

1 Least-Squares Regression: Solving Normal Equations

In linear regression, we seek a model that captures a linear relationship between input data and output data. The simplest variant is the least-squares formulation. In this scenario, we are given a data matrix $X \in \mathbb{R}^{n \times d}$, where each row represents a datapoint $X_i \in \mathbb{R}^d$. We are also given an associated vector of output values $y \in \mathbb{R}^n$. We define the problem to be

$$X \in \mathbb{R}^{n \times d}$$

$$\begin{bmatrix} -x_1^T \\ -x_2^T \\ \vdots \\ -x_n^T \end{bmatrix}$$

$$\begin{matrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{matrix}$$

$$X_i \rightarrow \hat{y}$$

$$\arg \min_w \|Xw - y\|^2.$$

$$2X^T X w - 2X^T y = 0$$

$$\Rightarrow X^T X \hat{w} = X^T y$$

By finding the gradient of the objective equation (with respect to w) and setting it equal to zero, we arrive at the normal equations

$$X^T X \hat{w} = X^T y.$$

$$A \hat{w} = b$$

Solving these normal equations will yield an optimal choice of weights \hat{w} for our linear model. One question that arises is, is there always a solution to the problem? When is the solution unique? We will answer these questions in this exercise.

- (a) Prove that a solution always exists to the normal equations, regardless of the choice of X and y .

Hint: Consider the normal equations to be a usual matrix-vector system of equations, $Aw = b$.

What is the range of values that the right-hand side can take on? What about the left-hand side?

$$\text{range}(X^T X) = \text{range}(X^T)$$

$$b \in \text{range}(X^T), \quad X^T X \hat{w} \in \text{range}(X^T)$$

- (b) When the matrix $X^T X$ is invertible, there exists a unique solution ($\hat{w} = (X^T X)^{-1} X^T y$). What conditions need to be true about $X^T X$ and X for this statement to be true? Express your answer in terms of *rank*.

$$\hat{w} = (X^T X)^{-1} X^T y$$

X has full row-rank

$$\text{rank}(X) = d$$

$$\text{rank}(X) < d$$

$X^T X$ non-inv

$$\underbrace{X^T X}_{d \times d \text{ rank } d} \Rightarrow \text{invertible}$$

- (c) If the matrix $X^T X$ is *not* invertible, there will be infinitely many solutions to the normal equations. One such solution can be defined in terms of the Moore–Penrose pseudoinverse of the matrix $X^T X$.

We define the pseudoinverse of A to be the matrix

$$A = U \Sigma V^T$$

$$A^+ = V \Sigma^+ U^T = \sum_{i: \sigma_i > 0} \frac{1}{\sigma_i} v_i u_i^T,$$

$A \in \mathbb{R}^{m \times n}$
 $A^+ \in \mathbb{R}^{n \times m}$

$$X^T X = V \Lambda V^T$$

$$(X^T X)^+ = V \Lambda^{-1} V^T$$

where Σ^+ is computed from Σ by taking the transpose A and inverting the nonzero singular values on the diagonal.

Verify that $\hat{w} = X^+ y$ is a solution to the normal equations

SVD

$$w = X^+ y$$

$$X^T X w = X^T y \quad U^T U = I$$

$$X^T X X^+ y = (V \Sigma^T U^T) (U \Sigma V^T) (V \Sigma^+ U^T) y$$

$$= V \Sigma^T \Sigma \Sigma^+ U^T y$$

$$= V \Sigma^T U^T y$$

$$= X^T y$$

$$A = U \begin{bmatrix} \sigma_1 & \sigma_2 & \dots & 0 & 0 \end{bmatrix} V^T$$

$$A^+ = V \underbrace{\begin{bmatrix} 1/\sigma_1 & 1/\sigma_2 & \dots & 0 & 0 \end{bmatrix}}_{\Sigma^+} U^T$$

$$\Sigma^T \begin{bmatrix} \sigma_1 & \sigma_2 & \sigma_3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1/\sigma_1 & 1/\sigma_2 & 1/\sigma_3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$= \Sigma \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \end{bmatrix} = \Sigma^T$$

2 The Least-Norm Solution of a Least-Squares Problem

Some least-squares linear regression problems are under-determined and have infinitely many solutions. In the last problem, we showed that the pseudo-inverse provided one such solution, but we don't want just any solution to this system.

In this problem, our goal is to provide an explicit expression for the *least-norm* least-squares estimator, defined to be

$$\widehat{w}_{LS, LN} = \arg \min_w \{ \|w\|_2^2 : w \text{ is a minimizer of } \|Xw - y\|^2 \},$$

$W = \left\{ \begin{bmatrix} \frac{1}{2} \\ 2 \\ x \end{bmatrix} : x \in \mathbb{R} \right\}$
 $\widehat{w}_{LS, LN} = \begin{bmatrix} \frac{1}{2} \\ 2 \\ 0 \end{bmatrix}$

where $X \in \mathbb{R}^{n \times d}$, $w \in \mathbb{R}^d$, and $y \in \mathbb{R}^n$.

- (a) Show that there exists a solution to the least-squares problem (to minimize $\|Xw - y\|^2$) that lies in the rowspace of X . **Hint:** Use the normal equations and the fundamental theorem of linear algebra.

$$X^T X w = X^T y$$

$$w = w_0 + \Delta$$

$\underbrace{w_0}_{\in \text{row}(X)} + \underbrace{\Delta}_{\in \text{null}(X^T X)}$

$$\text{null}(X^T X) = \text{null}(X) \perp \text{row}(X) = \text{range}(X^T)$$

$$X^T X (w_0 + \Delta) = X^T X w_0 + X^T X \Delta = X^T X w_0 = X^T y$$

$$X^T X w = X^T y$$

$$X^T X w_0 = X^T y$$

\downarrow
 $w_0 \in \text{row}(X)$

$$\|w\|_2^2 = \|w_0\|_2^2 + \|\Delta\|_2^2 + 2w_0^T \Delta$$

$$\geq \|w_0\|_2^2$$

- (b) Show that the solution w_0 in the rowspace is unique.

$$w'_0 \neq w_0 : w'_0 \in \text{row}(X), X^T X w'_0 = X^T y$$

$$\begin{aligned} X^T X w'_0 &= X^T y \\ -X^T X w_0 &= X^T y \\ \hline X^T X (w'_0 - w_0) &= 0 \Rightarrow (w'_0 - w_0) \in \text{null}(X) \quad \text{--- (1)} \end{aligned}$$

$$\begin{aligned} w'_0, w_0 &\in \text{row}(X) \\ \Rightarrow w'_0 - w_0 &\in \text{row}(X) \quad \text{--- (2)} \end{aligned}$$

$w'_0 - w_0 = 0$

- (c) Show that the solution we identified in part (a) is in fact the solution with the smallest ℓ_2 norm (i.e., the solution to the least norm problem $\widehat{w}_{LS, LN}$).

$$\begin{aligned} \|w\|_2^2 &= \|w_0\|^2 + \|\Delta\|^2 + 2w_0^T \Delta \xrightarrow{0} 0 \\ &\geq \|w_0\|^2 \end{aligned}$$

- (d) Show that $\widehat{w}_{LS, LN}$ is the pseudoinverse solution (from the last problem)

$$\widehat{w}_{LS, LN} = X^+ y = \sum_{i: \sigma_i > 0} \frac{1}{\sigma_i} \underbrace{v_i}_{\text{vector}} \underbrace{(u_i^T y)}_{\text{scalar}} = \text{some lin comb of the basis veds of row}(X)$$

In problem 1 we showed that the pseudo inverse was a solution to the normal equations. In part a) of this question, we showed that there was only one solution to the normal equations in the row space of X and in part b) that this solution in the row space is the solution of least norm. Thus, if the pseudo-inverse is in the row space of X it is the solution of least norm. Show this directly by checking that the above expression for $\widehat{w}_{LS, LN}$ is in the row space of X .

need to show

$$X = U \Sigma V^T = \sum_{i: \sigma_i > 0} \sigma_i u_i v_i^T$$

$\{v_i : \sigma_i > 0\}$ forms an orthonormal basis for $\text{row}(X)$.

$$z \in \text{null}(X)$$

$$Xz = \sum_{i: \sigma_i > 0} \sigma_i u_i (v_i^T z) = 0 \quad v_i^T z = 0 \quad \forall i: \sigma_i > 0$$

$$\{v_i : \sigma_i > 0\} \perp \text{null}(X)$$

3 Softmax Regression

Logistic regression directly models the probability of a data point x belonging to class 1, or $P(Y = 1|X = x) = \mathbf{g}(w^\top x)$ where \mathbf{g} is the sigmoid function $\mathbf{g}(z) = \frac{1}{1+e^{(-z)}}$. This is however limited to modeling binary classification problems. While logistic regression can be extended to the multi-class setting using many-to-one or one-to-one approaches, there exists a more elegant solution.

Rather than only modeling $P(Y = 1|X = x)$, softmax regression models the entire categorical distribution over k classes, $P(Y = 1|X = x), P(Y = 2|X = x), \dots, P(Y = k|X = x)$. It does so by leveraging a different linear model w_i for each of the k classes and the softmax function, $s(z)_i = \frac{e^{-z_i}}{\sum_{j=1}^k e^{-z_j}}$. Concretely:

$$P(Y = i|X = x) = \frac{e^{-w_i^\top x}}{\sum_{j=1}^k e^{-w_j^\top x}}$$

This essentially assumes each classes probability is proportional to $e^{-w_i^\top x}$ and normalizes by the sum of total values.

- (a) Show that in the case where $k = 2$, softmax regression is the same as logistic regression.
- (b) In it's default form given above, softmax regression is actually overparameterized – there are more parameters than needed for the same model. This should be evident in your answer to part a). Reformulate softmax regression such that it requires fewer parameters.
- (c) Recall binary cross-entropy loss:

$$L(\hat{y}, y) = -y \log \hat{y} - (1 - y) \log(1 - \hat{y})$$

How would you design the analogous loss function for softmax regression?