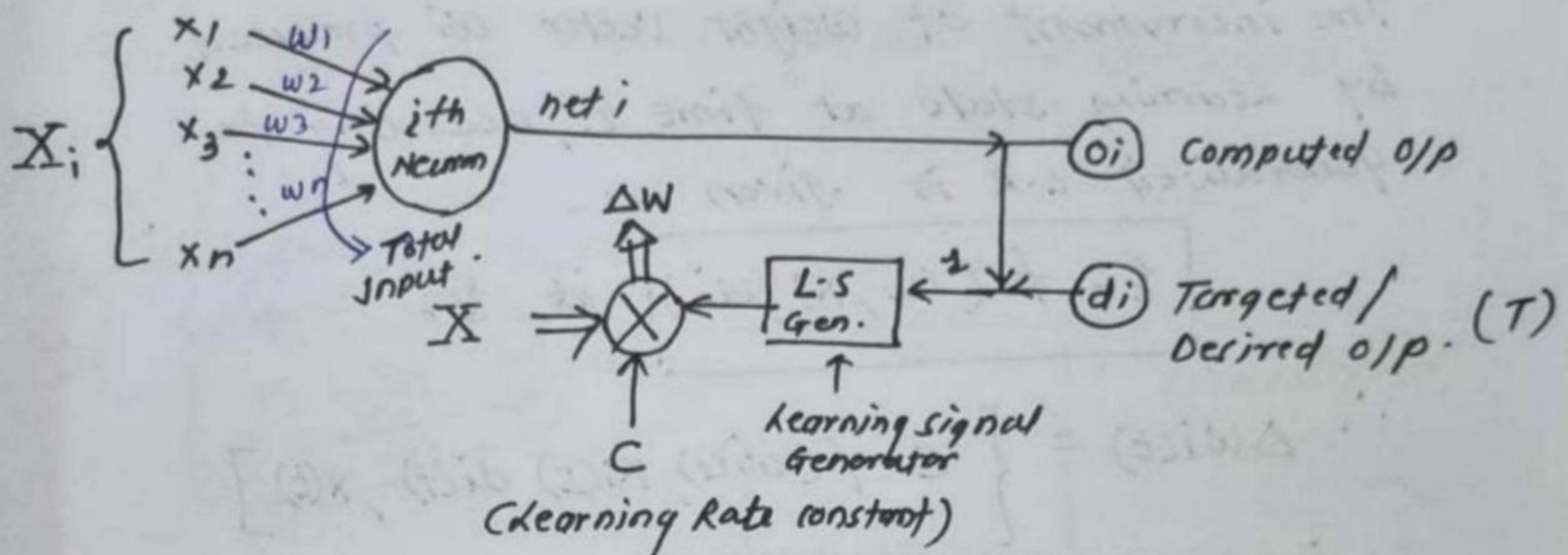


\* Generalised Learning Rule :- (AMARI - 1990)



consider any  $i$ -th neuron from NN-Architecture.

having input  $\rightarrow X_i$ , weight vectors -  $w_i$   
output  $\rightarrow O_i$

If we are using supervised learning then target or  
desired o/p  $d_i(T)$ .

$$x_i = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, \quad w_i = \begin{bmatrix} w_{i1} \\ w_{i2} \\ \vdots \\ w_{in} \end{bmatrix}, \quad w_i^T = [w_{i1}, w_{i2}, \dots, w_{in}]$$

$c \rightarrow$  learning rate constant

$r \rightarrow$  learning signal.

learning ~~rate~~  $r$  is general function of  $w_i$  (weight vector),  
signal

$X_i$ , and desired o/p ( $d_i$ )  $\rightarrow$  for supervised learning.

$$\boxed{\text{net } i = \sum_{i=1}^n (x_i, w_i)}$$

(1)

The increment of weight vector  $w_i$  produced by learning state at time  $t$ , according to generalised L.R is given as -

$$\boxed{\xi = f(w_i, x_i, d_i)} \text{ i.e., } \text{Eq}$$

$$\Delta w_{i(t)} = \left\{ C \cdot f(w_{i(t)}, x_{i(t)}, d_{i(t)}, x(t)) \right\}$$

$$\text{i.e., } \boxed{\Delta w_i(t) = C \cdot \xi \cdot x(t)} \quad \textcircled{A} - \text{Adjustment of weights.}$$

Where,  $C \rightarrow$  positive learning rate constant  
which determines rate of learning.

Thus, The weight vector adopted at time  $t$   
will becomes at next instant  $t+1$  as

$$\boxed{w_i(t+1) = w_i(t) + \Delta w_i(t)}$$

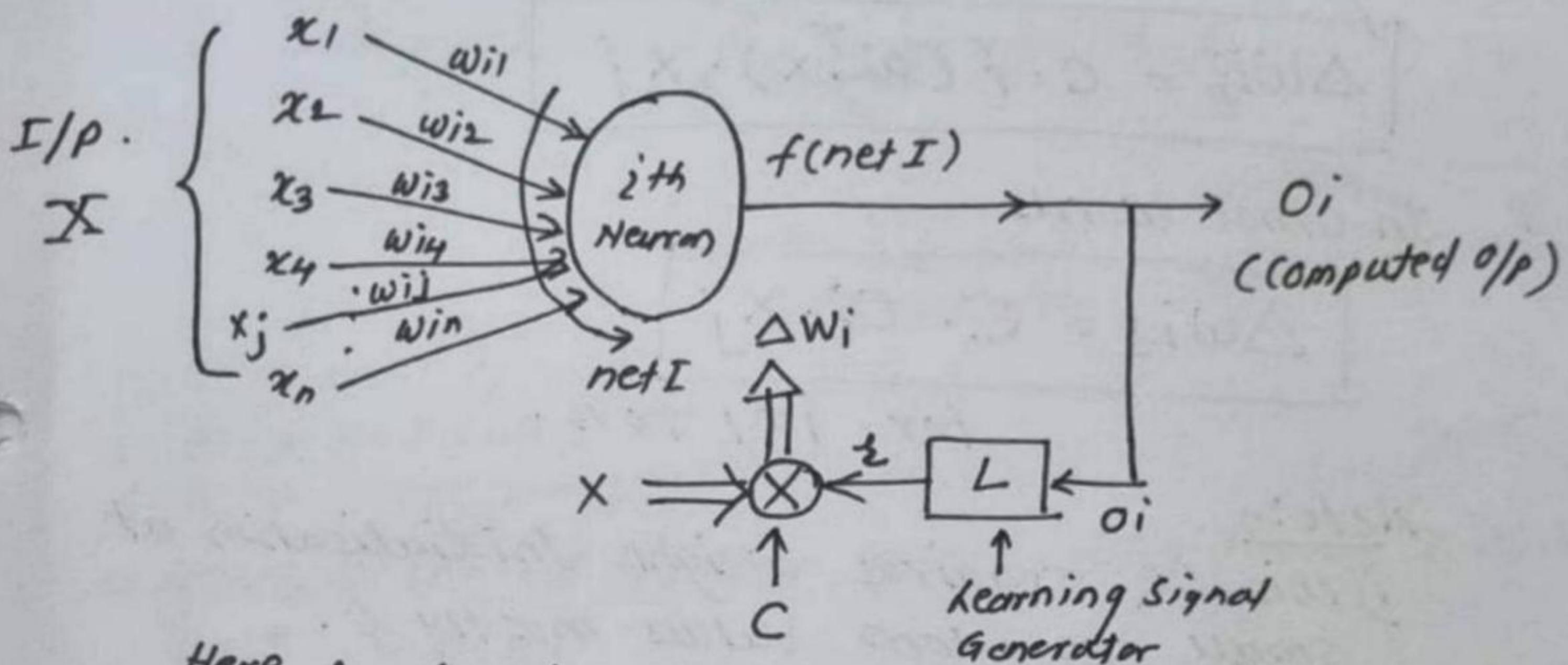
$$\text{i.e., } w_i(t+1) = w_i(t) + \left\{ C \cdot f[w_i(t), x(t), d_i(t)] \cdot x(t) \right\}$$

In general form

$$\boxed{w_i^{(k+1)} = w_i^{(k)} + C \cdot \xi \cdot (w_i^k, x^k, d_i^k)}$$

(2)

Hebbian Learning Rule: (1949 by Donald Hebb)  
 This rule is applicable for unsupervised learning.



Here,  $\varepsilon$  - learning signal  
 $C$  - the learning constant

Being unsupervised LR, this Hebbian LR the learning signal  $\varepsilon$  is computed o/p.

$$\text{ie, } \boxed{\varepsilon = O_i} \quad \text{ip, } (\omega^T \cdot x)$$

$$\text{where } O_i = f(\text{net I})$$

$$\boxed{O_i = f(\omega^T \cdot x)} \rightarrow \text{since } \boxed{\text{net} = \sum_{i=1}^n x_i w_i}$$

Thus Adjustment of weights ip,  $\Delta w_i$  of the weight vector becomes

$$\boxed{\Delta w_i = C \cdot \varepsilon \cdot x} \rightarrow \text{using Generalized LR.}$$

$$\therefore \boxed{\Delta w_i = C \cdot f(\omega^T \cdot x) \cdot x}$$

This is weight adjustment formula for all inputs.

(3)

Let's consider  $j$ th input to  $j$ th Neuron.  
with weight  $w_{jj}$ .

Using above formula -

$$\Delta w_{ij} = C \cdot f(\omega^T x) \cdot x_j$$

In other words -

$$\Delta w_{ij} = C \cdot o_i \cdot x_j$$

for  $i=1$  to  $n$ .

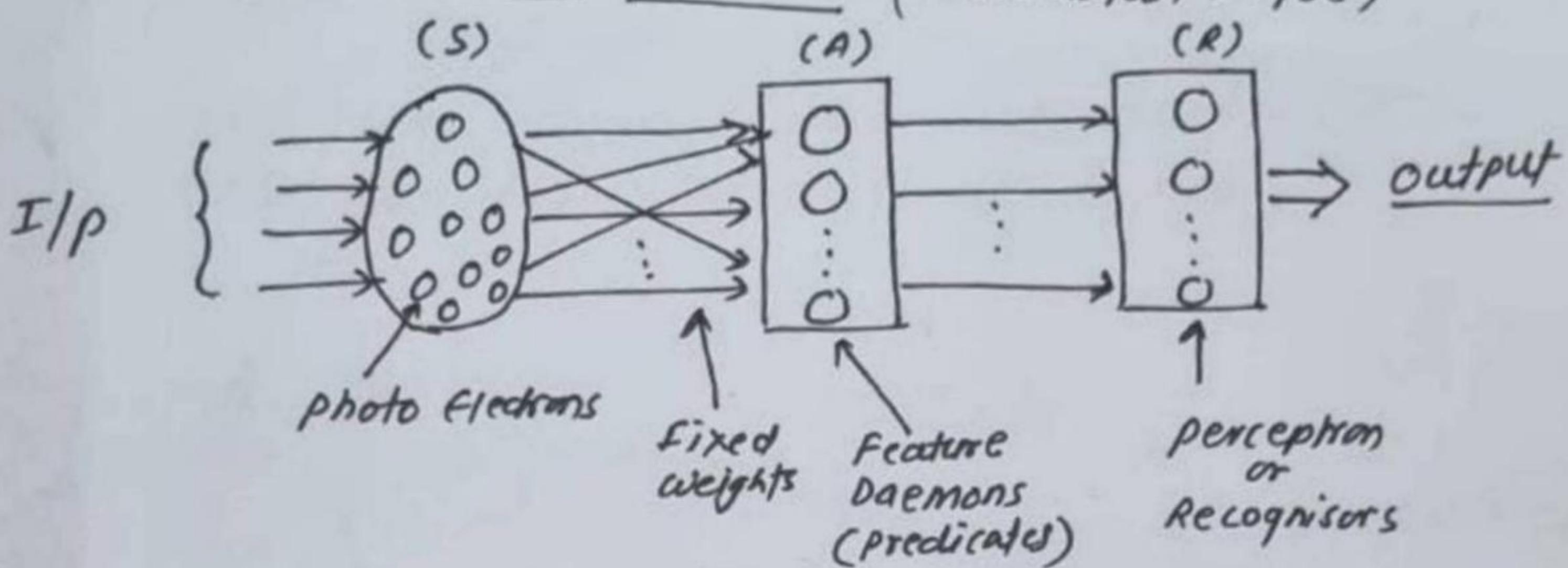
Note:-

- 1) This LR requires weight initialisation at small random values mostly 0.
- 2) This LR represents feed forward, unsupervised learning.
- 3) Thus this rule states that if the cross product of S/I/P and O/P ie,  $o_i x_j$  is positive that results in increase of weight  $w_{ij}$  otherwise weight decreases.

—X—

(Supervised Learning)

2) PERCEPTRON MODEL: (Rosenblatt - 1958)



[  
S → Sensory unit  
A → Association unit  
R → Recognition unit]

\* Model inspired for the human vision having 3 basic units S, A, R.

\* Basic units of S-unit are photo detectors (Approx. 400)

\* Association unit consists of predicates or feature Demons. which store features extracted by S unit.

\* R-unit consists of Recognisors or perceptions which produced O/P.

\* weights betw S-A units are fixed.

\* weights betw A-R unit are adjustable.

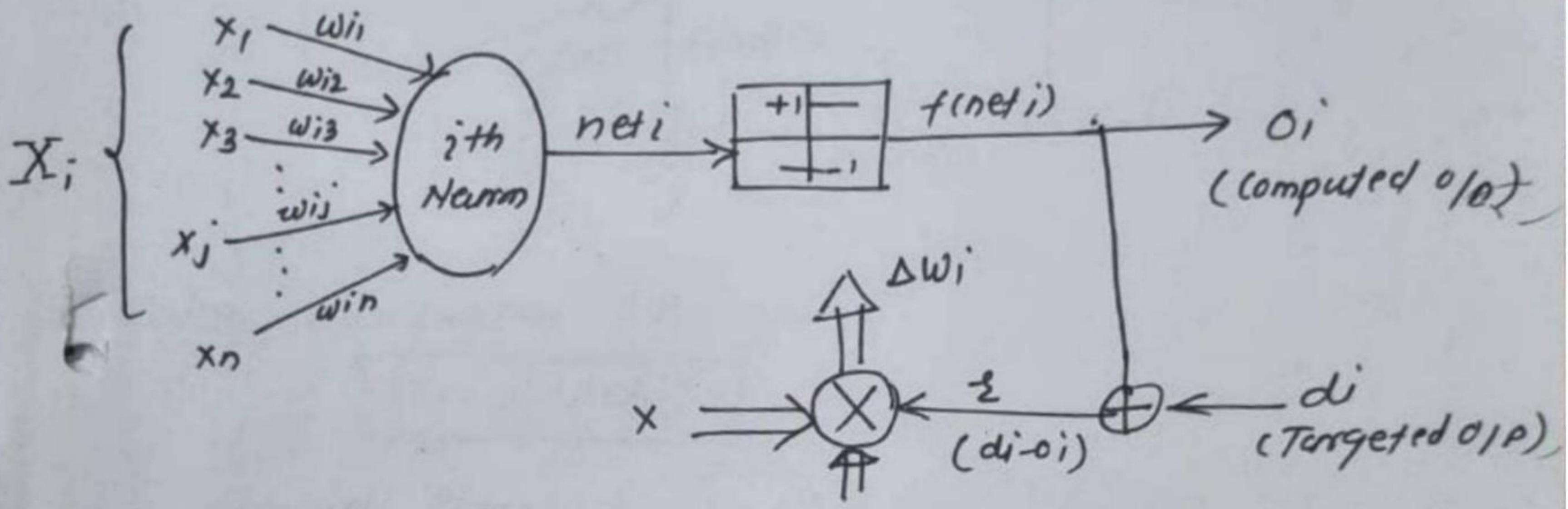
Working:- 1) If the total I/P coming to photo detectors (S-unit) is greater than or equal to threshold of O/P is 1 else 0.

2)

⑤

## \* Perception LR (Rosenblatt - 1958)

This rule is applicable for feed forward networks with supervised Learning.



Here, learning signal  $e$  is

$$e = d_i - o_i$$

$$o_i = f(net_i) = \text{sgn}(net_i)$$

$$\Delta w_{ij} = c \cdot e \cdot x_j$$

$$\therefore \Delta w_{ij} = c [d_i - o_i] \cdot x_j$$

$$\therefore \Delta w_{ij} = c [d_i - \text{sgn}(net_i)] \cdot x_j$$

for input link  $j$

Adjustment of weight  $\Delta w_{ij}$

$$\boxed{\Delta w_{ij} = c \cdot [d_i - \text{sgn}(net_i)] \cdot x_j}$$

$$\text{If } d_i = -1, o_i = 1$$

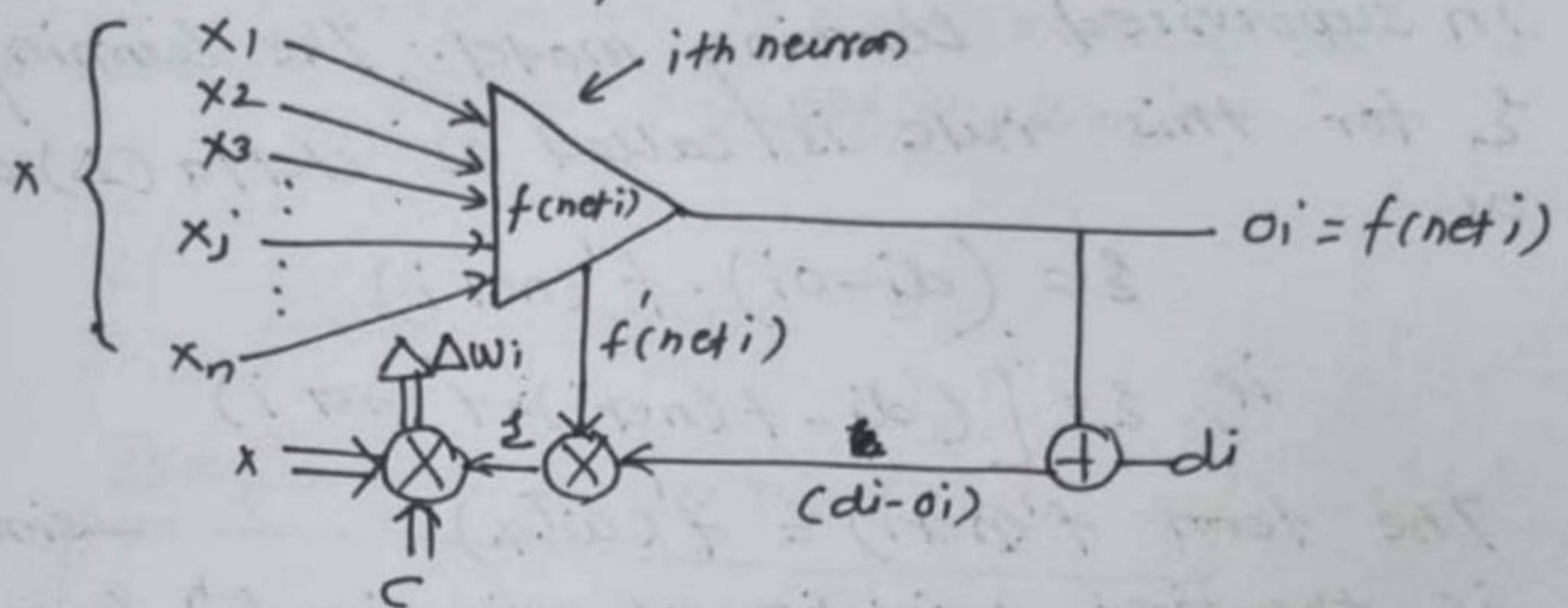
$$\boxed{\Delta w = -2cx}$$

$$\text{if } d_i = 1, o_i = -1$$

$$\boxed{\Delta w = +2cx}$$

(6)

## Delta Learning Rule



Using Generalised LR

$$o_i = f(\text{net}_i)$$

Learning signal  $\xi$  is

$$\xi = (d_i - o_i) * f'(\text{net}_i)$$

$$\therefore \xi = [(d_i - o_i) * f'(\text{net}_i)] \cdot f'(\text{net}_i) \quad \text{--- since } o_i = f(\text{net}_i)$$

Hence

$$\Delta w_i = c \cdot \xi \cdot x$$

$$\therefore \Delta w_i = c [(d_i - o_i) * f'(\text{net}_i)] \cdot x$$

$$\Delta w_i = c \{[(d_i - o_i) * f'(\text{net}_i)]\} \cdot x$$

$$\Delta w_i = c [(d_i - o_i) * f'(\text{net}_i)] \cdot x$$

for  $j^{th}$  S/P.

$$\Delta w_{ij} = c [(d_i - o_i) * f'(\text{net}_i)] \cdot x_j \quad \text{--- ①}$$

①

This rule is valid for continuous activation function in supervised learning model. The learning signal  $\xi$  for this rule is called as delta ( $\Delta$ ) and defined as

$$\xi = (d_i - o_i) \cdot f'(net_i)$$

$$iP, \xi = [(d_i - f(net_i)) \cdot f'(net_i)]$$

The term  $f'(net_i) = f'(w^T \cdot x)$  — since  $net_i = (w^T \cdot x)$   
is the first derivative of activation function  $f \cdot f(net_i)$

This LR can be also derived from the condition of Least square error b/w  $O_i$  and  $d_i$ . Calculating the gradient vector wrt  $w_i$  of the square error it can be defined as.

$$\boxed{E = \frac{1}{2} (d_i - o_i)^2} \quad \text{— since error is } E = (d_i - o_i)$$

$$E = \frac{1}{2} [d_i - f(w^T \cdot x)]^2 \quad \text{— (1)}$$

The error gradient vector value is

$$\nabla E = -(d_i - o_i) \cdot f'(w^T \cdot x) \cdot x \rightarrow \nabla E = \frac{\partial E}{\partial w_i}$$

The components of gradient vectors are

$$\frac{\partial E}{\partial w_{ij}} = -(d_i - o_i) \cdot f'(w^T \cdot x) \cdot x_j \text{ — for } j^{\text{th}} \text{ S/P.}$$

5

⑧

Since the minimisation of error requires the weight change in a negative gradient direction.

$$\text{ie, } \Delta w_{ij} = -\eta \cdot \nabla F$$

$$\therefore \Delta w_{ij} = -\eta \cdot [-(d_i - o_i) \cdot f'(w^T \cdot x) \cdot x_j]$$
$$\therefore \boxed{\Delta w_{ij} = \eta \cdot [(d_i - o_i) \cdot f'(w^T \cdot x) \cdot x_j]} \quad \textcircled{B}$$

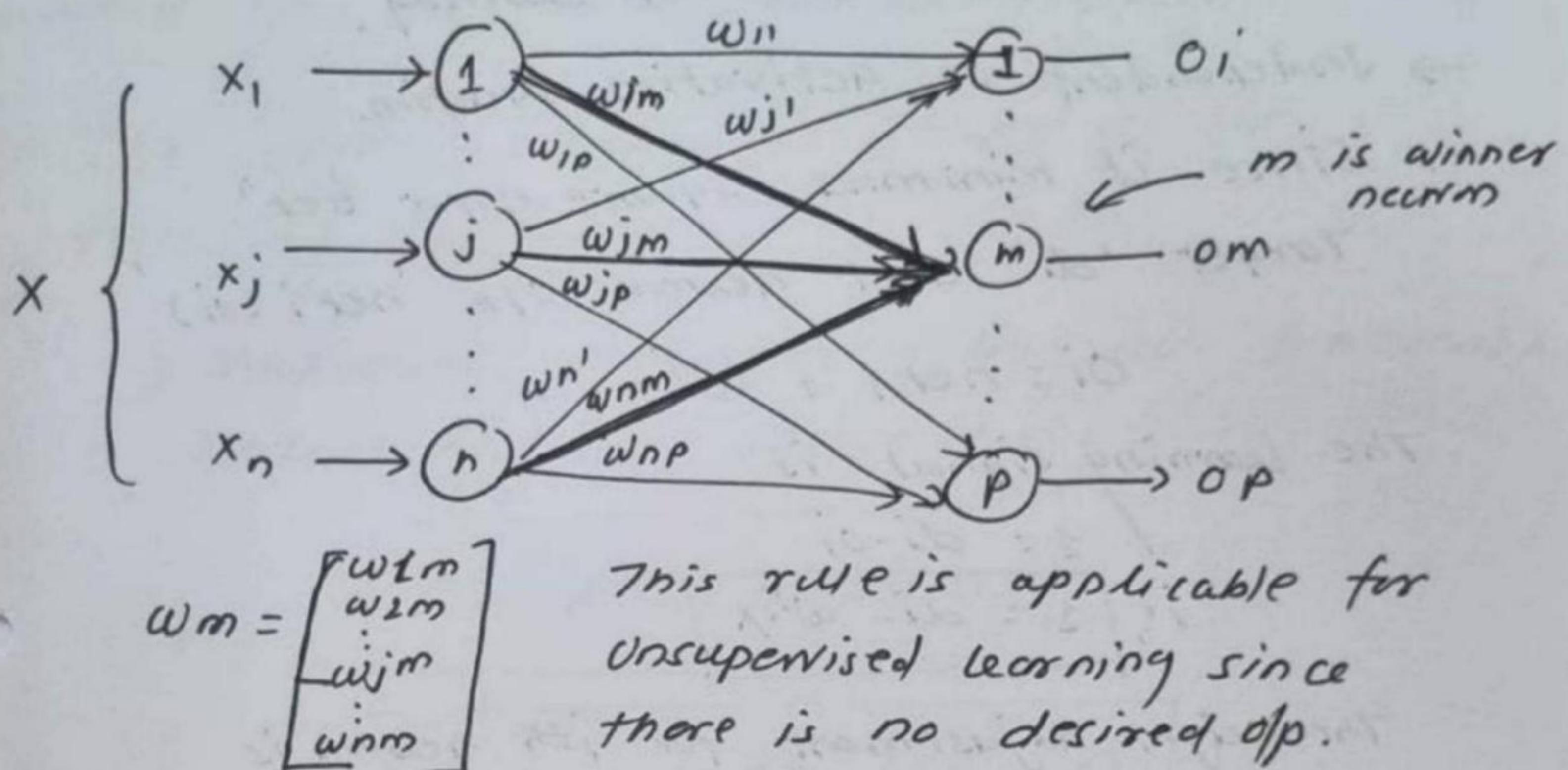
Here,  $\eta$  is some tve constant

Thus from equ<sup>n</sup>.  $\textcircled{A}$  &  $\textcircled{B}$  we can conclude that the weight adjustment term which we get using generalised LR is similar to the value which we compute using error gradient.

using G-LR -  $\Delta w_{ij} = c[(d_i - o_i) \cdot f'(w^T \cdot x) \cdot x_j] \quad \textcircled{A}$

using Error gradient  $\Delta w_{ij} = \eta [(d_i - o_i) \cdot f'(w^T \cdot x) \cdot x_j] \quad \textcircled{B}$

## Competitive LR (Winner take All) Rule



This LR only can be demonstrated or explain for output layer of 'p' neurons.

This is example of competitive learning in Unsupervised Learning.

⇒ This LR based on the assumption that one of the neuron in op layer say 'm' neuron has maximum response due to input 'x'. Thus this neuron is declared as a winning neuron. It has weights -  $[w_{1m}, w_{2m}, \dots, w_{jm}, \dots, w_{nm}]$ .

⇒ for next iteration only these weights undergo updation using formula

$$\Delta w_m = \alpha (X - w_m)$$

for jth neuron

$$\Delta w_j = \alpha (X - w_m) \quad \text{for } j = 1 \text{ to } n.$$

(10)

## Widrow-Hoff LR (1962)

- Applicable for supervised Learning.
- Independent of activation function.
- Since it minimize square error bet'

Target 'd<sub>i</sub>' and neuron o<sub>i</sub>, 'net<sub>i</sub>(o<sub>i</sub>)'

$$o_i = \text{net}_i = w^T \cdot x$$

The learning signal is

$$\begin{aligned} \xi &= d_i - o_i \\ \text{or, } \xi &= d_i - w^T \cdot x \end{aligned}$$

The weight adjustment for i<sup>th</sup> neuron is

$$\Delta w_i = c \cdot \xi \cdot x$$

$$\therefore \Delta w_i = c \cdot [(d_i - w^T \cdot x)] \cdot x \quad \text{--- (4)}$$

Thus for j<sup>th</sup> neuron input

$$\Delta w_{ij} = c \cdot [(d_i - (w^T \cdot x))] \cdot x_j \quad \text{--- (5)}$$

Its special case of Delta LR.

$$f(w^T \cdot x) = w^T \cdot x$$

Activation fun is  $f(w^T \cdot x) = f(\text{net}_i) = 1$ .

The eqn of DLR becomes.

$$\Delta w_{ij} = c \cdot (d_i - o_i) \cdot x_j$$

(a)  
11

Where  $\alpha$  is a small learning constant  
and it decreases as learning progresses.

⇒ The winner selection is based on the  
following criteria.

i) maximum activation among all  $P$  neurons  
participating in competition.

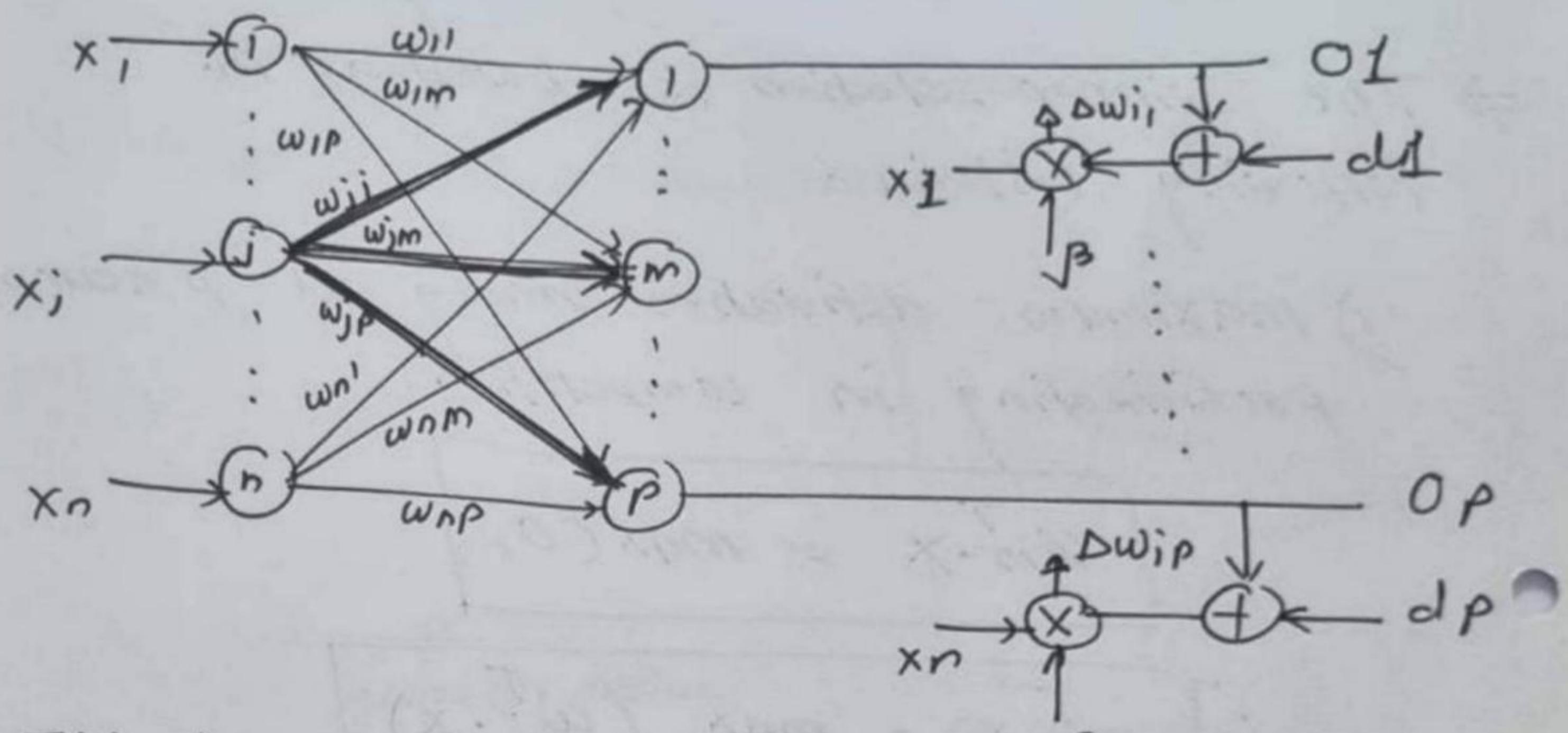
$$\boxed{\omega_m^T \cdot x = \max(\alpha_i)}$$

$$\boxed{\omega_m^T \cdot x = \max_{i=1 \text{ to } P} (\omega_i^T \cdot x)}$$

— x —



## Outstar LR



This is example of supervised LR used to provide learning of repetitive and characteristics properties of S/I/P - O/I/P relationship.

It suppose to allow a n/w to extract statistical properties of the S/I/P & O/I/P signals.

weight adjustment can be computed as.

$$\Delta w_j = \beta [d_j - w_j]$$

and Individual weight adjustment

$$\boxed{\Delta w_{mj} = \beta [d - w_{mj}]} \text{ for } m = 1 \text{ to } P$$

$\beta$  is small +ve learning constant and it decreases as learning progresses.

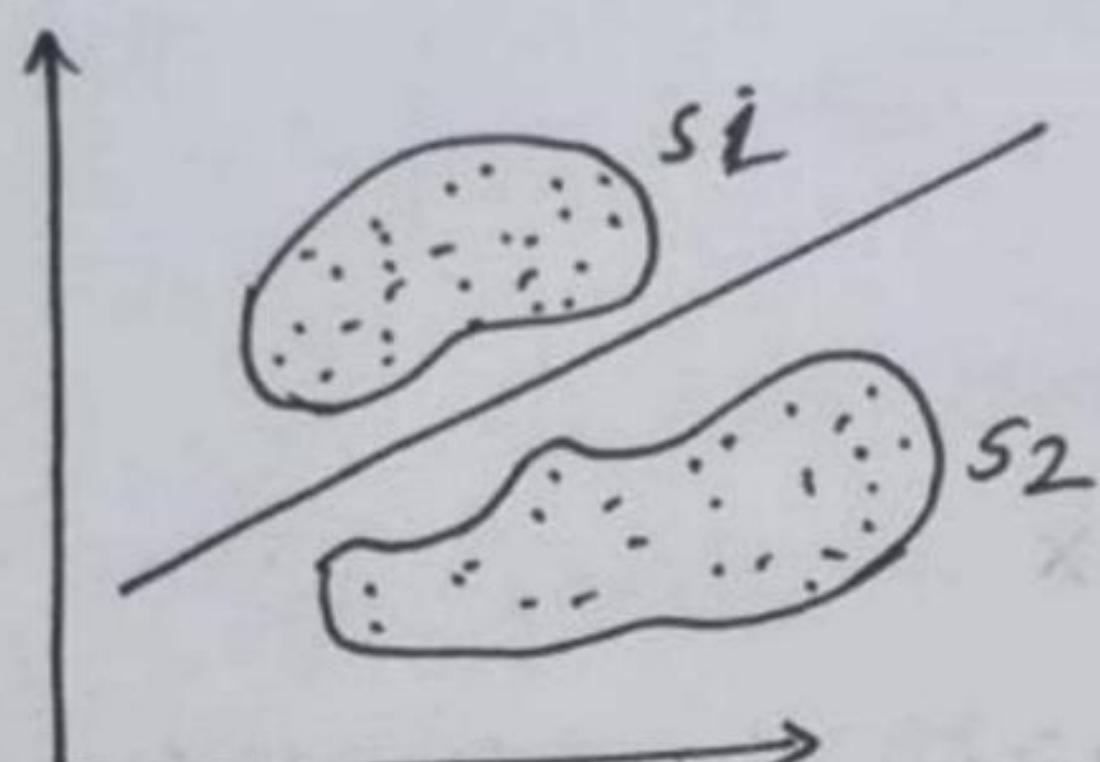
This rule typically ensures that the o/p pattern becomes similar to undistorted desired o/p after repeatedly applying the weight adjustment formula on distorted o/p.

(1) (2)

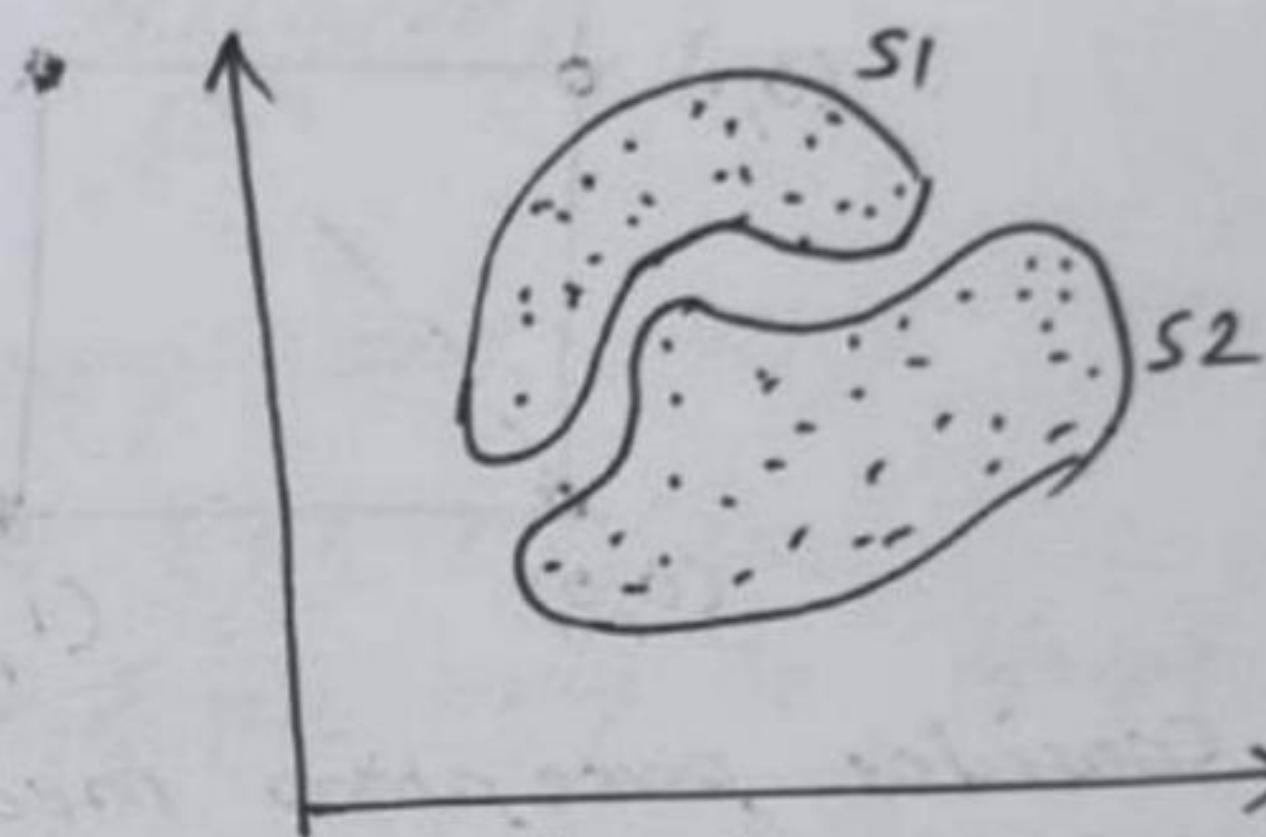
## \* Linear separability

perception model can not handle the tasks which are linearly separable.

Sets of points in 2-D spaces are linearly separable if the ~~two~~ sets can be separated by a straight line.



(a) Linearly separable patterns



(b) Non-Linearly separable patterns.

⇒ A set of points in  $n$ -dimensional space are linearly separable if there is a hyperplane of  $(n-1)$  dimension that separates the sets.

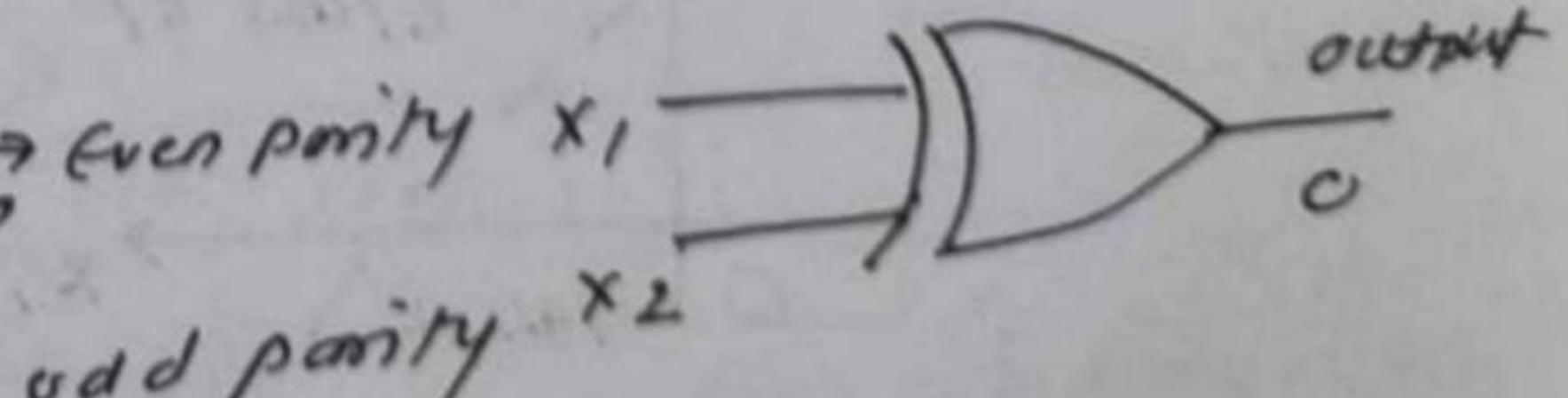
The perception cannot find weights for classification type of problem that are not linearly separable. It can be illustrated by X-OR problem.

## \* X-OR problem :-

X-OR is logical operation given as .

$x_1$	$x_2$	output
0	0	0
1	1	0
0	1	1
1	0	1

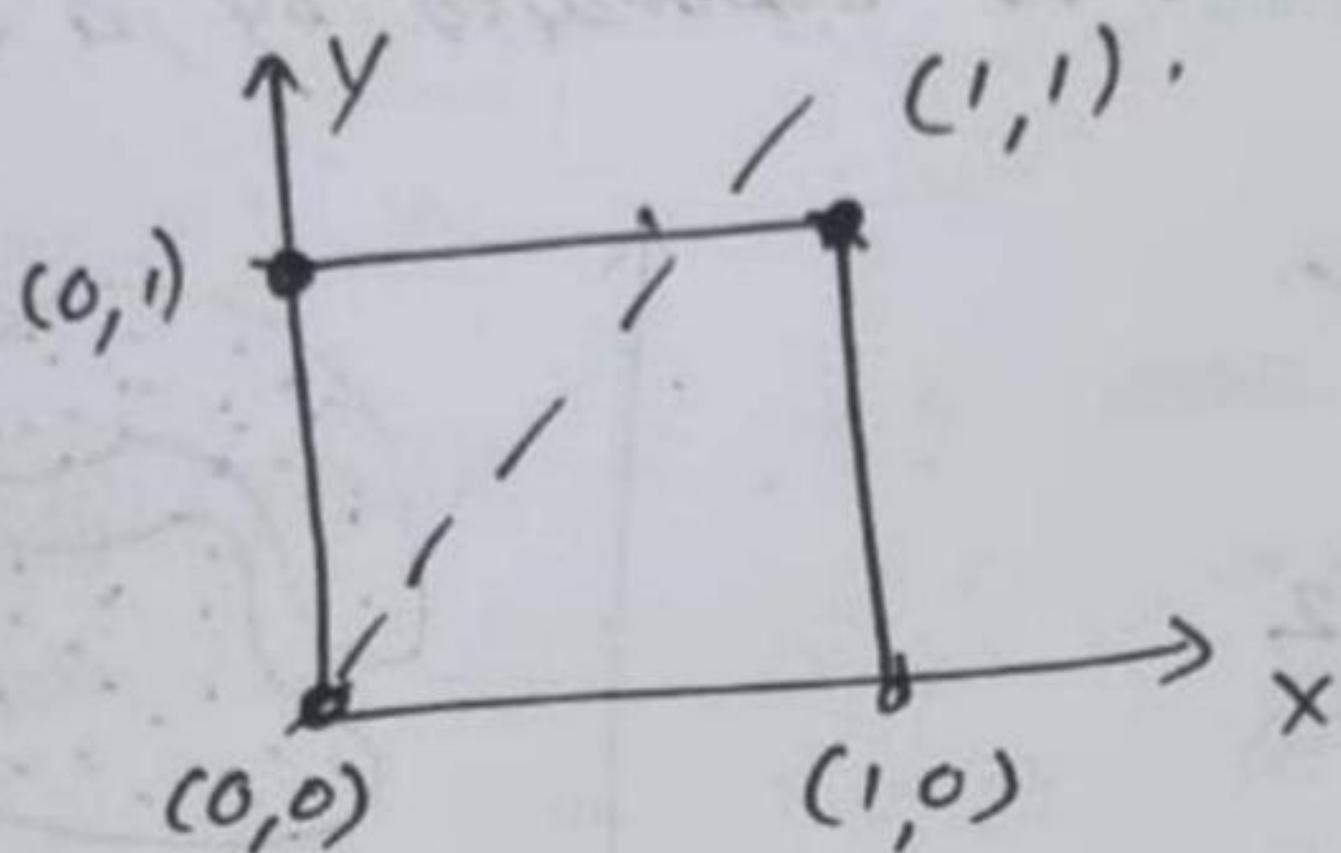
(A)



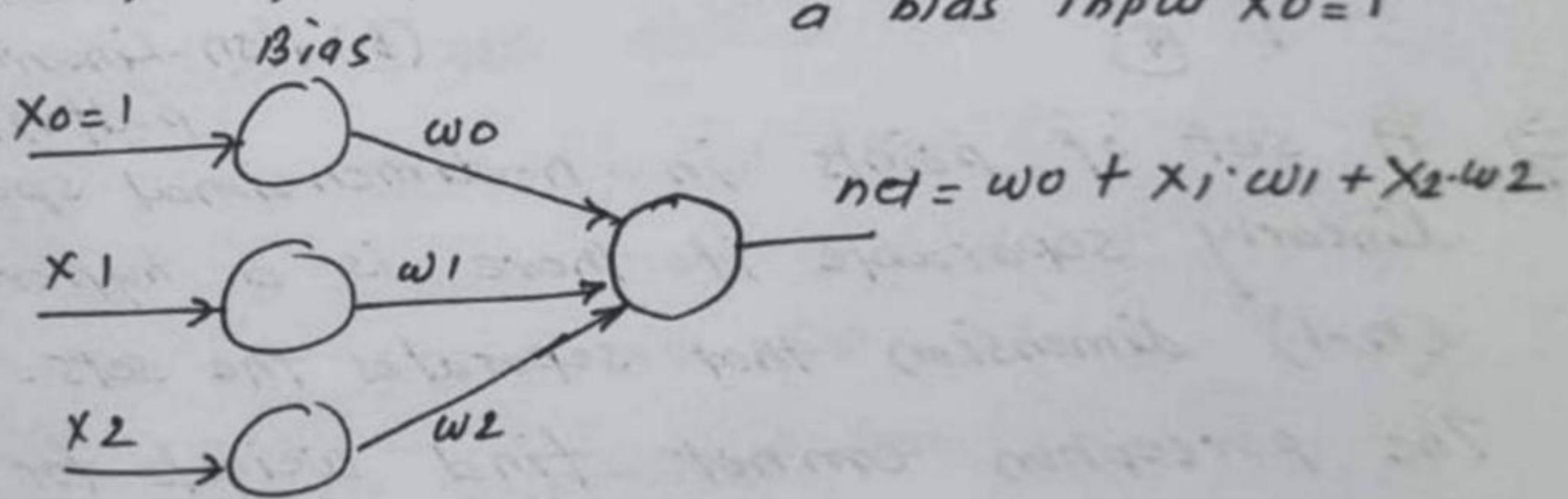
The problem/task for ANN is to classify the inputs as odd parity or even parity.

[odd parity  $\rightarrow$  odd no. of 1, even parity  $\rightarrow$  even no. of 1]

This is impossible to find a line separating even parity input patterns from odd parity input patterns.



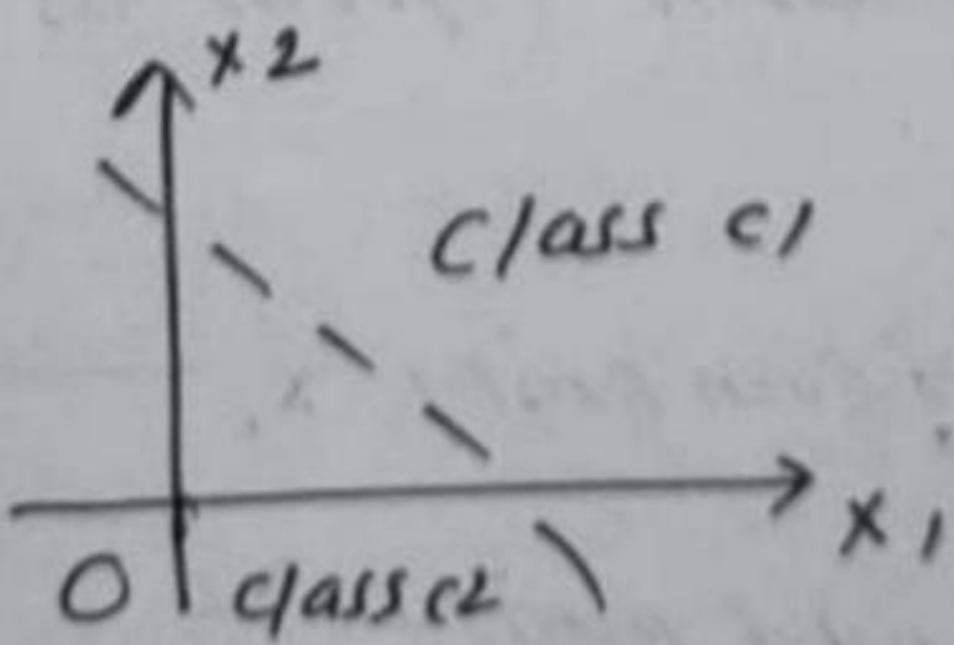
Consider perceptron model with two inputs  $x_1, x_2$  & a bias input  $x_0 = 1$



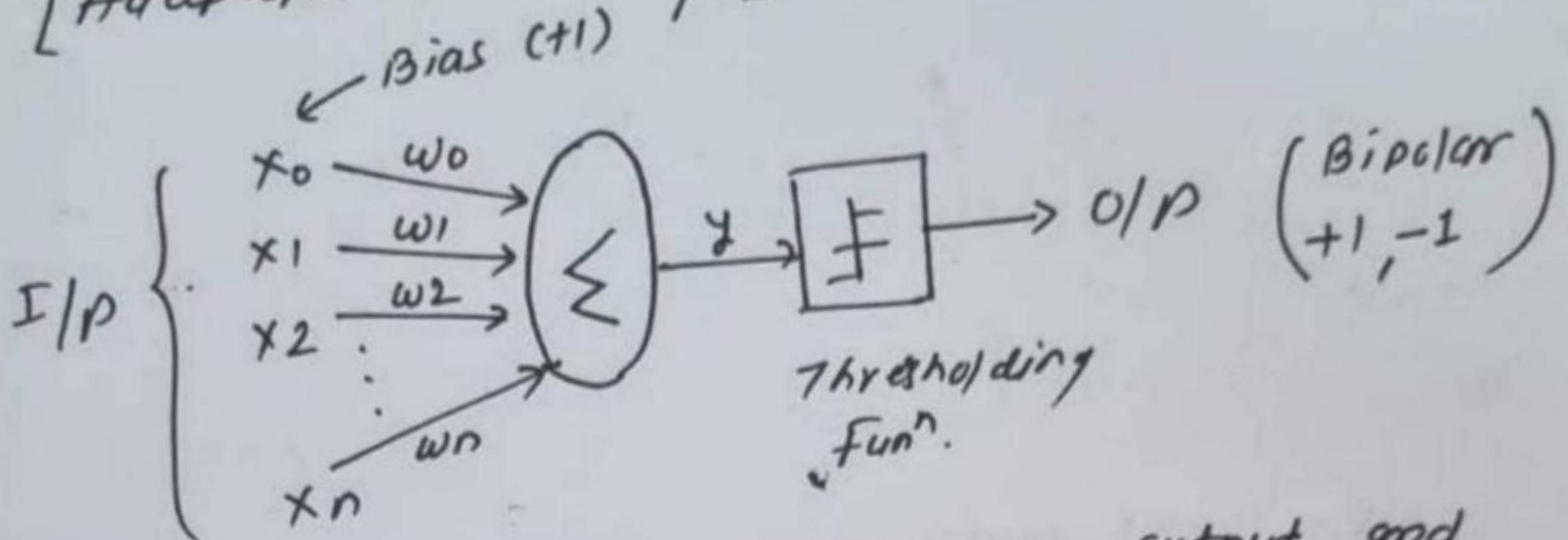
$$net = w_0 + x_1 \cdot w_1 + x_2 \cdot w_2$$

This is eqn. of straight line ( $y = mx + c$ )

This straight line acts as decision boundary separating the points into class  $c_1$  &  $c_2$ .



ADALINE n/w :- [Barnard Widrow] - 1960  
 - Hoff  
 [Adaptive linear n/w]



In this n/w there is only one output and o/p values are bipolar (+1 or -1). However the I/P  $x_1$  &  $x_2$  may be binary, bipolar are real values.

The bias weight is  $w_0$  and I/P is  $x_0 = +1$

Firing Rule:- If the weighted sum of I/P Input is greater than or equal to 0 then o/p is 1 otherwise -1.

This n/w adopts supervised learning algo. which is similar to perceptron.

This learning algo. is known as Least mean square [LMS] or delta rule and is given as

$$w_j^{\text{new}} = w_j^{\text{old}} + \alpha (d_i - o_i) \cdot x_i$$

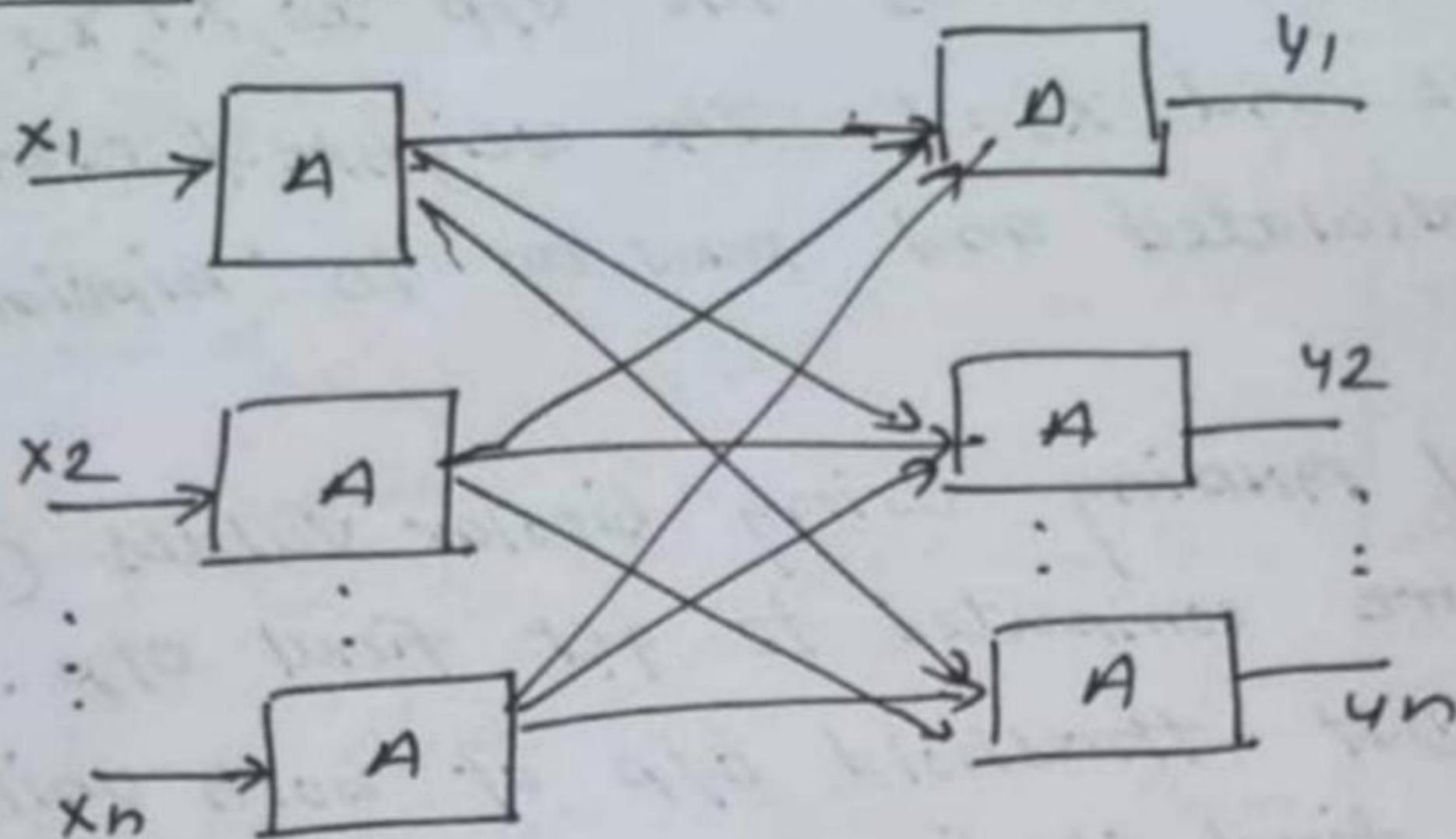
for any jth I/P

$$w_{ij}^{\text{new}} = w_{ij}^{\text{old}} + \alpha (d_i - o_i) \cdot x_{ij}$$

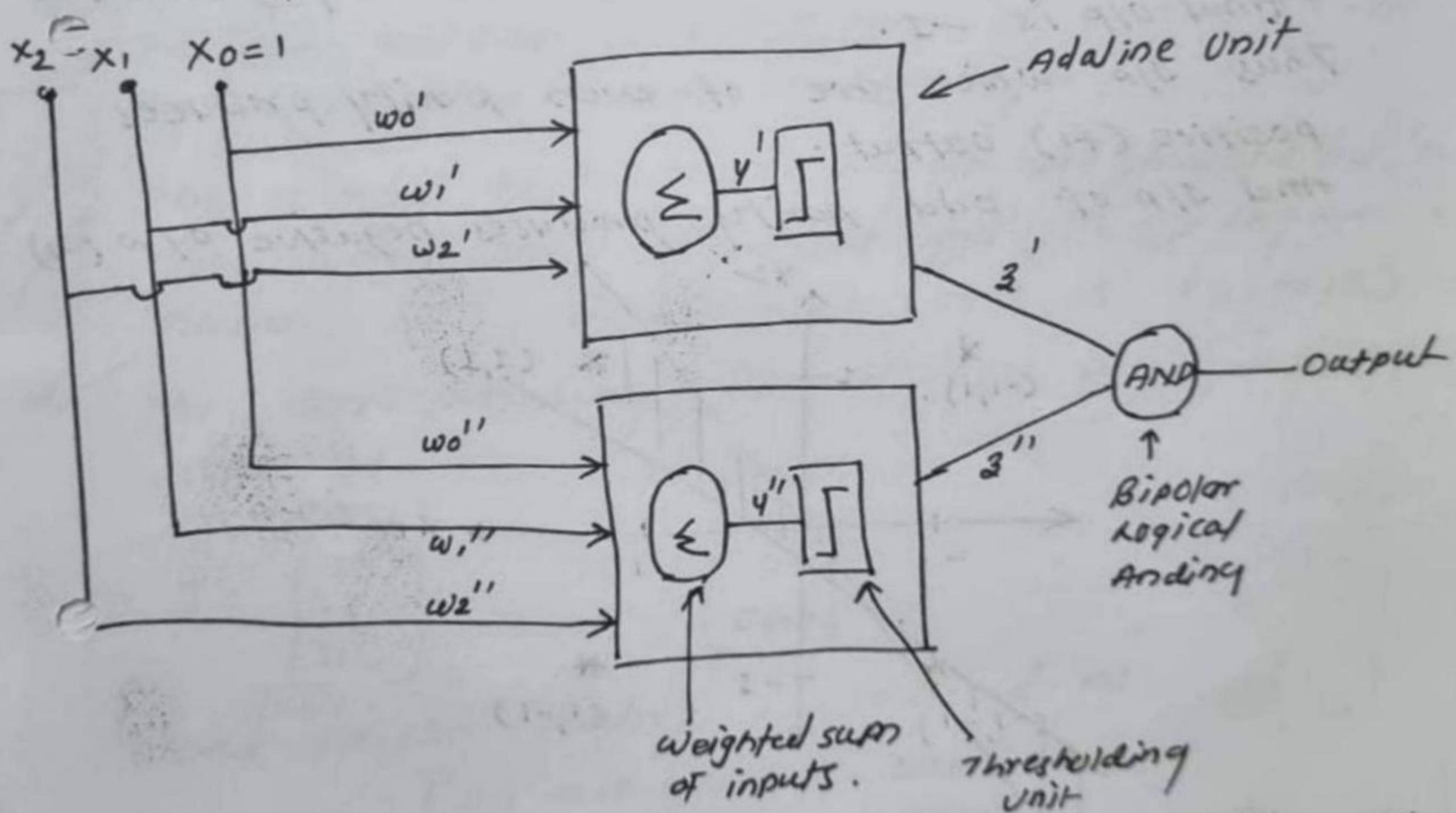
$\alpha$  - learning coefficient  
 $d_i$  - target

These networks is used in all high speed modems, telephone switching systems to ~~cancel~~ correct the echo in long distance communication circ.

MADALINE (many Adaline) N/W



SOLVING X-OR PROBLEM USING MADALINE N/W



The use of many Adaline helps to handle problem of non-linearity separability.

using  $\alpha$ -Adaline we can solve X-OR problem.

Every Adaline receives the S/I/P  $x_0, x_1, x_2$  where  $x_0$  is bias and  $x_0 = 1$ . The weighted sum of S/I/P is calculated and pass on to 'Bipolar thresholding unit.'

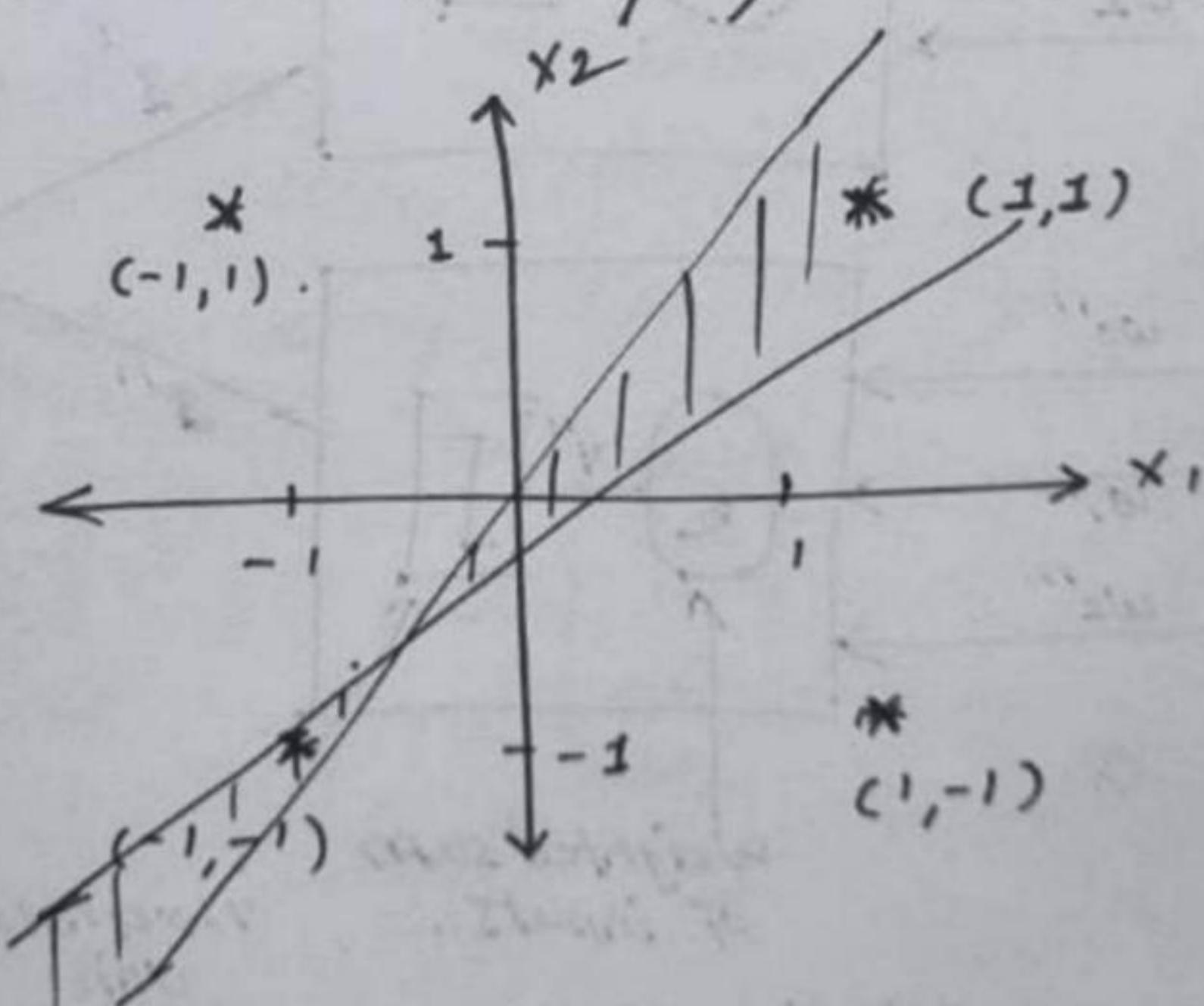
The logical ANDing Using bipolar values  $(1, -1)$  of 2-units are computed to get final O/I/P.

Condition: - 1) If threshold O/I/P of both units is +1 or -1 then final O/I/P is +1.

2) If threshold O/I/P are different  $(+1, -1)$  then the final O/I/P is -1.

Thus S/I/P which are of even parity produces positive (+1) output.

And S/I/P of odd parity produces negative O/I/P (-1)



Binary

T.T

$x_0$	$x_1$	$x_2$	O/I/P
1	0	0	+1
1	1	1	+1
1	0	1	-1
1	1	0	-1

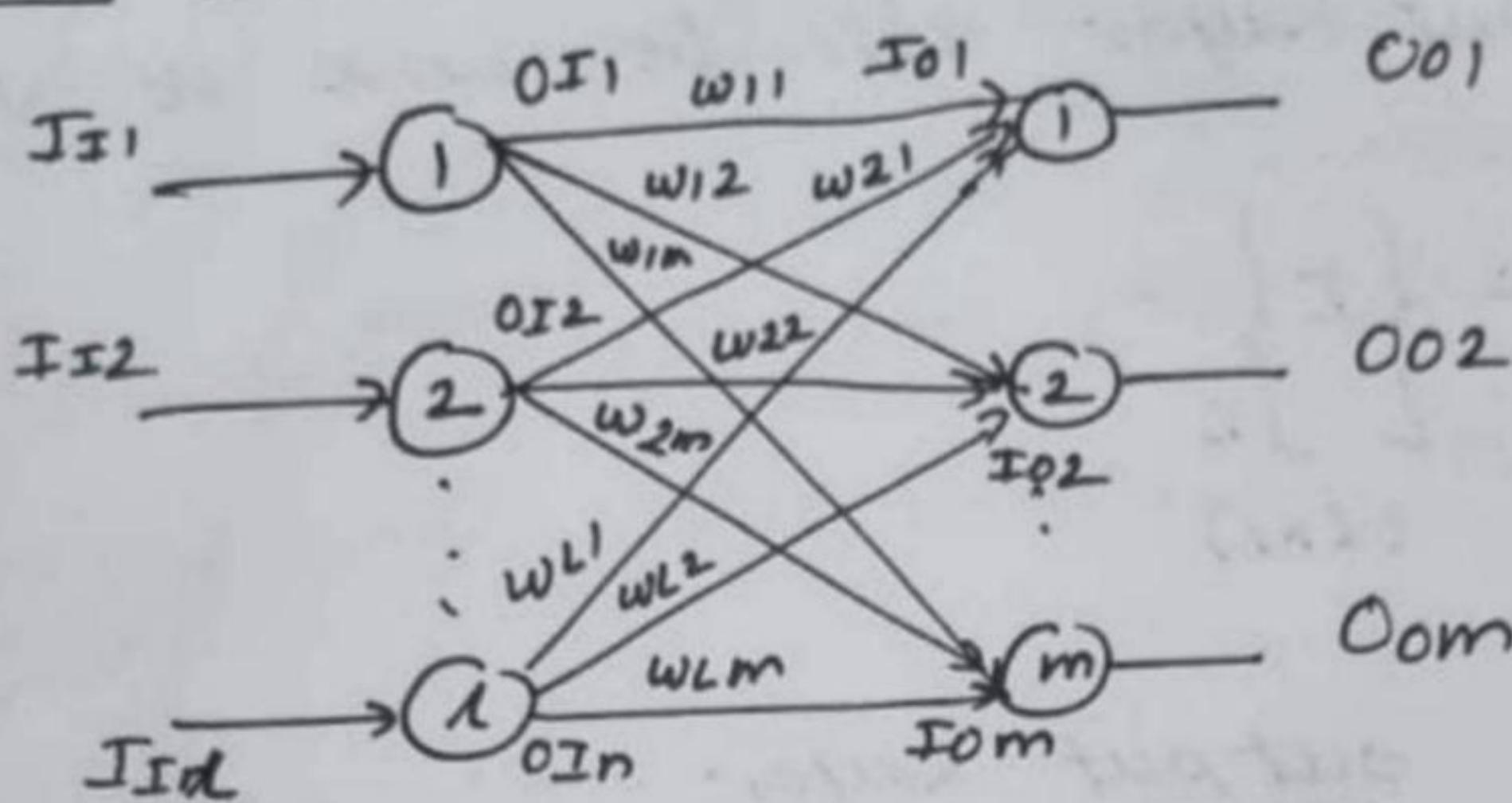
$\Rightarrow$

1
1
0
0

18

## Back propagation Network :- (Supervised Learning)

### \* SLFFN Analysis :-



$I_I \rightarrow$  Input to Input layer  
 $O_I \rightarrow$  O/P of Input layer  
 $I_O \rightarrow$  Input to Output layer  
 $O_O \rightarrow$  O/P of O/P layer

Consider SLFFN with total ' $L$ ' neurons in I/P layer and ' $m$ ' neurons in O/P layer.

→ The weights betn these layers are denoted by ' $w$ '.  
 Thus weight betn  $i^{th}$  input and  $j^{th}$  O/P layer or neuron is  $w_{ij}$  (for  $i = 1$  to  $n$  &  $j = 1$  to  $m$ )

→ The corresponding I/P and O/P are denoted as vector as .

$$I = \begin{Bmatrix} I_{I1} \\ I_{I2} \\ \vdots \\ I_{IL} \end{Bmatrix}_{(L \times 1)}$$

$$O = \begin{Bmatrix} O_{O1} \\ O_{O2} \\ \vdots \\ O_{Om} \end{Bmatrix}_{(m \times 1)}$$

and weight matrix is denoted as .

$$W = \begin{bmatrix} w_{11} & w_{12} & w_{13} & \dots & w_{1m} \\ w_{21} & w_{22} & w_{23} & \dots & w_{2m} \\ \vdots & & & & \\ w_{L1} & w_{L2} & w_{L3} & \dots & w_{Lm} \end{bmatrix}_{(L \times m)}$$

Assuming linear activation fun for I/P layer and Unipolar sigmoidal fun for O/P layer .

### Step : 1) O/P of Input layer.

since we use linear activation  $f(u)$  for I/P layer  
O/P of input layer will be same as input.

$$\begin{matrix} \{O\}_I \\ I \end{matrix} = \begin{matrix} \{I\}_I \\ I \end{matrix}$$

$(L \times 1) \quad (L \times 1)$

### Step : 2) I/P to output layer

consider some  $j$ th O/P layer neuron.  
so input to  $j$ th neuron will be.

$$I_{Qj} = O_{I1} \cdot w_{1j} + O_{I2} \cdot w_{2j} + \dots + O_{IL} \cdot w_{Lj}$$

for  $j = 1 \text{ to } m$

Hence in vector form

$$\begin{matrix} \{I\}_0 \\ (m \times 1) \end{matrix} = [\mathbf{W}]^T \cdot \begin{matrix} \{O\}_I \\ I \end{matrix}$$

$(m \times L) \quad (L \times 1)$

### Step : 3) O/P of output layer

since we are using unipolar sigmoidal  $f(u)$ .

$$O = \frac{1}{1 + e^{-A \cdot I}} \rightarrow A \rightarrow \text{sigmoidal gain}$$

$$\{O\}_0 = f([\mathbf{w}] \cdot \{I\}_0)$$

$$\text{i.e., } \{O\}_0 = \begin{bmatrix} \frac{1}{1 + e^{-A \cdot I_{01}}} \\ \vdots \\ \frac{1}{1 + e^{-A \cdot I_{0j}}} \\ \vdots \\ \frac{1}{1 + e^{-A \cdot I_{0m}}} \end{bmatrix}$$



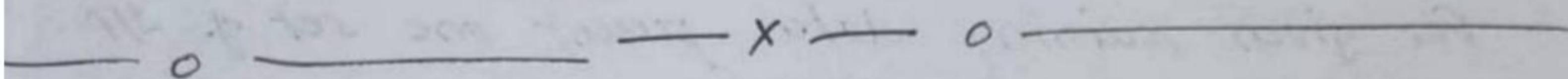
## Back Propagation Algorithm :- (MLFFN)

Algo:-

Step 1:- Initialize the weights.

Step 2:- Repeat, for each training pattern, train the network for that pattern.

Step 3:- Until the error is acceptably low.



Step 1) Normalised and initialise the S/P and O/P w.r.t their maximum ~~weights~~.

Thus, for a n/w of 'l' i/p layer neurons.  
S/P vector will be:

$$\{I\}_I^{lx1}$$

and for n o/p layer neurons O/P vector  
will be  $\{O\}_O^{nx1}$

Step 2) Assume the no. of neurons in hidden layer  
lies b/w  $1 < m < 2l$

Step 3) Let matrix  $[v]$  represents weights b/w  
S/P - hidden layer and  $[w]$  represents hidden-  
O/P layer.

Initialise weights to small random values  
usually from -1 to 1.

(21)

for general problem  $\lambda$  can be assumed as 1.  
and the threshold value can be consider as 0.  
Then,

$[v]^0$  and  $[w]^0$  = random weights.

so,  $\Delta v = 0$  &  $\Delta w = 0$ .

#### Step:4 Input layer computation :-

For given training data present one set of S/P  
and forget O/P. present the pattern to the S/P  
layer  $\{I\}_I$ . By using linear activation fu<sup>n</sup> the  
O/P of input layer can be computed as.

$$\{O\}_I = \{I\}_I \\ (l \times 1) \quad (l \times 1)$$

#### Step:5 Hidden layer computation

The S/P to hidden layer can be computed as

$$\{I\}_H = [v]^T \cdot \{O\}_I$$

$$\text{i.e., } \{I\}_H = [v]^T \cdot \{I\}_I \\ (m \times 1) \quad (m \times l) \quad (l \times 1)$$

In vector form;

$$\begin{Bmatrix} I_{H1} \\ I_{H2} \\ I_{H3} \\ \vdots \\ I_{Hm} \end{Bmatrix} = [v]^T \cdot \begin{Bmatrix} I_{I1} \\ I_{I2} \\ \vdots \\ I_{IL} \end{Bmatrix}$$

(47)

Step 6) The o/p of hidden layer for  $p^{th}$  hidden layer neuron can be represented as

$$O_{HP} = \frac{1}{1 + e^{-A \cdot I_{HP}}}$$

$$O_{HP} = \frac{1}{1 + e^{-I_{HP}}} \quad \therefore \lambda = 1$$

Hence

$$\{O\}_H = \left\{ \begin{array}{c} \frac{1}{1 + e^{-\Delta H_1}} \\ \vdots \\ \frac{1}{1 + e^{-\Delta H_D}} \\ \vdots \\ \frac{1}{1 + e^{-\Delta H_m}} \end{array} \right\}$$

Step: 7      O/P Layer      computations.  
I/P to O/P Layer. computations

$$\{I\}_o = [w]^T \cdot \{o\}_h$$

Step: 8) O/P of 9<sup>th</sup> O/P Layer neuron is

$$O_{02} = \frac{1}{1 + e^{-n \cdot \overrightarrow{I_{02}}}} = \frac{1}{1 + e^{-x_{02}}}$$

$$\{0\}_0 = \begin{bmatrix} \frac{1}{1+e^{-x_0}} \\ \vdots \\ \frac{1}{1+e^{-x_n}} \end{bmatrix}$$

Step: 9) Using Root mean square Error formula we can write error as.

$$E = \frac{1}{2} (T_0 - O_0)^2$$

$T_0 = d_0 = \text{Expected O/P.}$

Thus for DFA layer we will get.

Calculate the error and difference b/w computed O/P & desired (target) O/P for  $i^{th}$

training set.

$$E_p = \sqrt{\sum (T_i - O_{0i})^2}$$

for  $i = 1 \text{ to } n$ .

Step 10) find vector  $\{df\}$  as.

$$\{df\} = \begin{cases} (T_1 - O_{01}) \cdot O_{01} \cdot (1 - O_{01}) \\ (T_K - O_{0K}) \cdot O_{0K} \cdot (1 - O_{0K}) \end{cases}$$

Step 11) find  $Y$  matrix as

$$[Y] = \{O\}_H \cdot \{d\} \quad \leftarrow \text{Transpose of } \{df\}$$

Step 12) find  $\Delta w$  as

$$[\Delta w]^{t+1} = \alpha \cdot [\Delta w]^t + \eta \cdot [Y]$$

(\*)

Step: 13 > Find vector  $e$  ie  $\{e\}$  as

$$\begin{matrix} \{e\} \\ (m \times 1) \end{matrix} = \begin{matrix} [w] \\ (m \times n) \end{matrix} \cdot \begin{matrix} \{d\} \\ (n \times 1) \end{matrix}$$

Find  $\{d^*\}$  as

$$\begin{matrix} \{d^*\} \\ m \times 1 \end{matrix} = \left\{ \begin{matrix} e_1 \cdot (0_{H1}) \cdot (1 - 0_{H1}) \\ \vdots \\ e_i \cdot (0_{Hi}) \cdot (1 - 0_{Hi}) \\ \vdots \\ e_m \cdot (0_{Hm}) \cdot (1 - 0_{Hm}) \end{matrix} \right\}$$

Find  $[x]$  as.

$$\begin{matrix} [x] \\ l \times m \end{matrix} = \begin{matrix} \{0\}_I \\ l \times 1 \end{matrix} \cdot \langle d^* \rangle$$

$$\begin{matrix} [x] \\ l \times m \end{matrix} = \begin{matrix} \{I\}_T \\ l \times 1 \end{matrix} \cdot \begin{matrix} \langle d^* \rangle \\ (l \times m) \end{matrix}$$

Step: 14

Find  $\Delta V$  as

$$\begin{matrix} [\Delta V] \\ l \times m \end{matrix}^{t+1} = \alpha \cdot \begin{matrix} [v] \\ l \times m \end{matrix}^t + \eta \cdot [x]$$

Step: 15

Find new weights as

$$\begin{matrix} [v] \\ l \times m \end{matrix}^{t+1} = \begin{matrix} [v] \\ l \times m \end{matrix}^t + \begin{matrix} [\Delta V] \\ l \times m \end{matrix}^{t+1}$$

$$\begin{matrix} [w] \\ m \times n \end{matrix}^{t+1} = \begin{matrix} [w] \\ m \times n \end{matrix}^t + \begin{matrix} [\Delta w] \\ m \times n \end{matrix}^{t+1}$$

(65)

Step:16) Find error rate as

$$\text{Error Rate} = \frac{\sum EP}{n}$$

$n \rightarrow$  total no. of training sets.

Step:17) Repeat from step ④ to ⑯ until  
the converging of error rate is less  
than the tolerance value

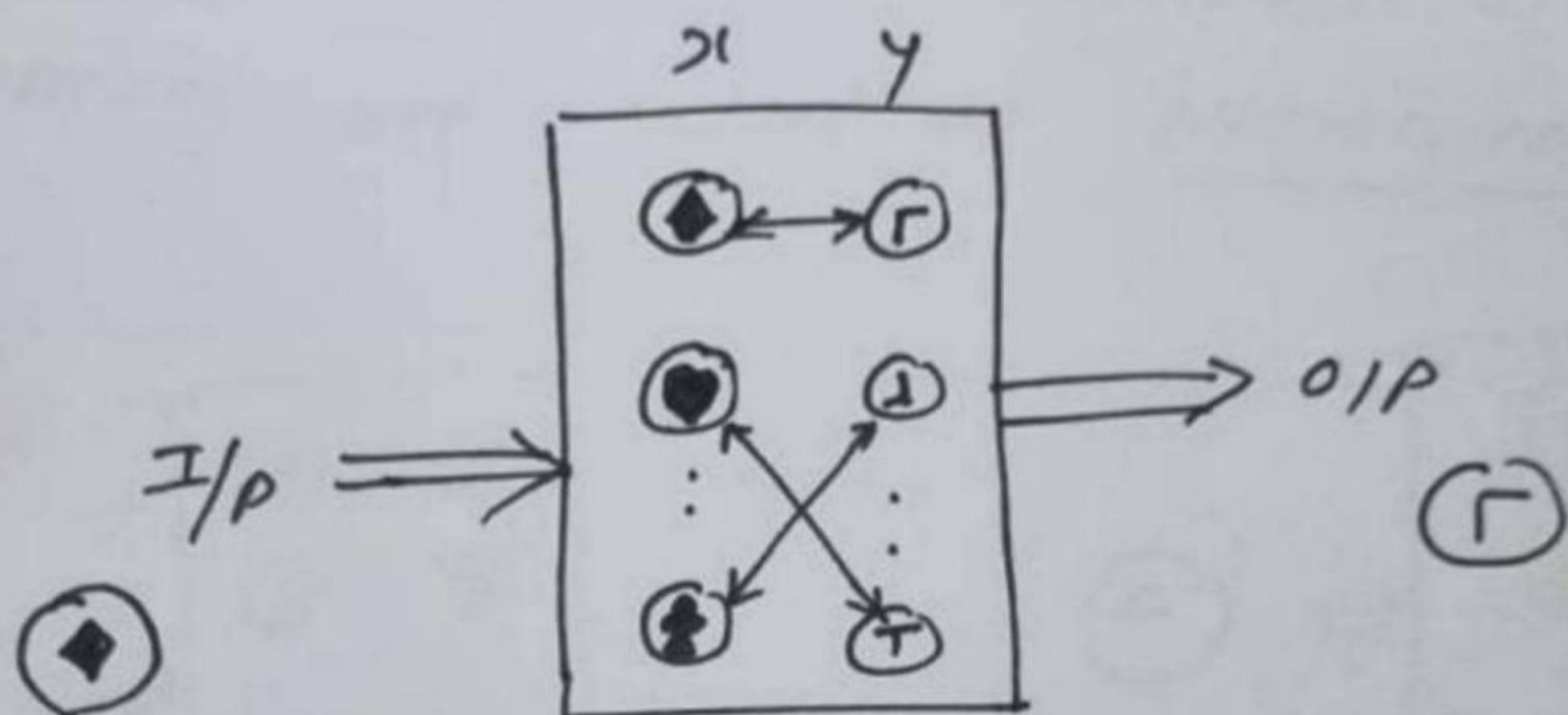
— X —

(26)

## Associative memory

It is a storehouse of associated patterns which are encoded in some form, when a storehouse triggered with any pattern, the associated pattern pair is recalled or output.

The S/I/P pattern will be an exact replica of stored pattern or distorted or partial pattern.



Here there are associated pattern pairs.

$$\rightarrow (x, \gamma)$$

$$\rightarrow (y, T)$$

$$\rightarrow (z, J)$$

The association is always represented by directional arrow.

$\Rightarrow$  If the associated pattern pair  $(x, y)$  are different and the model recalls  $y$ , if  $x$  is inputted, then it is referred as Hetero associative memory.

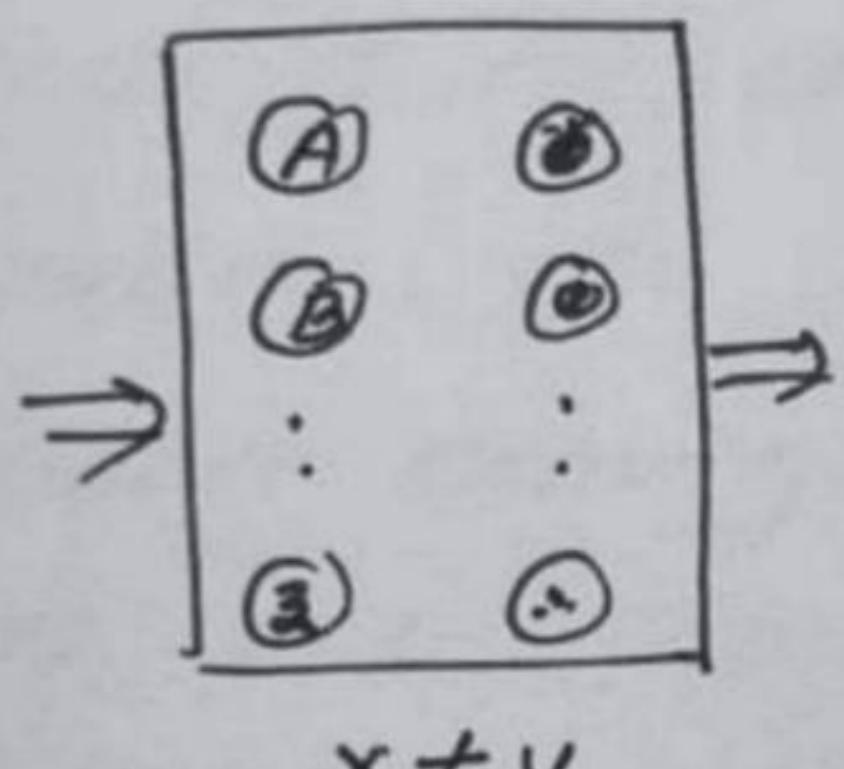
$\Rightarrow$  If the associated pattern pair  $(x, y)$  are same then it is referred as ~~Auto~~ Auto associative memory.



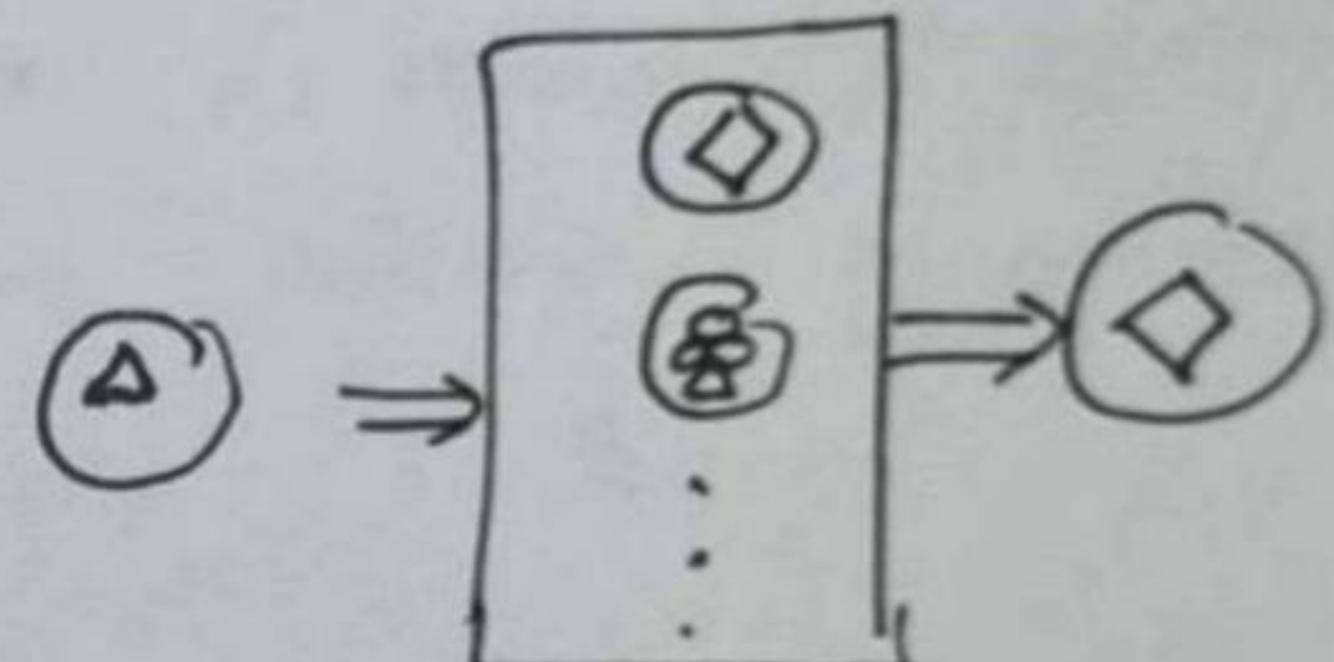
Heteroassociative memory are used for association. and Autoassociative memory are used for image refinement. i.e., if distorted or partial image is given it will recall complete image.

⇒ Associative correlation memory are called as Auto correlators and heteroassociative correlation memory are called as Hetero correlators

Ex:-

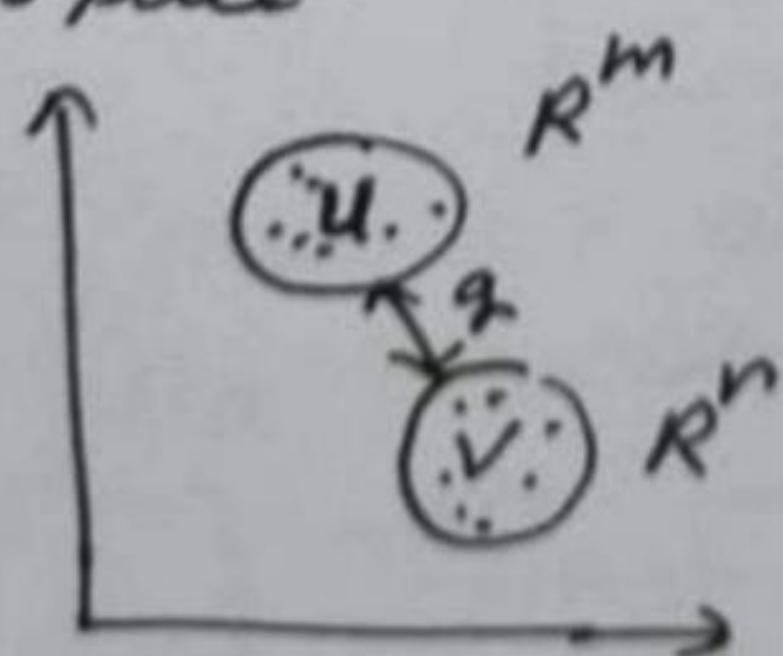


Hetero association



Auto association

Thus we can say autoassociative memory is a concept of mapping 'g' between 2 pattern space.



If u belongs to Region M and v belongs to region n. then

$$\bar{v} = g(\bar{u})$$

(23)

Here,  $\bar{v}$  is general non-linear matrix like operator so we can represent.

$$\boxed{\bar{v} = M(\bar{u})}$$

The operator  $M$  has different forms for different memory models.

The algorithm which computes ' $M$ ' is known as the recording or storage Algo.

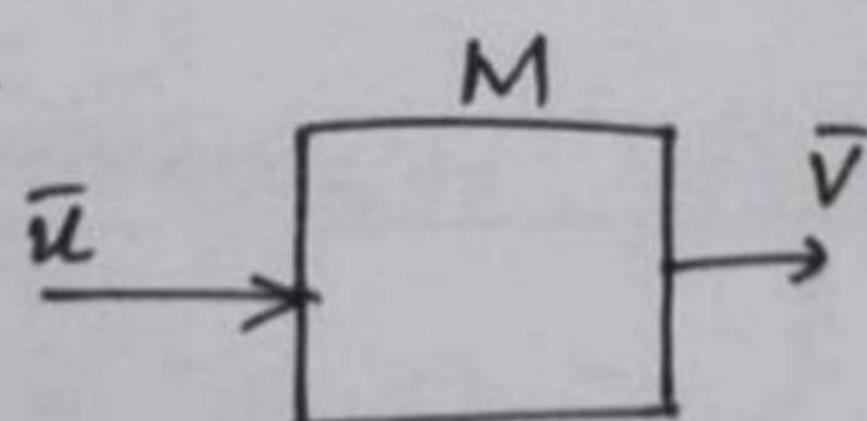
In most of the cases ' $M$ ' is computed using J/P pattern vector based on principle of recall associative memory.

There are two models.

- ① static      ② Dynamic.

static :- static model / N/W recalls the o/p if J/P is given in 1 forward pass.

(Non-recurrent)



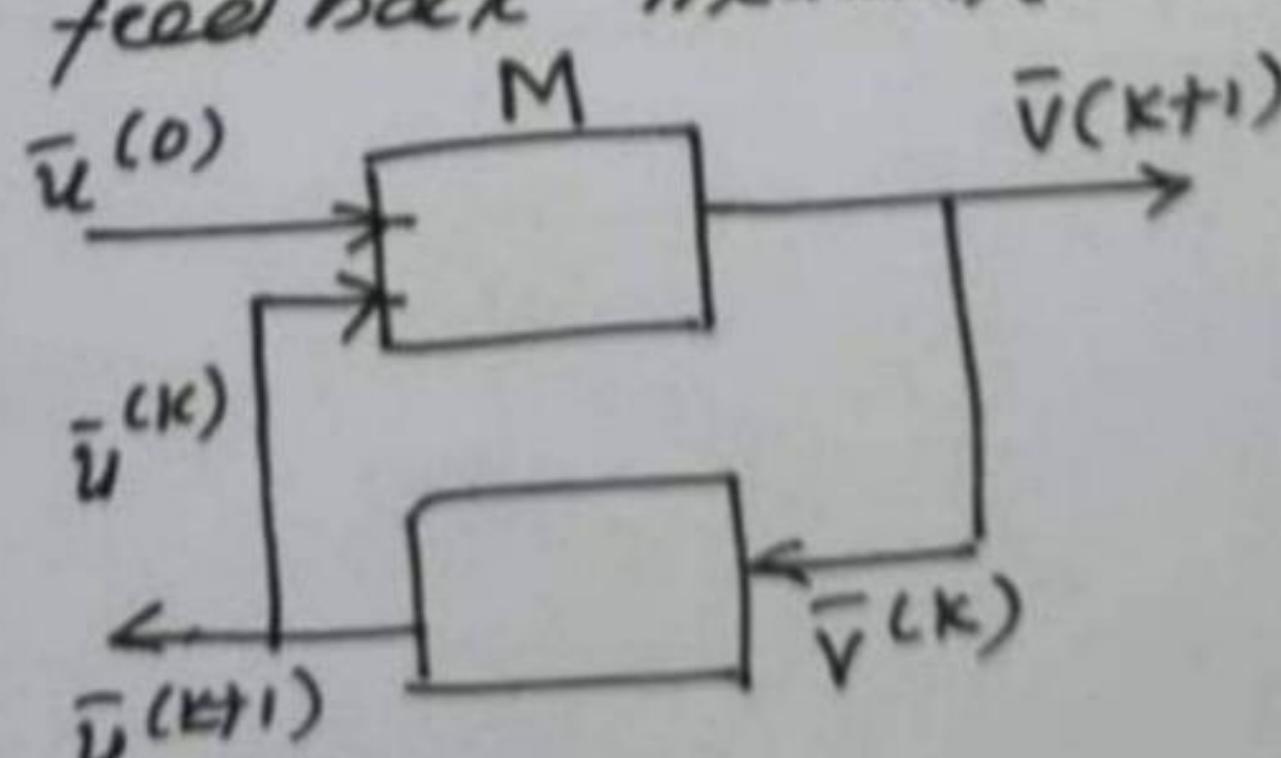
$$\boxed{\bar{v} = M(\bar{u})}$$

Dynamic :- Dynamic n/w recalls the pattern through J/P feedback mechanism which takes time.

(Recurrent)

$$\bar{v}^{(k)} = M(\bar{u}^{(k)})$$

$$\bar{v}^{(k+1)} = M(\bar{u}^{(k)}, \bar{v}^{(k)})$$



(?) 29

## Autocorrelators:- (Amari)

The first order Auto-correlator obtain its connection matrix, which is association of pattern with itself, by multiplying a pattern element with every other pattern element.

$$T = \sum_{i=1}^n [A_i]^T \cdot [A_i]$$

Here  $T = [t_{ij}]$  is  $(P \times Q)$  connection matrix

$$A_i \in \{-1, 1\}^P$$

⇒ The autocorrelation recall equation is a vector matrix multiplication followed by a point wise non-linear threshold operation.

The recall eq<sup>n</sup> is given as.

$$a_j^{\text{new}} = f(a_i \cdot t_{ij}, a_j^{\text{old}}) \quad \text{where } A_i = (a_1, a_2, a_3, \dots, a_p)$$

The two parameters bipolar threshold fun<sup>n</sup> is

$$f(\alpha, \beta) = \begin{cases} 1, & \text{if } \alpha > 0 \\ \beta, & \text{if } \alpha = 0 \\ -1, & \text{if } \alpha < 0 \end{cases}$$

(3D)

Ex:- Consider a first order auto correlation having stored patterns -

$$A_1 = (-1, 1, -1, 1)$$

$$A_2 = (1, 1, 1, -1)$$

$$A_3 = (-1, -1, -1, 1)$$

If following patterns

$$A' = (1, 1, 1, -1) \text{ &}$$

$A'' = (1, 1, 1, 1)$  given as input, then check

which pattern will recalled.

$\Rightarrow$  Find connection matrix as

$$\tau = \tau_1 + \tau_2 + \tau_3$$

$$\begin{aligned} \tau_1 &= [A_1]^T \cdot [A_1] \\ &= \begin{bmatrix} 1 \\ 1 \\ -1 \\ 1 \end{bmatrix} \cdot [-1, 1, -1, 1] \\ &= \begin{bmatrix} 1 & -1 & 1 & -1 \\ -1 & 1 & -1 & 1 \\ 1 & -1 & 1 & -1 \\ -1 & 1 & -1 & 1 \end{bmatrix} \end{aligned} \quad \begin{aligned} \tau_2 &= [A_2]^T \cdot [A_2] \\ &= \begin{bmatrix} 1 \\ 1 \\ 1 \\ -1 \end{bmatrix} \cdot [1, 1, 1, -1] \\ &= \begin{bmatrix} 1 & 1 & 1 & -1 \\ 1 & 1 & 1 & -1 \\ 1 & 1 & 1 & -1 \\ -1 & -1 & -1 & 1 \end{bmatrix} \end{aligned} \quad \begin{aligned} \tau_3 &= [A_3]^T \cdot [A_3] \\ &= \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} \cdot [-1, -1, -1, 1] \\ &= \begin{bmatrix} 1 & -1 & -1 & 1 \\ -1 & -1 & -1 & 1 \\ -1 & -1 & -1 & 1 \\ 1 & 1 & 1 & -1 \end{bmatrix} \end{aligned}$$

$$\therefore \tau = \tau_1 + \tau_2 + \tau_3 = \begin{bmatrix} 3 & 1 & 3 & -3 \\ 1 & 3 & 1 & -1 \\ 3 & 1 & 3 & -3 \\ -3 & -1 & -3 & 3 \end{bmatrix}$$

(3/4)

### Recognition of stored pattern:-

for i/p pattern  $A' = (1, 1, 1, -1)$

$$q_j^{\text{new}} = f(A_{j1}, A_{j2}, A_{j3}, A_{j4}, q_j^{\text{old}})$$

$$q_{j1}^{\text{new}} = f(3+1+3+3, 1)$$

$$= f(10, 1)$$

since  $\alpha > 0$

$$\boxed{q_{j1}^{\text{new}} = 1}$$

$$q_{j2}^{\text{new}} = f(1+3+1+1, 1)$$

$$= f(6, 1) \quad \because \alpha > 0$$

$$\boxed{q_{j2}^{\text{new}} = 1}$$

$$q_{j3}^{\text{new}} = f(3+1+3+3, 1)$$

$$= f(10, 1) \quad \therefore \alpha > 0$$

$$\boxed{q_{j3}^{\text{new}} = 1}$$

$$q_{j4}^{\text{new}} = f(-3-1-3-3, -1)$$

$$= f(-10, -1)$$

$$= -1 \quad \because \alpha < 0$$

(32)

$$T = \begin{bmatrix} 3 & 1 & 3-3 \\ 1 & 3 & 1 & -1 \\ 3 & 1 & 3-3 \\ -3 & -1 & -3 & 3 \end{bmatrix}$$

$$q_j^{\text{new}} = (1, 1, 1, -1)$$

Since

$$q_j^{\text{new}} = A_2$$

$A_2$  will be recalled for  
 $A'$  as input

## Recognition of Noisy Pattern

When  $A'' = (1, 1, 1, 1)$  is distorted pattern given as input to model.

$$A_j^{\text{new}} = (A_{j1}, A_{j2}, A_{j3}, A_{j4})$$

$$\begin{aligned} A_{j1}^{\text{new}} &= f(3+1+3-3, 1) \\ &= f(4, 1) \\ &= 1 \quad (\text{since } \alpha > 0) \end{aligned} \quad \left| \begin{aligned} A_{j2}^{\text{new}} &= f(1+3+1-1) \\ &= f(4, 1) \\ &= 1 \end{aligned} \right.$$

$$\begin{aligned} A_{j3}^{\text{new}} &= f(3+1+3-3, 1) \\ &= f(4, 1) \\ &= 1 \end{aligned} \quad \left| \begin{aligned} A_{j4}^{\text{new}} &= f(-3+1-3+3, 1) \\ &= f(-4, 1) \\ &= -1 \quad \text{since } \alpha < 0 \end{aligned} \right.$$

$\therefore q_j^{\text{new}} = A_2$  if stored pattern  $A_2$  will be recalled if  $A'' = (1, 1, 1, 1)$  is given

X — X — X —

Another method (Using Hamming distance)

$$HD(x, y) = \sum_{i=1}^n |x_i - y_i|$$

Thus HD of  $A'$  from each stored pattern is

$$HD(A', A_1) = [1 - (-1)] + (1 - 1) + [1 - (-1)] + (1 - 1) = 4$$

$$HD(A', A_2) = 2$$

$$HD(A', A_3) = 6 \quad \left| \begin{array}{l} \text{since } HD(A', A_2) = 2 \text{ it is very} \\ \text{closed hence } A_2 \text{ will be recalled} \end{array} \right.$$

(4)  
(33)

Hw1)

$$A_1 = (1, 1, 1, -1)$$

$$A_2 = (-1, -1, -1, 1)$$

$$A_3 = (1, -1, 1, -1)$$

$$A_4 = (-1, 1, -1, 1)$$

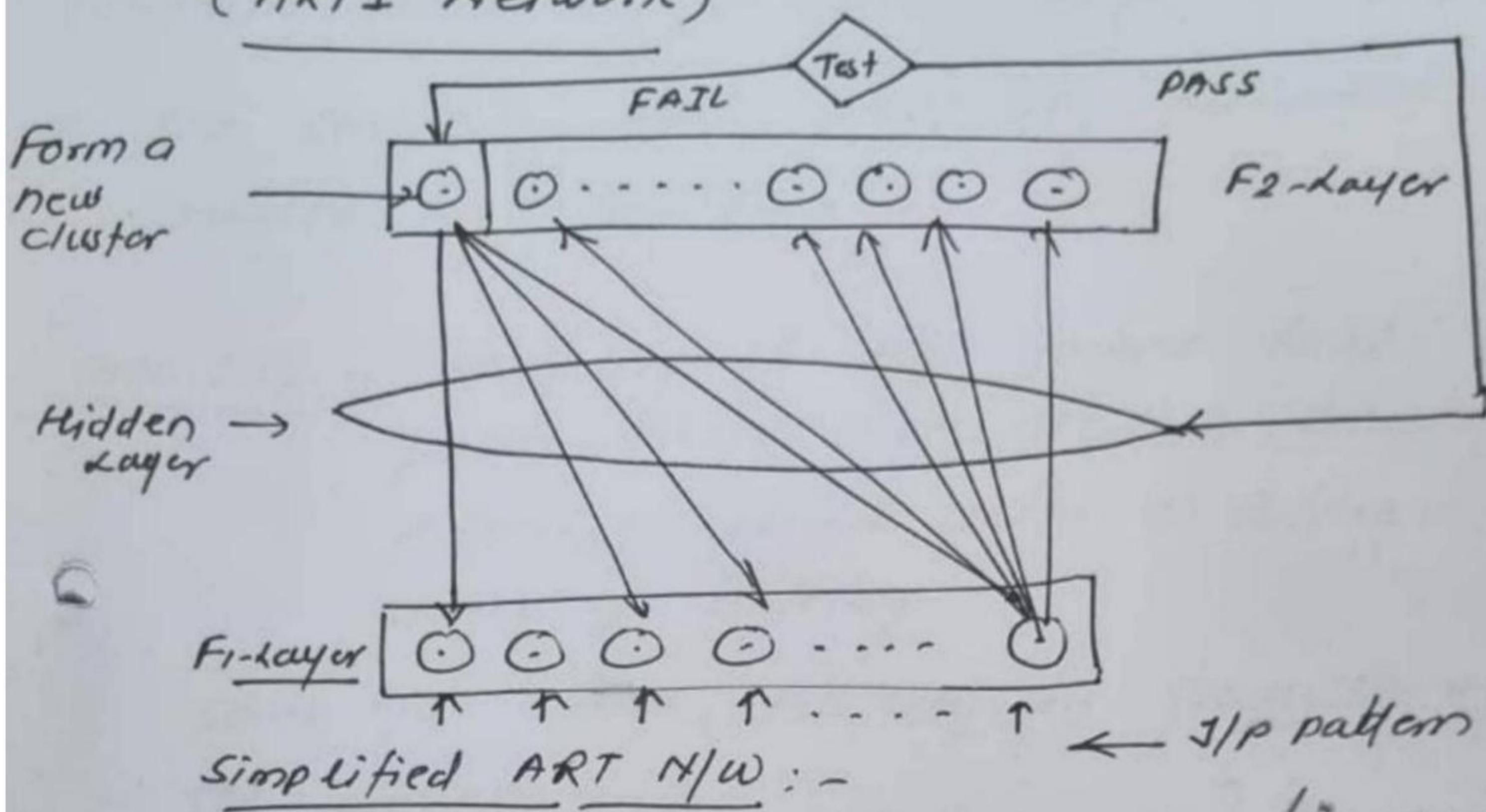
$$A' = (1, 1, 1, -1)$$

$$A'' = (1, -1, 1, 1)$$

Hw2) validate your result with HD method.

(F)  
(24)

## Adaptive Resonance Theory (Grossberg & Carpenter) (ART1 Network)



- ART1 N/W is used for clustering binary vectors.
- we can present S/I pattern in any order.
- When a pattern is presented an appropriate cluster is chosen and cluster weights are adjusted to the cluster unit to learn the pattern.
- The weights on the cluster unit can be considered as exemplar for pattern & placed in cluster.
- This N/W works in unsupervised mode. Once the N/W is trained we can present training pattern several times.
- The pattern may be placed on one cluster unit for the 1st time & then on different cluster unit when it is presented later due to change in weights.

① 35

- Thus the pattern oscillating among different cluster units at different stages of training.
- The stability and plasticity dilemma was proposed by Grossberg.

Stability:- stability of n/w means that a pattern should not oscillate among different cluster units at different stages of training.

some n/w achieve stability by gradually reducing the learning rate.

plasticity:- it is ability of the n/w to respond to learn new pattern equally at any stage of learning.

—x—

(36)

## Fuzzy set:-

Defn:- A fuzzy set can be defined as -

If  $X$  is a universal set and  $x$  is a particular element of  $X$  then fuzzy set  $\tilde{A}$  is defined as  
 $X$  must be represented as collection of ordered pairs

$$\tilde{A} = \{(x, \mu_{\tilde{A}}^{(x)}), x \in X\}$$

Where each pair  $(x, \mu_{\tilde{A}}^{(x)})$  is a singleton.

In discrete form :-

$$\tilde{A} = \sum_{x_i \in X} \mu_{\tilde{A}}^{(x_i)} | x_i \text{ - using Zadeh notation}$$

In continuous form :-

$$\tilde{A} = \int_X \mu_{\tilde{A}}^{(x)} / x$$

Using Zadeh notation

$$\tilde{A} = \sum_{x_i \in X} \frac{\mu_{\tilde{A}}^{(x_i)}}{x_i}$$

Ex:- Consider a universal set of students  $X$ ,

$$X = \{S_1, S_2, S_3, S_4, S_5\}$$

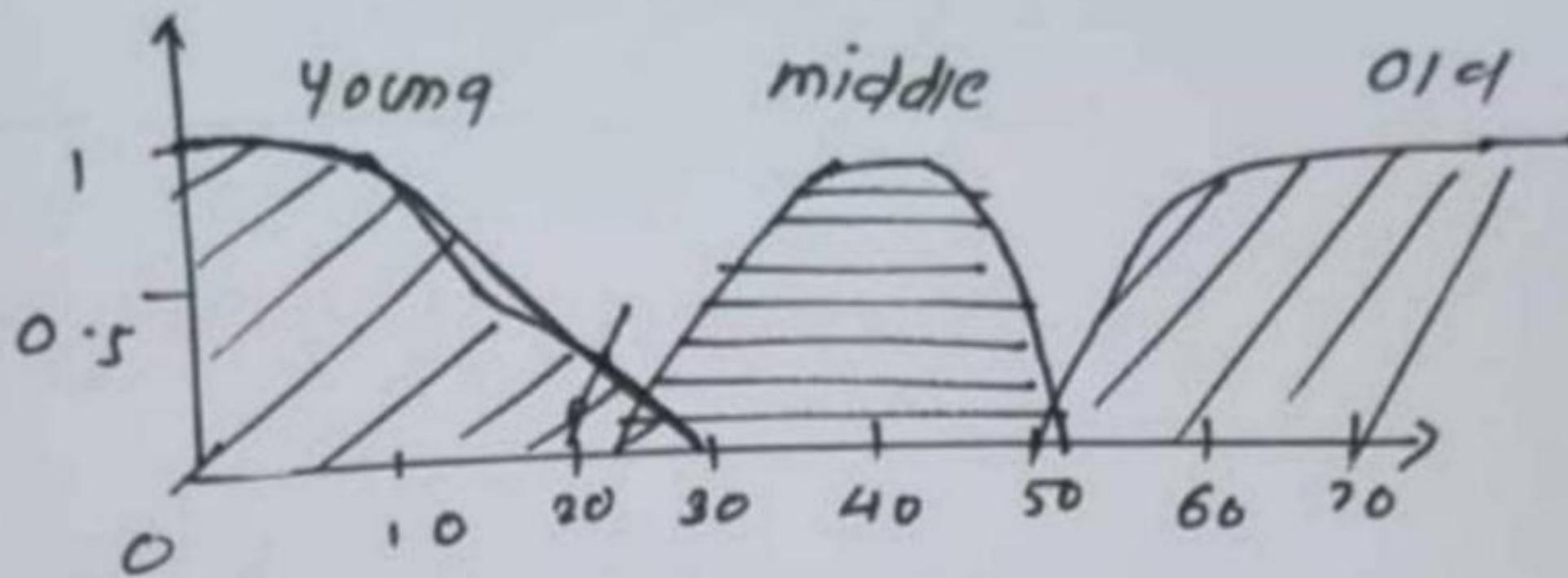
Let  $\tilde{A}$  is a fuzzy set of 'smart' student. here  
'smart' is a fuzzy linguistic term.

$$\text{then, } \tilde{A} = \{(S_1, 0.5), (S_2, 0.7), (S_3, 1), (S_4, 0), (S_5, 0.6)\}$$

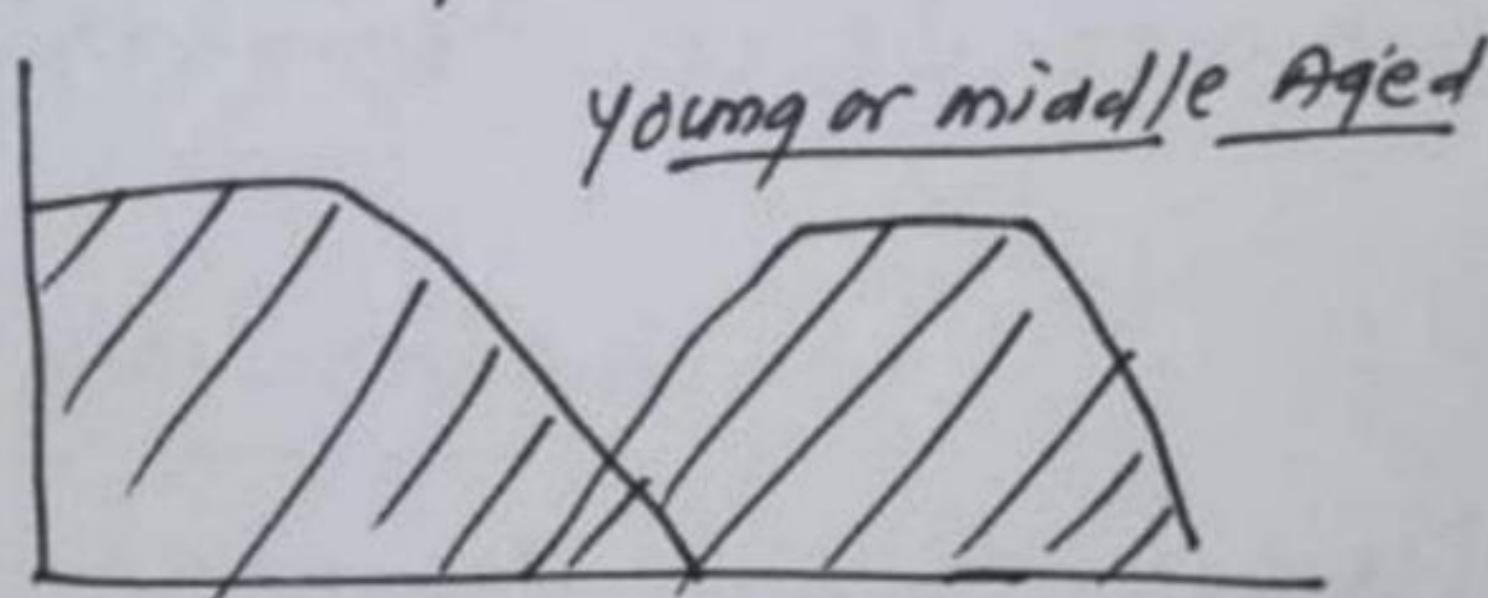
Here,  $\tilde{A}$  indicates that smartness of  $S_1$  is 0.5.

## Example of operations in FS:-

Consider an example of FS representing young, middle age, old age or.



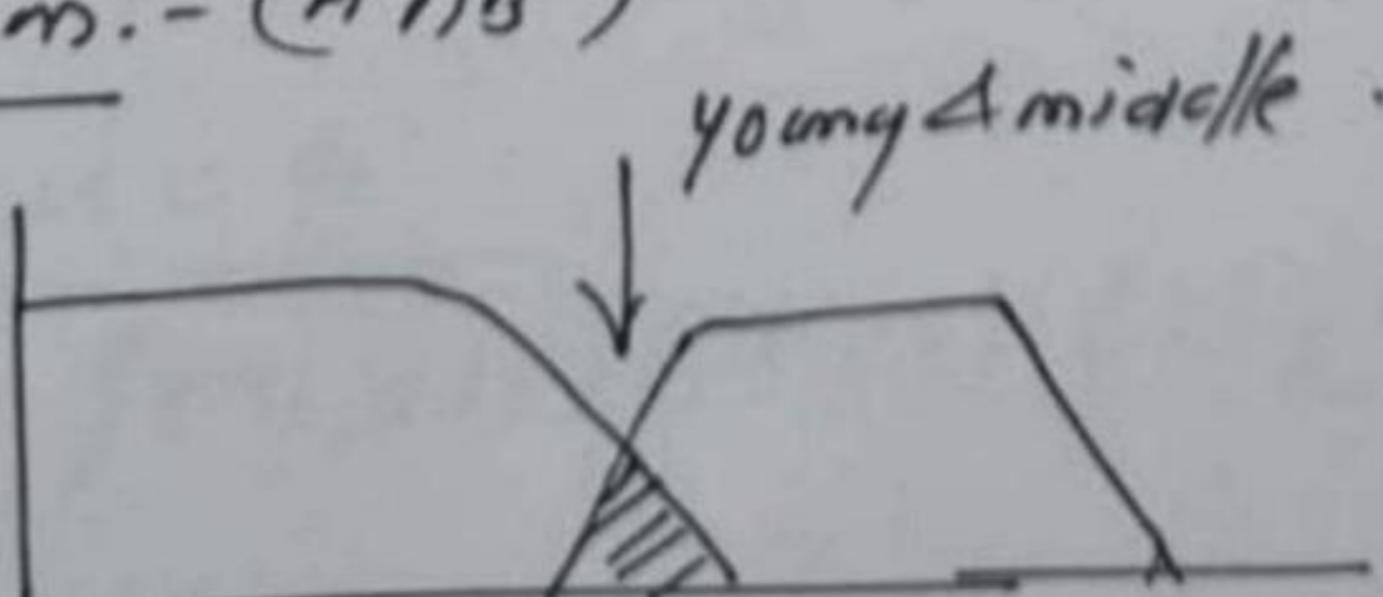
① Union :- Let  $\tilde{A}$  be the set of young and  $\tilde{B}$  is set of middle aged. Then  $\tilde{A} \cup \tilde{B}$  represents the fuzzy set of "young or middle age".



$$\text{if } \begin{cases} \tilde{A} = \{(x_1, 0.5), (x_2, 0.7), (x_3, 0)\} \\ \tilde{B} = \{(x_1, 0.8), (x_2, 0.2), (x_3, 1)\} \end{cases} \quad \left\{ \mu_{\tilde{A} \cup \tilde{B}} = \max(\mu_{\tilde{A}}, \mu_{\tilde{B}}) \right.$$

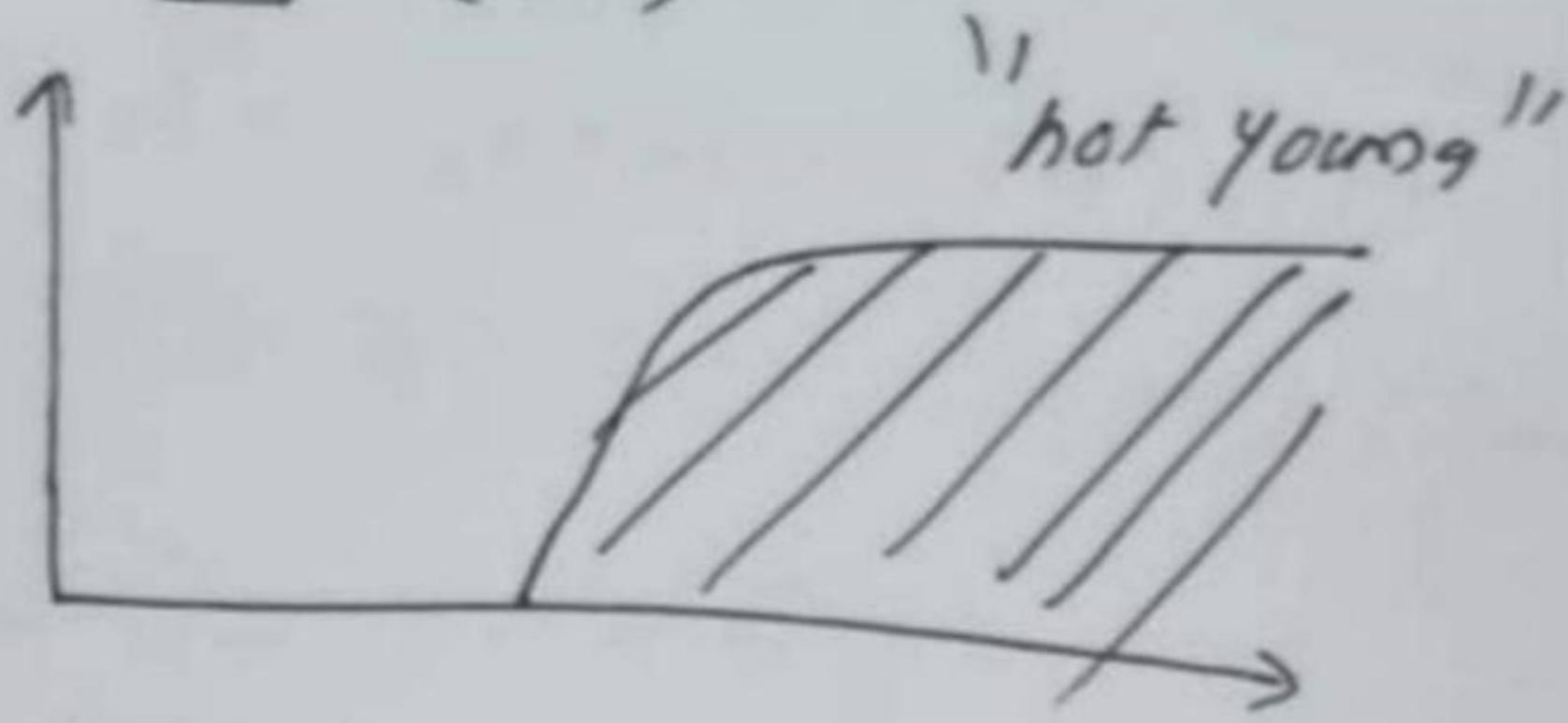
$$\text{Then } \tilde{A} \cup \tilde{B} = \{(x_1, 0.8), (x_2, 0.7), (x_3, 1)\}$$

② Intersection :-  $(\tilde{A} \cap \tilde{B})$



$$\tilde{A} \cap \tilde{B} = \{(x_1, 0.5), (x_2, 0.2), (x_3, 0)\}$$

③ Complement :  $(\tilde{A}^c)$



$$\tilde{A} = \{(x_1, 0.5), (x_2, 0.4), (x_3, 1)\}$$

④ Product of FS :-  $\tilde{A} \cdot \tilde{B}$

If  $\tilde{A} = \{(x_1, 0.2), (x_2, 0.8), (x_3, 0.4)\}$

$\tilde{B} = \{(x_1, 0.5), (x_2, 0), (x_3, 0.1)\}$

$$\therefore \tilde{A} \cdot \tilde{B} = \{(x_1, 0.08), (x_2, 0), (x_3, 0.04)\}$$

⑤ product of FS with misp no. :-

If  $\tilde{A} = \{(x_1, 0.5), (x_2, 0.6), (x_3, 0.8)\}$

and  $\alpha = 0.3$

$$\therefore A \cdot \tilde{A} = \{(x_1, 0.12), (x_2, 0.18), (x_3, 0.24)\}.$$

⑥ Power of FS :-  $\tilde{A}^\alpha$

If  $\tilde{A} = \{(x_1, 0.4), (x_2, 0.2), (x_3, 0.7)\}$

&  $\alpha = 2$

$$\therefore \tilde{A}^2 = \{(x_1, 0.16), (x_2, 0.04), (x_3, 0.49)\}.$$

(39)

⑦ Difference :- (-), (')

$$\text{If } \tilde{A} = \{(x_1, 0.2), (x_2, 0.5), (x_3, 0.6)\}$$

$$\tilde{B} = \{(x_1, 0.1), (x_2, 0.4), (x_3, 0.3)\}$$

$$\tilde{A} - \tilde{B} = \underline{(\tilde{A} \cap \tilde{B}^c)}$$

$$\tilde{B}^c = \{(x_1, 0.9), (x_2, 0.6), (x_3, 0.5)\}$$

$$\tilde{A} - \tilde{B} = \{(x_1, 0.2), (x_2, 0.5), (x_3, 0.5)\}$$

⑧ Disjunctive sum :-  $\tilde{A} \tilde{\oplus} \tilde{B}$

$$\tilde{A} \tilde{\oplus} \tilde{B} = (\tilde{A}^c \cap \tilde{B}) \cup (\tilde{A} \cap \tilde{B}^c)$$

$$\tilde{A}^c = \{(x_1, 0.8), (x_2, 0.5), (x_3, 0.4)\}$$

$$\tilde{B}^c = \{(x_1, 0.9), (x_2, 0.6), (x_3, 0.5)\}$$

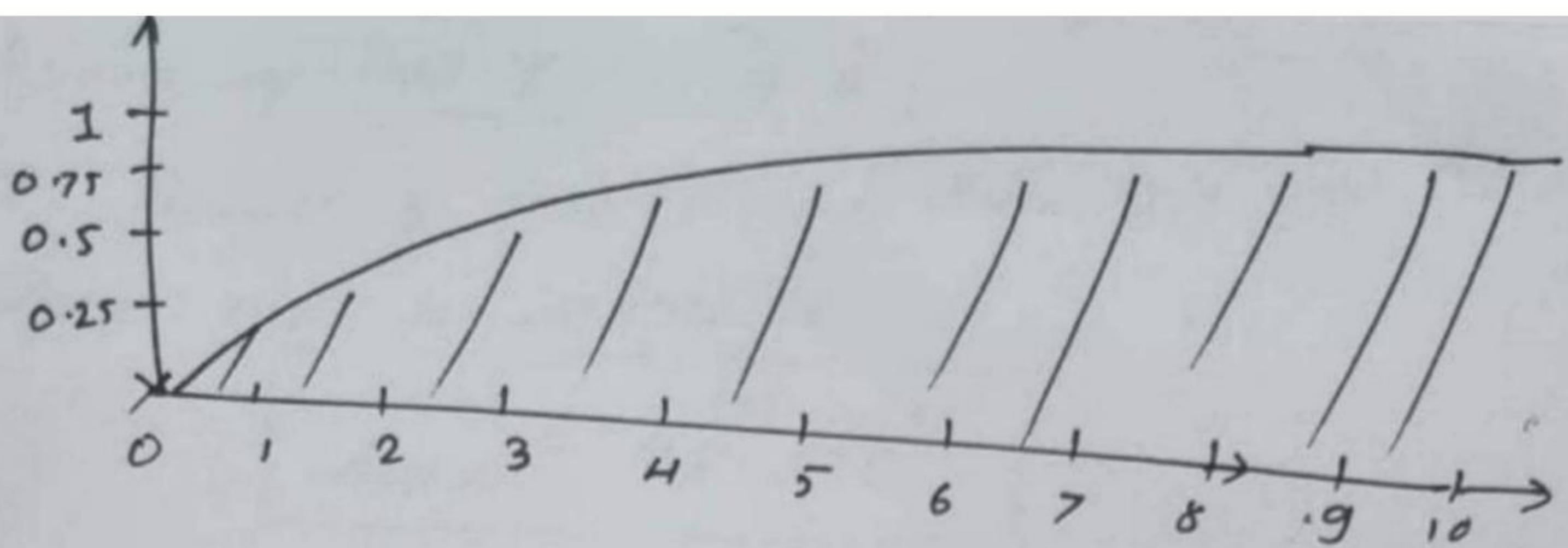
$$\therefore (\tilde{A}^c \cap \tilde{B}) = \{(x_1, 0.1), (x_2, 0.4), (x_3, 0.4)\}$$

$$(\tilde{A} \cap \tilde{B}^c) = \{(x_1, 0.2), (x_2, 0.5), (x_3, 0.5)\}$$

$$\therefore \tilde{A} \tilde{\oplus} \tilde{B} = \underline{\{(x_1, 0.2), (x_2, 0.5), (x_3, 0.5)\}}$$

(40)

(3)



### Operations on fuzzy set:-

Given  $X$  be a universal set and  $\tilde{A}$  &  $\tilde{B}$  be the two fuzzy sets defined on  $X$  with  $\mu_{\tilde{A}}^{(x)}$  &  $\mu_{\tilde{B}}^{(x)}$  as their membership fun.

#### ① Union : $(\tilde{A} \cup \tilde{B})$

The union of two fuzzy sets  $\tilde{A}$  &  $\tilde{B}$  is a new fuzzy set  $\tilde{A} \cup \tilde{B}$  on  $X$  with membership fun.

$$\mu_{\tilde{A} \cup \tilde{B}}^{(x)} = \max (\mu_{\tilde{A}}^{(x)}, \mu_{\tilde{B}}^{(x)})$$

#### ② Intersection : $(\tilde{A} \cap \tilde{B})$

The intersection of two fuzzy sets  $\tilde{A}$  &  $\tilde{B}$  is a new fuzzy set  $\tilde{A} \cap \tilde{B}$  on  $X$  with membership fun.

$$\mu_{\tilde{A} \cap \tilde{B}}^{(x)} = \min (\mu_{\tilde{A}}^{(x)}, \mu_{\tilde{B}}^{(x)})$$

#### ③ Compliment : $(\tilde{A}^c)$

The compliment of fs  $\tilde{A}$  is a new fs  $\tilde{A}^c$  with membership fun.

$$\mu_{\tilde{A}^c}^{(x)} = 1 - (\mu_{\tilde{A}}^{(x)})$$

(41)

4) Product of two fs:- ( $\tilde{A} \cdot \tilde{B}$ )

The product of two fs  $\tilde{A} \cdot \tilde{B}$  is a new fs  $\tilde{A} \cdot \tilde{B}$  whose mf is defined as.

$$M_{\tilde{A} \cdot \tilde{B}}^{(x)} = M_A^{(x)} \cdot M_B^{(x)}$$

5) Product of fs with crisp no. ( $a \cdot \tilde{A}$ )

Multiplying a fs  $\tilde{A}$  by a, a crisp no. results in a new fs  $a \cdot \tilde{A}$  with mf.

$$M_{a \cdot \tilde{A}}^{(x)} = a \cdot M_{\tilde{A}}^{(x)}$$

6) Power of fs:- ( $\tilde{A}^k$ )

The k power of fs  $\tilde{A}$  is a new fs  $\tilde{A}^k$  whose mf is given as

$$M_{\tilde{A}^k}^{(x)} = (M_{\tilde{A}}^{(x)})^k$$

7) Difference :- (-) or (')

The difference of two fs  $\tilde{A} - \tilde{B}$  is a new fs  $\tilde{A} - \tilde{B}$  whose mf is given as

$$\tilde{A} - \tilde{B} = (\tilde{A} \cap \tilde{B}^c)$$

8) Disjunction / Disjunctive sum :  $\oplus$

The disjunctive sum of two fs  $\tilde{A} + \tilde{B}$  is a new fs  $\tilde{A} \oplus \tilde{B}$  defined as.

$$\tilde{A} \oplus \tilde{B} = (\tilde{A}^c \cap \tilde{B}) \cup (\tilde{A} \cap \tilde{B}^c)$$

(42)

\*  $\alpha$ -cuts & strong  $\alpha$ -cuts of FS:-

(1)

$\alpha$ -cut and strong  $\alpha$ -cuts are the properties of FS, which can be defined as follows -

i)  $\alpha$ -cuts :-  $\alpha$ -cut is a new crisp set defined on fuzzy set  $\tilde{A}$  over a universe of discourse  $X$  as

$$\boxed{A^\alpha = \{x \mid A(x) \geq \alpha\}}$$

ii) strong  $\alpha$ -cuts :- strong  $\alpha$ -cuts is a new crisp set defined on a FS  $\tilde{A}$  over a universal set  $X$  as

$$\boxed{A^{\alpha+} = \{x \mid A(x) > \alpha\}}$$

Ex:- Find the  $\alpha$ -cuts & strong  $\alpha$ -cuts for  $\alpha = 0.5$  of set  $\tilde{A}$

$$\tilde{A} = \left\{ \frac{0.2}{1}, \frac{0.3}{2}, \frac{0.4}{3}, \frac{0.5}{6}, \frac{0.7}{7}, \frac{0.8}{8}, \frac{0.9}{10} \right\}$$

$$\Rightarrow \tilde{A} = \{(1, 0.2), (2, 0.3), (3, 0.4), (6, 0.5), (7, 0.7), (8, 0.8), (10, 0.9)\}$$

$\alpha$ -cuts :-

i) For  $\alpha = 0.2$

$$A^{0.2} = \left\{ \frac{1}{1}, \frac{1}{2}, \frac{1}{3}, \frac{1}{6}, \frac{1}{7}, \frac{1}{8}, \frac{1}{10} \right\}$$

$$A^{0.2} = \{1, 2, 3, 6, 7, 8, 10\}$$

ii) For  $\alpha = 0.3$

$$A^{0.3} = \{2, 3, 6, 7, 8, 10\}$$

(43)

(2)

iii) for  $\alpha = 0.4$ 

$$A^{0.4} = \{3, 6, 7, 8, 10\}$$

iv) for  $\alpha = 0.5$ 

$$A^{0.5} = \{6, 7, 8, 10\}$$

v) for  $\alpha = 0.7$ 

$$A^{0.7} = \{7, 8, 10\}$$

vi) for  $\alpha = 0.8$ 

$$A^{0.8} = \{8, 10\}$$

vii) for  $\alpha = 0.9$ 

$$A^{0.9} = \{10\}$$

 $\longrightarrow X \longrightarrow$ Strong  $\alpha$ -cuts:-i) for  $\alpha = 0.2$ 

$$A^{+0.2} = \{2, 3, 6, 7, 8, 10\}$$

ii) for  $\alpha = 0.3$ 

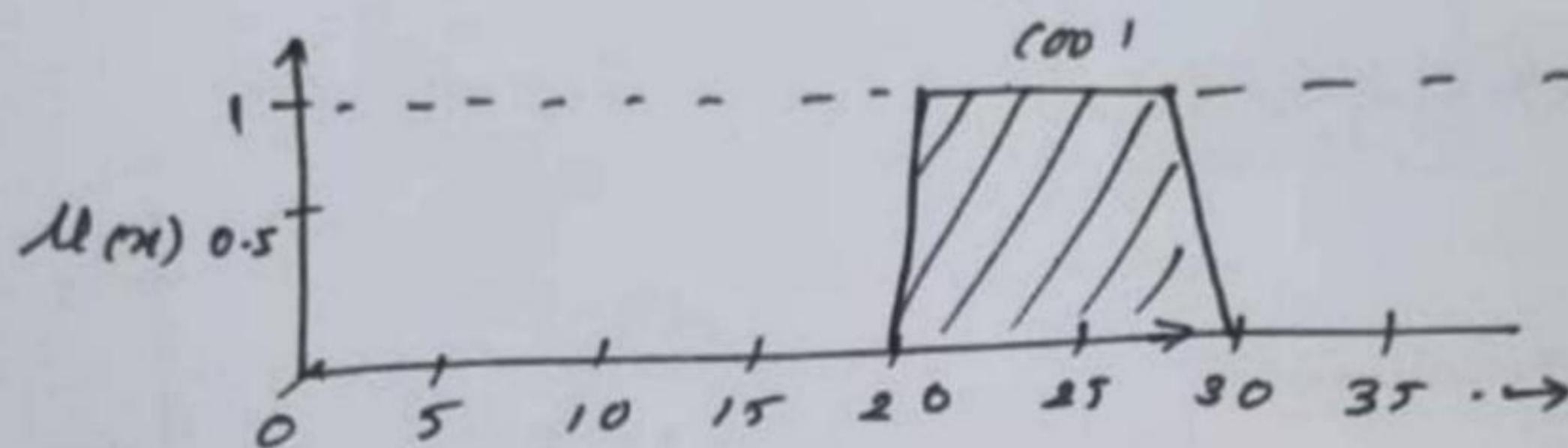
$$A^{+0.3} = \{3, 6, 7, 8, 10\}$$

iii) for  $\alpha = 0.4$  -  $A^{+0.4} = \{6, 7, 8, 10\}$ iv) for  $\alpha = 0.5$  -  $A^{+0.5} = \{7, 8, 10\}$ v) for  $\alpha = 0.8$  -  $A^{+0.8} = \{10\}$ vi) for  $\alpha = 0.9$  -  $A^{+0.9} = \{\emptyset\}$ . $\longrightarrow X \longrightarrow$   
64

## membership function:-

The membership fun values always described by discrete values and by continuous function.

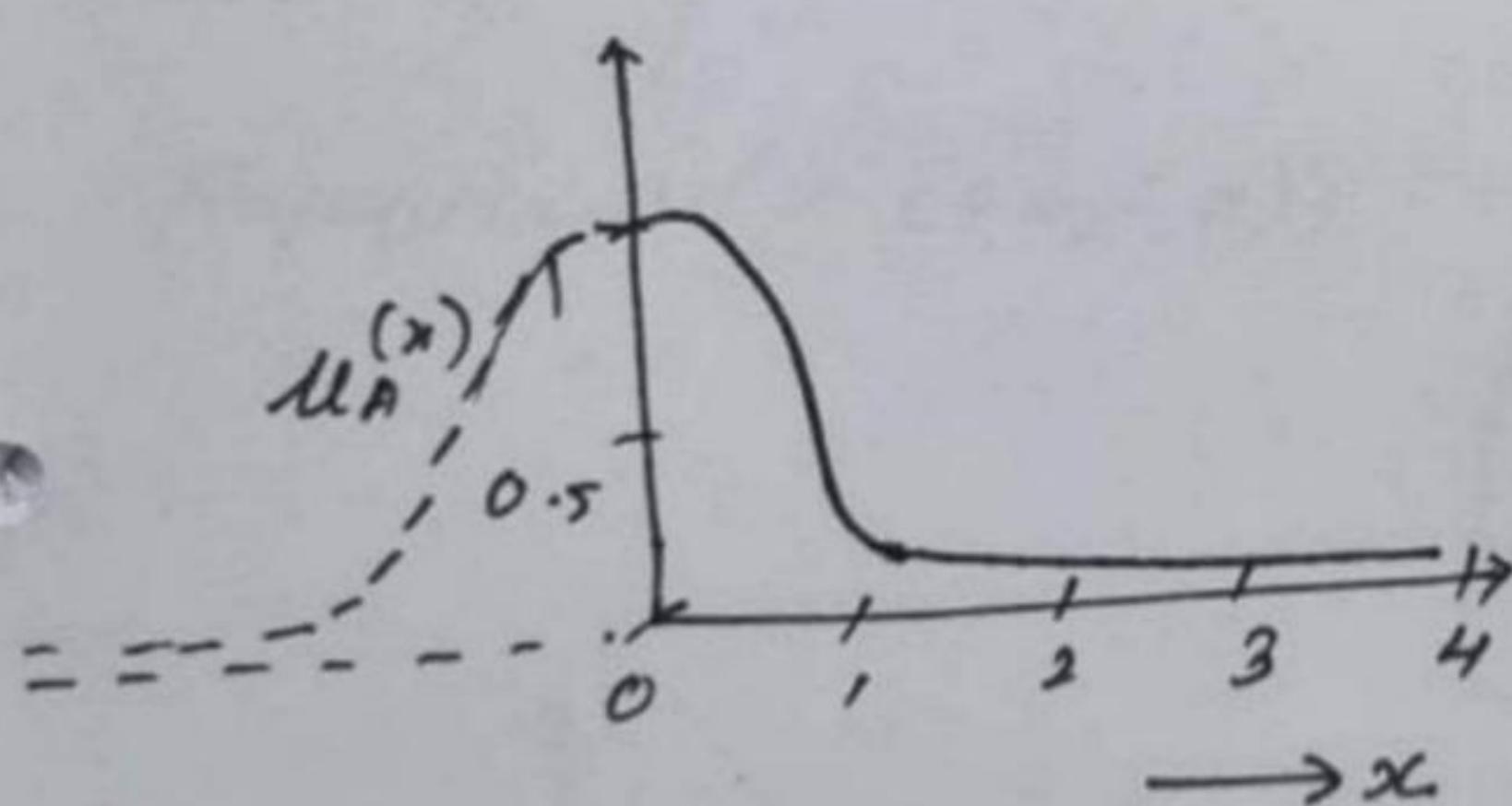
The fuzzy membership fun for fuzzy linguistic form "cool" related to temp. may represented as



A mf can be also given mathematically.

$$\text{Ex:- } \mu_A(x) = \frac{1}{1+x^2}$$

$$\text{For } x = \{0, 1, 2, 3, 4\}$$



x	$\mu_A(x)$
0	1
1	0.25
2	1/9
3	1/16
4	1/25

Ques:- Construct and plot fuzzy set, defined by function  $f(x) = \frac{x}{x+2}$  on universe of discourse.  $X = \{0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10\}$ . (45)

x	0	1	2	3	4	5	6	7	8	9	10
$f(x)$	0	$\frac{1}{3}$	$\frac{2}{4}$	$\frac{3}{5}$	$\frac{4}{6}$	$\frac{5}{7}$	$\frac{6}{8}$	$\frac{7}{9}$	$\frac{8}{10}$	$\frac{9}{11}$	$\frac{10}{12}$

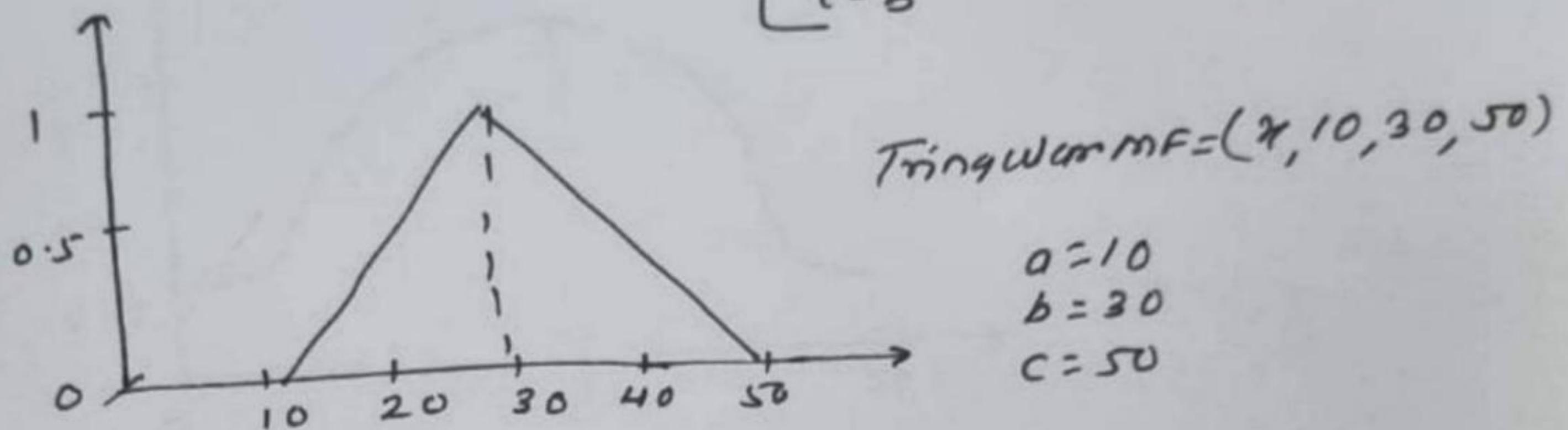
(3)

## Types of membership fun:-

### (i) Triangular MF :-

specified by 3 parameters -  $\{a, b, c\}$ .

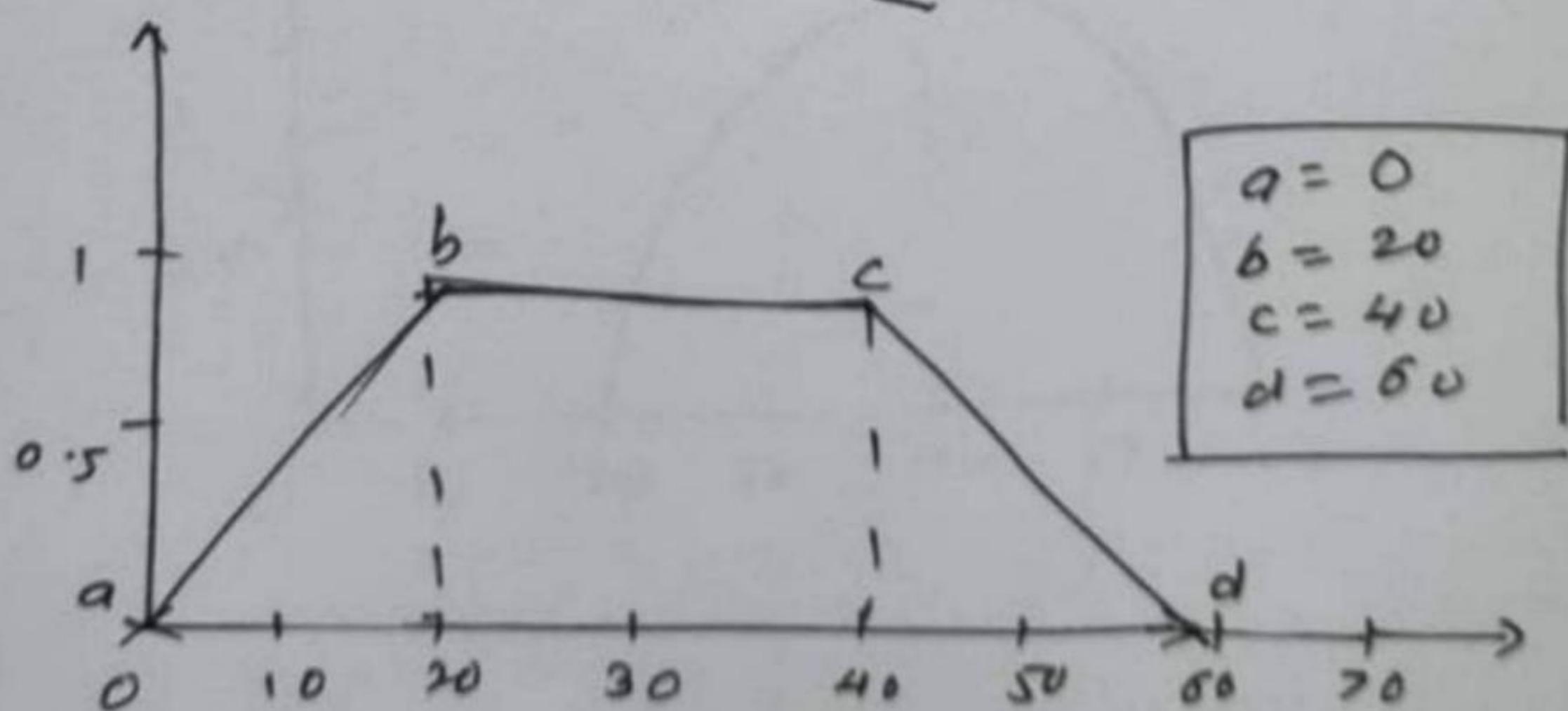
$$\text{Triangular}(x, (a, b, c)) = \begin{cases} 0 & x \leq a \\ \frac{x-a}{b-a} & a \leq x \leq b \\ \frac{c-x}{c-b} & b \leq x \leq c \end{cases}$$



### (ii) Trapezoidal MF :-

specified by 4 parameters  $\{a, b, c, d\}$ .

$$\text{Trapezoidal}(x, (a, b, c, d)) = \begin{cases} 0 & x \leq a \\ \frac{x-a}{b-a} & a \leq x \leq b \\ 1 & b \leq x \leq c \\ \frac{d-x}{d-c} & c \leq x \leq d \\ 0 & d \leq x \end{cases}$$



(410)

③ Gaussian mf :-

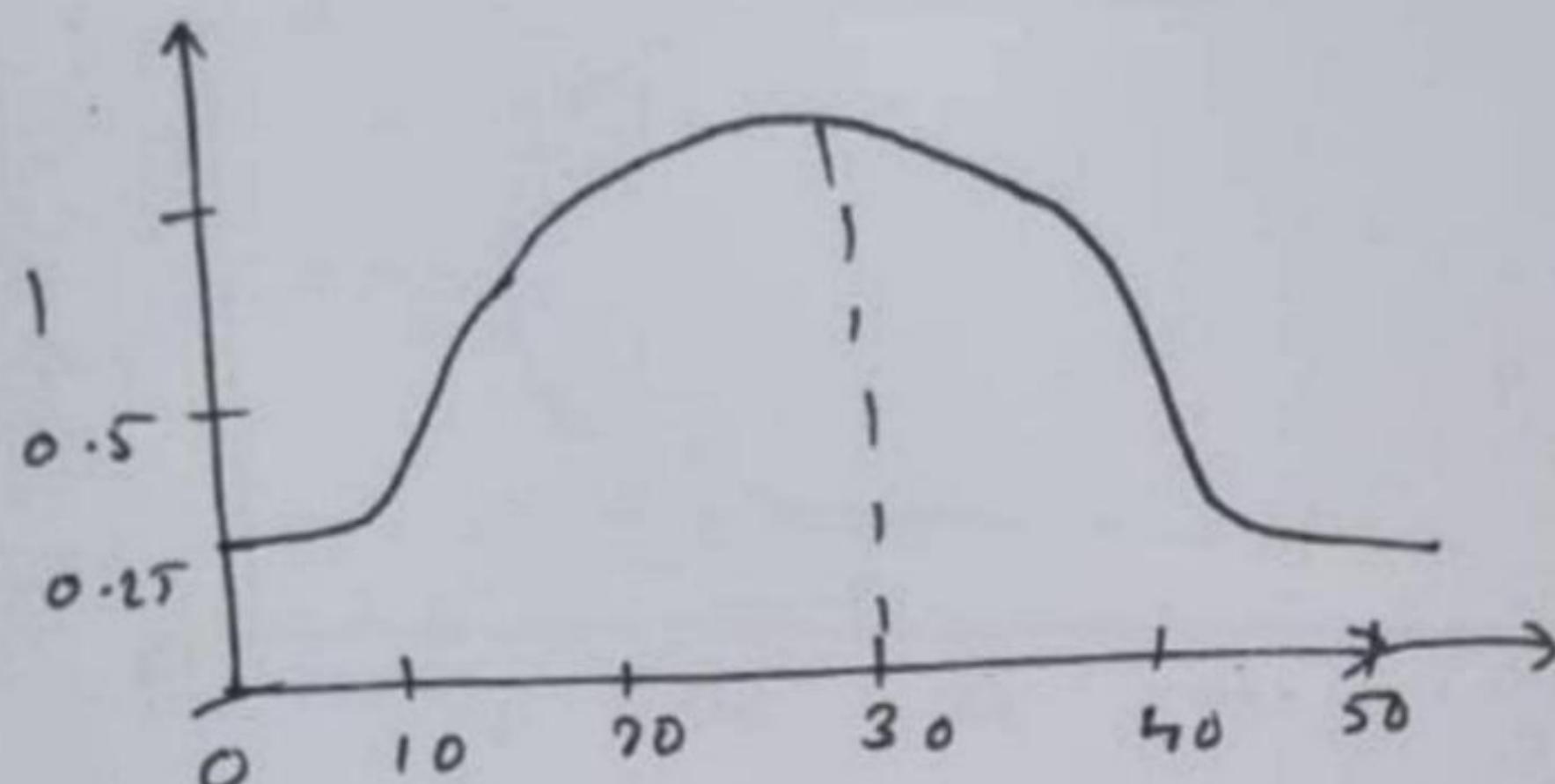
(4)

Determined by two parameters  $(c, \sigma)$

$$\text{Gaussian } (x, c, \sigma) = e^{\frac{1}{2}} \cdot \left( \frac{x-c}{\sigma} \right)^2$$

where  $c$  - mf centre

$\sigma$  - mf width.

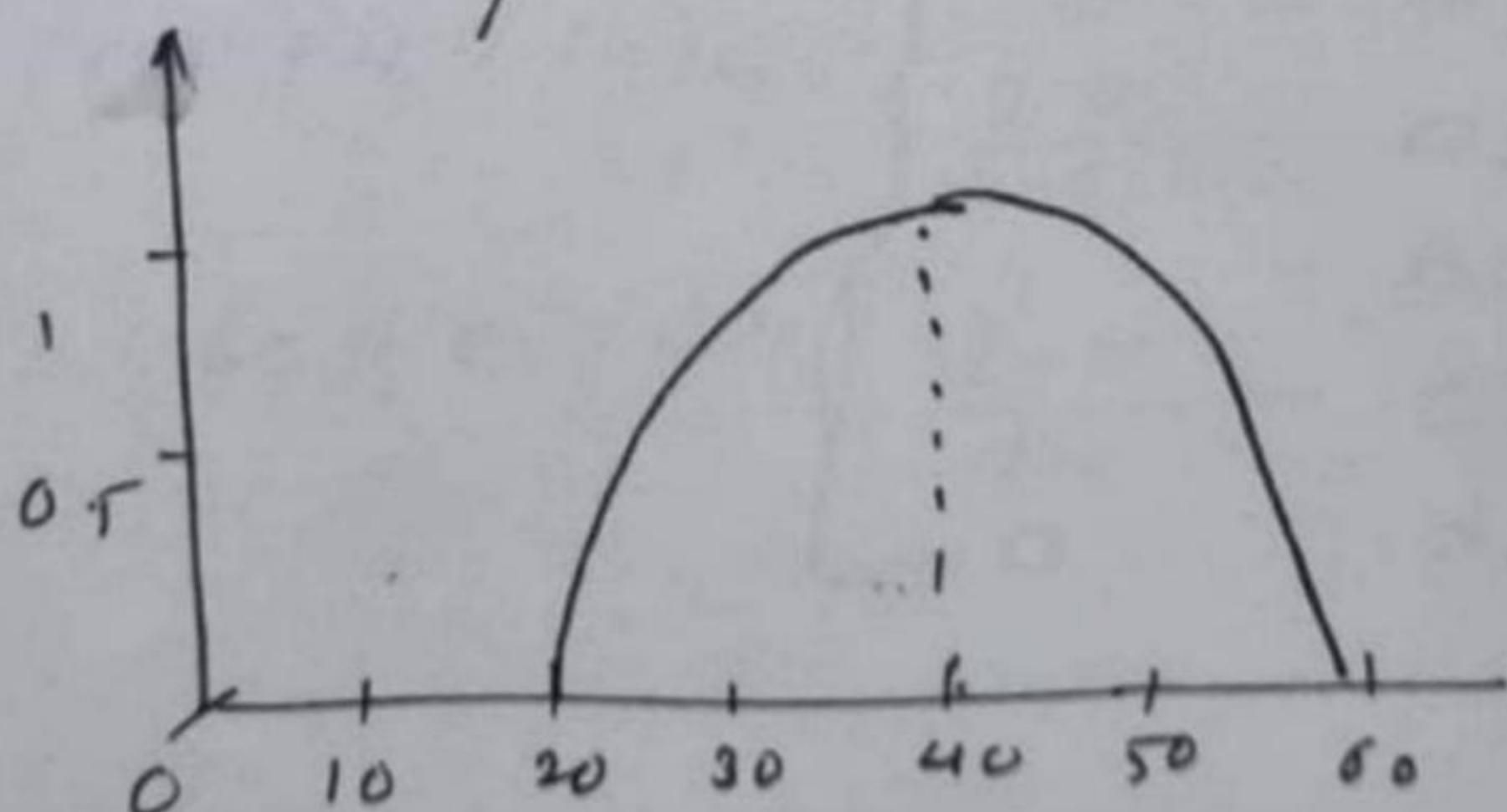


④ Generalised Bell shape mf :-

Defined by 3-parameters.  $(a, b, c)$

$$\text{Bell } (x, a, b, c) = \frac{1}{1 + \left| \frac{x-c}{a} \right|^{2b}}$$

where,  $b$  is usually positive



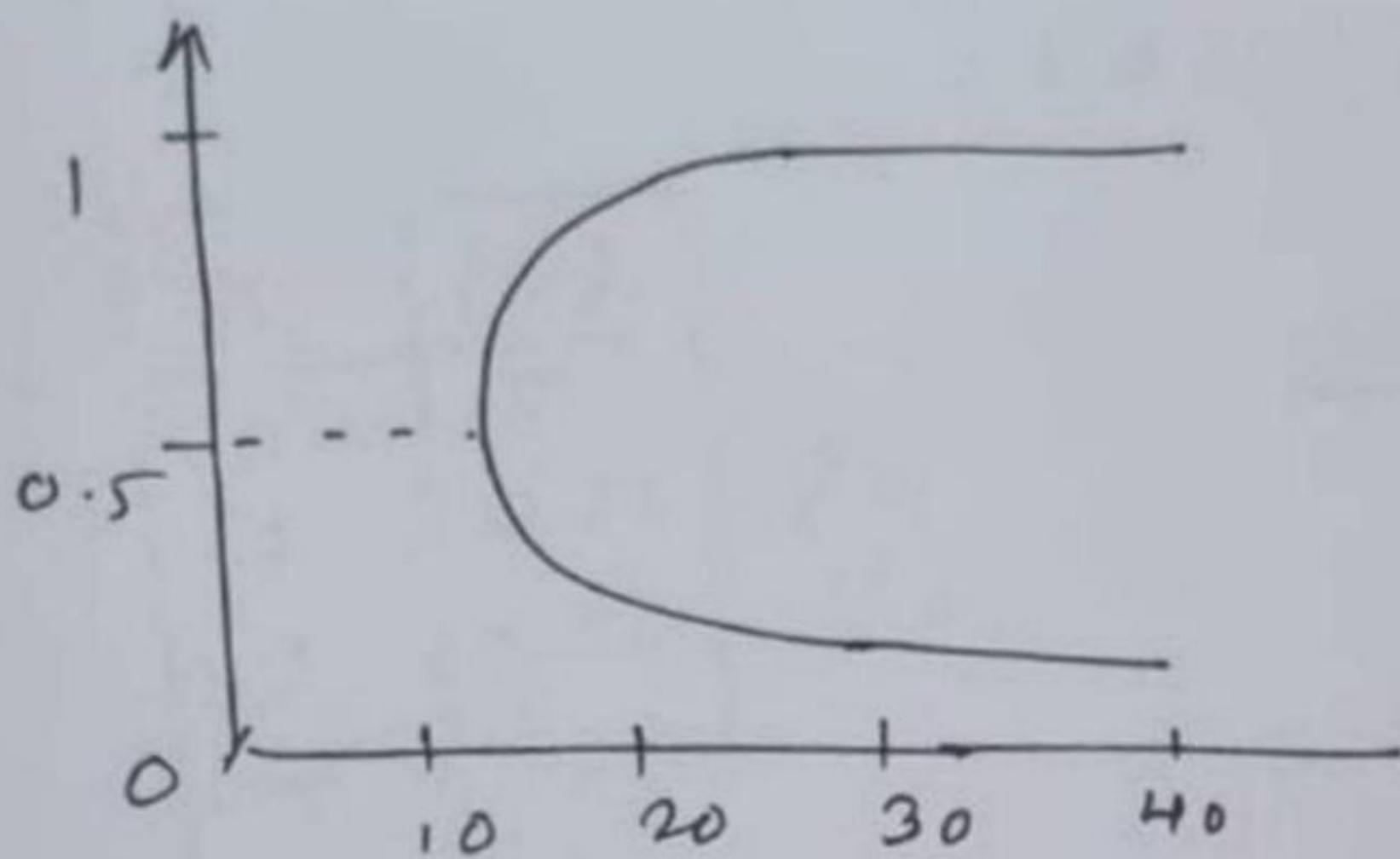
(47)

(5)

⑤ Sigmoidal MF :-

defined by 3 parameters ( $a, b, c$ )  
as

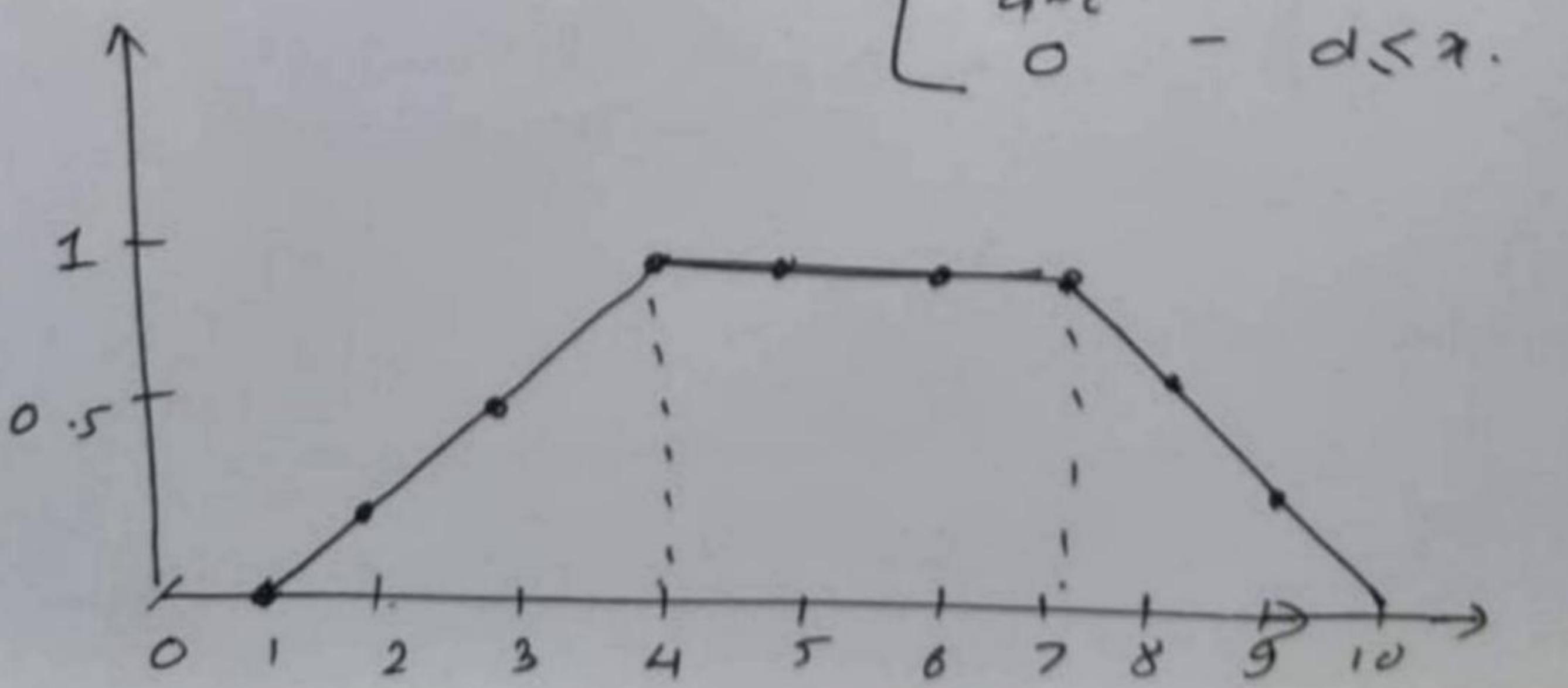
$$\text{Sigmoidal}(x; a, b, c) = \frac{1}{1 + \exp(-a(x-c))}$$



Numerical :- construct a FS defined by  $f_u^n$   
 $f(x; a, b, c, d)$  given below on universe of  
dis course  $X = \{1, 2, 3, \dots, 10\}$ .

$$f(x; 1, 4, 7, 10) = \begin{cases} 0 & - x \leq a \\ \frac{x-a}{b-a} & - a \leq x \leq b \\ 1 & - b \leq x \leq c \\ \frac{d-x}{d-c} & - c \leq x \leq d \\ 0 & - d \leq x \end{cases}$$

Here  $a = 1, b = 4, c = 7, d = 10$



(48)

Let  $\hat{A}$  is F.S defined by  $f_A$ . (6)

$$f(x: a, b, c, d)$$

then

$$\hat{A} = \{(1, 0), (2, 0.33), (3, 0.66), (4, 1), (5, 1), (6, 1), (7, 1), (8, 0.66), (9, 0.33), (10, 0)\}.$$

$x$	$t(x)$	
1	0	
2	0.33	$1/3$
3	0.66	$2/3$
4	1	
5	1	
6	1	
7		
8	0.66	$2/3$
9	0.33	$1/3$
10	0	

using formula

(4g)

## Crisp Relations:-

Cartesian product :-  $(A \times B)$

The cartesian product of two crisp sets  $A$  &  $B$  denoted by  $A \times B$  is the set of all ordered pairs such that, the first element in the pair belongs to set  $A$  and second element belongs to set  $B$ .

$$\text{i.e., } A \times B = \{(a, b) \mid a \in A \text{ & } b \in B\}$$

Ex:-  $A_1 = \{a, b\}$ ,  $A_2 = \{1, 2\}$  &  $A_3 = \{\alpha\}$

then,  $A_1 \times A_2 = \{(a, 1), (a, 2), (b, 1), (b, 2)\}$

$|A_1 \times A_2| = 4 \quad - \quad \therefore |A_1| = 2, |A_2| = 2$

2)  $|A_1 \times A_2 \times A_3| = \{(a, 1, \alpha), (a, 2, \alpha), (b, 1, \alpha), (b, 2, \alpha)\}$

Relation:- An  $n$ -ary relation denoted as  $R(x_1, x_2, \dots, x_n)$  among crisp sets  $x_1, x_2, \dots$  is a subset of the cartesian product

$$\prod_{i=1}^n x_i.$$

for binary relation  $R(X, Y)$ , where

$$X = \{x_1, x_2, \dots, x_n\} \text{ &}$$

$$Y = \{y_1, y_2, \dots, y_m\}$$

The relation matrix  $R$  is a 2-D matrix  
where  $X$  - Represents rows and  $Y$  represents  
columns.

$$\text{and } R(i, j) = 1, \text{ if } (x_i, y_j) \in R$$

$$R(i, j) = 0, \text{ if } (x_i, y_j) \notin R$$

Ex:-

$$X = \{1, 2, 3, 4\}$$

$$\text{Here, } |X| = 4.$$

$$\text{then } X \times X = \{(1, 1), (1, 2), (1, 3), (1, 4), (2, 1), (2, 2), (2, 3), (2, 4), (3, 1), (3, 2), (3, 3), (3, 4), (4, 1), (4, 2), (4, 3), (4, 4)\}$$

Let Relation  $R$  be defined as.

$$R = \{(x, y) / y = x + 1 \text{ & } x, y \in X\}$$

Then, the Relation matrix  $R$  can be given as.

$$R = \begin{bmatrix} & 1 & 2 & 3 & 4 \\ 1 & 0 & 1 & 0 & 0 \\ 2 & 0 & 0 & 1 & 0 \\ 3 & 0 & 0 & 0 & 1 \\ 4 & 0 & 0 & 0 & 0 \end{bmatrix}$$

(57)

## Operations on crisp relations

### ① Union [R ∪ S]

$$R \cup S (x, y) = \max (R(x, y), S(x, y))$$

### ② Intersection [R ∩ S]

$$R \cap S (x, y) = \min (R(x, y), S(x, y))$$

### ③ Complement : $\bar{R} / R^C$

$$\bar{R} (x, y) = 1 - R (x, y).$$

### ④ Composition : R ∘ S

If R is relation on X, Y and S is relation on Y, Z then the composition of relation on X, Z is defined as

$$R \circ S = \left\{ (x, z) \mid (x, y) \in X \times Z \text{ and } y \in Y \text{ such that } (x, y) \in R \text{ and } (y, z) \in S \right\}.$$

(52)

### ⑤ min-max composition:-

Given the relation matrices of relations  $R$  &  $s$ .

The min-max composition is defined as

for  $T = R \oslash s$

$$\text{where, } T(x, z) = \max [\min (R(x, y), (s(y, z))]$$

Ex:- Let  $R$  &  $s$  be defined on sets

$$X = \{1, 3, 5\} \quad \text{and} \quad Y = \{1, 3, 5\}$$

$$\therefore X \times Y = \{1, 3, 5\} \times \{1, 3, 5\}$$

$$= \{(1, 1), (1, 3), (1, 5), (3, 1), (3, 3), (3, 5), (5, 1), (5, 3), (5, 5)\}$$

Let Relation

$$R : \{(x, y) \mid y = x+2\}$$

$$S : \{(x, y) \mid x < y\}$$

$$\therefore R = \{(1, 3), (3, 5)\}$$

$$S = \{(1, 3), (1, 5), (3, 5)\}$$

Relation matrix

$$R = \begin{bmatrix} & 3 & 5 \\ 1 & 0 & 1 & 0 \\ 3 & 0 & 0 & 1 \\ 5 & 0 & 0 & 0 \end{bmatrix}$$

$$S = \begin{bmatrix} & 1 & 3 & 5 \\ 1 & 0 & 1 & 1 \\ 3 & 0 & 0 & 1 \\ 5 & 0 & 0 & 0 \end{bmatrix}$$

(53)

$$R = \begin{matrix} & 1 & 3 & 5 \\ 1 & \left[ \begin{array}{ccc|c} & 0 & 1 & 0 \\ & 0 & 0 & 1 \\ \hline 0 & 0 & 0 & 0 \end{array} \right] \\ 3 & \rightarrow & \rightarrow & \rightarrow \\ 5 & \rightarrow & \rightarrow & \rightarrow \end{matrix}$$

$$S = \begin{matrix} & 1 & 3 & 5 \\ 1 & \left[ \begin{array}{c|c|c} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \\ \hline 0 & 0 & 0 \end{array} \right] \\ 3 & \downarrow & \downarrow & \downarrow \\ 5 & \downarrow & \downarrow & \downarrow \end{matrix}$$

Using min-max composition

$$T = R \oslash S = \begin{matrix} & 1 & 3 & 5 \\ 1 & \left[ \begin{array}{ccc|c} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ \hline 0 & 0 & 0 \end{array} \right] \\ 3 & \text{- result} \\ 5 & \rightarrow \end{matrix}$$

$$\begin{aligned} R \oslash S(1,1) &= \max \left[ \min(R(1,1)), (S(1,1)) \right], \\ &\quad \min(R(1,3)), (S(1,3)), \\ &\quad \min(R(1,5)), (S(1,5)) \right] \\ &= \max \left[ \min(0,0), \min(1,0), \min(0,0) \right] \\ &= \max [0, 0, 0] \\ &= 0 \end{aligned}$$

and so on —

(34)

## Fuzzy Relations:-

A fuzzy relation is a fuzzy set defined on a cartesian product of a crisp set  $\{x_1, x_2, x_3 \dots x_n\}$ , where  $n$ -tuple  $(x_1, x_2, x_3 \dots x_n)$  may have the varying degree of membership within the relation.

The membership value indicates the state of relation between the tuples.

Let  $R$  is fuzzy relation bet<sup>n</sup> two set  $X_1, X_2$

Where  $X_1$  is set of diseases.

$X_2$  is set of symptoms.

$$X_1 = \{\text{Typhoid, viral fever, common cold}\}$$

$$X_2 = \{\text{shivering, Running Nose, High fever}\}$$

Then

	RN	HF	SH
TY	0.1	0.9	0.8
VF	0.2	0.9	0.7
CC	0.9	0.4	0.6

(75)

## Fuzzy Correlation Product :-

Let Fuzzy set  $\tilde{A}$  is defined on universal set  $X$  and Fuzzy set  $\tilde{B}$  is defined on universal set  $Y$ .

Let correlation product bct<sup>n</sup> fs  $\tilde{A} \times \tilde{B}$  is  $\tilde{A} \times \tilde{B}$  and resulting in relation  $\tilde{R}$  is given as

$$\tilde{R} = \tilde{A} \times \tilde{B} \subset X \times Y \text{ (subset of } X \times Y)$$

where  $\tilde{R}$  has its membership fun given by

$$\boxed{\mu_{\tilde{R}}^{(x,y)} = \mu_{\tilde{A} \times \tilde{B}}^{(x,y)}}$$

$$\boxed{\mu_{\tilde{R}}^{(x,y)} = \min [\mu_{\tilde{A}}^{(x,u)}, \mu_{\tilde{B}}^{(y,v)}]}$$

Ex:- Let  $\tilde{A}$  &  $\tilde{B}$  are two fs defined on universal set on  $X$  &  $Y$ . and the fuzzy relation  $R$  resulting out of fuzzy correlation product can be given as

$$X = \{x_1, x_2, x_3\}, Y = \{y_1, y_2\}$$

$$\tilde{A} = \{(x_1, 0.2), (x_2, 0.7), (x_3, 0.4)\}$$

$$\tilde{B} = \{(y_1, 0.5), (y_2, 0.8)\}$$

Then  $\tilde{R} = \tilde{A} \times \tilde{B} =$

	$y_1$	$y_2$
$x_1$	0.2	0.2
$x_2$	0.5	0.6
$x_3$	0.4	0.4

(61)

$$\tilde{R}(x_1, y_1) = \min \left[ \mu_{\tilde{A}}^{(x_1)}, \mu_{\tilde{B}}^{(y_1)} \right]$$

$$= \min [0.2, 0.5]$$

$$= \underline{0.2}$$

$$\tilde{R}(x_1, y_2) = \min \left[ \mu_{\tilde{A}}^{(x_1)}, \mu_{\tilde{B}}^{(y_2)} \right] = \min [0.2, 0.6] = 0.2$$

$$\tilde{R}(x_2, y_1) = \min \left[ \mu_{\tilde{A}}^{(x_2)}, \mu_{\tilde{B}}^{(y_1)} \right] = \min [0.7, 0.5] = 0.5$$

$$\tilde{R}(x_2, y_2) = \min \left[ \mu_{\tilde{A}}^{(x_2)}, \mu_{\tilde{B}}^{(y_2)} \right] = \min [0.7, 0.6] = 0.6$$

$$\tilde{R}(x_3, y_1) = \min [0.4, 0.5] = 0.4$$

$$\tilde{R}(x_3, y_2) = \min [0.4, 0.6] = \underline{0.4}$$

$$\therefore \tilde{R} = \tilde{A} \times \tilde{B} = \begin{matrix} & \begin{matrix} x_1 & x_2 \end{matrix} \\ \begin{matrix} y_1 \\ y_2 \\ y_3 \end{matrix} & \begin{bmatrix} 0.2 & 0.2 \\ 0.5 & 0.6 \\ 0.4 & 0.4 \end{bmatrix} \end{matrix}$$

Operations on fuzzy Relations:-

Let  $\tilde{R}$  &  $\tilde{S}$  be the two fuzzy relations on  $X \times Y$

① Union :-  $(\tilde{R} \cup \tilde{S})$

$$\mu_{\tilde{R} \cup \tilde{S}}^{(x,y)} = \max (\mu_{\tilde{R}}^{(x,y)}, \mu_{\tilde{S}}^{(x,y)})$$

② Intersection :-  $(\tilde{R} \cap \tilde{S})$

$$\mu_{\tilde{R} \cap \tilde{S}}^{(x,y)} = \min (\mu_{\tilde{R}}^{(x,y)}, \mu_{\tilde{S}}^{(x,y)})$$

50

③ Compliment :  $(\tilde{R}^C)$

$$\boxed{\mu_{\tilde{R}^C}^{(x,u)} = 1 - \mu_{\tilde{R}}^{(x,u)}}$$

④ Composition:-  $\tilde{R} \circ \tilde{S}$

Suppose  $\tilde{R}$  is a fuzzy relation defined on  $X \times Y$ , and  $\tilde{S}$  is fuzzy relation defined on  $Y \times Z$  then  $\tilde{R} \circ \tilde{S}$  is a fuzzy relation on  $X \times Z$  and the fuzzy min-max composition can be defined as -

$$\boxed{\mu_{\tilde{R} \circ \tilde{S}}^{(x,z)} = \max \left[ \min \left( \mu_{\tilde{R}}^{(x,y)}, \mu_{\tilde{S}}^{(y,z)} \right) \right]}$$

⑤

Ex:- Given

$$X = \{x_1, x_2, x_3\}$$

$$Y = \{y_1, y_2\}$$

$$Z = \{z_1, z_2, z_3\}$$

Let  $\tilde{R}$  is fuzzy relation as

$$\tilde{R} = \begin{bmatrix} x_1 & 0.5 & 0.1 \\ x_2 & 0.2 & 0.9 \\ x_3 & 0.8 & 0.6 \end{bmatrix}$$

and  $\tilde{S}$  is fuzzy relation as

$$\tilde{S} = \begin{bmatrix} z_1 & z_2 & z_3 \\ y_1 & 0.6 & 0.4 & 0.7 \\ y_2 & 0.5 & 0.8 & 0.9 \end{bmatrix}$$

Find  $\tilde{R} \circ \tilde{S} \rightarrow X \times Z$

$$\Rightarrow \tilde{R} \circ \tilde{S} = \begin{bmatrix} z_1 & z_2 & z_3 \\ x_1 & 0.5 & 0.4 & 0.5 \\ x_2 & 0.5 & 0.8 & 0.9 \\ x_3 & 0.6 & 0.6 & 0.7 \end{bmatrix} - \text{Result}$$

$$\begin{aligned} u_{\tilde{R} \circ \tilde{S}}^{(x_1, z_1)} &= \max \left[ \min(0.5, 0.6), \min(0.1, 0.5) \right] \\ &= \max [0.5, 0.1] \\ &= \underline{\underline{0.5}} \end{aligned}$$

$$\begin{aligned} u_{\tilde{R} \circ \tilde{S}}^{(x_1, z_2)} &= \max \left[ \min(0.5, 0.4), \min(0.1, 0.8) \right] \\ &= \underline{\underline{0.4}} \end{aligned}$$

$$\begin{aligned} u_{\tilde{R} \circ \tilde{S}}^{(x_1, z_3)} &= \max \left[ \min(0.5, 0.7), \min(0.1, 0.9) \right] \\ &= \underline{\underline{0.5}} \end{aligned}$$

and so on —

$$Ex:-2) X = \{x_1, x_2, x_3\}$$

$$Y = \{y_1, y_2\}$$

$$Z = \{z_1, z_2, z_3\}$$

$$\tilde{R} = \begin{matrix} & y_1 & y_2 \\ x_1 & \begin{bmatrix} 0.4 & 0.2 \\ 0.2 & 0.7 \end{bmatrix} \\ x_2 & \\ x_3 & \begin{bmatrix} 0.9 & 0.6 \end{bmatrix} \end{matrix}$$

$$\tilde{S} = \begin{matrix} & z_1 & z_2 & z_3 \\ y_1 & \begin{bmatrix} 0.6 & 0.5 & 0.8 \end{bmatrix} \\ y_2 & \begin{bmatrix} 0.6 & 0.7 & 0.8 \end{bmatrix} \end{matrix}$$

$$\text{Find } \tilde{R} \circ \tilde{S}.$$

$\Rightarrow$  Result :

$$\tilde{R} \circ \tilde{S} = \begin{matrix} & z_1 & z_2 & z_3 \\ x_1 & \begin{bmatrix} 0.4 & 0.4 & 0.4 \\ 0.6 & 0.7 & 0.7 \\ 0.6 & 0.6 & 0.8 \end{bmatrix} \\ x_2 & \\ x_3 & \end{matrix}$$

Ex: 3) : consider a set  $P = \{P_1, P_2, P_3, P_4\}$  of four varieties of paddy plants, set ~~D = {D\_1, D\_2, D\_3, D\_4}~~ of various diseases set  $D = \{D_1, D_2, D_3, D_4\}$  of various diseases affecting plants and  $S = \{S_1, S_2, S_3, S_4\}$  be the common symptoms of the diseases.

Let  $\tilde{R}$  be relation on  $P \times D$  and  $\tilde{S}$  be the relation on  $D \times S$ .

$$\text{for } \tilde{R} = \begin{matrix} & D_1 & D_2 & D_3 & D_4 \\ P_1 & \begin{bmatrix} 0.6 & 0.6 & 0.9 & 0.8 \end{bmatrix} \\ P_2 & \begin{bmatrix} 0.1 & 0.2 & 0.9 & 0.8 \end{bmatrix} \\ P_3 & \begin{bmatrix} 0.9 & 0.3 & 0.4 & 0.8 \end{bmatrix} \\ P_4 & \begin{bmatrix} 0.9 & 0.8 & 0.1 & 0.2 \end{bmatrix} \end{matrix},$$

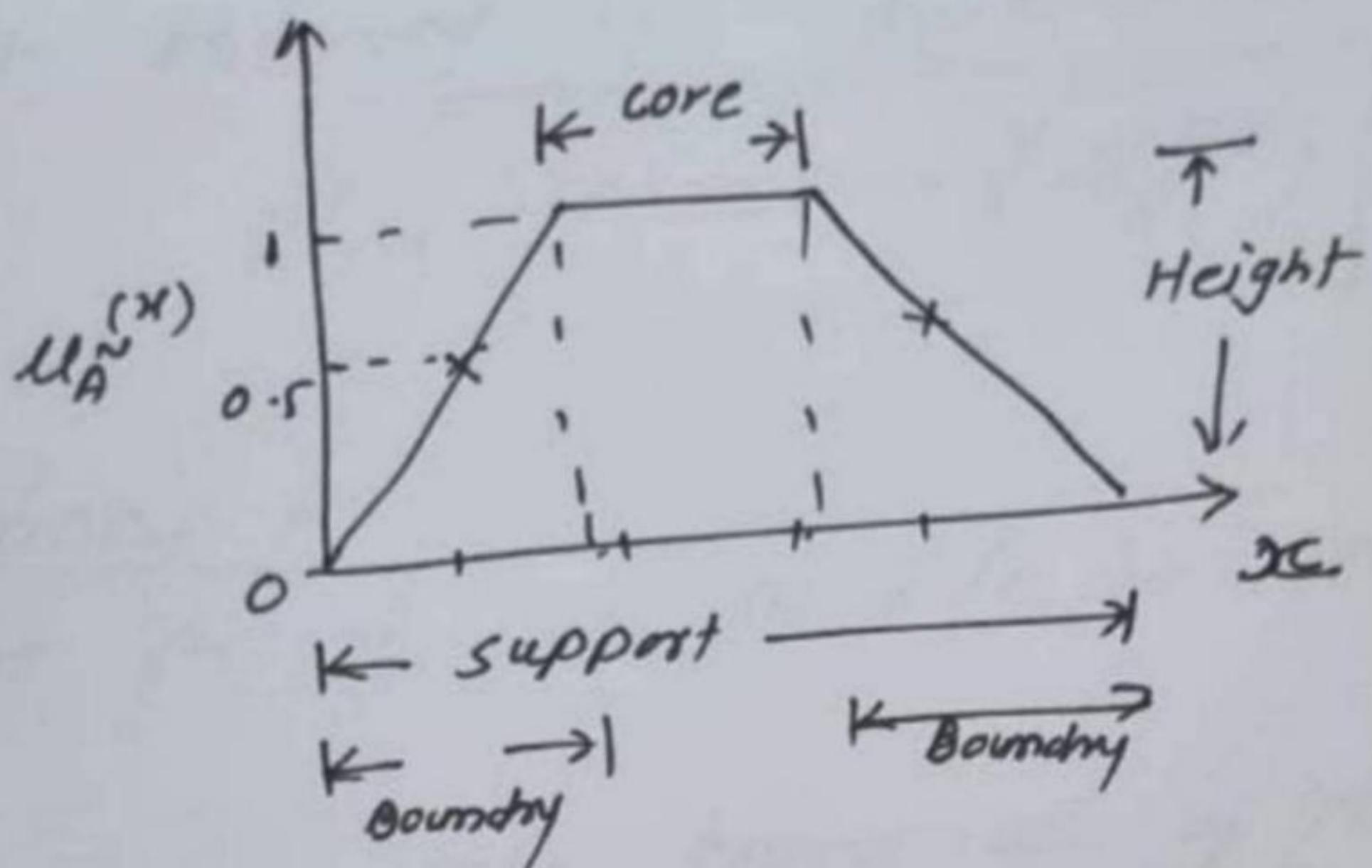
$$\tilde{S} = \begin{matrix} & S_1 & S_2 & S_3 & S_4 \\ D_1 & \begin{bmatrix} 0.1 & 0.2 & 0.7 & 0.9 \end{bmatrix} \\ D_2 & \begin{bmatrix} 1 & 1 & 0.4 & 0.6 \end{bmatrix} \\ D_3 & \begin{bmatrix} 0 & 0 & 0.5 & 0.9 \end{bmatrix} \\ D_4 & \begin{bmatrix} 0.9 & 1 & 0.8 & 0.2 \end{bmatrix} \end{matrix}$$

obtain the association of plants with the different symptoms of diseases using min-max composition.

(59)

## Some concepts in FS Theory

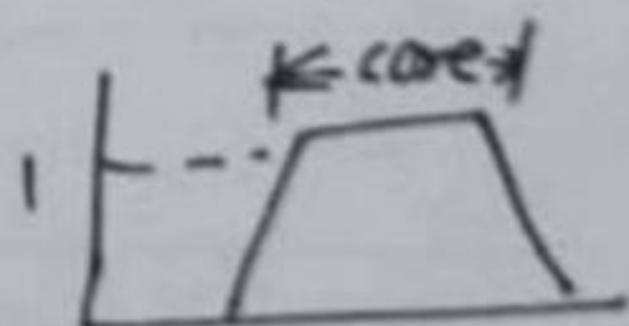
consider a MF as



### 1) core [ $c(\tilde{A})$ ]:-

The core of membership function for some fuzzy set  $\tilde{A}$  is defined as the region of universe  $\mathcal{X}$  discourse that is characterized by complete or full membership in set  $\tilde{A}$ .

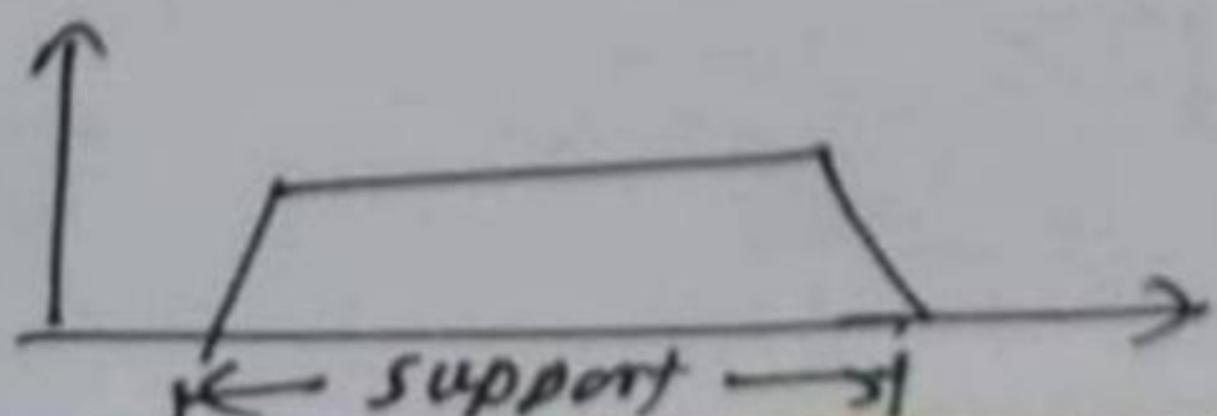
Thus core contains those elements of universal set such that  $M_{\tilde{A}}(x) = 1$ .



### 2) Support [ $s(\tilde{A})$ ]

The support of MF for some fs  $\tilde{A}$  is defined as the region of universe that is characterized by non-zero membership in set  $\tilde{A}$ .

thus support consists of those elements  $x$  of the universal set such that  $M_{\tilde{A}}(x) > 0$

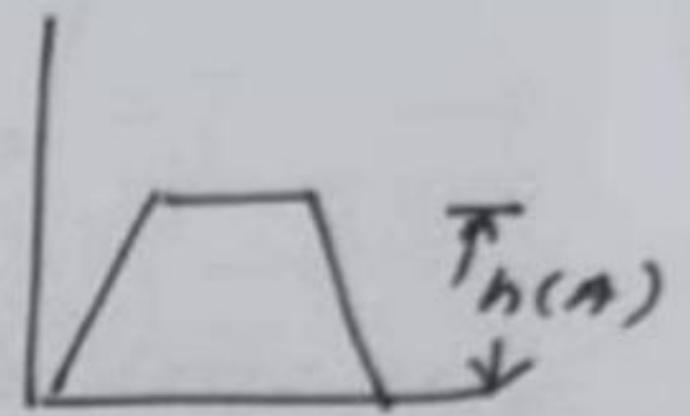


(62)

③ Height of FS [  $h(A)$  ]

The height of FS  $\tilde{A}$  is the largest membership grade obtained by any element in set  $\tilde{A}$ .

if, 
$$h(A) = \max(M_{\tilde{A}}^{(n)})$$

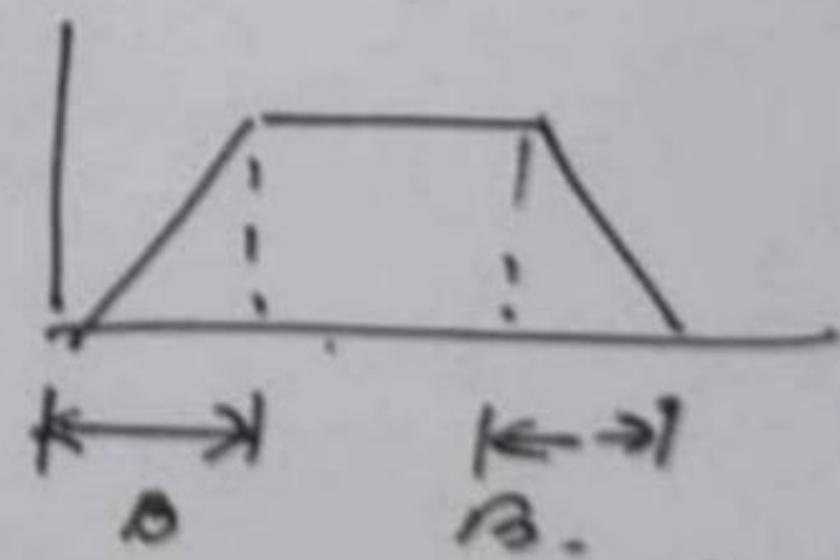


④ Normal FS:-

The FS  $\tilde{A}$  is said to be normal if  $h(A)=1$

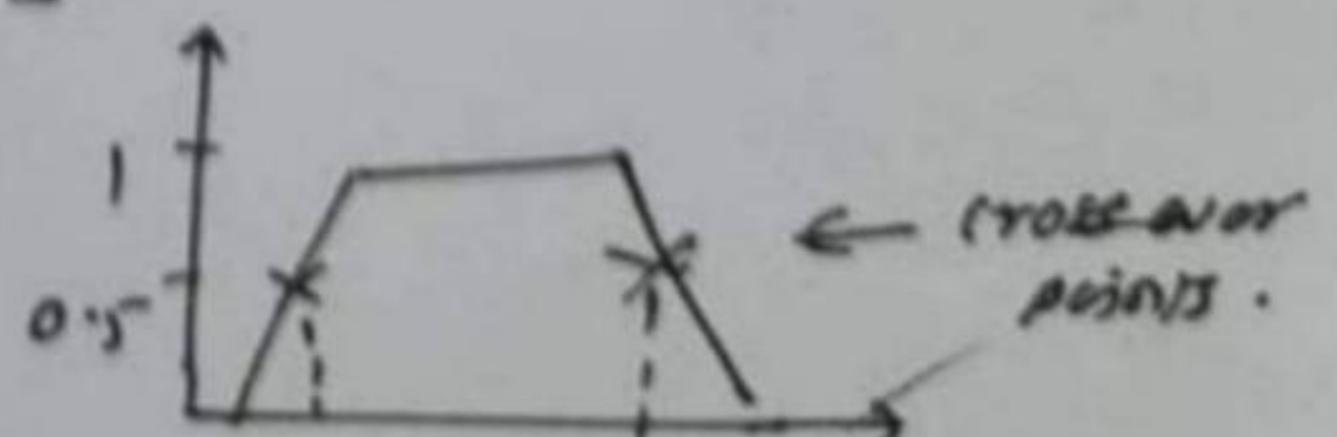
⑤ Boundary :- The boundaries of MF for some FS  $\tilde{A}$  are defined as the region of universe that have non-zero membership but not complete membership.

If, The boundaries consists of those elements  $x$  of the universe such that  $0 < M_{\tilde{A}}^{(n)} < 1$ .



⑥ Cross-over points :- The cross over point of a MF  $\tilde{A}$  is defined as the element in the universe for which a particular fuzzy set  $\tilde{A}$  has value equal to 0.5.

if,  $M_{\tilde{A}}^{(n)} = 0.5$

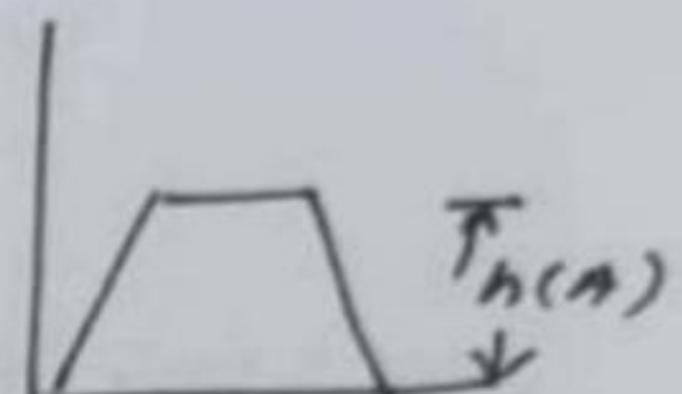


(63)

③ Height of fs [  $h(A)$  ]

The height of fs  $\tilde{A}^n$  is the largest membership grade obtained by any element in set  $\tilde{A}$ .

if, 
$$h(A) = \max (\mu_{\tilde{A}^n}^{(x)})$$

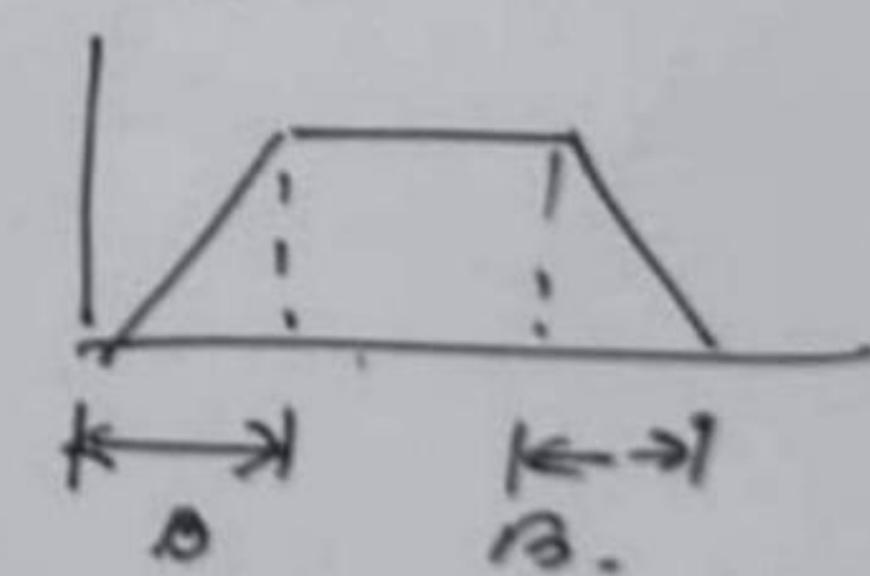


④ Normal fs:-

The fs  $\tilde{A}^n$  is said to be normal if  $h(A)=1$

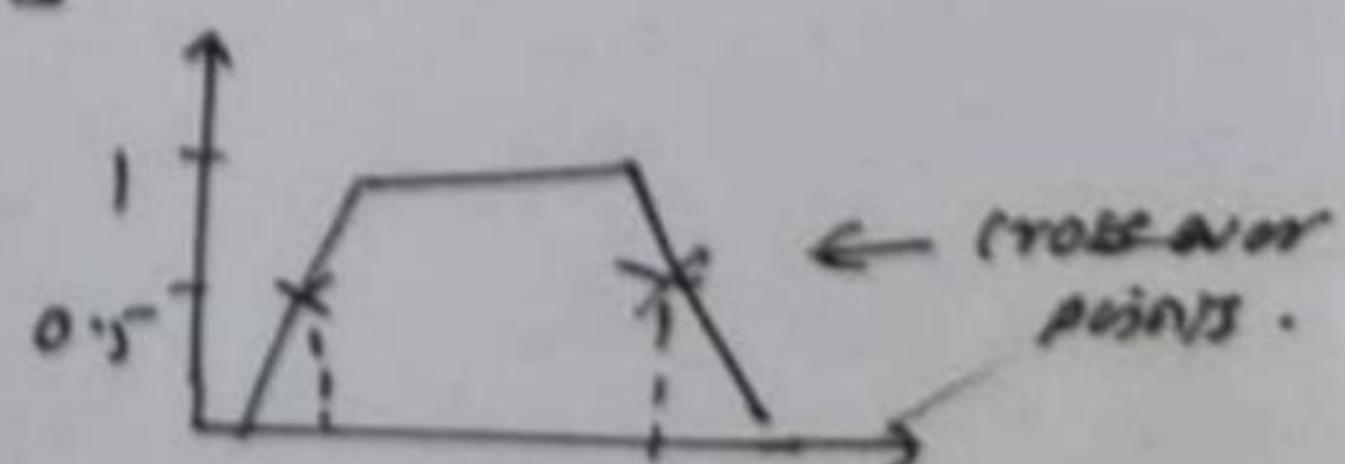
⑤ Boundary :- The boundaries of MF for some fs  $\tilde{A}$  are defined as the region of universe that have non-zero membership but not complete membership.

If, The boundaries consists of those elements  $x$  of the universe such that  $0 < \mu_{\tilde{A}}^{(x)} < 1$ .



⑥ Cross-over points:- The cross over point of a MF  $\tilde{A}^n$  is defined as the element in the universe for which a particular fuzzy set  $\tilde{A}$  has value equal to 0.5.

if,  $\mu_{\tilde{A}^n}^{(x)} = 0.5$



(6.3)

Ex:-

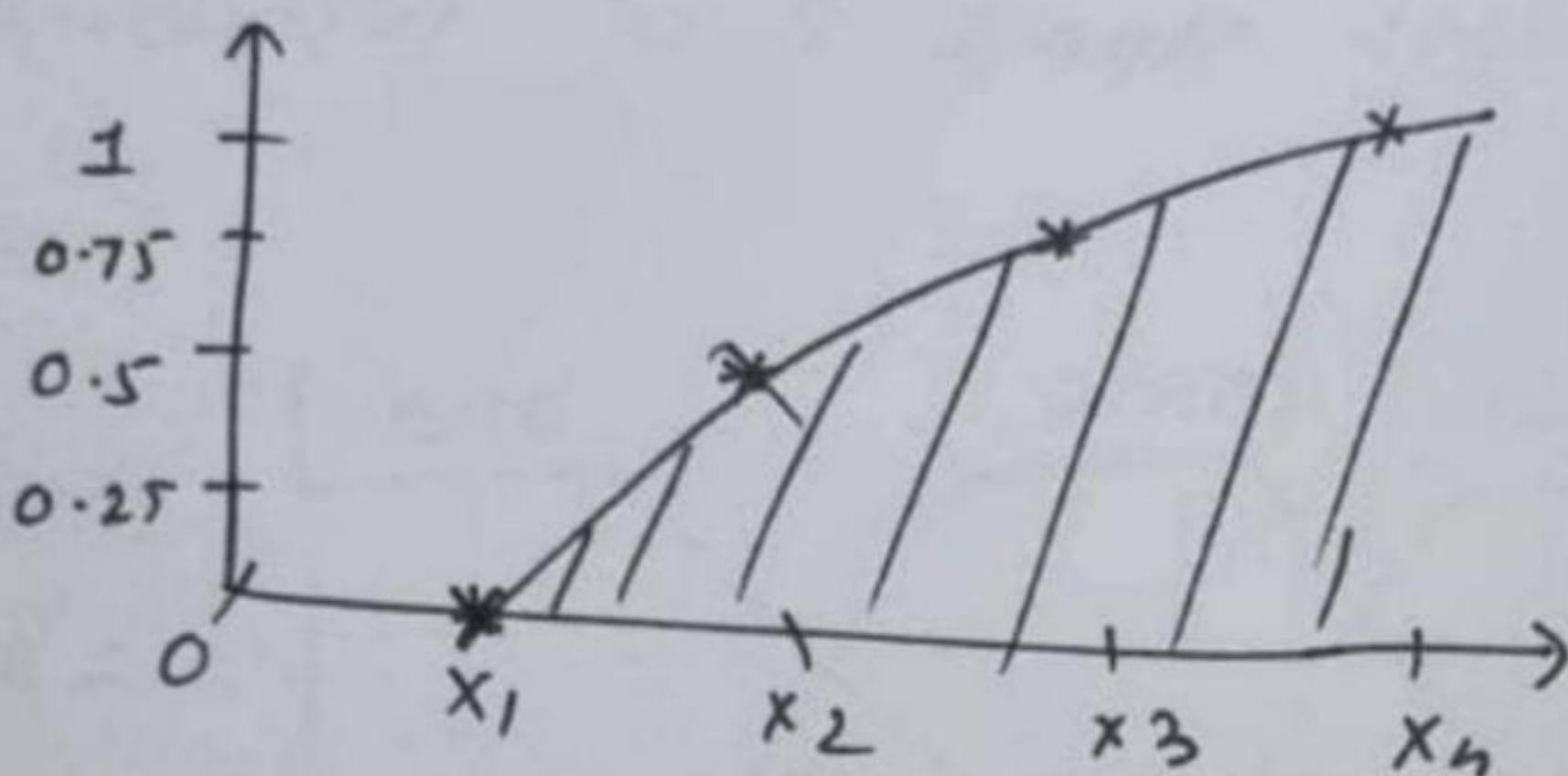
consider the universal set  $X = \{x_1, x_2, x_3, x_4\}$

let  $\tilde{A}$  is FS defined on univ. set  $x$  as

$$\tilde{A} = [(x_1, 0), (x_2, 0.5), (x_3, 0.75), (x_4, 1)]$$

find - 1) support 2) core 3) height 4) cross over  
points of FS, 5) Is this set normal?

⇒



1) support of FS  $\tilde{A}$  -

$$S(\tilde{A}) = \{x_1, x_2, x_3, x_4\}$$

2) core of FS  $\tilde{A}$  -

$$C(\tilde{A}) = \{x_4\}$$

3) height of FS  $\tilde{A}$  -

$$h(\tilde{A}) = 1$$

4) Cross over point of FS  $\tilde{A}$  ~~is  $x_2$~~

5) Yes this FS is normal  
since  $h(\tilde{A}) = 1$ .

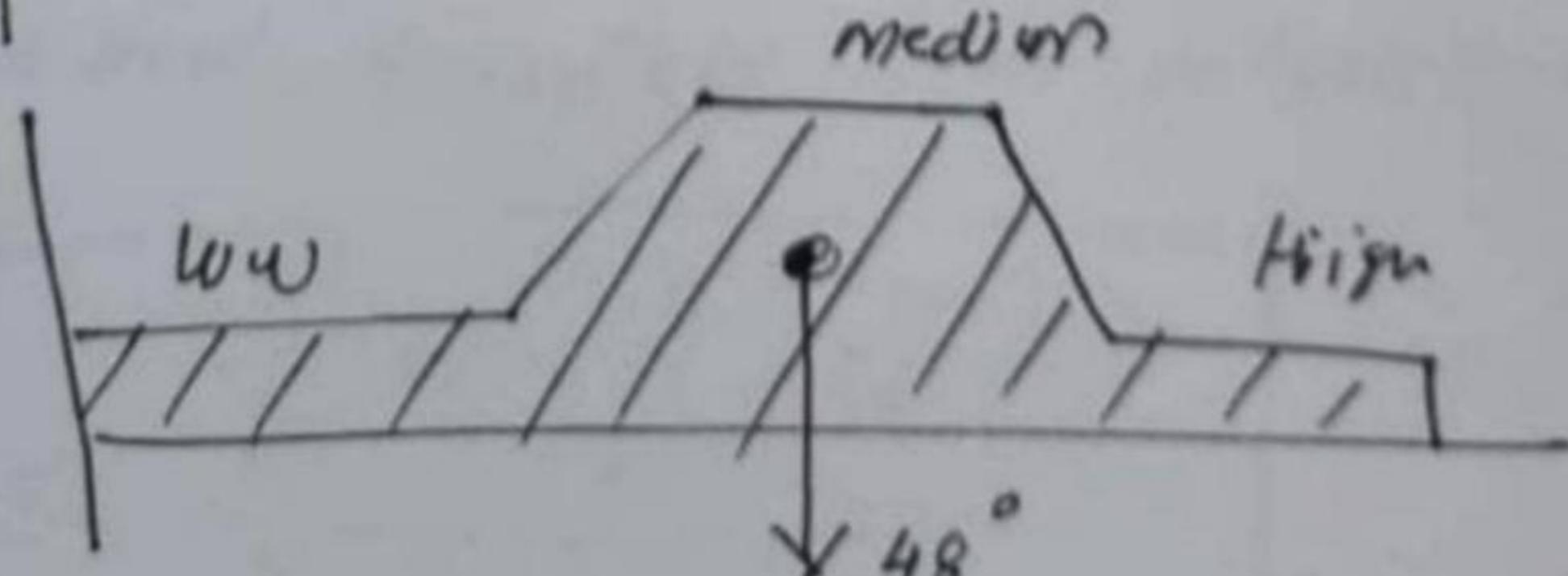
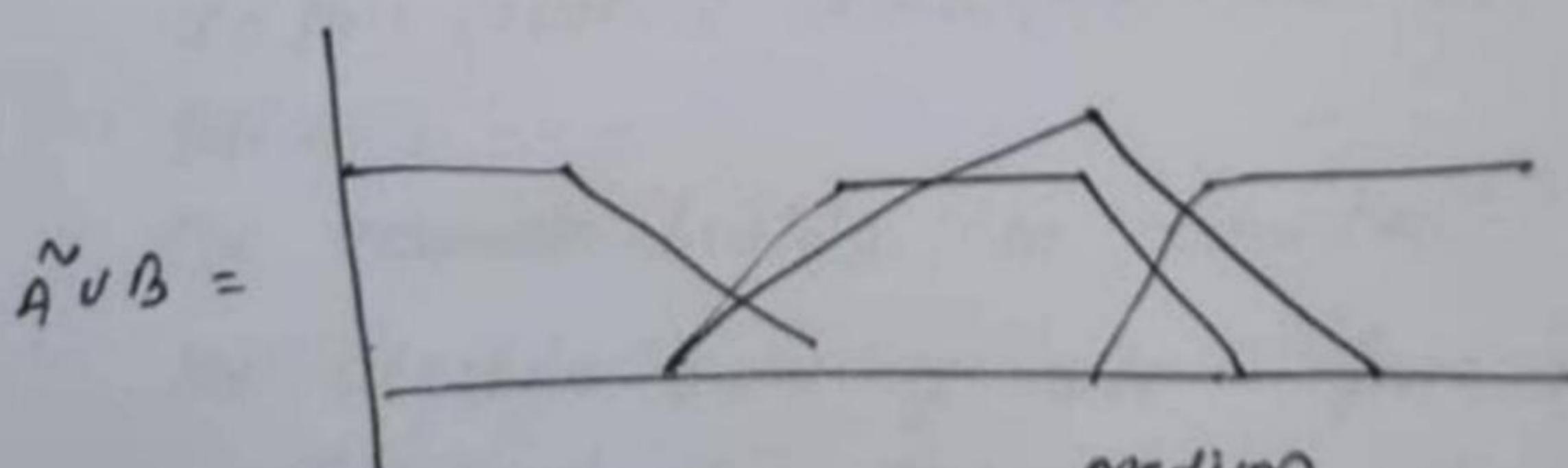
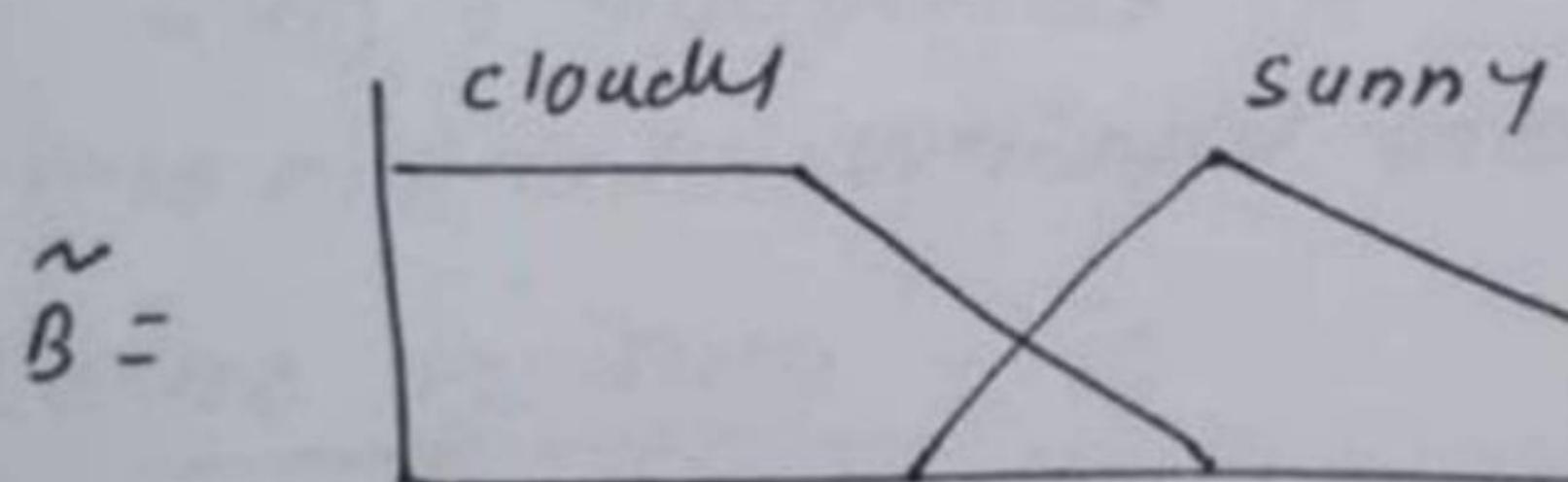
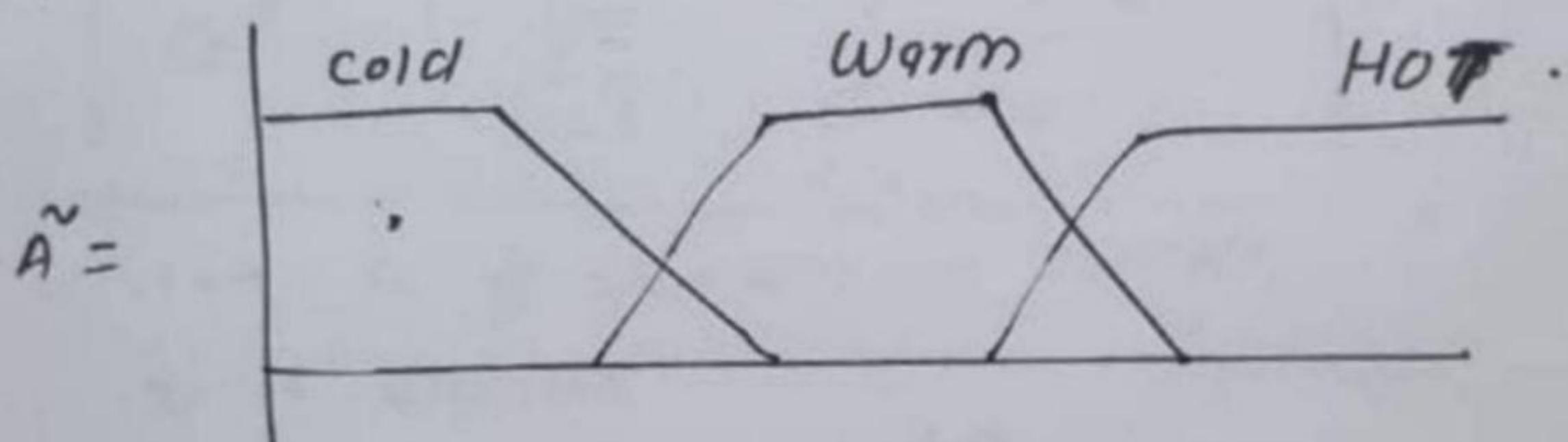
## Defuzzification

The conversion of FS to a single crisp value is called as Defuzzification.

It is reverse of fuzzification.

For a system whose o/p is fuzzy, it is easier to take a crisp decision, if the output is represented as a single scalar quantity.

Ex:-



Defuzzification

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There are 3 methods used for defuzzifications -

- ① centroid method (centre of area/ centre of gravity)
- ② centre of sum.
- ③ mean of maxima.

### ① centroid method :-

In this method the centre of area is calculated which is occupied by fuzzy set. It is represented as .

$$x^* = \sum_{i=1}^n \frac{x_i \cdot \mu_{x_i}(x_i)}{\sum_{i=1}^n \mu_{x_i}}$$

$n \rightarrow$  No. of elements in sample.

$x_i \rightarrow$  elements

$\mu(x_i) \rightarrow$  membership function.

- In this method overlaped areas are considered once.

### ② centre of sum:-

In this method overlaped area are considered twice.

Cos ~~resets~~ builds the resultant mf by taking the algebraic sum of outputs from each of the contributable fuzzy set. The defuzzified value.

$x^*$  is

$$x^* = \frac{\sum_{i=1}^n x_i \cdot \sum_{k=1}^n \tilde{\mu}_{A_k}^{(x_i)}}{\sum_{i=1}^n \sum_{k=1}^n \tilde{\mu}_{A_k}^{(x_i)}}$$

(S)

## Fuzzy If-Then-Else

### Fuzzy propositions:-

A fuzzy proposition is a statement which acquires a fuzzy truth value.

Thus, given  $\tilde{P}$  to to a fuzzy proposition,  $T(\tilde{P})$  represents a truth value (0-1). attached to  $\tilde{P}$ .

Fuzzy propositions are associated with fuzzy sets.

The fuzzy membership value associated with the fuzzy set  $\tilde{A}$  for  $\tilde{P}$  is treated as the fuzzy truth value  $T(\tilde{P})$ .

if,  $T(\tilde{P}) = \mu_{\tilde{A}}^{(x)}$  - where  $0 \leq \mu_{\tilde{A}}^{(x)} \leq 1$ .

### Example :-

$\tilde{P}$  : Ram is honest

$T(\tilde{P}) = 0.8$ , if  $\tilde{P}$  is partially true.

$T(\tilde{P}) = 1$ , if  $\tilde{P}$  is absolutely true.

### Fuzzy connectives:-

(i) Negation : —

(ii) Disjunction : ∨

(iii) Conjunction : ∧

(iv) Implication :  $\Rightarrow$

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Ex:- Let  $\tilde{P}$ ,  $\tilde{Q}$  are fuzzy propositions and  $T(\tilde{P})$ ,  $T(\tilde{Q})$  are their truth values.

symbol	connective	usage	definition
-	Negation	$\tilde{P}^c$	$1 - T(\tilde{P})$
$\vee$	Disjunction	$\tilde{P} \vee \tilde{Q}$	$\max[T(\tilde{P}), T(\tilde{Q})]$
$\wedge$	Conjunction	$\tilde{P} \wedge \tilde{Q}$	$\min[T(\tilde{P}), T(\tilde{Q})]$
$\Rightarrow$	Implication	$\tilde{P} \Rightarrow \tilde{Q}$	$\tilde{P}^c \vee \tilde{Q} = \max(1 - T(\tilde{P}), T(\tilde{Q}))$

$\tilde{P}$  &  $\tilde{Q}$  related by the  $\Rightarrow$  operator are known as antecedent and consequent respectively.

$\Rightarrow$  represents the If-THEN statement as If  $x$  is  $A$  THEN  $y$  is  $B$ , is equivalent to

$$\tilde{R} = (A \tilde{x} B) \cup (\tilde{A} \tilde{x} y)$$

The membership fun. of  $\tilde{R}$  is given by

$$M_{\tilde{R}}^{(x,y)} = \max \left[ \min(M_A^{(x)}, M_B^{(y)}), 1 - M_A^{(x)} \right]$$

(69)

Ex:- 1

$\tilde{P}$ : Mary is efficient.  $T(\tilde{P}) = 0.8$

$\tilde{Q}$ : Ram is efficient,  $T(\tilde{Q}) = 0.65$

(i)  $\tilde{P}^c$ : Mary is not efficient

$$T(\tilde{P}^c) = 1 - T(\tilde{P}) = 1 - 0.8 = 0.2$$

(ii)  $\tilde{P} \wedge \tilde{Q}$ : Mary is efficient and so is Ram.

$$\begin{aligned} T(\tilde{P} \wedge \tilde{Q}) &= \min(T(\tilde{P}), T(\tilde{Q})) \\ &= \min(0.8, 0.65) \\ &= 0.65 \end{aligned}$$

(iii)  $T(\tilde{P} \vee \tilde{Q})$ : Either Mary or Ram is efficient

$$\begin{aligned} T(\tilde{P} \vee \tilde{Q}) &= \max(T(\tilde{P}), T(\tilde{Q})) \\ &= \max(0.8, 0.65) \\ &= 0.8 \end{aligned}$$

(iv)  $\tilde{P} \Rightarrow \tilde{Q}$ : If Mary is efficient then so is Ram

$$\begin{aligned} T(\tilde{P} \Rightarrow \tilde{Q}) &= \max(1 - T(\tilde{P}), T(\tilde{Q})) \\ &= \max(1 - 0.8, 0.65) \\ &= \max(0.2, 0.65) \\ &= 0.65 \end{aligned}$$

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Ex:2 :- Let  $X = [a, b, c, d]$

$$Y = [1, 2, 3, 4]$$

and  $\tilde{A} = [(a, 0), (b, 0.8), (c, 0.6), (d, 1)]$

$$\tilde{B} = \{(1, 0.2), (2, 1), (3, 0.8), (4, 0)\}$$

$$\tilde{C} = \{(1, 0), (2, 0.4), (3, 1), (4, 0.8)\}$$

Determine the implication relations.

(i) If  $x$  is  $\tilde{A}$  THEN  $y$  is  $\tilde{B}$ .

(ii) If  $x$  is  $\tilde{A}$  THEN  $y$  is  $\tilde{B}$  ELSE  $y$  is  $\tilde{C}$

$\Rightarrow$

(i) compute  
 $\tilde{R} = (\tilde{A} \times \tilde{B}) \cup (\tilde{A} \times Y)$  where.

$$\mu_{\tilde{R}}^{(x,y)} = \max(\min(\mu_{\tilde{A}}^{(x)}, \mu_{\tilde{B}}^{(y)}), 1 - \mu_{\tilde{A}}^{(x)})$$

$\tilde{A} \times \tilde{B} = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} a \\ b \\ c \\ d \end{matrix} & \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0.2 & 0.8 & 0.8 & 0 \\ 0.2 & 0.6 & 0.6 & 0 \\ 0.2 & 1 & 0.8 & 0 \end{bmatrix} \end{matrix}$  ,  $\tilde{A} \times Y = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} a \\ b \\ c \\ d \end{matrix} & \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0.2 & 0.2 & 0.2 & 0.2 \\ 0.4 & 0.4 & 0.4 & 0.4 \\ 0 & 0 & 0 & 0 \end{bmatrix} \end{matrix}$

Here  $y$  could be viewed as

$\{(1, 1), (2, 1), (3, 1), (4, 1)\}$  a fuzzy set all of whose elements  $x$  have  $\mu(x)=1$

$\therefore \tilde{R} = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} a \\ b \\ c \\ d \end{matrix} & \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0.2 & 0.8 & 0.8 & 0.2 \\ 0.4 & 0.6 & 0.6 & 0.4 \\ 0.2 & 1 & 0.8 & 0 \end{bmatrix} \end{matrix}$  This represents  
 $\rightarrow$  If  $x$  is  $\tilde{A}$  THEN  $y$  is  $\tilde{B}$ .

(7)

(ii) compute

$$\tilde{R} = (\tilde{A} \times \tilde{B}) \cup (\tilde{A}^c \times \tilde{C}) \text{ where.}$$

$$\mu_{\tilde{R}}(x, y) = \max \left[ \min \left( \mu_{\tilde{A}}^{(x)}, \mu_{\tilde{B}}^{(y)} \right), \min \left( 1 - \mu_{\tilde{A}}^{(x)}, \mu_{\tilde{C}}^{(y)} \right) \right]$$

$$\tilde{A} \times \tilde{B} = \begin{matrix} & a \\ & b \\ & c \\ & d \end{matrix} \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0.2 & 0.8 & 0.8 & 0 \\ 0.2 & 0.6 & 0.6 & 0 \\ 0.2 & 1 & 0.8 & 0 \end{bmatrix}_{1 \ 2 \ 3 \ 4}$$

$$\tilde{A}^c \times \tilde{C} = \begin{matrix} & a \\ & b \\ & c \\ & d \end{matrix} \begin{bmatrix} 0 & 0.4 & 1 & 0.8 \\ 0 & 0.2 & 0.2 & 0.2 \\ 0 & 0.4 & 0.4 & 0.4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Therefore

$$\tilde{R} = \max \left( (\tilde{A} \times \tilde{B}), (\tilde{A}^c \times \tilde{C}) \right)$$

$$\tilde{R} = \begin{matrix} & a \\ & b \\ & c \\ & d \end{matrix} \begin{bmatrix} 0 & 0.4 & 1 & 0.8 \\ 0.2 & 0.8 & 0.8 & 0.2 \\ 0.2 & 0.6 & 0.6 & 0.4 \\ 0.2 & 1 & 0.8 & 0 \end{bmatrix}_{1 \ 2 \ 3 \ 4}$$

The above  $\tilde{R}$  represents  
If  $x$  is  $\tilde{A}$  THEN  $y$  is  $\tilde{B}$  ELSE  $y$  is  $\tilde{C}$ .

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## Fuzzy Inferences (Approximate reasoning)

Refers to computational procedures used for evaluating linguistic descriptions.

Two important inferring procedures are -

(i) Generalised modus Ponens (GMP)

(ii) Generalised modus Tollens (GMT).

i) GMP is stated as -

IF  $x$  is  $\tilde{A}$  THEN  $y$  is  $\tilde{B}$

$$\rightarrow \frac{x \text{ is } \tilde{A}^{\text{if}}}{y \text{ is } \tilde{B}^{\text{then}}}$$

Here  $\tilde{A}, \tilde{B}, \tilde{A}^{\text{if}}, \tilde{B}^{\text{then}}$  are fuzzy terms.

Every fuzzy linguistic statement above the line is analytically known and what is below is analytically unknown.

To compute the membership function of  $\tilde{B}'$  the min-max composition of fuzzy set  $\tilde{A}'$  with  $\tilde{R}(x, y)$  which is known implication relation (IF-THEN) relation is used. that is

$$\tilde{B}' = \tilde{A}' \odot \tilde{R}(x, y)$$

$$\text{i.e., } \mu_{\tilde{B}'}^{(y)} = \max \left( \min \left( \mu_{\tilde{A}'}^{(x)}, \mu_{\tilde{R}}^{(x, y)} \right) \right)$$

where,  $\mu_{\tilde{A}'}^{(x)}$  is mf of  $\tilde{A}'$ ,  $\mu_{\tilde{R}}^{(x, y)}$  is mf of implication relation &  $\mu_{\tilde{B}'}^{(y)}$  is mf of  $\tilde{B}'$ .

(ii) GmT has the form.

IF  $x$  is  $\tilde{A}$  THEN  $y$  is  $\tilde{B}$ .

$$\rightarrow \frac{y \text{ is } \tilde{B}'}{x \text{ is } \tilde{A}'}$$

The membership of  $\tilde{A}'$  is computed as

$$\tilde{A}' = \tilde{B}' \odot R(x, y)$$

$$\text{if } \mu_{\tilde{A}'}^{(x)} = \max \left[ \min(\mu_{\tilde{B}'}^{(y)}, \mu_R^{(x,y)}) \right]$$

— o —

Ex:- Apply the fuzzy modus Ponens rule to deduce Rotation is quite slow. given

(i) If the temp. is high then the rotation is slow.

(ii) The temp. is very very high.

Let  $\tilde{H}$  (High),  $\tilde{VH}$  (very high),  $\tilde{S}$  (slow) and  $\tilde{QS}$  (quite slow) indicates the associated fuzzy set as follows.

for  $X = \{30, 40, 50, 60, 70, 80, 90, 100\}$  the set of temperatures

and  $y = \{10, 20, 30, 40, 50, 60\}$  the <sup>set of</sup> rotation/min.

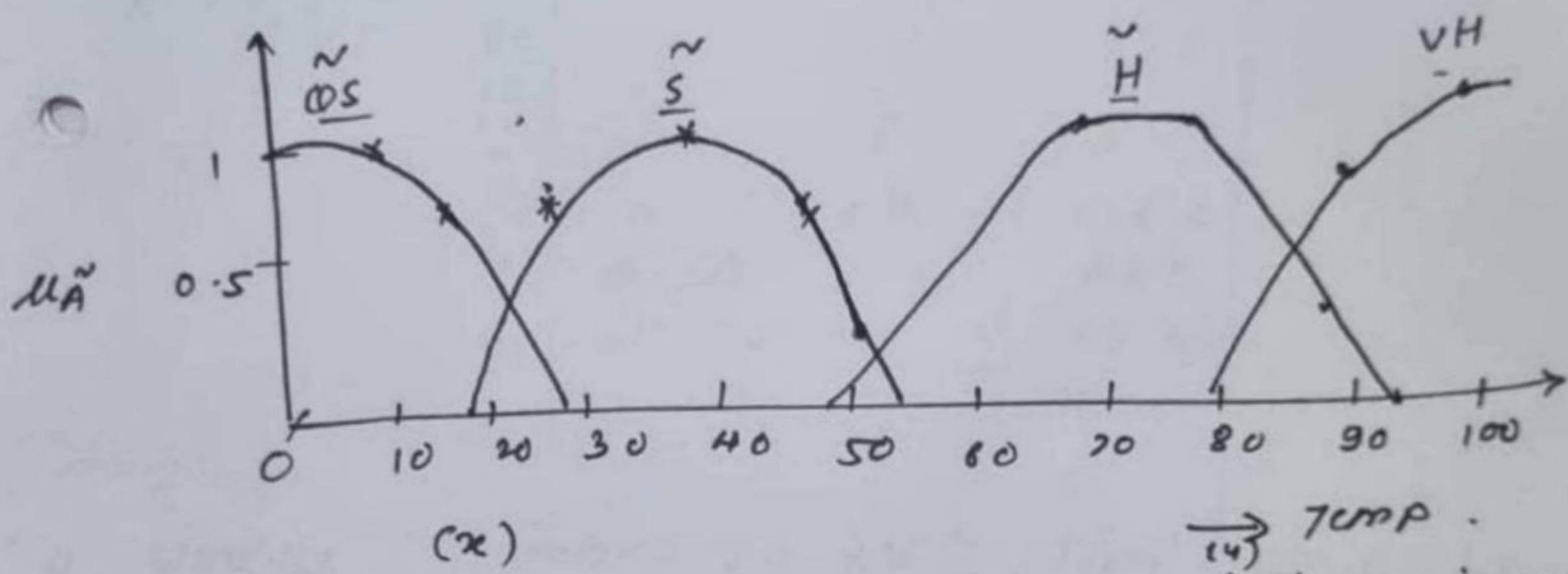
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$$\tilde{H} = \{(70, 1), (80, 1), (90, 0.3)\}$$

$$\tilde{V_H} = \{(90, 0.9), (100, 1)\}$$

$$\tilde{G_S} = \{(10, 1), (20, 0.8)\}$$

$$\tilde{S} = \{(30, 0.8), (40, 1), (50, 0.6)\}$$



(i) If the temp. is high then rotation is slow  
To derive  $\tilde{R}(x, y)$  representing the above implication relation.

$$\tilde{R}(x, y) = \max(\tilde{H} \times \tilde{S}, \tilde{H} \times \tilde{y})$$

$$\tilde{H} \times \tilde{S} = \begin{matrix} & \begin{matrix} 10 & 20 & 30 & 40 & 50 & 60 \end{matrix} \\ \begin{matrix} 30 \\ 40 \\ 50 \\ 60 \\ 70 \\ 80 \\ 90 \\ 100 \end{matrix} & \left[ \begin{matrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0.8 & 1 & 0.6 & 0 \\ 0 & 0 & 0.8 & 1 & 0.6 & 0 \\ 0 & 0 & 0.3 & 0.3 & 0.3 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{matrix} \right] \end{matrix}$$

(75)

$$\tilde{H}^C \times y =$$

	10	20	30	40	50	60
30	1	1	1	1	1	1
40	1	1	1	1	1	1
50	1	1	1	1	1	1
60	1	1	1	1	1	1
70	0	0	0	0	0	0
80	0	0	0	0	0	0
90	0.7	0.7	0.7	0.7	0.7	0.7
100	1	1	1	1	1	1

$$\tilde{R}^C(x, y) =$$

	10	20	30	40	50	60
30	1	1	1	1	1	1
40	1	1	1	1	1	1
50	1	1	1	1	1	1
60	1	1	1	1	1	1
70	0	0	0.8	1	0.6, 0	
80	0	0	0.8	1	0.6, 0	
90	0.7	0.7	0.7	0.7	0.7	0.7
100	1	1	1	1	1	1

To deduce Rotation is quite slow we make use of composition rule.

$$\hat{Q}^S = V \tilde{H} \circ R(x, y)$$

$$= [0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0.9 \ 1] \times$$

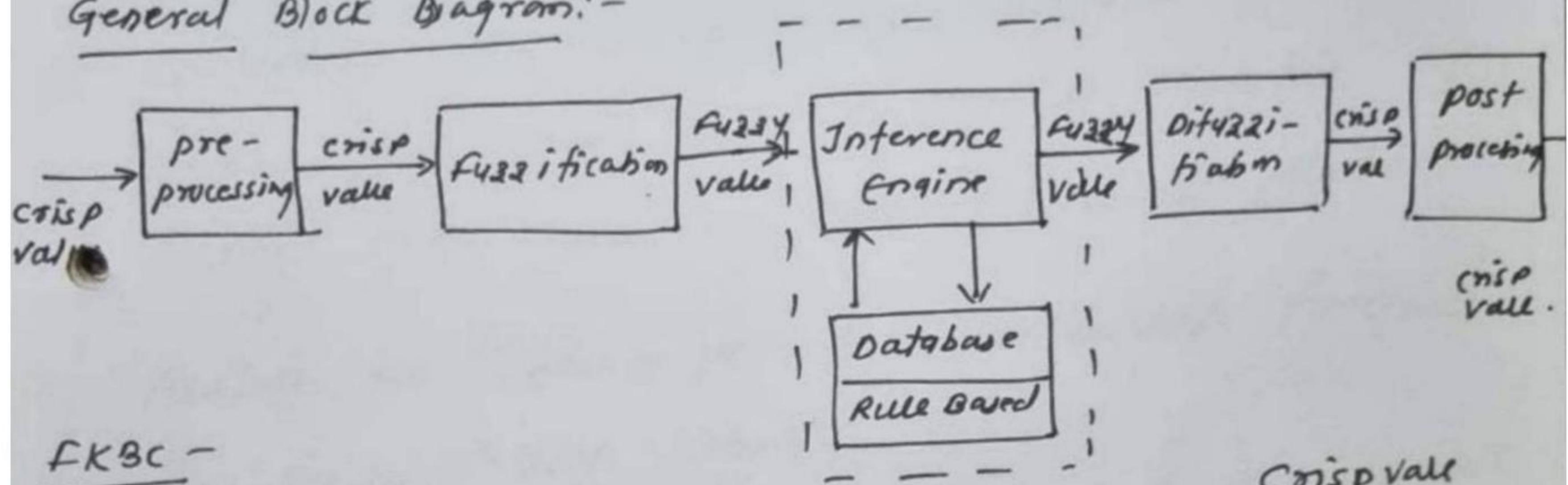
$$\begin{bmatrix} & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \end{bmatrix}$$

$$= [1 \ 1 \ 1 \ 1 \ 1 \ 1 \ 1]$$

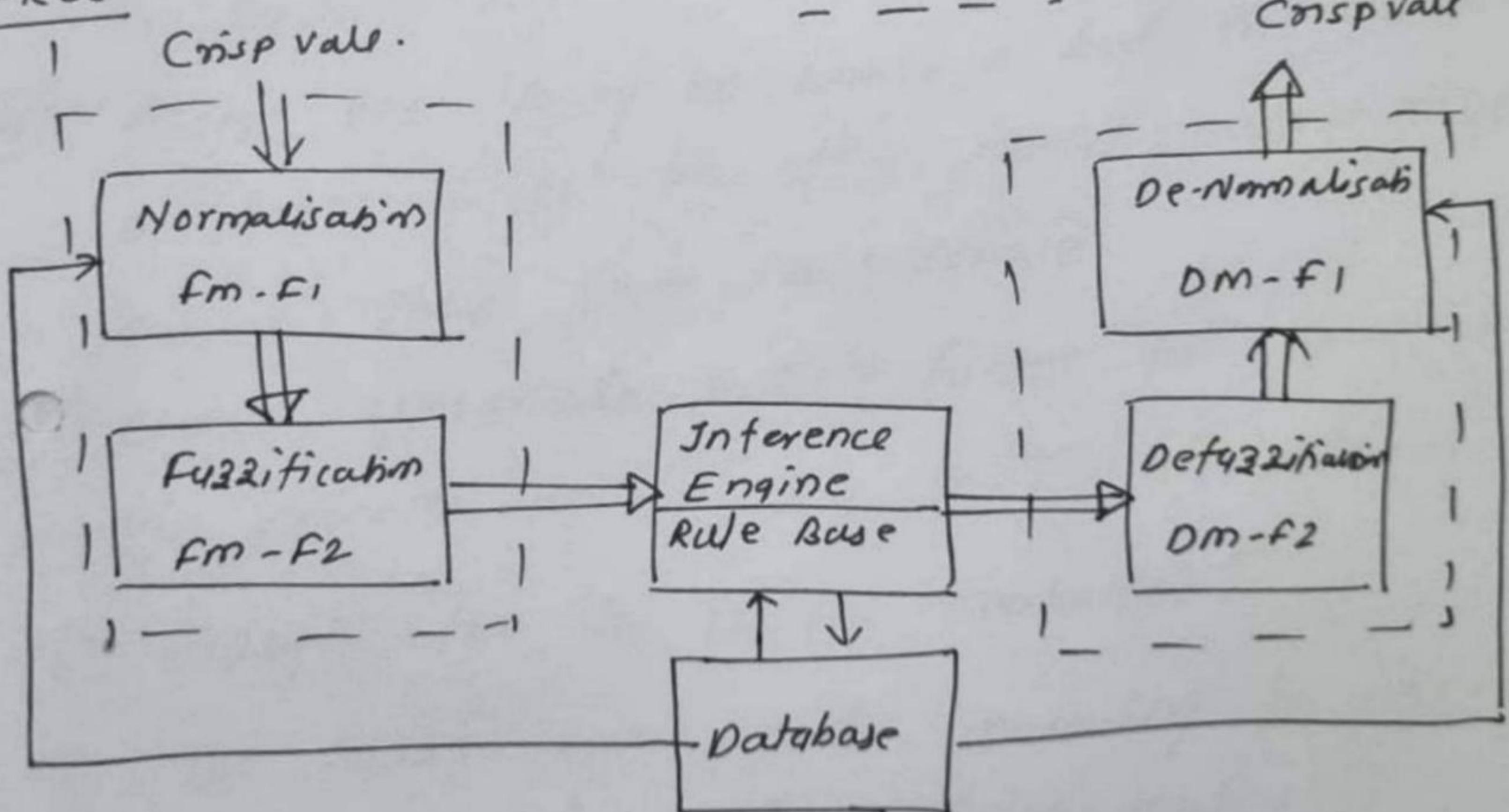
## Fuzzy control systems:-

FKBC - fuzzy knowledge based controllers.

### General Block Diagram:-



FKBC -



→ computational flow

→ information flow

fm-F1 — fuzzification Normalisation

Dm-F1 — diffuzzification Normalisation

Dm-F2 → Defuzzification modu.

## Steps for Designing FLC:-

- ① Identify the variables (input states & output) of the problem.
- ② Partition the universe of discourse or interval spanned by each variable into a number of fuzzy sets, assigning each linguistic label.
- ③ Assign or determine the membership functions for each fuzzy subsets.
- ④ Assign the fuzzy relationship bet<sup>n</sup> the inputs or fuzzy subsets on other hand output fuzzy subsets. Thus form a rulebase.
- ⑤ Choose appropriate scaling factor for input and o/p variables to  $[0 \text{ to } 1]$  or  $[-1, 1]$  interval.
- ⑥ fuzzify the I/P to the controller.
- ⑦ use fuzzy approximate reasoning to infer the o/p contributed from each rule.
- ⑧ Aggregate the fuzzy outputs recommended by each rule.
- ⑨ Apply defuzzification to form crisp o/p.