



for 1 training example

Neural n/w representation :-

$z^{[1]} = w^{[1]}x + b^{[1]}$ components of one layer

$a^{[1]} = \sigma(z^{[1]})$

$z^{[2]} = w^{[2]}.a^{[1]} + b^{[2]}$

$a^{[2]} = \sigma(z^{[2]})$

$z^{[1]} = \begin{bmatrix} w_1^{[1]T} & w_2^{[1]T} & w_3^{[1]T} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} b_1^{[1]} \\ b_2^{[1]} \\ b_3^{[1]} \end{bmatrix}$

$z^{[2]} = \begin{bmatrix} w_1^{[2]T} & w_2^{[2]T} & w_3^{[2]T} \end{bmatrix} \begin{bmatrix} a_1^{[1]} \\ a_2^{[1]} \\ a_3^{[1]} \end{bmatrix} + \begin{bmatrix} b_1^{[2]} \\ b_2^{[2]} \\ b_3^{[2]} \end{bmatrix}$

$a^{[2]} = \begin{bmatrix} a_1^{[2]} \\ a_2^{[2]} \\ a_3^{[2]} \end{bmatrix}$

$3 \times 3 \quad 3 \times 1 \quad \text{dimensions of weight matrix and } [x_1, x_2, x_3]$

$\star w_2 \vee j$
logic of transpose

So, in short, equations :-

$$z^{[1]} = w \cdot x + b \quad \{ \text{for one layer}\}$$

$$3 \times 1 \quad \boxed{3 \times 3 \quad 3 \times 1} \quad 3 \times 1$$

$$a^{[1]} = \sigma(z^{[1]})$$

$$z^{[2]} = w^{[2]}.a^{[1]} + b^{[2]}$$

$$a^{[2]} = \sigma(z^{[2]})$$

* Vectorization across multiple examples :-

for $i = 1$ to m :-

$$z^{[1](i)} = w^{[1]} \cdot x^{(i)} + b^{[1](i)}$$

$$a^{[1](i)} = \sigma(z^{[1](i)})$$

$$z^{[2](i)} = w^{[2]}.a^{[1](i)} + b^{[2](i)}$$

$$a^{[2](i)} = \sigma(z^{[2](i)})$$

* Gradient Descent ! :-

$$dz^{[2]} = A^{[2]} - y$$

$$dw^{[2]} = \frac{1}{m} * dz^{[2]} * A^{[2]T}$$

$$db^{[2]} = \frac{1}{m} * np.sum(dz^{[2]}, axis=1, keepdims=True)$$

$$dw^{[1]} = \frac{1}{m} * dz^{[1]} * x^T \quad x^T = A^{[1]T}$$

$$db^{[1]} = \frac{1}{m} * np.sum(dz^{[1]}, axis=1, keepdims=True)$$

* Initialize with small random weights. $x \rightarrow$ important

Large weights \rightarrow large $z \rightarrow z \approx 0$, problem in backpropagation

& gradient descent

* Computing Gradients

$$(x, \omega, b) \rightarrow z = w^T x + b \quad a = \sigma(z) \quad l(a, y)$$

$$\frac{\partial l}{\partial \omega} = dz \cdot x \quad \frac{\partial l}{\partial b} = dz \cdot 1$$

$$\frac{\partial l}{\partial x} = dw \cdot \omega \quad \frac{\partial l}{\partial \omega} = dz \cdot x^T$$

$$\frac{\partial l}{\partial b} = db \cdot 1 \quad \frac{\partial l}{\partial b} = dz \cdot 1$$

$$\frac{\partial l}{\partial \omega} = dw \cdot \omega \quad \frac{\partial l}{\partial \omega} = dz \cdot \omega^T$$

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