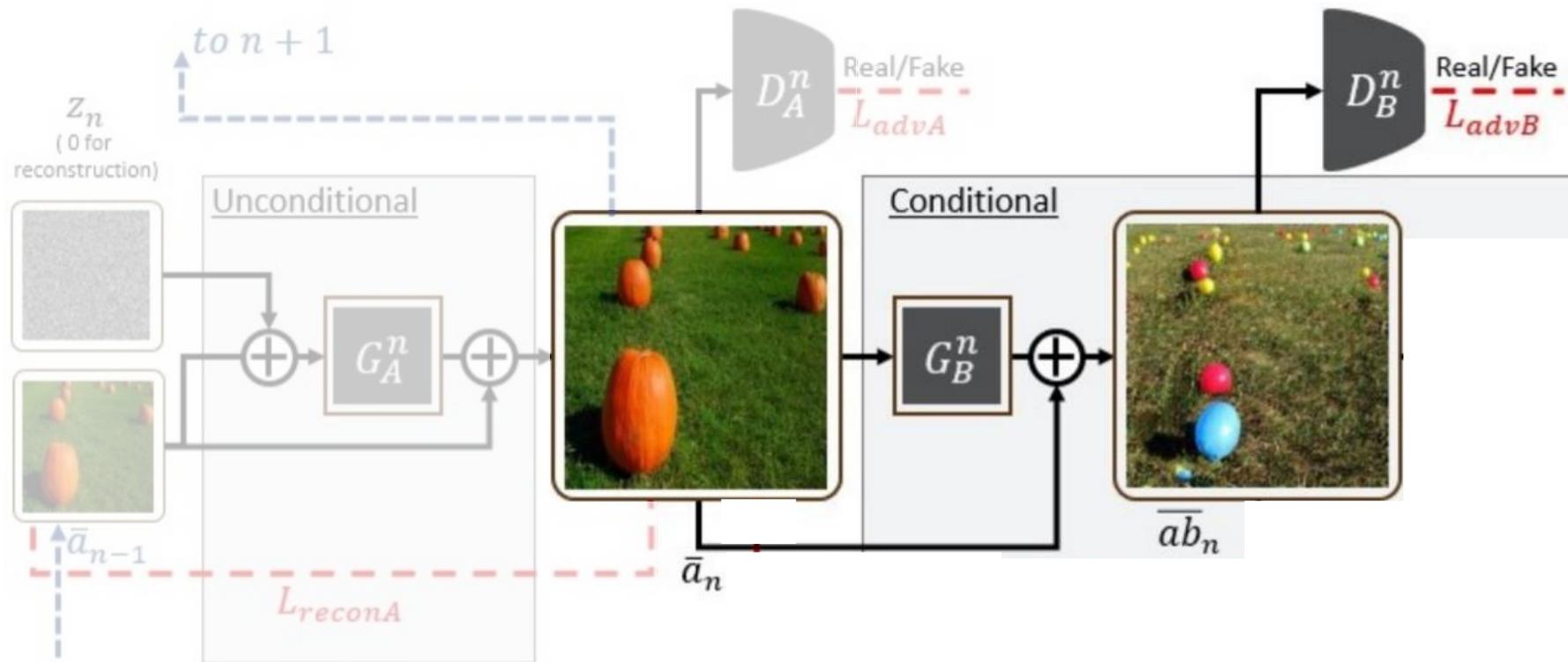
# Unconditional Generation (Level 0)



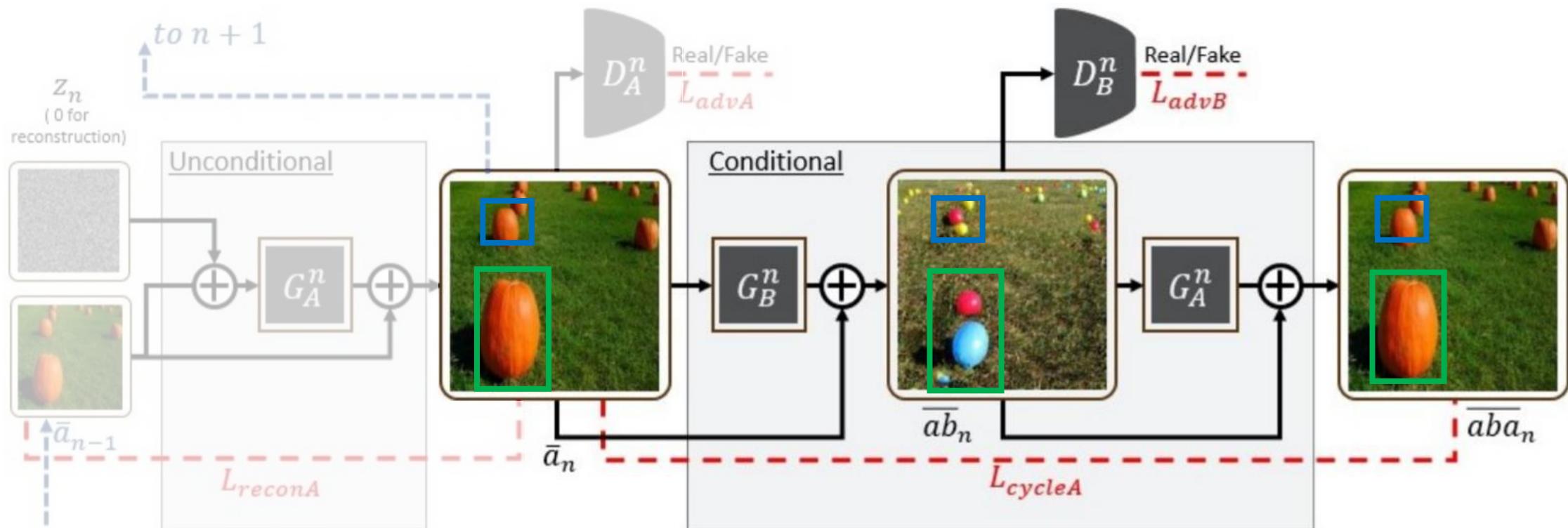
# Unconditional Generation (Level n)



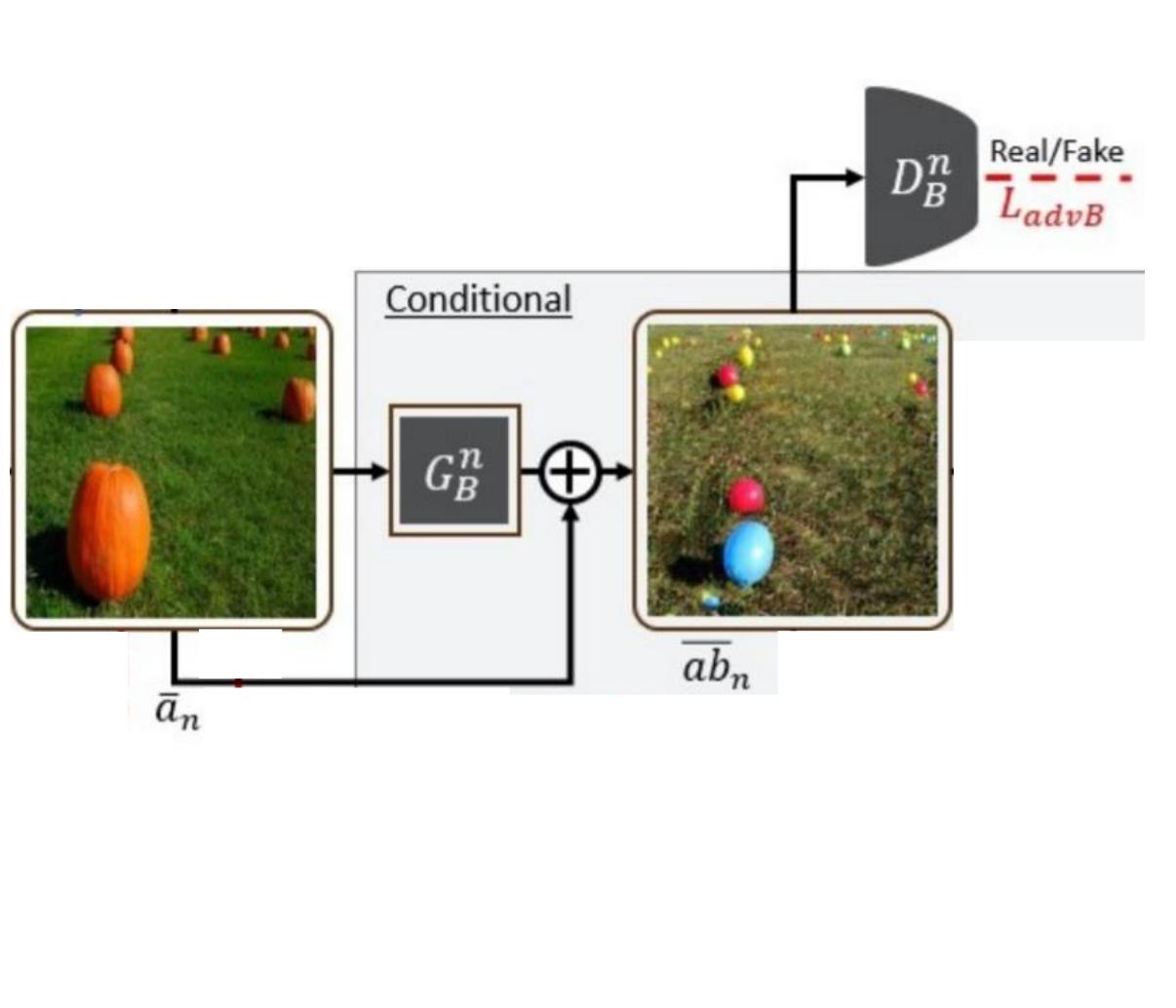
# Conditional Generation (Level n)



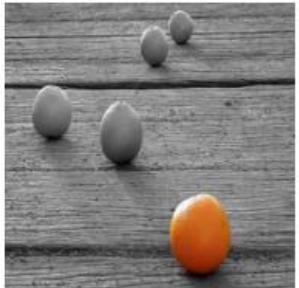
# Conditional Generation (Level n)



# Coarse and Mid Scales: Residual Training



Target



Source



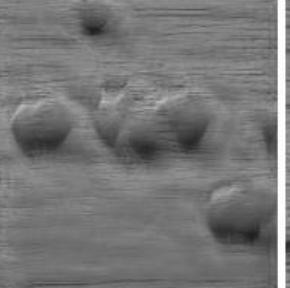
Ours



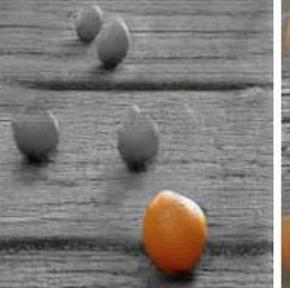
DIA



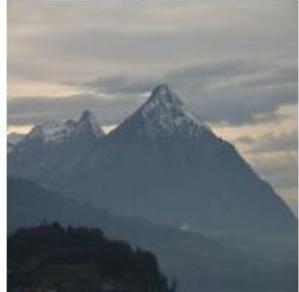
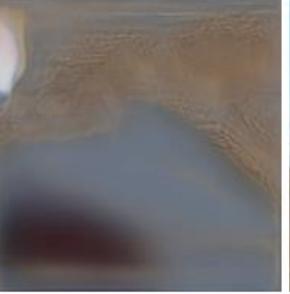
SinGAN



Cycle



Style

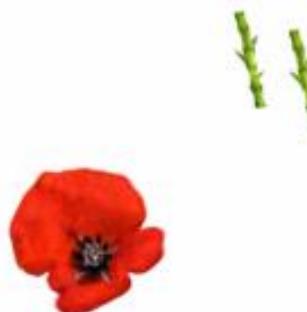


# Multiple Class Types

Input



Output



# Paint to Image

Input



Sketch



Ours



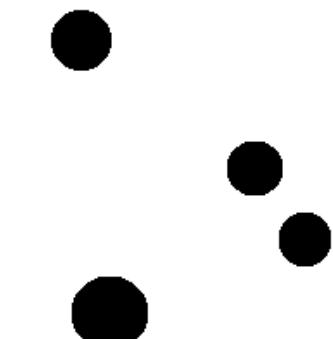
Input



Sketch



Ours



# Video Generation



# Structure Manipulation for Videos

# Hierarchical Patch VAE-GAN: Generating Diverse Videos from a Single Sample

S. Gur\*, S. Benaim\*, L. Wolf. NeurIPS 2020 (\*Equal contribution)

Real

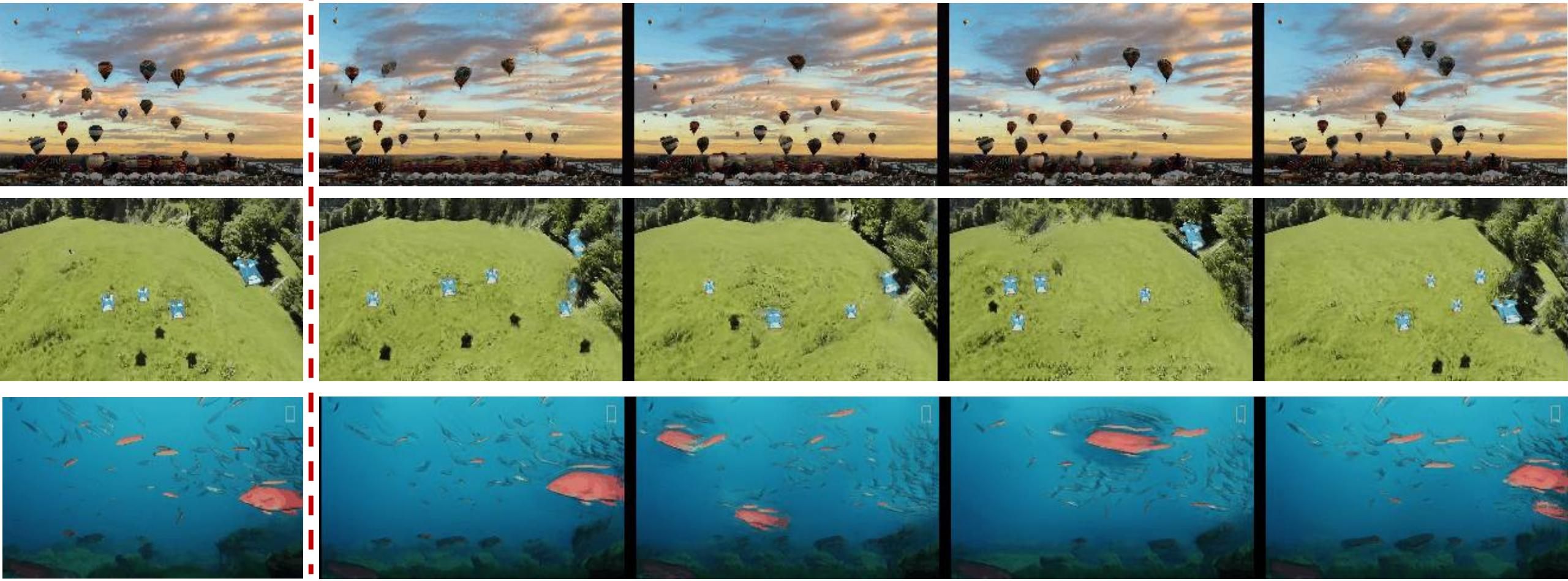


# Hierarchical Patch VAE-GAN: Generating Diverse Videos from a Single Sample

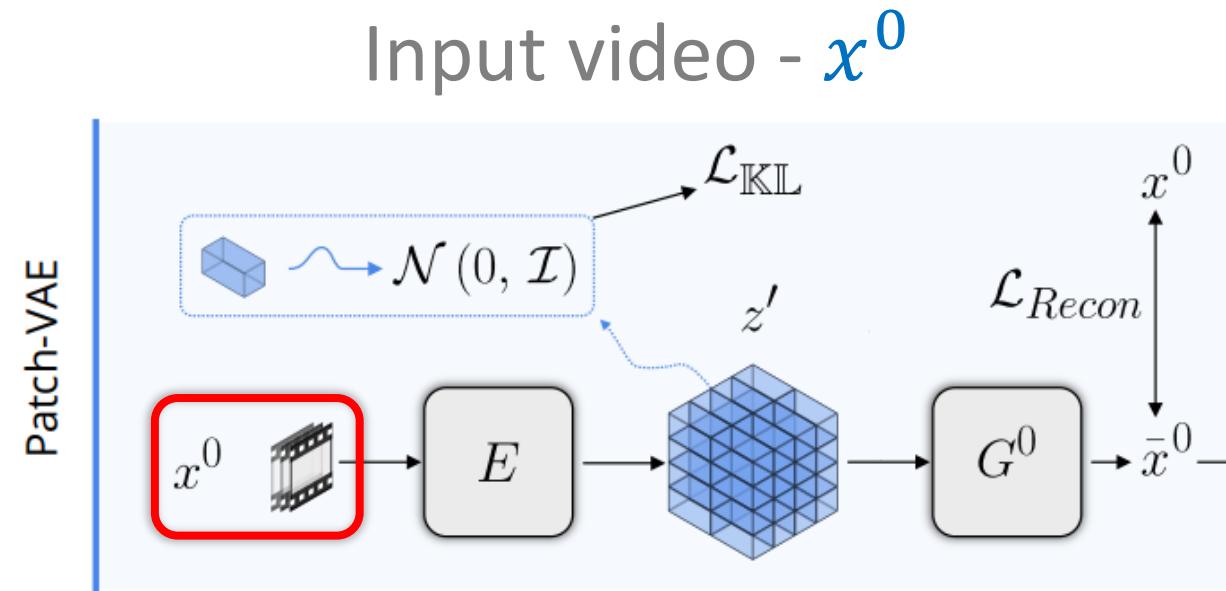
S. Gur\*, S. Benaim\*, L. Wolf. NeurIPS 2020 (\*Equal contribution)

Real

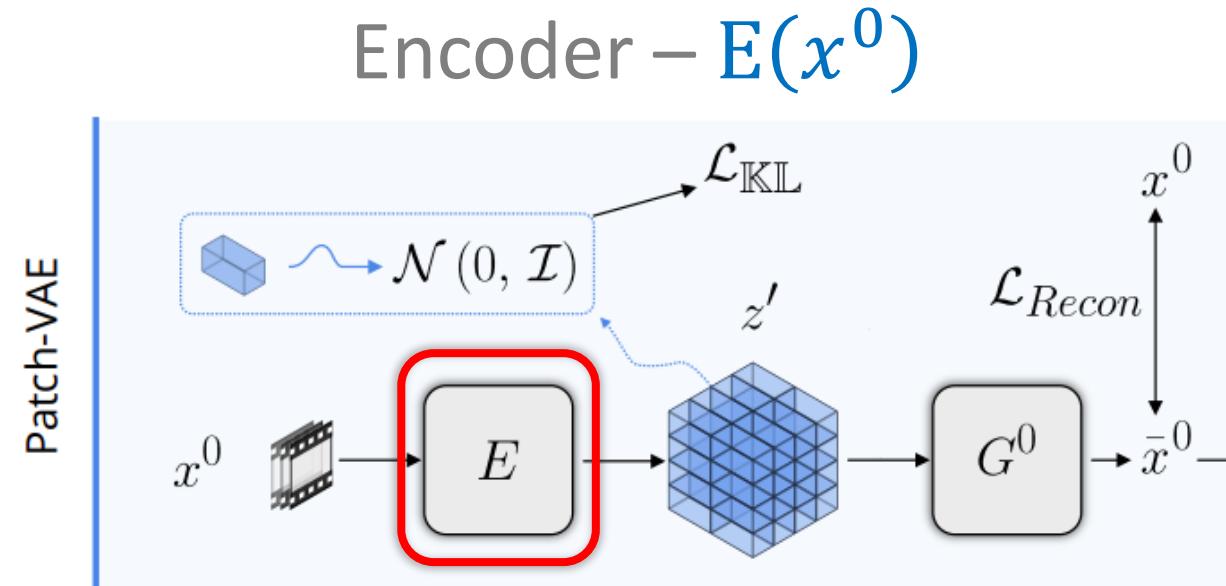
Generated Samples (13 Frames)



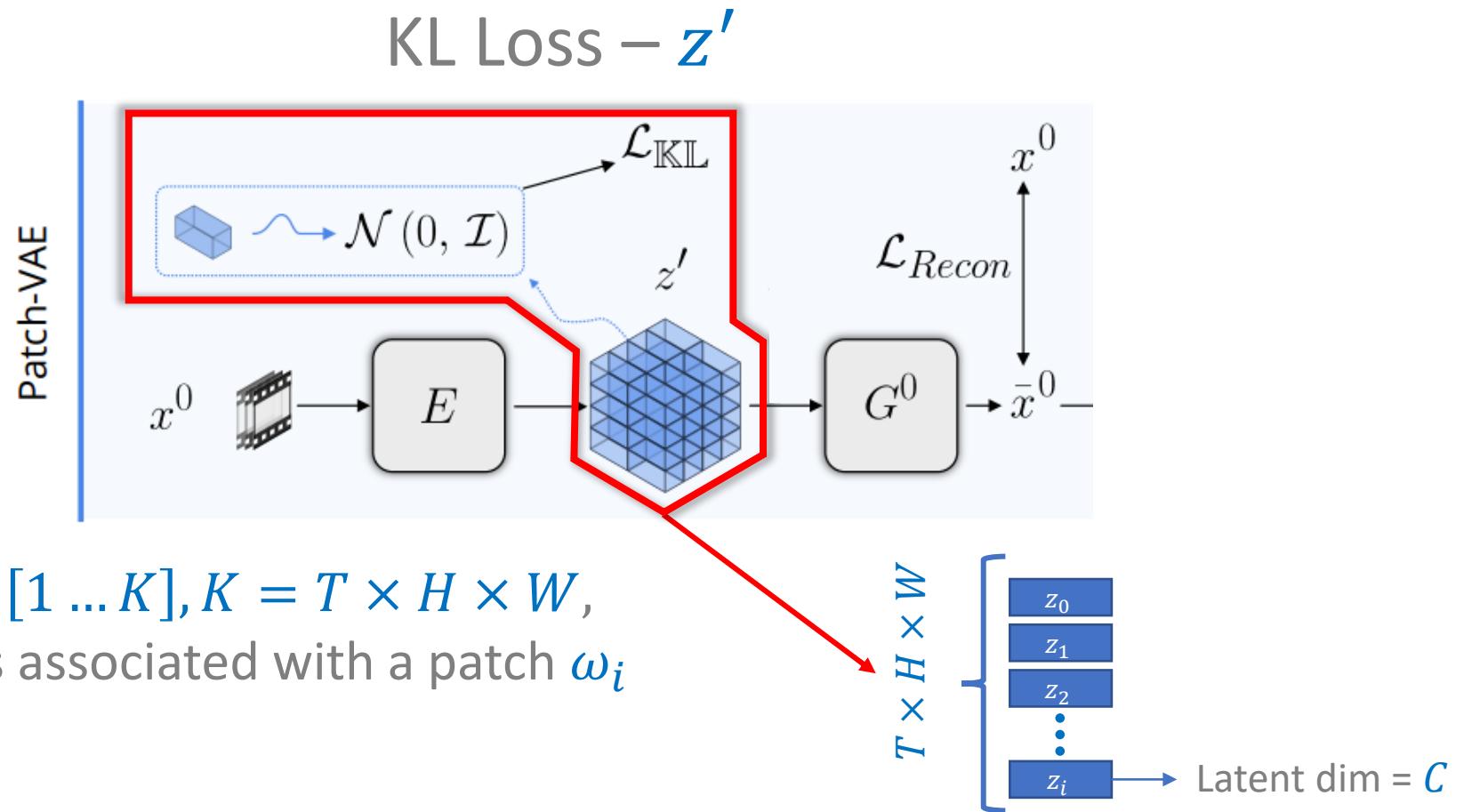
# Proposed Approach: Patch VAE



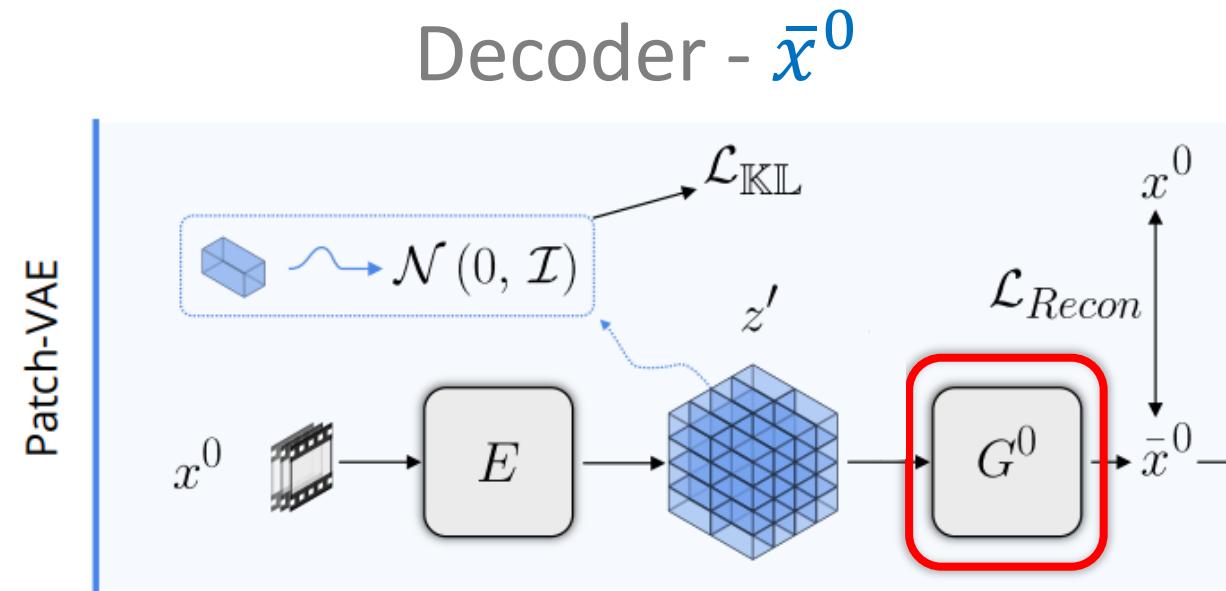
# Proposed Approach: Patch VAE



# Proposed Approach: Patch VAE

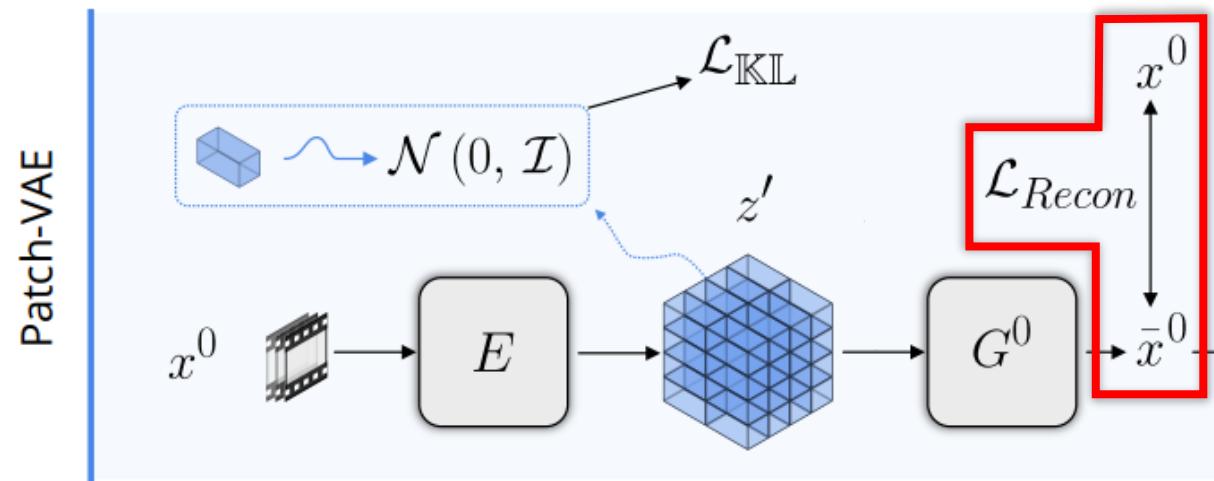


# Proposed Approach: Patch VAE



# Proposed Approach: Patch VAE

Reconstruction loss



# Proposed Approach: Hierarchical Patch VAE

Coarsest scale:  
**Low** resolution  
and frame rate

$x^0$  (Real)  
 $\bar{x}^0$  (Generated)

LEVEL = 0

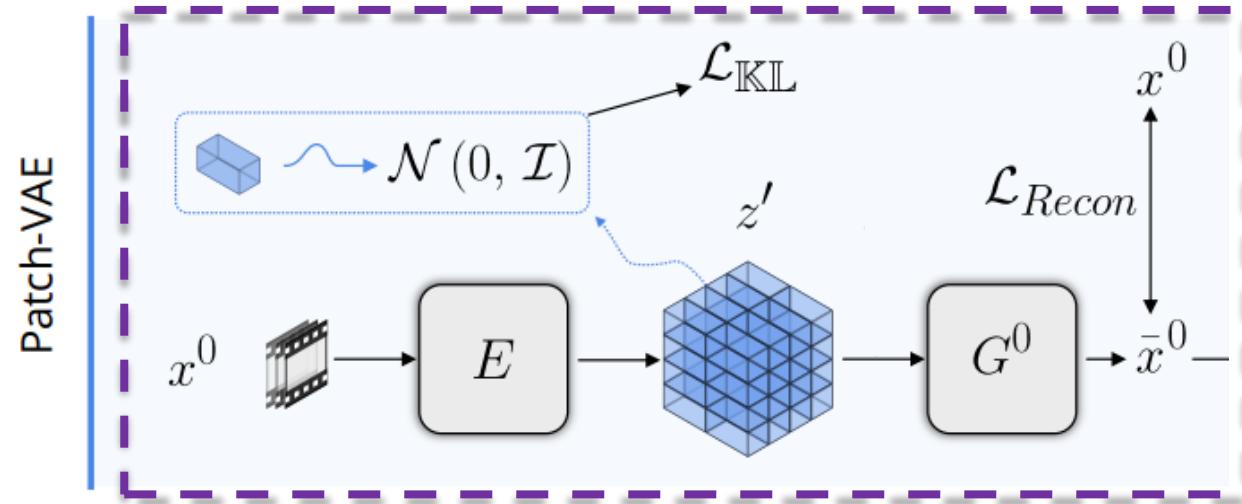


Finest scale:  
**High** resolution  
and frame rate

$x^N$  (Real)  
 $\bar{x}^N$  (Generated)

LEVEL =  $N$

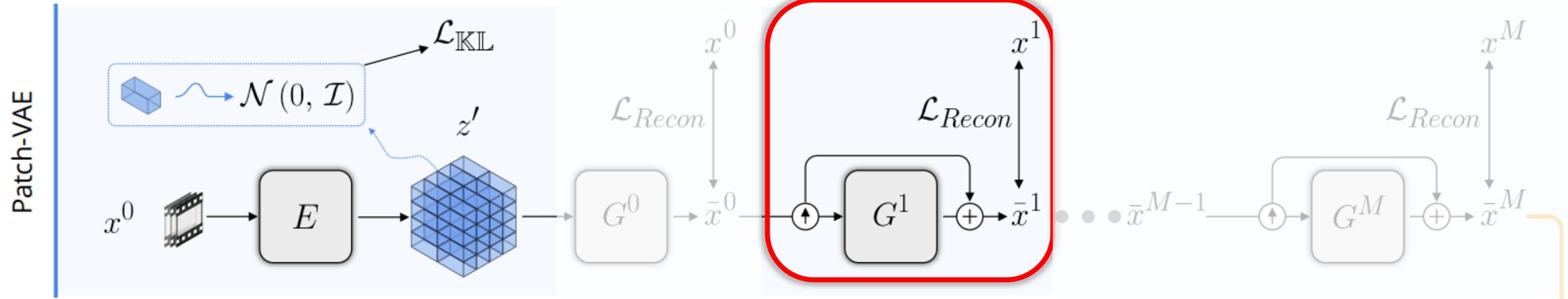
# Proposed Approach: Hierarchical Patch VAE



LEVEL = 0

# Proposed Approach: Hierarchical Patch VAE

Up-sampling block -  $\bar{x}^1$

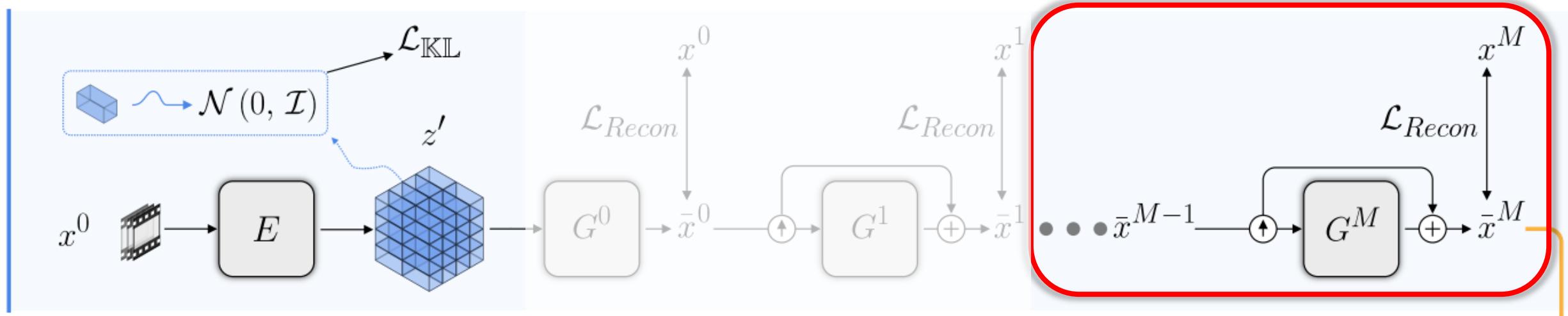


LEVEL = 1

# Proposed Approach: Hierarchical Patch VAE

Hierarchical up-sampling up to  $\bar{x}^M$

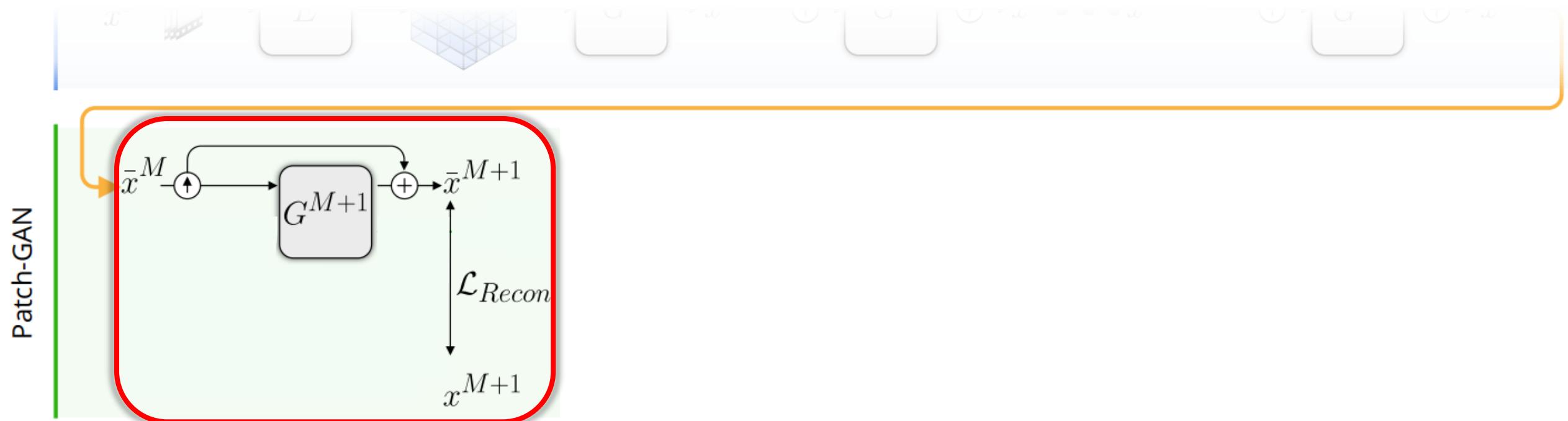
Patch-VAE



LEVEL  $\leq M$

# Proposed Approach: Hierarchical Patch VAE GAN

Up-sampling block  $\bar{x}^{M+1}$



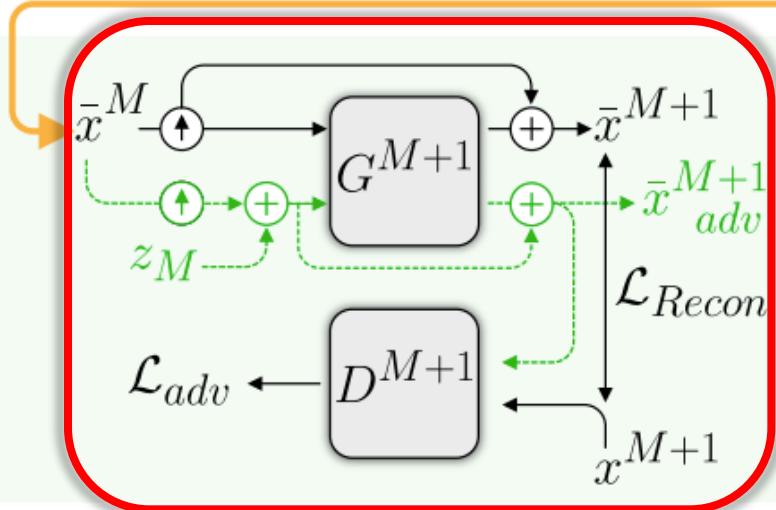
LEVEL =  $M + 1$

# Proposed Approach: Hierarchical Patch VAE GAN

Adversarial training



Patch-GAN

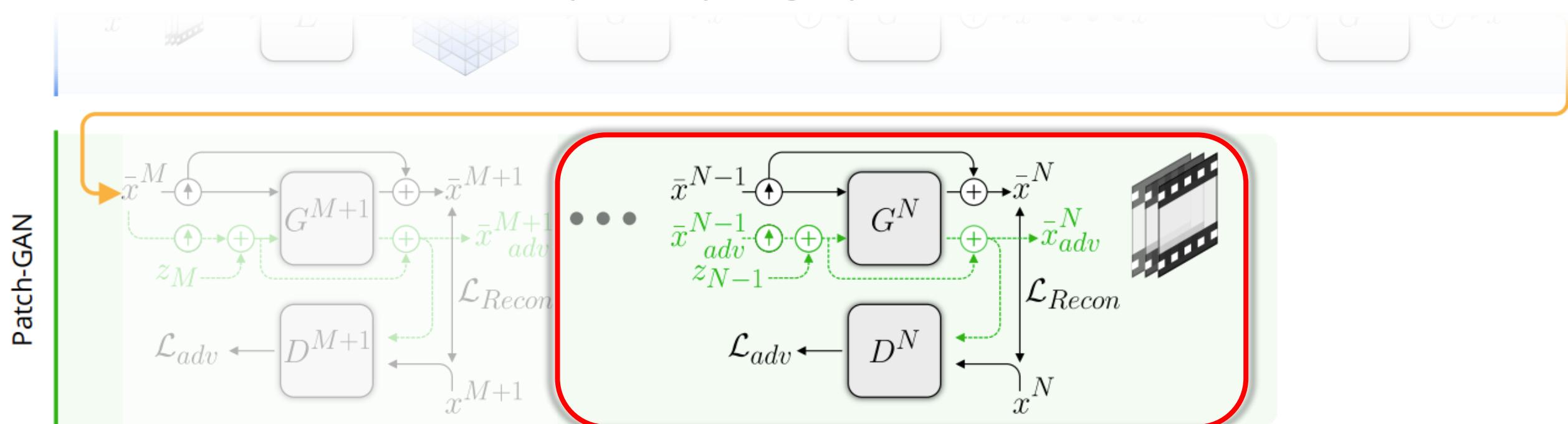


Added noise  $z_M$

LEVEL =  $M + 1$

# Proposed Approach: Hierarchical Patch VAE GAN

Hierarchical up-sampling up to final resolution  $\bar{x}^N$



$$M + 1 < \text{LEVEL} \leq N$$

# Effect of Number of patch-VAE levels



Training Video

9 Levels Total



1 p-VAE – 8 p-GAN



8 p-VAE – 1 p-GAN

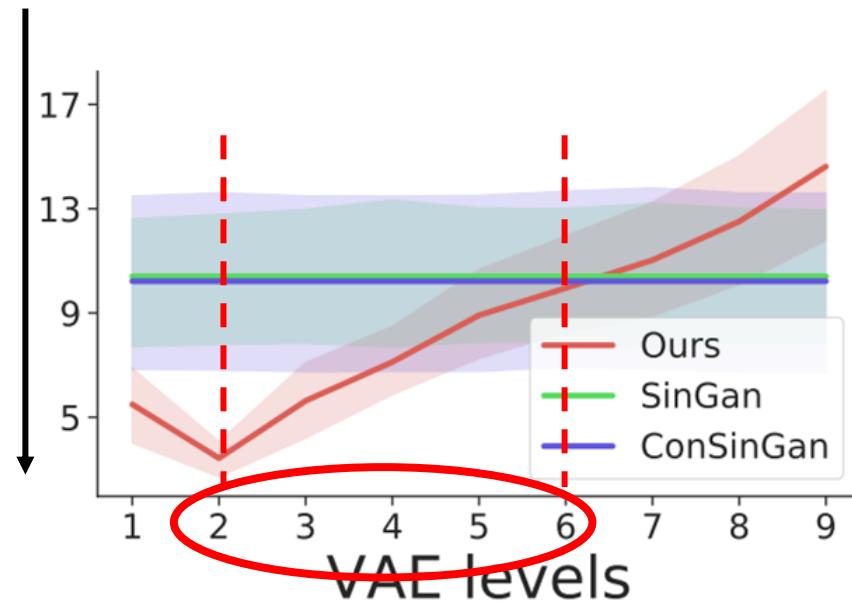


3 p-VAE – 6 p-GAN

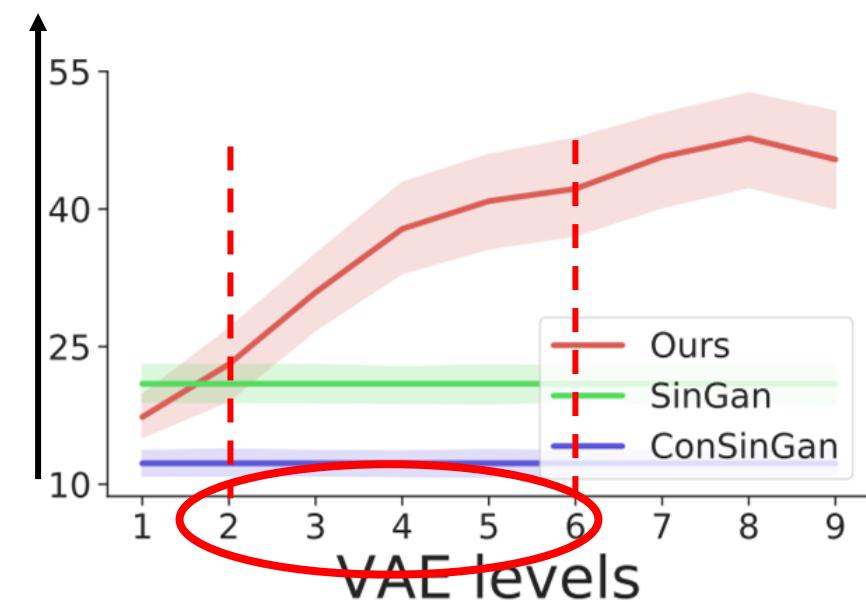
# Effect of Number of patch-VAE levels

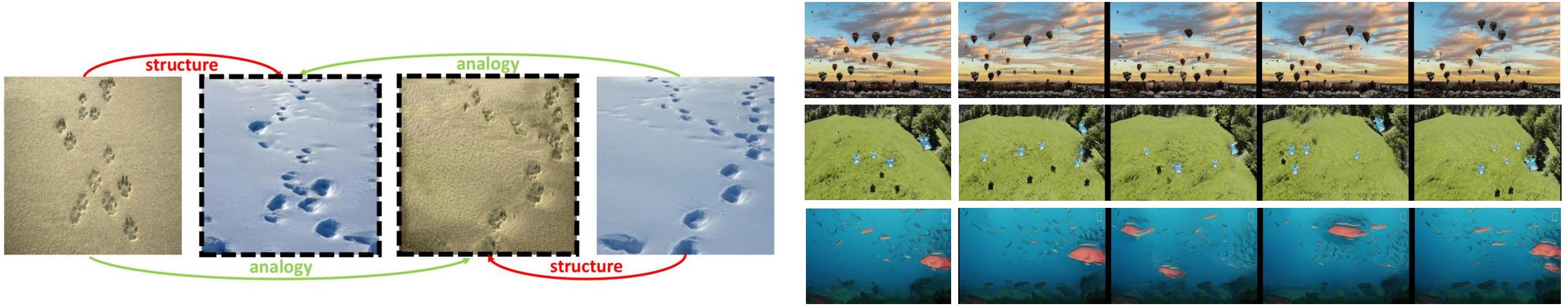
Total of 9 layers

Quality  
**(Lower is Better)**



Diversity  
**(Higher is Better)**





## Part II: Manipulating Structure



# SpeedNet: Learning the Speediness in Videos

**S. Benaim, A. Ephrat, O. Lang, I. Mosseri, W. T. Freeman, M. Rubinstein, M. Irani, T. Dekel.**  
CVPR 2020.

Slower



Normal speed



Faster



<https://speednet-cvpr20.github.io/>

# Automatically predict “speediness”

Uniform Speed Up (2x)



Adaptive speed up (2x)

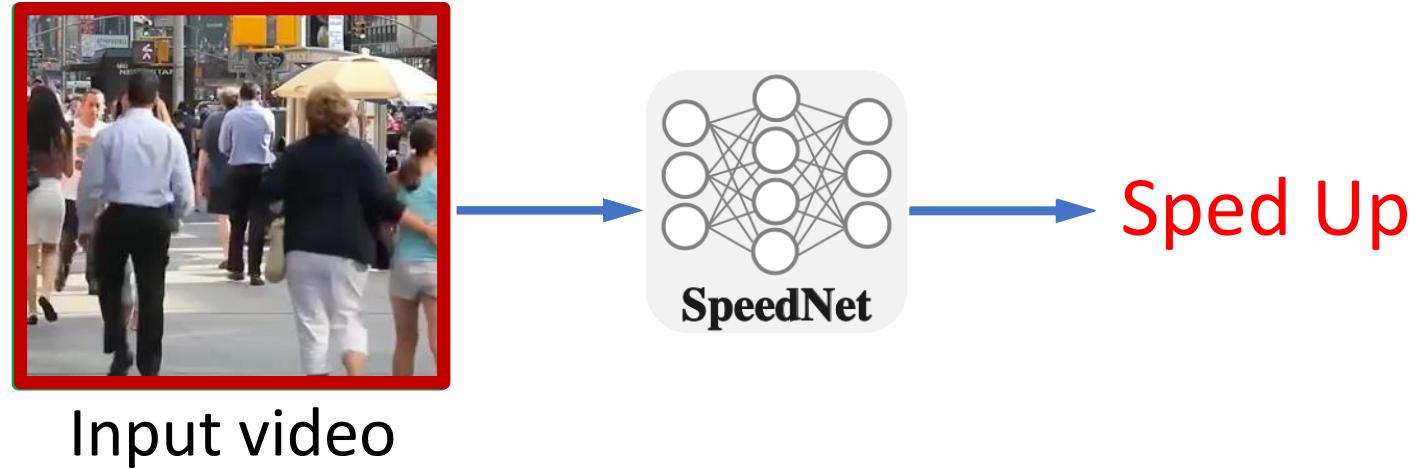


Other Applications:

- Self-supervised action recognition
- Video retrieval

# Training SpeedNet

Self-supervised  
training



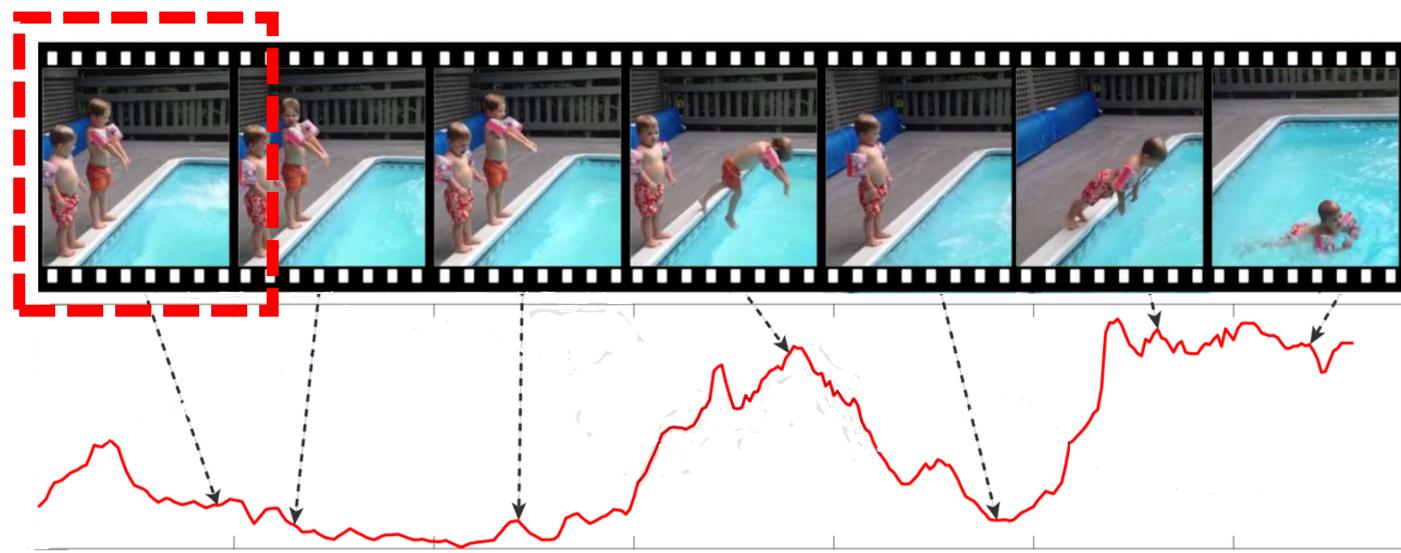
- Spatial augmentations
- Temporal augmentations
- Same-batch training

# Adaptive video speedup

Inference on full  
sped-up video

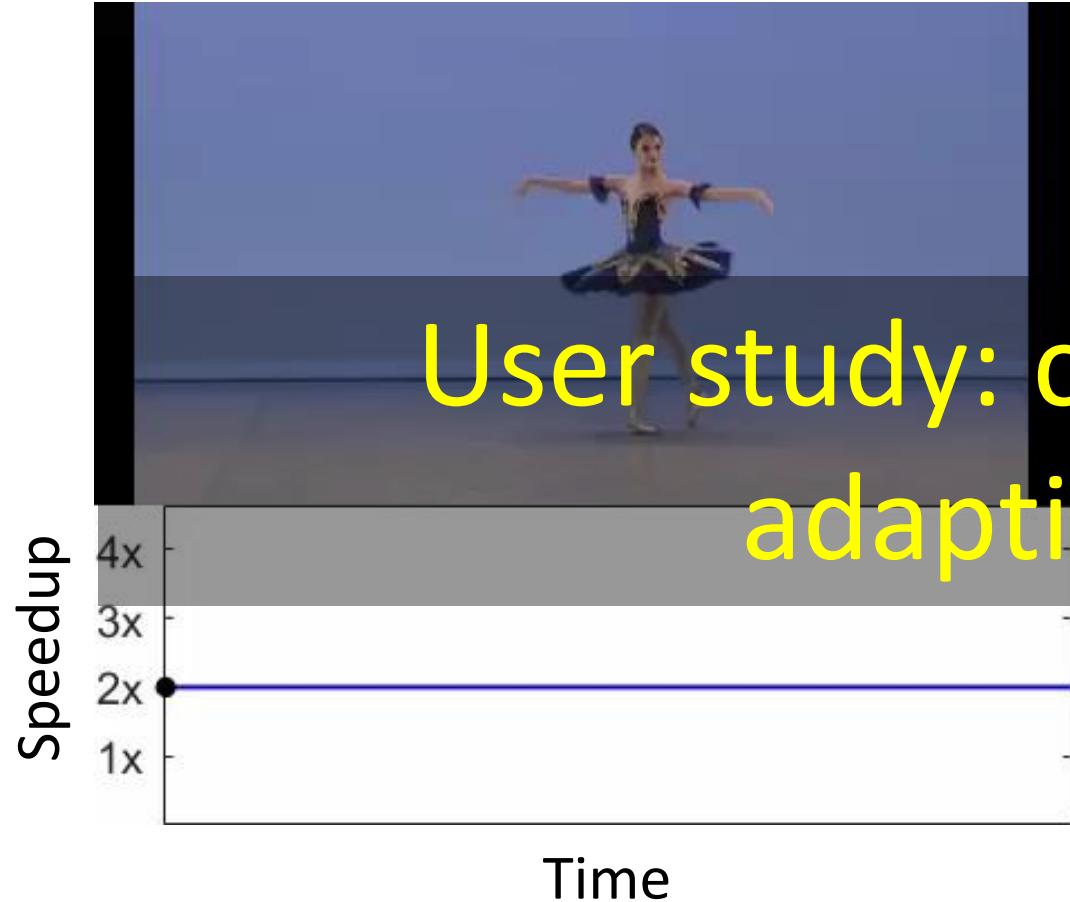
Sped-up

Normal speed



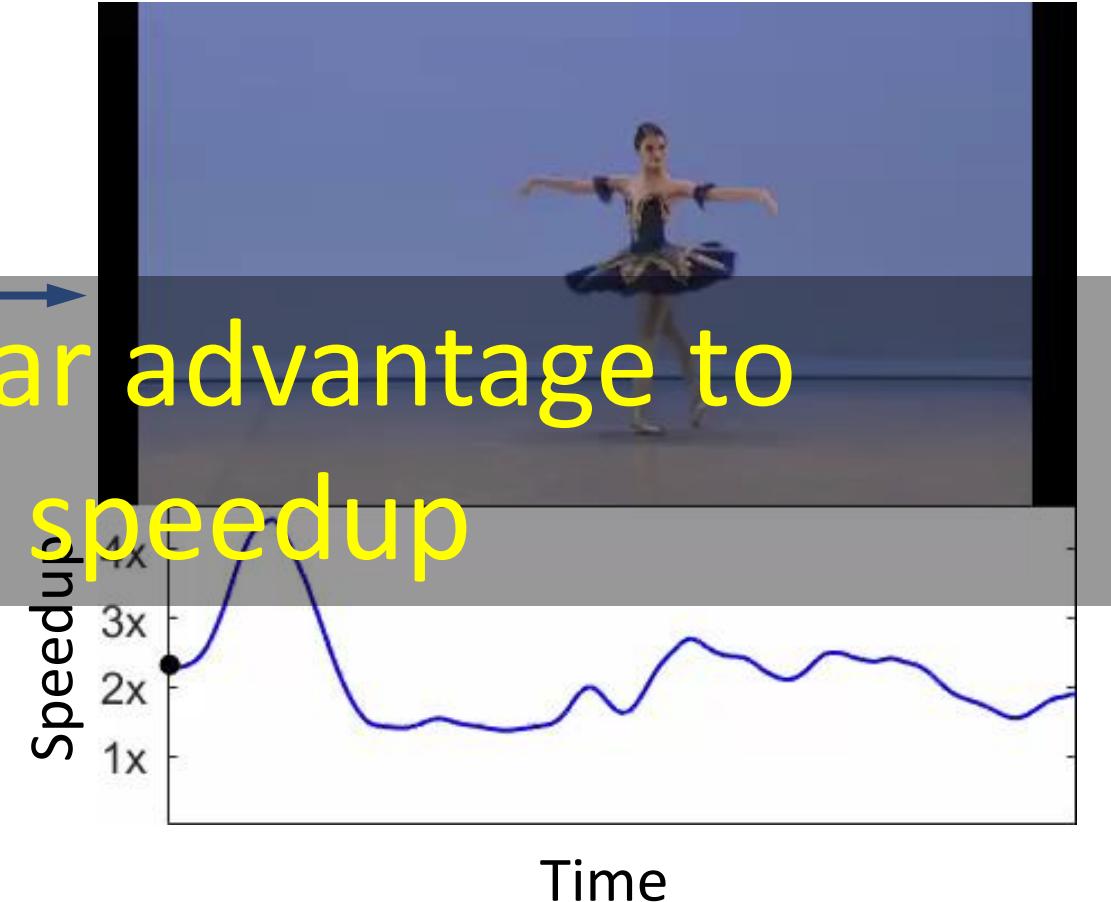
# Adaptive video speedup

Total time =  $\frac{1}{2}$  input time



**Uniform** Speedup

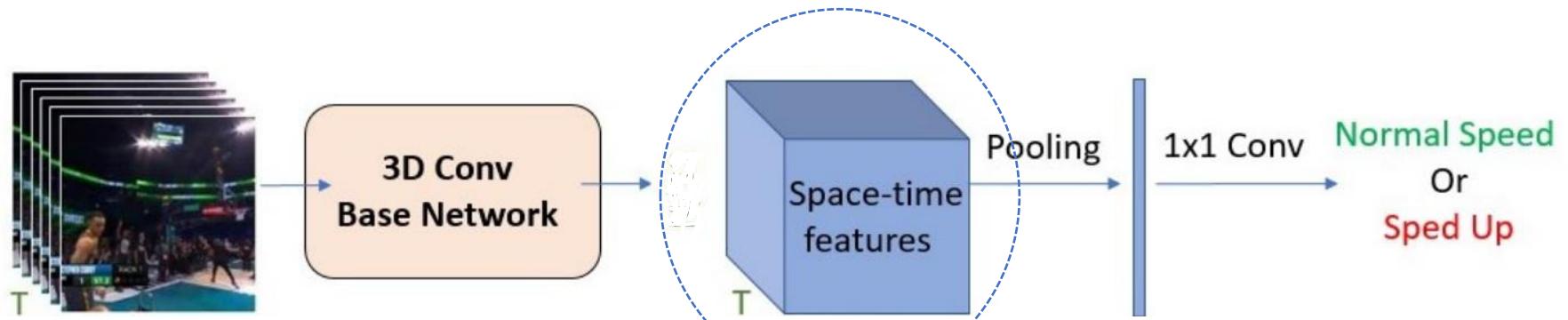
Total time =  $\frac{1}{2}$  input time



**Adaptive** Speedup (ours)

# Other self supervised tasks

Train SpeedNet

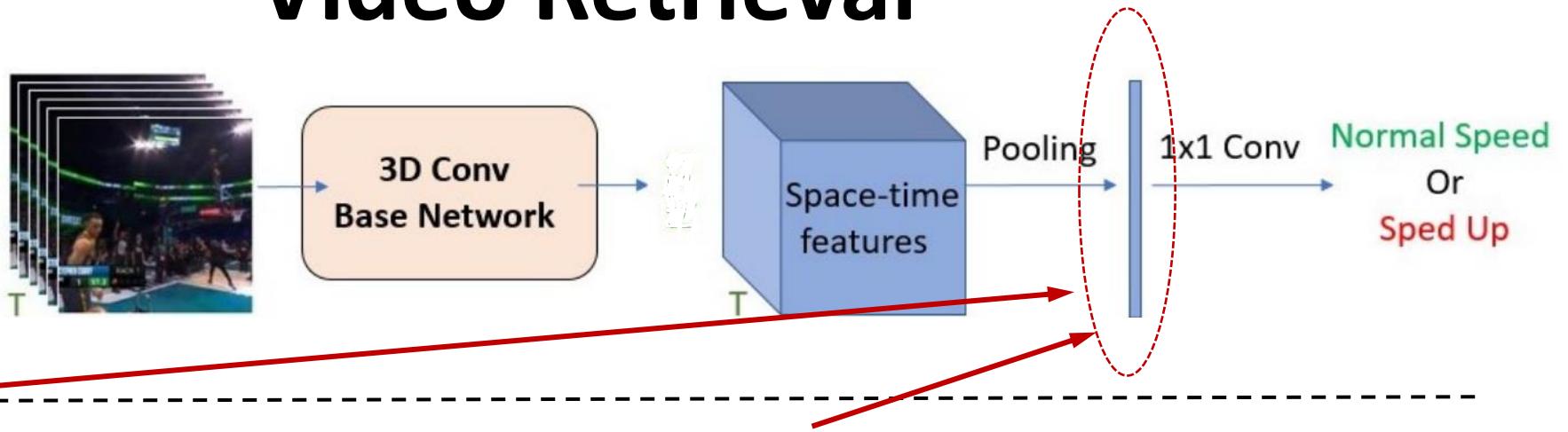


Self Supervised Action Recognition

Method	Initialization	Architecture	Supervised accuracy	
			UCF101	HMDB51
Random init		S3D-G	73.8	46.4
ImageNet inflated		S3D-G	86.6	57.7
Kinetics supervised		S3D-G	96.8	74.5
CubicPuzzle [19]		3D-ResNet18	65.8	33.7
Order [40]		R(2+1)D	72.4	30.9
DPC [13]		3D-ResNet34	75.7	35.7
AoT [38]		T-CAM	79.4	-
SpeedNet (Ours)		S3D-G	81.1	48.8
Random init		I3D	47.9	29.6
SpeedNet (Ours)		I3D	66.7	43.7

# Other self supervised tasks: Video Retrieval

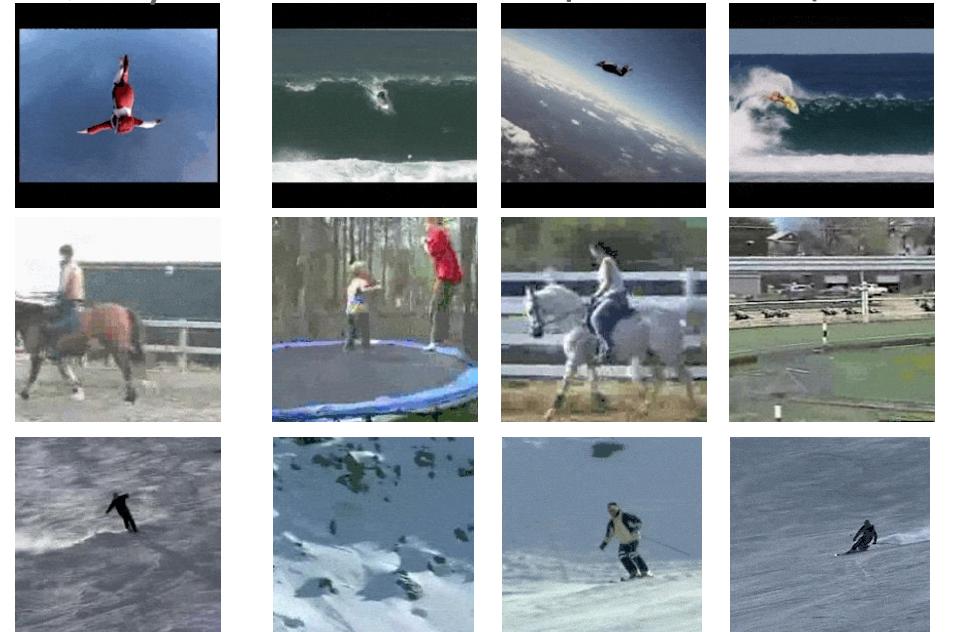
Train SpeedNet



Query      Retrieved top-3 results (Within)



Query      Retrieved top-3 results (Across)



“Memory Eleven”: An artistic video by Bill Newsinger:  
[https://www.youtube.com/watch?v=djylSOWi\\_lo](https://www.youtube.com/watch?v=djylSOWi_lo)



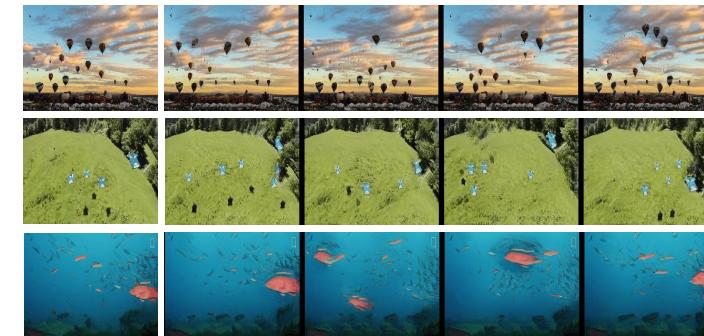
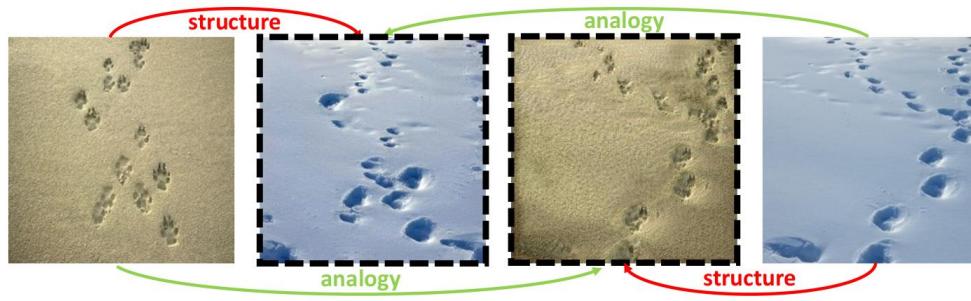
# Spatio-Temporal Visualizations

blue/green =  
normal speed

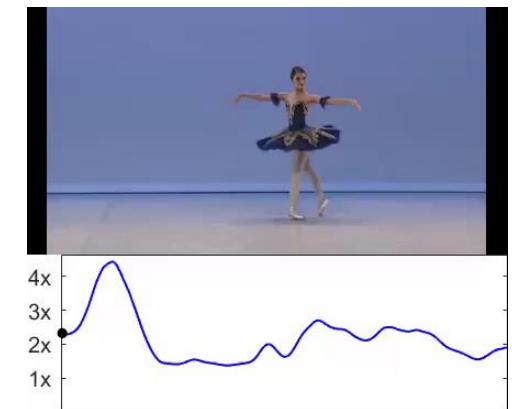
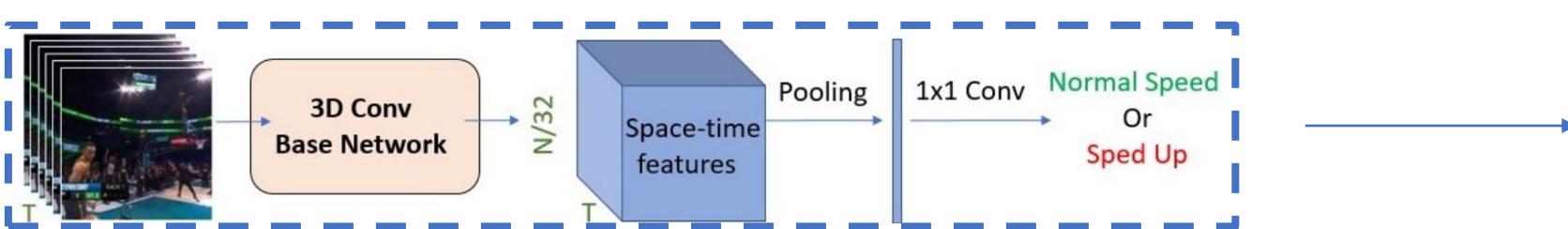
yellow/orange =  
slowed down



# Part I: Manipulating Structure



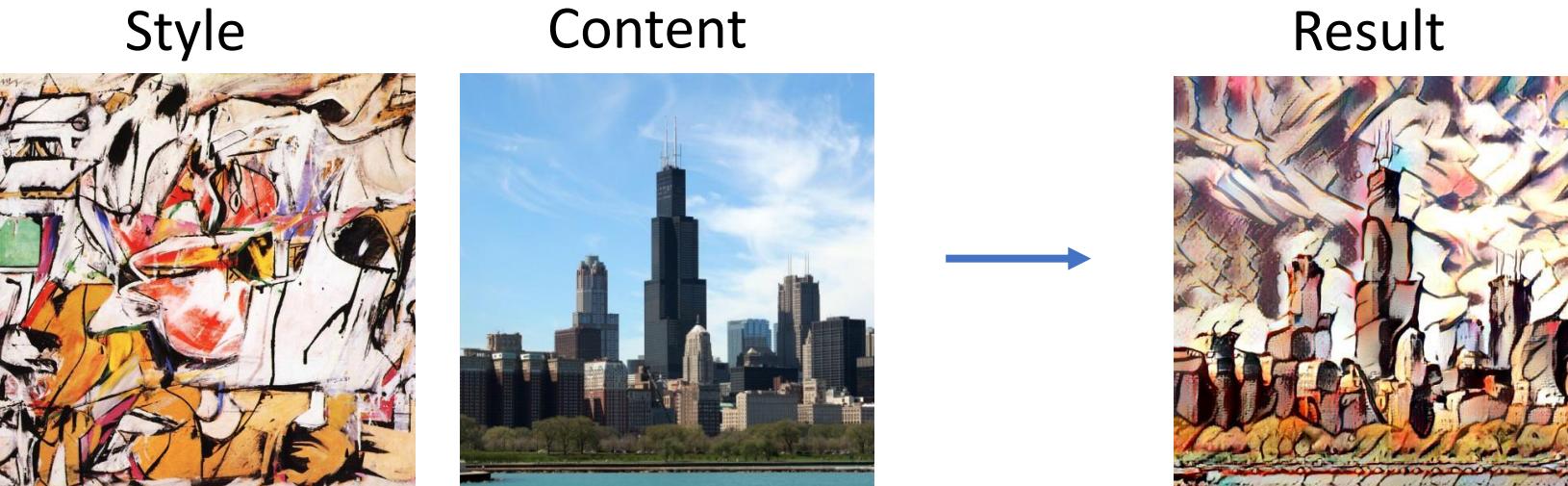
# Part II: Manipulating by Understanding Structure



# Part III: Structure Preserving Manipulation

# Permuted AdaIN: Reducing the Bias Towards Global Statistics in Image Classification

O. Nuriel, S. Benaim, L. Wolf. CVPR 2021.



# Structure Preserving Transformation

- $a \in \mathbb{R}^{C \times H \times W}$  and  $b \in \mathbb{R}^{C \times H \times W}$  be the activations of some encoder E applied on images  $I_a$  and  $I_b$  respectively.

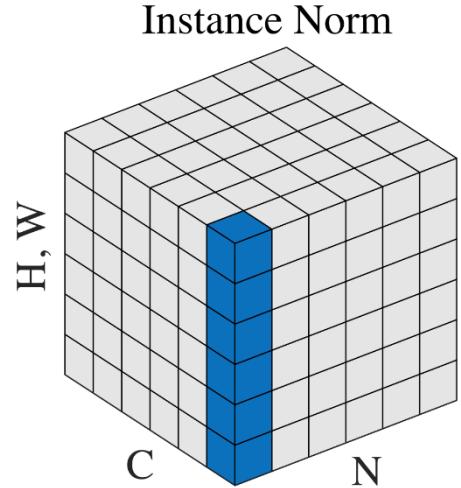
$$a = E( \quad )$$



$$b = E( \quad )$$



# Instance Normalization



$$b = E($$



)

$$IN(b)_{chw} = \left( \frac{b_{chw} - \mu_c(b)}{\sigma_c(b)} \right)$$

# Adaptive Instance Normalization

$$a = E( \quad )$$



$$b = E( \quad )$$

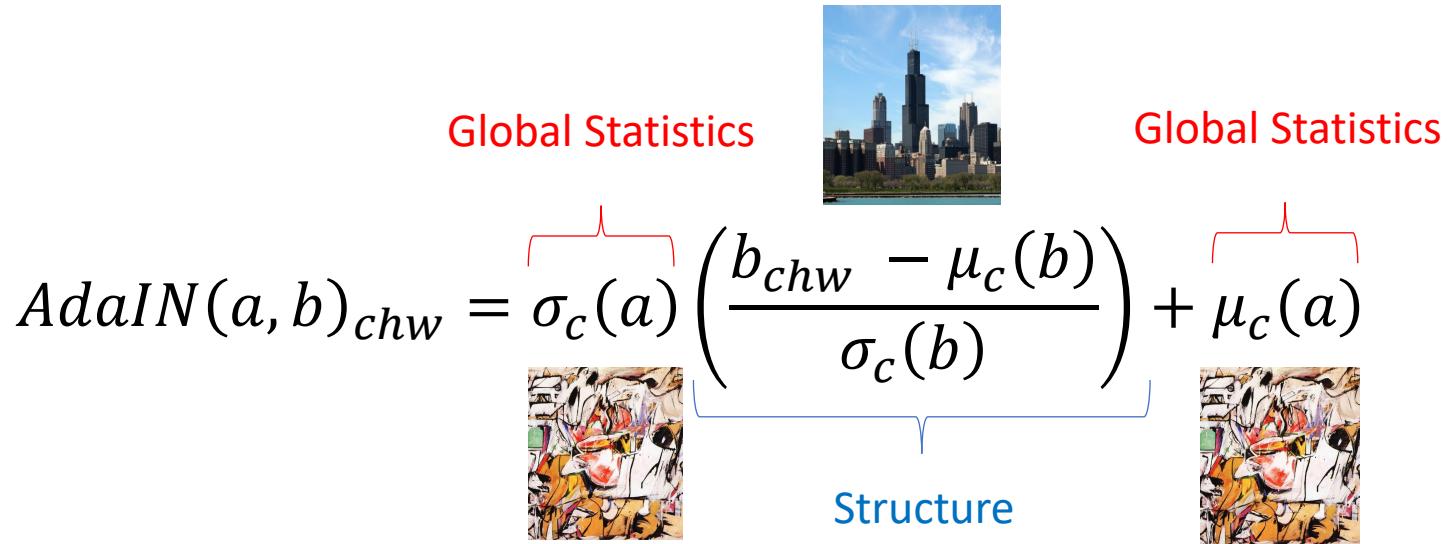


$$AdaIN(a, b)_{chw} = \sigma_c(a) \left( \frac{b_{chw} - \mu_c(b)}{\sigma_c(b)} \right) + \mu_c(a)$$

# Adaptive Instance Normalization

$$AdaIN(a, b)_{chw} = \sigma_c(a) \left( \frac{b_{chw} - \mu_c(b)}{\sigma_c(b)} \right) + \mu_c(a)$$

Structure



- AdaIN **swaps the global statistics** of  $a$  to those of  $b$
- $\mu$  and  $\sigma$  represent the **global statistics** of an image (such as brightness, contrast, lighting, global color changes and global texture)
- **Structure** represents information relating to shape of objects

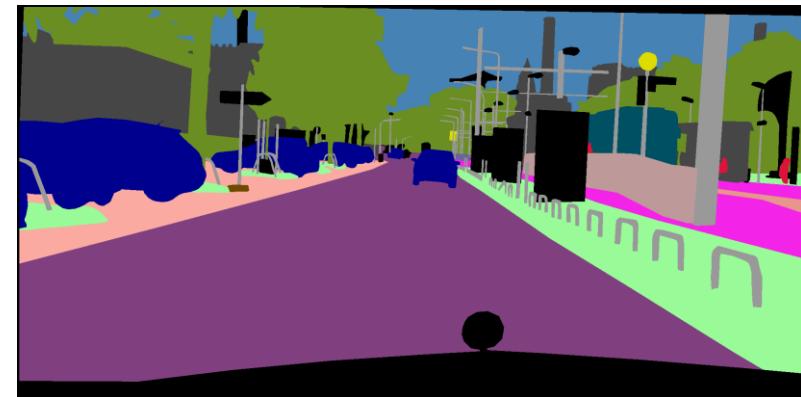
# Domain Adaptation

Supervised training on source domain and unsupervised on target domain

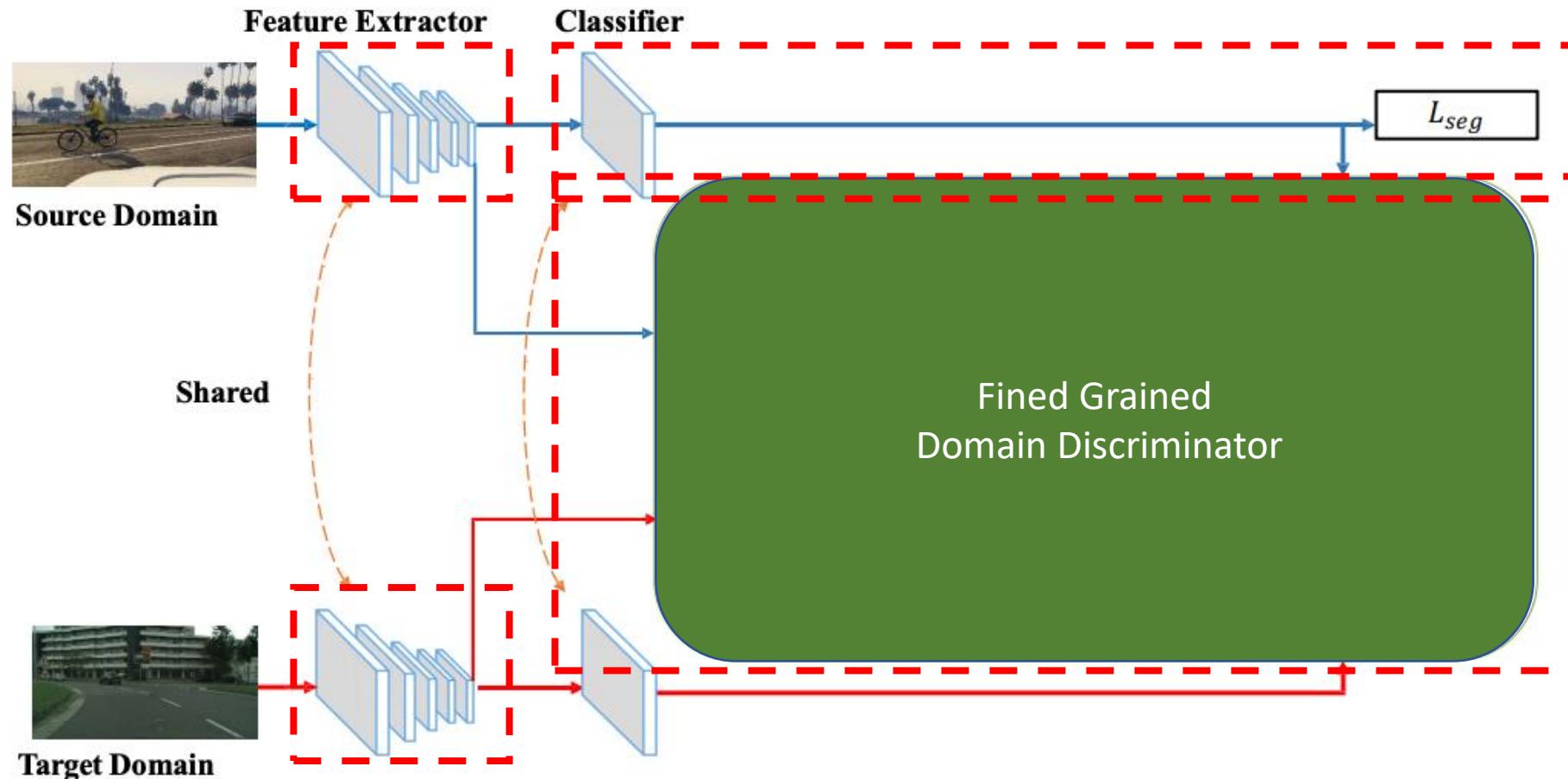
Source: GTAV



Target: Cityscapes

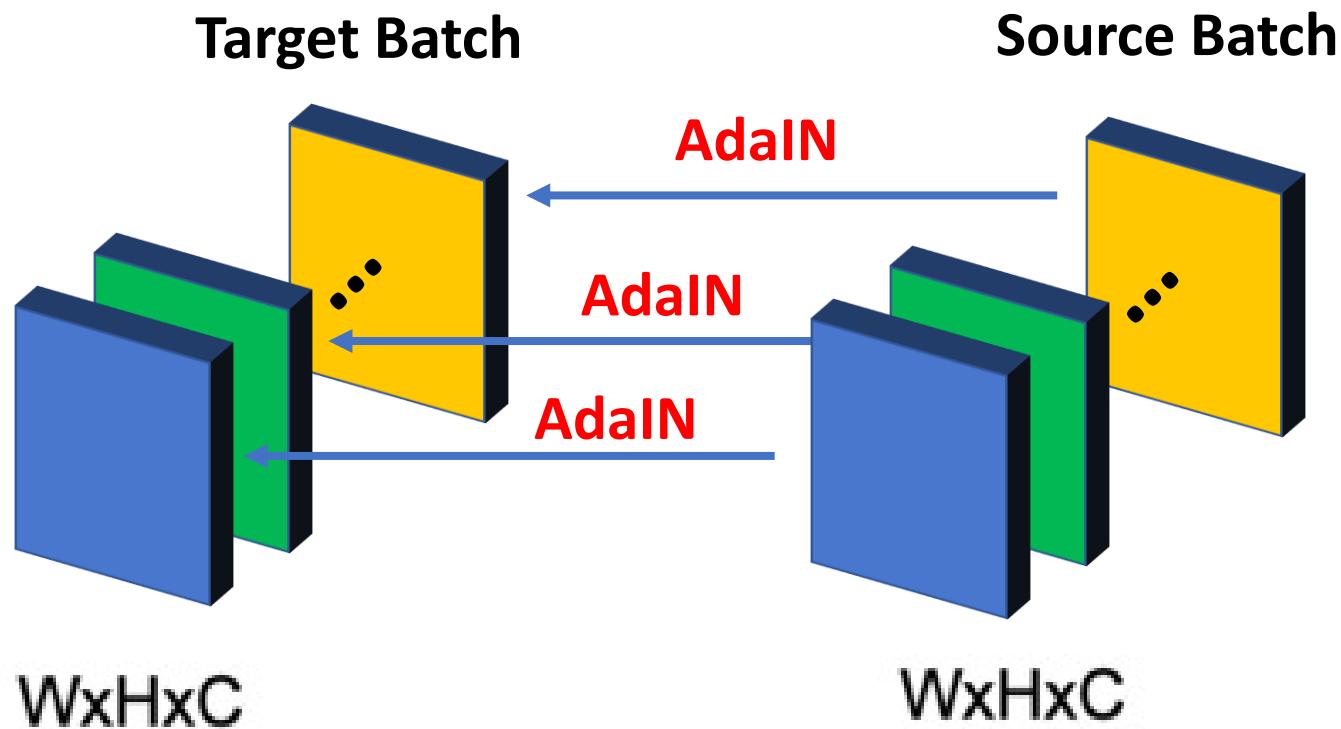


# Domain Adaptation

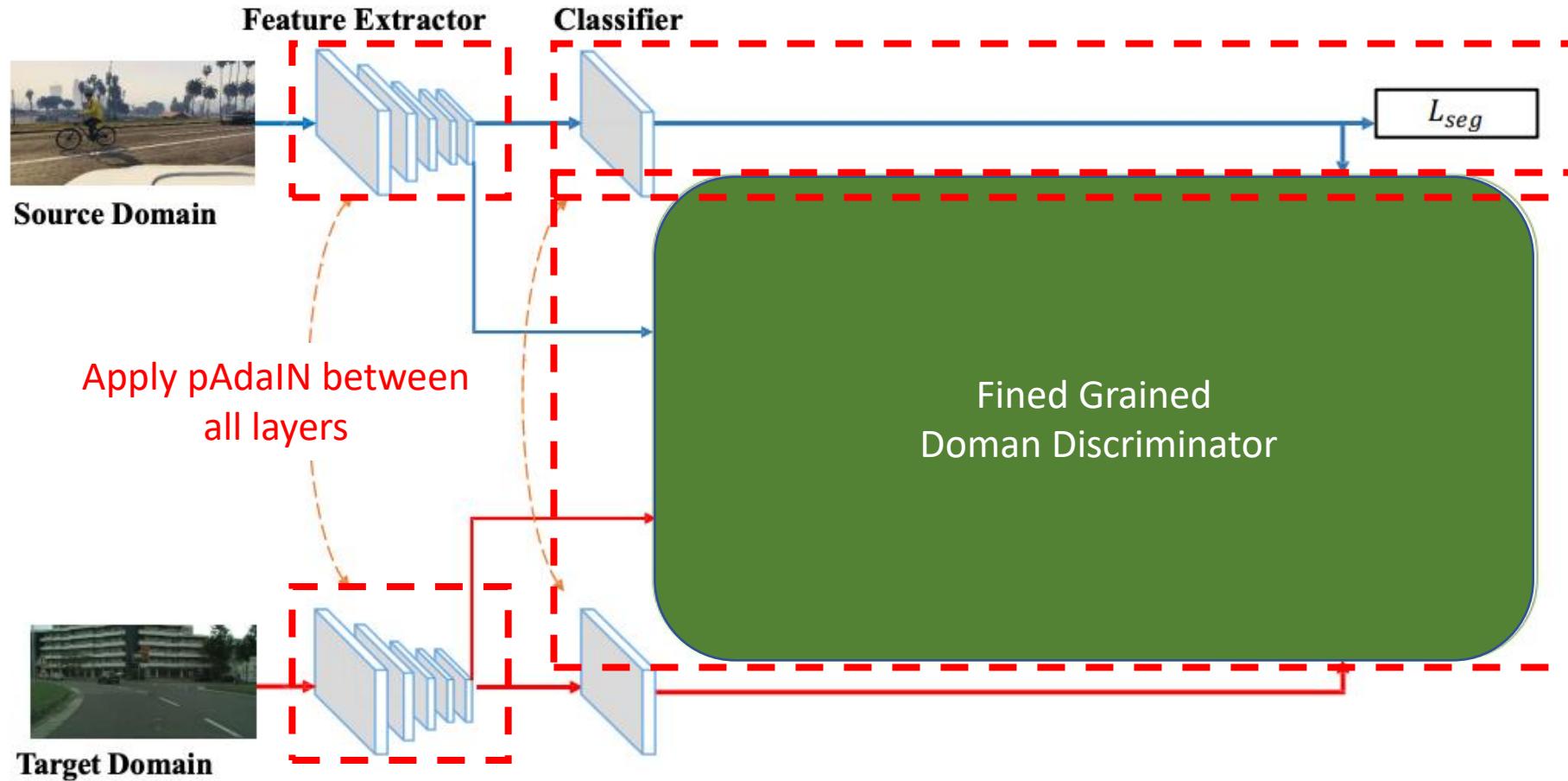


# Domain Adaptation

- Swap global statistics of target features with those of source features by applying AdaIN with probability p.
- Apply at every layer of the feature extractor.



# Domain Adaptation

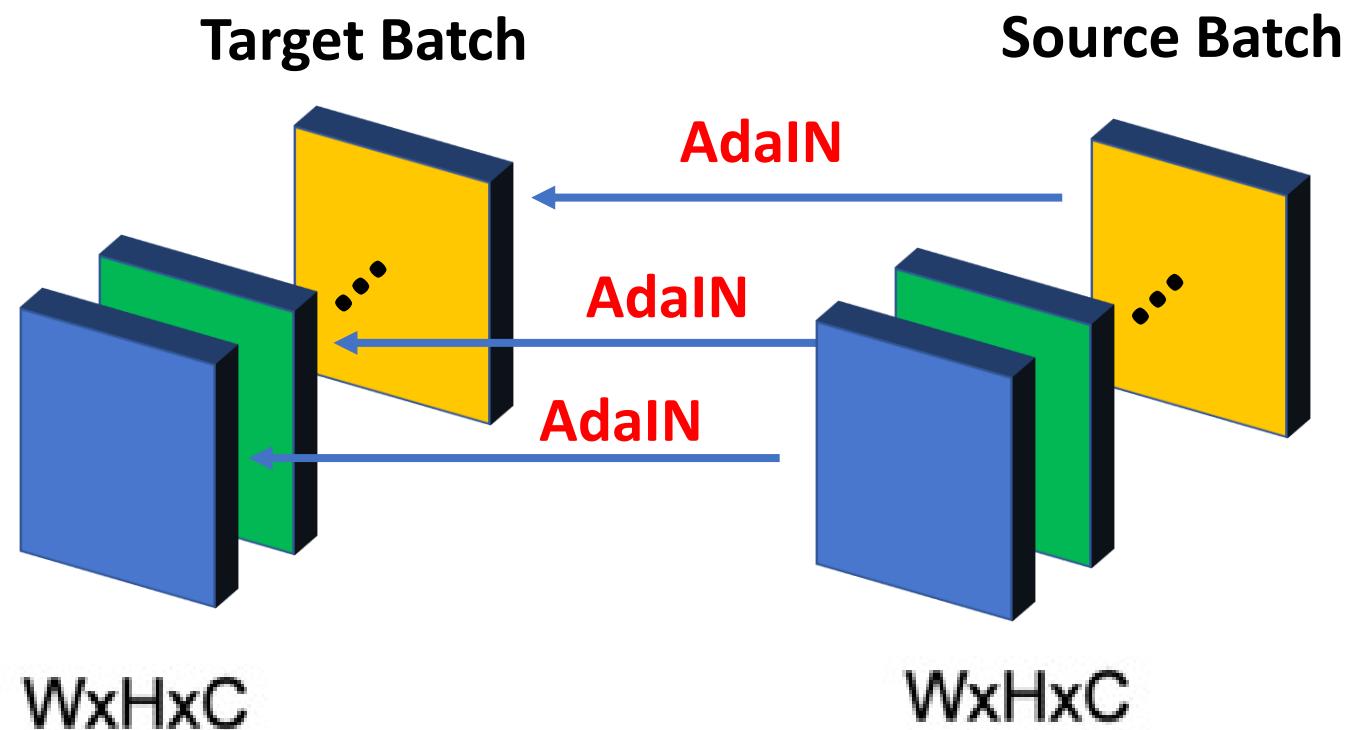


# Domain Adaptation

GTAV to Cityscapes

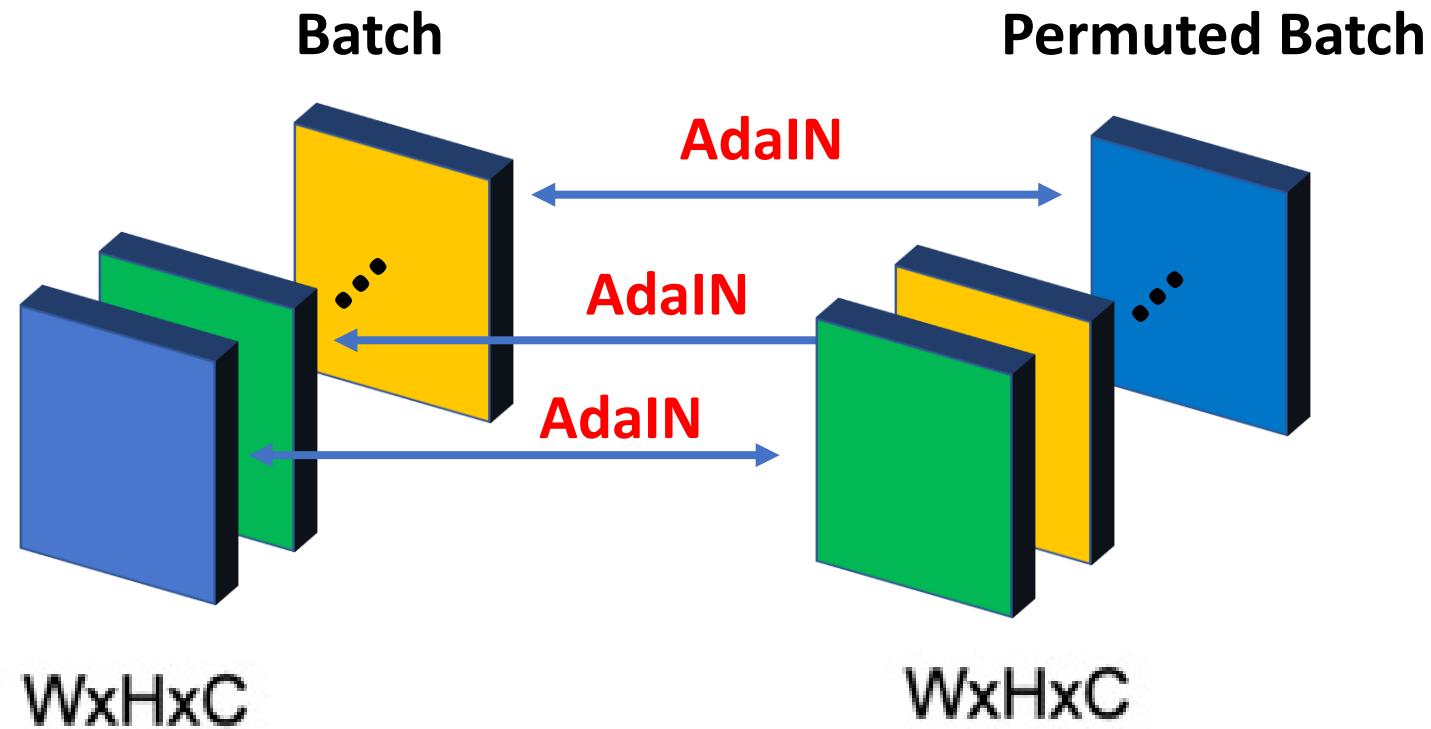
AdaptSegNet [35]	86.5	36.0	79.9	23.4	23.3	23.9	35.2	14.8	83.4	33.3	75.6	58.5	27.6	73.7	32.5	35.4	3.9	30.1	28.1	42.4
SIBAN [28]	88.5	35.4	79.5	26.3	24.3	28.5	32.5	18.3	81.2	40.0	76.5	58.1	25.8	82.6	30.3	34.4	3.4	21.6	21.5	42.6
CLAN [29]	87.0	27.1	79.6	27.3	23.3	28.3	<b>35.5</b>	24.2	83.6	27.4	74.2	58.6	28.0	76.2	33.1	36.7	6.7	31.9	31.4	43.2
AdaptPatch [36]	92.3	51.9	82.1	29.2	25.1	24.5	33.8	<b>33.0</b>	82.4	32.8	82.2	58.6	27.2	84.3	33.4	46.3	2.2	29.5	32.3	46.5
ADVENT [38]	89.4	33.1	81.0	26.6	26.8	27.2	33.5	24.7	83.9	36.7	78.8	58.7	30.5	84.8	38.5	44.5	1.7	31.6	32.4	45.5
FADA [40]	92.5	47.5	85.1	37.6	<b>32.8</b>	<b>33.4</b>	33.8	18.4	85.3	37.7	83.5	63.2	<b>39.7</b>	87.5	32.9	47.8	1.6	34.9	<b>39.5</b>	49.2
<b>FADA [40] + pAdaIN</b>	<b>93.3</b>	<b>55.7</b>	<b>85.6</b>	<b>38.3</b>	29.6	31.2	34.2	17.8	<b>86.2</b>	<b>41.0</b>	<b>88.8</b>	<b>65.1</b>	37.1	<b>87.6</b>	<b>45.9</b>	<b>55.1</b>	15.1	<b>39.4</b>	31.1	<b>51.5</b>

# Domain Adaptation



# Image Classification

Swap global statistics between every two elements in the batch



# Image Classification

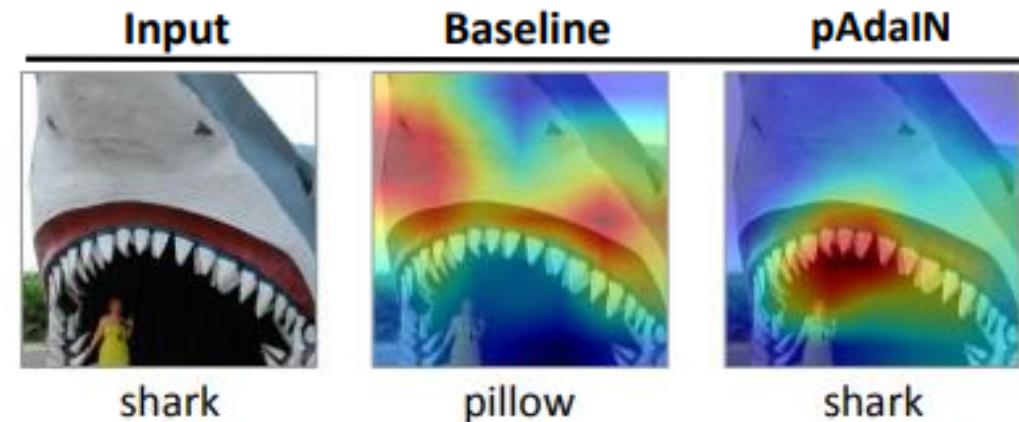
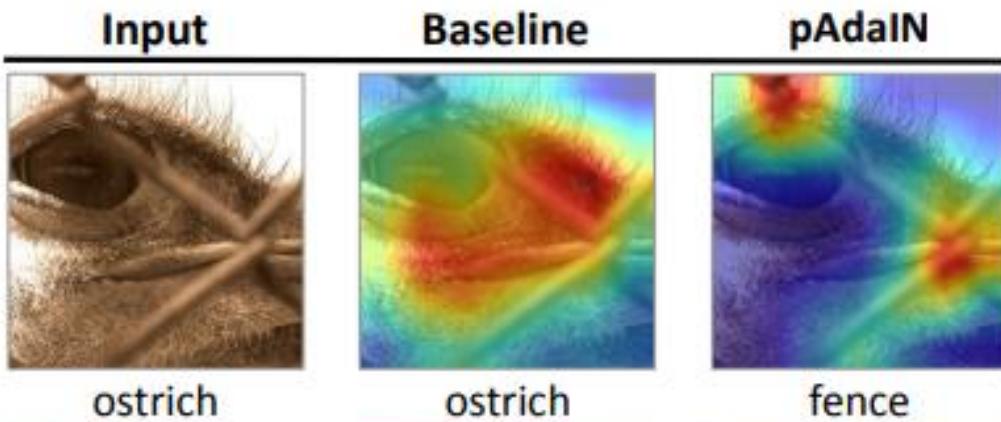
ImageNet

Method	Architecture	Top-1 Accuracy	Top-5 Accuracy
Baseline	ResNet50	77.1	93.63
pAdaIN	ResNet50	<b>77.7</b>	<b>93.93</b>
Baseline	ResNet101	78.13	93.71
pAdaIN	ResNet101	<b>78.8</b>	<b>94.35</b>
Baseline	ResNet152	78.31	94.06
pAdaIN	ResNet152	<b>79.13</b>	<b>94.64</b>

Cifar100

Method	Architecture	CIFAR 100
Baseline	PyramidNet	83.49
pAdaIN	PyramidNet	<b>84.17</b>
Baseline	ResNet18	76.13
pAdaIN	ResNet18	<b>77.82</b>
Baseline	ResNet50	78.22
pAdaIN	ResNet50	<b>79.03</b>

# Image Classification



# Robustness Towards Corruption

ImageNet-C

Gaussian Noise



Shot Noise



Impulse Noise



Defocus Blur



Frosted Glass Blur



Motion Blur



Zoom Blur



Snow



Frost



Fog



Brightness



Contrast



Elastic



Pixelate



JPEG



# Robustness Towards Corruption

CIFAR100-C

	Baseline	Cutout [8]	Mixup [43]	CutMix [43]	Auto-Augment [7]	Adversarial Training [30]	Augmix [18]	pAdaIN+ Augmix
DenseNet-BC	59.3	59.6	55.4	59.2	53.9	55.2	38.9	<b>37.5</b>
ResNext-29	53.4	54.6	51.4	54.1	51.3	54.4	34.4	<b>31.6</b>

## Category Wise Breakdown

Dataset	Network	Architecture	E	mCE	Noise				Blur				Weather				Digital			
					Gauss.	Shot	Impulse	Defocus	Glass	Motion	Zoom	Snow	Frost	Fog	Bright	Contrast	Elastic	Pixel	JPEG	
INet-C	Baseline	ResNet50	22.9	76.7	80	82	83	75	89	78	80	78	75	66	57	71	85	77	77	
INet-C	pAdaIN	ResNet50	<b>22.3</b>	<b>72.8</b>	<b>78</b>	<b>79</b>	<b>81</b>	<b>70</b>	<b>87</b>	<b>74</b>	<b>76</b>	<b>74</b>	<b>71</b>	<b>64</b>	<b>55</b>	<b>65</b>	<b>82</b>	<b>66</b>	<b>71</b>	
C100-C	Augmix [18]	DenseNet-BC	24.2	38.9	60	51	41	27	55	31	29	36	39	35	28	37	33	39	41	
C100-C	Augmix+pAdaIN	DenseNet-BC	<b>22.2</b>	<b>37.5</b>	<b>58</b>	<b>49</b>	<b>40</b>	<b>26</b>	<b>54</b>	<b>30</b>	<b>28</b>	<b>35</b>	<b>38</b>	<b>33</b>	<b>25</b>	<b>36</b>	<b>32</b>	<b>37</b>	<b>40</b>	
C100-C	Augmix [18]	ResNext-29	21.0	34.4	<b>56</b>	<b>48</b>	32	23	<b>49</b>	27	25	32	35	32	24	32	30	34	37	
C100-C	Augmix+pAdaIN	ResNext-29	<b>17.3</b>	<b>31.6</b>	58	<b>48</b>	<b>24</b>	<b>20</b>	54	<b>23</b>	<b>21</b>	<b>28</b>	<b>30</b>	<b>25</b>	<b>19</b>	<b>27</b>	<b>27</b>	<b>33</b>	<b>36</b>	

## Manipulating Structure

- Multi-sample approaches
- Structural analogies
- Novel videos of similar structure

## Manipulating by Understanding Structure

- Speed up videos “gracefully” using “speed” as supervision

## Structure Preserving Manipulation

- Image classification and domain adaptation

**Structure** is Key to **Image Understanding**

**Demonstrate** using **Structure Aware Manipulation**

### Next?

- 3D-aware structure manipulation
- Manipulating multiple objects in videos
- Functional relationships: A person riding a bike vs a person beside a bike

Thank You! Questions?