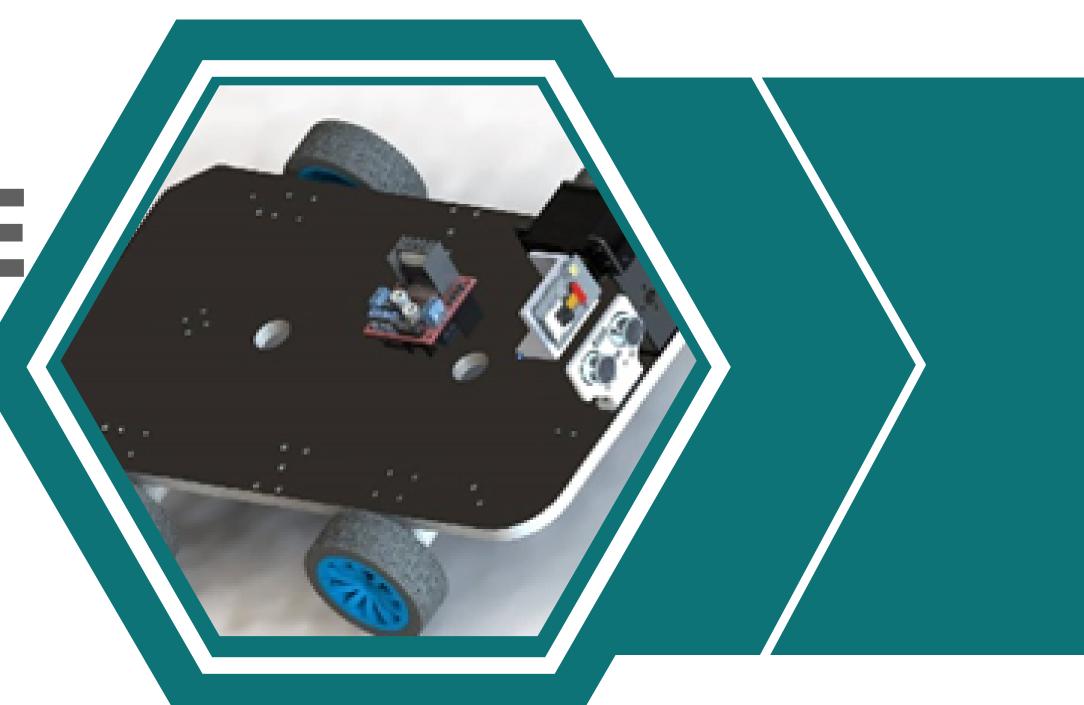
# SURVEILLANCE ROBOT

GRADUATION PROJECT II SEPTEMBER, 2022



## Team

**Supervisor:** 



Prepared by:

Dr.Aladdin Masri



Sahar Saleh



Hala Abduljalil



- **Team**
- Hardware Components
- > Future work
- Demo

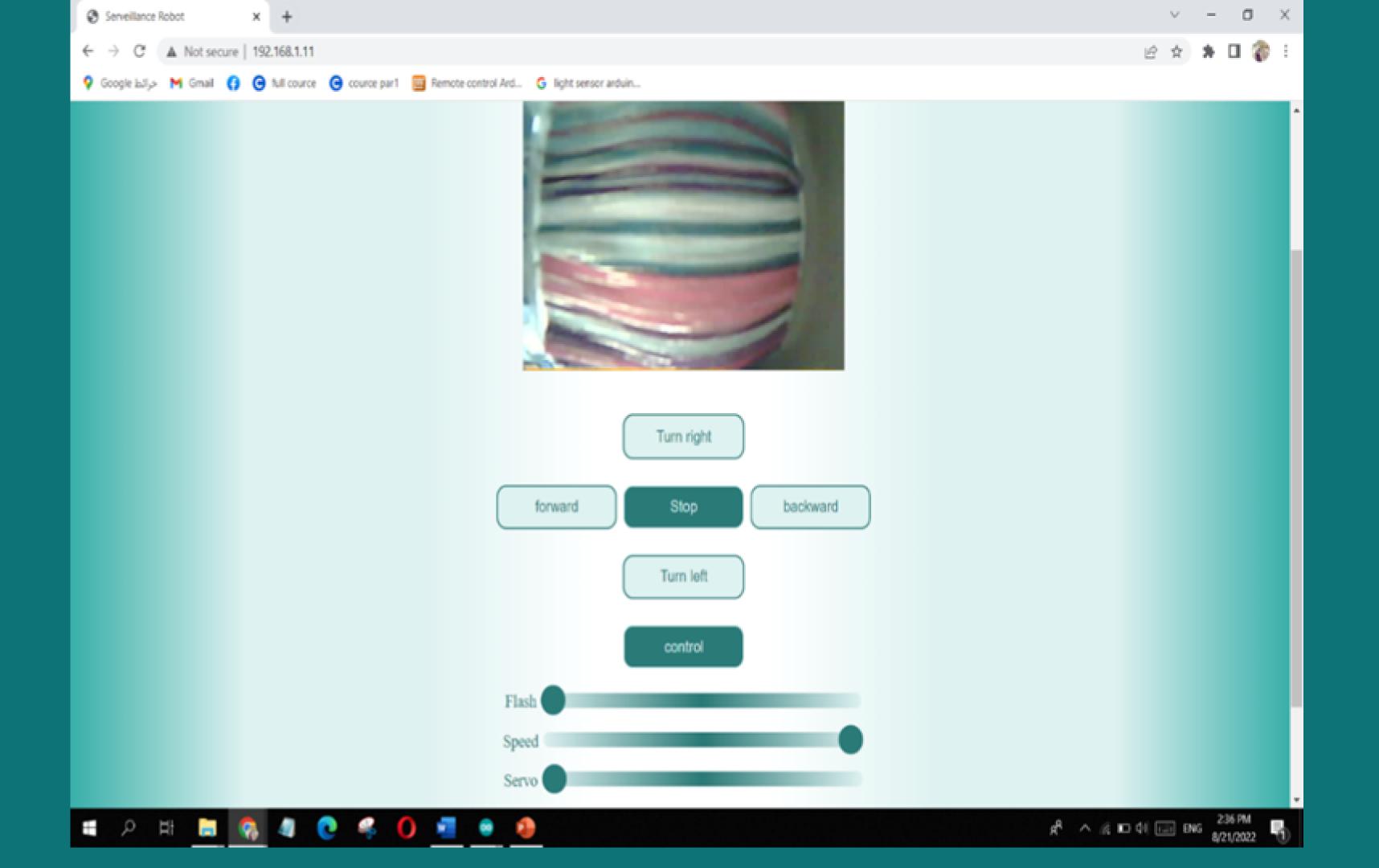
- **Introduction**
- **Features**
- **Overall Design**

#### Introduction:

surveillance robot is a possible solution to discover places that it is dangerous for humans to be in these places.

in this project we designed a robot that could be controlled in two different modes :control it to move forward ,backward ,rotate left and right using web page or an autonomous mode which makes the robot move individually .





#### Features

#### the features we worked in this project as follows:

- 1. we controlled the speed of the robot in range from 0 to 255(highest)
- 2. we put the esp-32 camera on a servo that could be controlled to move up and down.
- 3. we controlled the flash to make a better streaming for camera in the dark

#### Features

4.we added a gas sensor that Measures the proportion of gas . and if it exceeds the allowed limit it will send us a notification massege "there is a gas leakage" to signal app .

5. IR sensor :as above it will send a notification " IR detects an object here "6. LDR: If the place is dark the leds will be on .



#### Features

7. motion sensor: if the motion sensor detects a movement, the camera will capture a photo and send it to our telegram account.



# Microcontrollers:



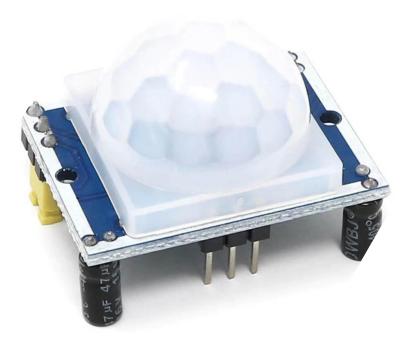
**ESP32-Camera** 



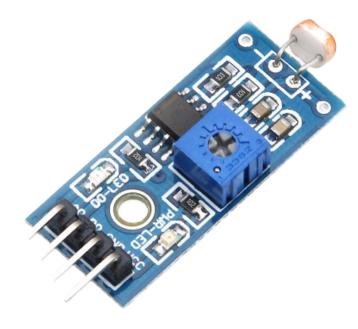
# Sensors:



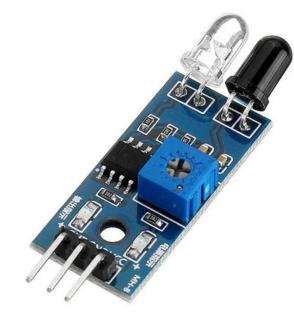
**Ultra Sonic** 



**Motion Sensor** 



**LDR Sensor** 



**IR Sensor** 



**Gas Sensor** 

# Motors:



Micro Servo

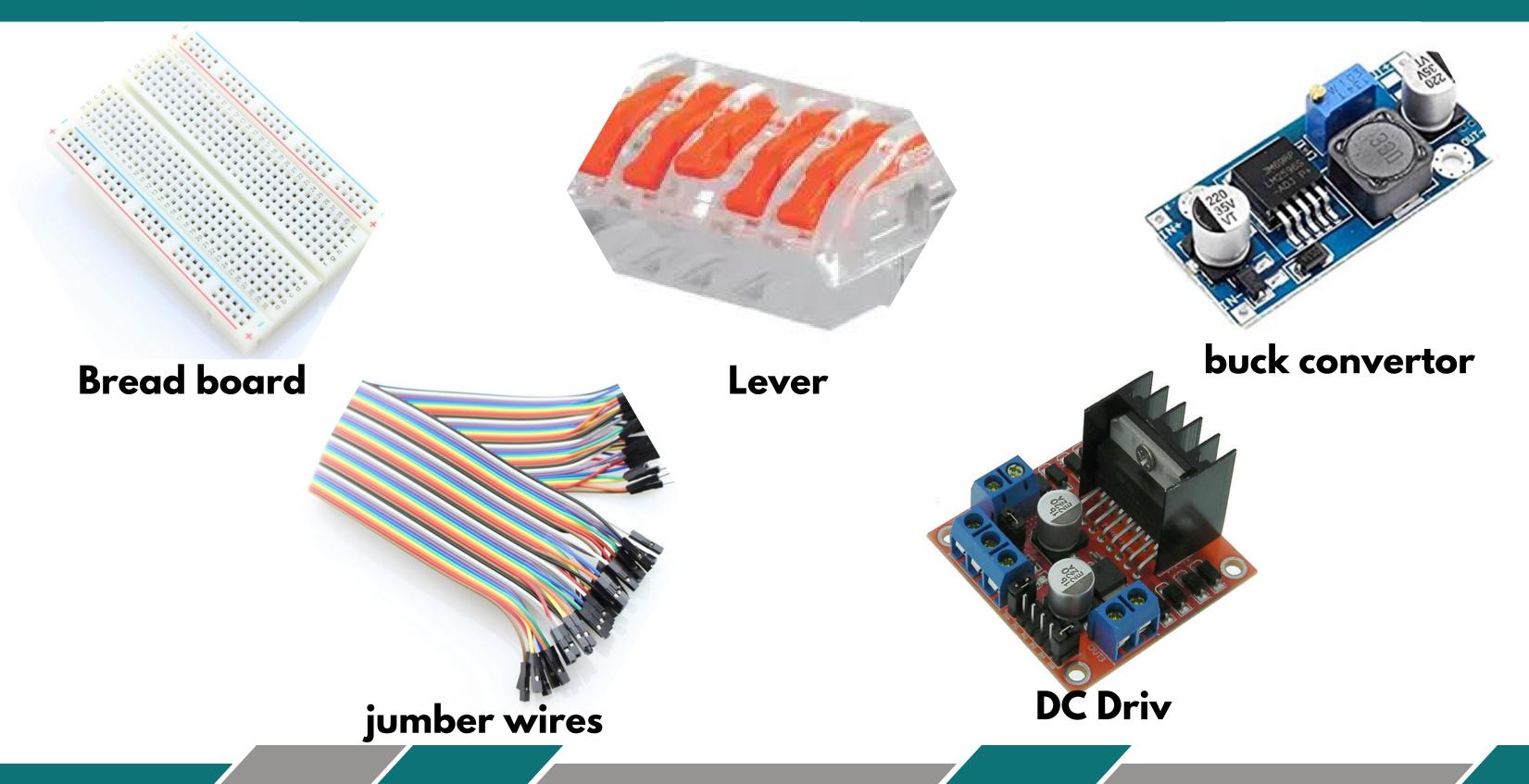


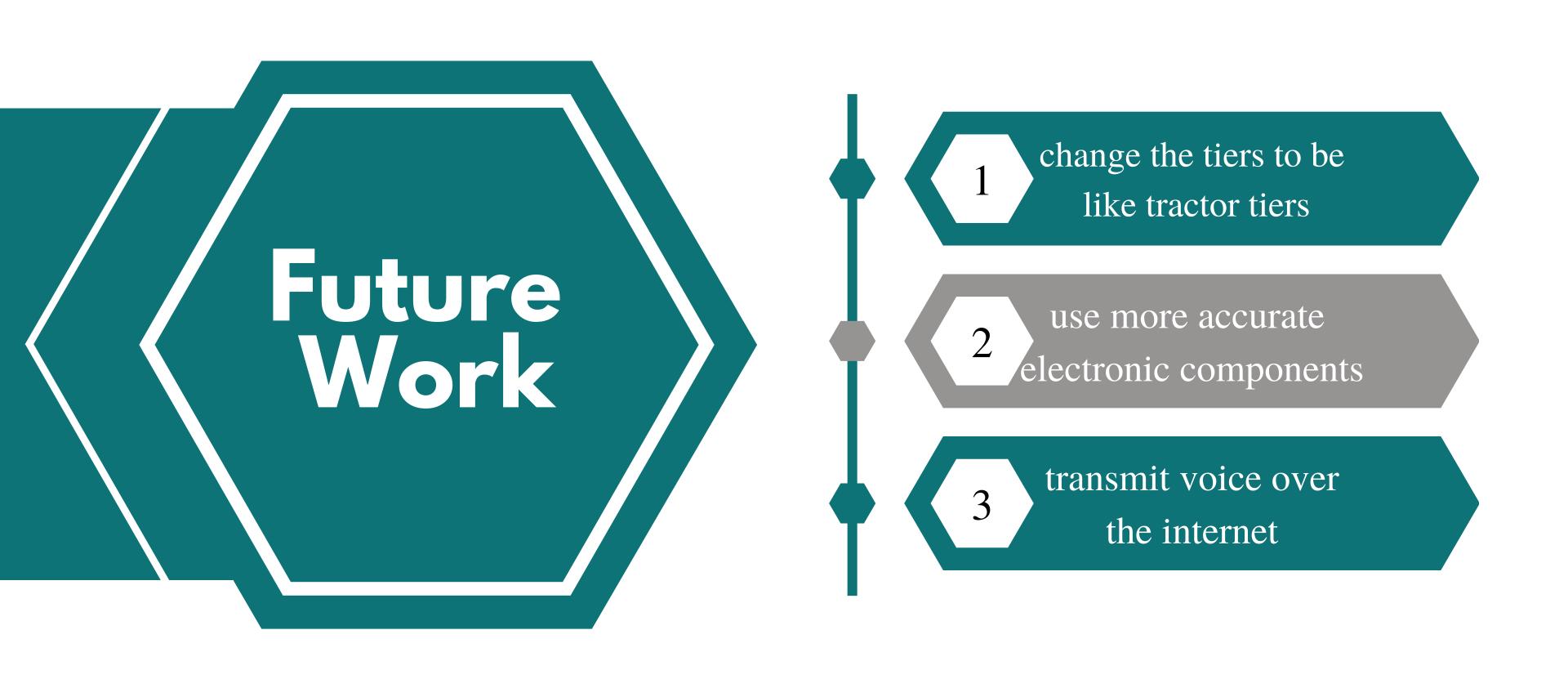
MG995 servo motor



JGA25 Motor x4

# Other Components:





### DEMO

hope you'll like it

<u>youtube link</u>

