

# An Introduction to Statistical Depth Functions

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Satvik Saha

Supervised by Dr. Anirvan Chakraborty

12 December, 2023

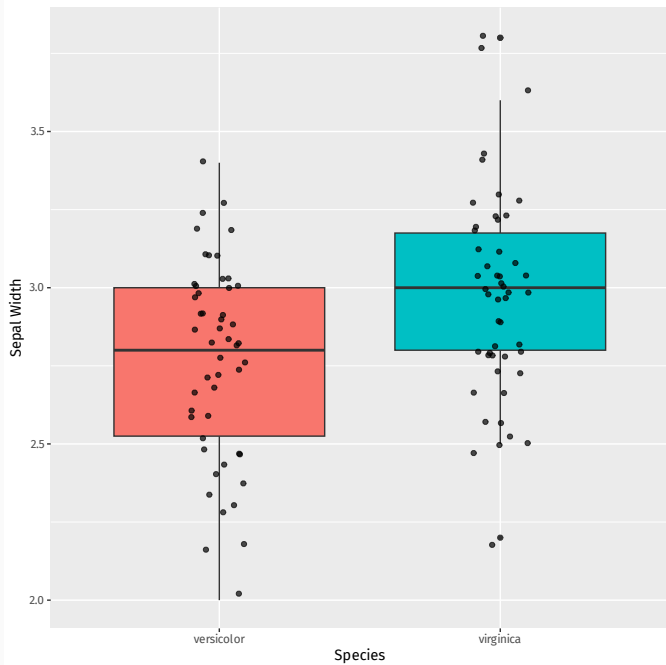
Department of Mathematics and Statistics,  
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# Outline

1. A two-sample testing problem
2. Depth Functions
3. The Depth-Depth plot
4. Depth based classification
5. Depth functions for Functional Data
6. Future work

## A two-sample testing problem

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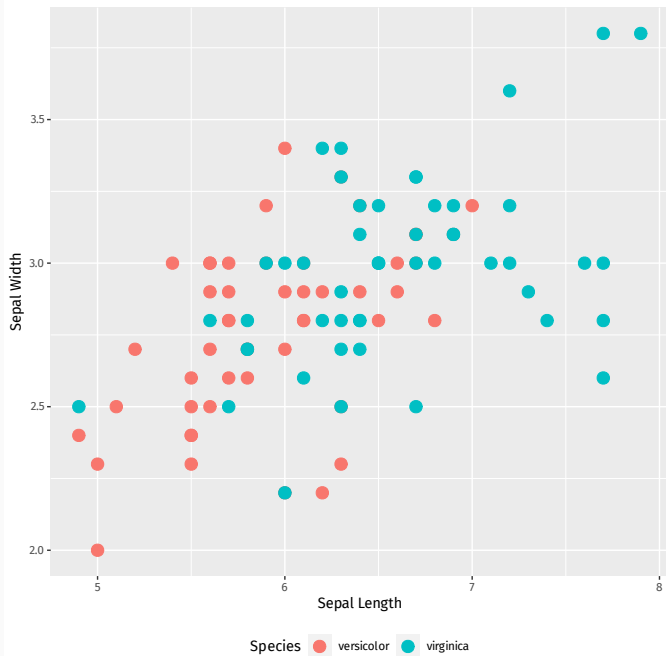


# Wilcoxon rank sum test

Given two random samples  $X_1, \dots, X_m$  and  $Y_1, \dots, Y_n$ , construct

$$W = \sum_j r(Y_j, \mathcal{D}_F \cup \mathcal{D}_G), \quad r(Y, \mathcal{D}) = \sum_{Z \in \mathcal{D}} \mathbf{1}(Z \leq Y).$$

This is *distribution free* under the null hypothesis that both samples have the same underlying distribution.



# A generalization for multivariate data

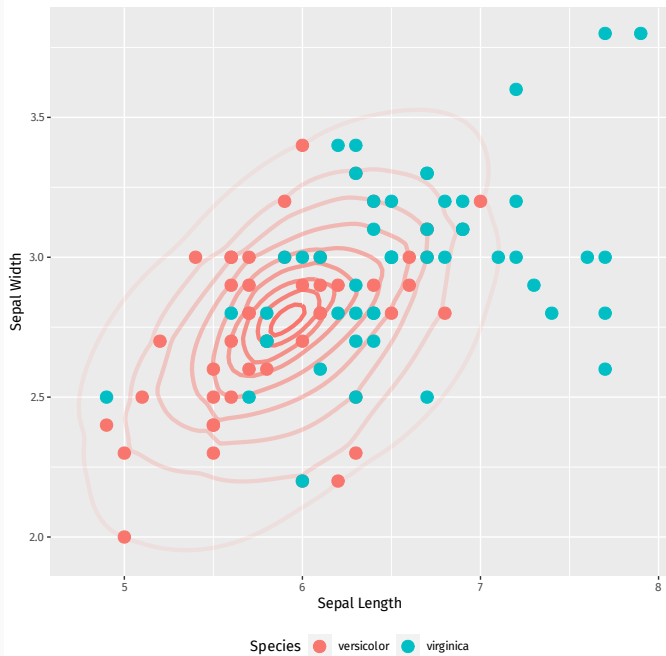
Given *multivariate* data, we wish to construct

$$W^* = \sum_j r(Y_j, \mathcal{D}_F \cup \mathcal{D}_G), \quad r^*(Y, \mathcal{D}) = \sum_{Z \in \mathcal{D}} \mathbf{1}(Z \text{ ?? } Y).$$

Furthermore, we want  $W^*$  to be able to detect differences in location and scale between  $F$  and  $G$ .

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Liu, R.Y., & Singh, K. (1993) A Quality Index Based on Data Depth and Multivariate Rank Tests.





How do we quantify this notion of centrality?

# Depth Functions

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# Depth Functions

A *depth function* quantifies how central a point  $x$  is with respect to a distribution  $F$ .

Points which are *more central* are said to be *deeper*.

This framework allows many rank based nonparametric techniques to be translated to a broader class of data, e.g. multivariate and functional data.

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# Some applications of depth functions

1. Inference procedures
  - Hypothesis tests
  - Rank tests
  - Multivariate quantiles
  - Confidence regions
2. Exploratory data analysis
3. Classification and clustering
4. Outlier detection

## Depth Functions in $\mathbb{R}^p$

Let  $D: \mathbb{R}^p \times \mathcal{F} \rightarrow \mathbb{R}$  be **bounded, non-negative, continuous**, and satisfy the following properties.

1. **Affine invariance:**  $D(A\mathbf{x} + b, F_{A\mathbf{x}+b}) = D(\mathbf{x}, F_X)$ .
2. **Maximality at centre:**  $D(\theta, F_X) = \sup_{\mathbf{x} \in \mathbb{R}^p} D(\mathbf{x}, F)$ .
3. **Monotonicity along rays:**  $D(\mathbf{x}, F) \leq D(\theta + \alpha(\mathbf{x} - \theta), F)$ .
4. **Vanish at infinity:**  $D(\mathbf{x}, F) \rightarrow 0$  as  $\|\mathbf{x}\| \rightarrow \infty$ .

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Zuo, Y., & Serfling, R. (2000) General notions of statistical depth function

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# Depth contours

The *region of depth  $d$*  is defined by

$$\mathcal{R}(d, F) = \{\mathbf{x} \in \mathbb{R}^p \mid D(\mathbf{x}, F) \geq d\}.$$

The boundary  $\partial\mathcal{R}(d, F)$  is called the *contour of depth  $d$* .

Define

$$R(\mathbf{x}, F) = P(D(Y, F) \geq D(\mathbf{x}, F) \mid Y \sim F).$$

Then, as long as  $D(\cdot, F)$  is continuous, the probability integral transform gives

$$R(X, F) \sim \text{Uniform}[0, 1].$$

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Liu, R.Y., Parelius, J.M., & Singh, K. (1999) Multivariate analysis by data depth: descriptive statistics, graphics and inference

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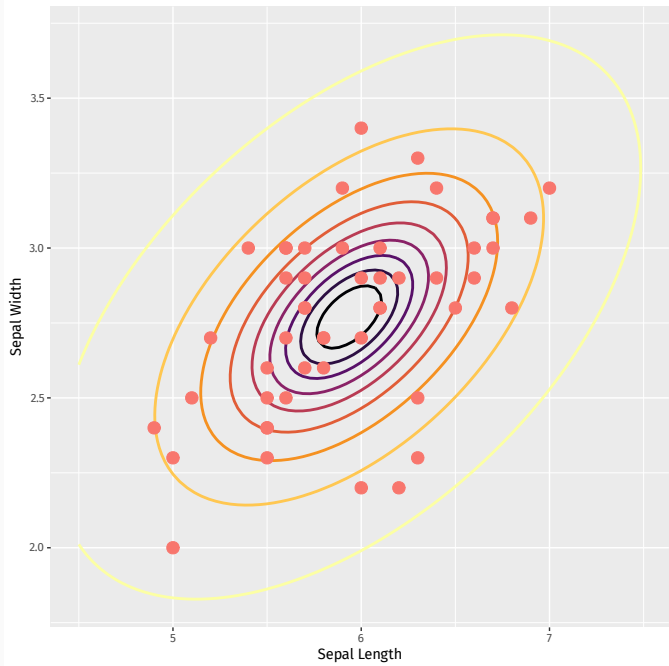
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Liu, R.Y., Parelius, J.M, & Singh, K. (1999) Multivariate analysis by data depth: descriptive statistics, graphics and inference

Produces elliptic contours, using the first two moments of the given distribution.

$$D_{Mh}(x, F) = \frac{1}{1 + (x - \mu)\Sigma^{-1}(x - \mu)}.$$

A robust version can be obtained by using MCD estimators.

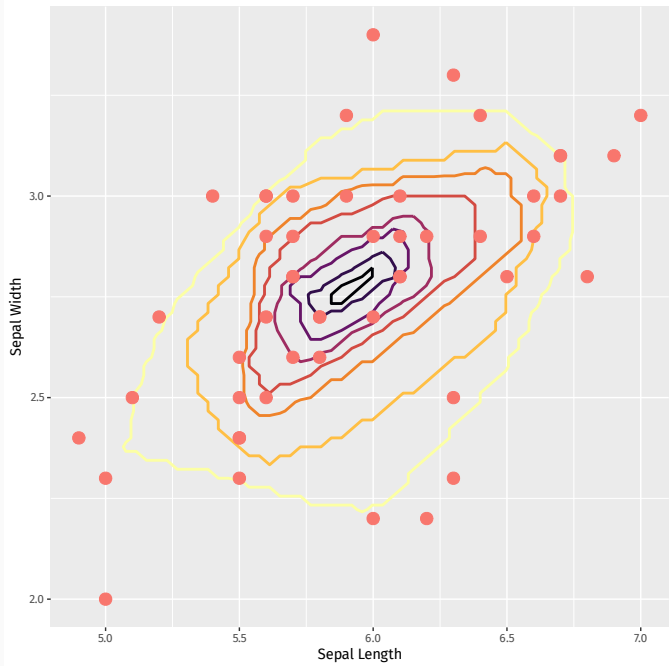




## Halfspace/Tukey depth

Given a point  $\mathbf{x} \in \mathbb{R}^p$ , examine all hyperplanes through  $\mathbf{x}$ , and find the halfspace with the least probability.

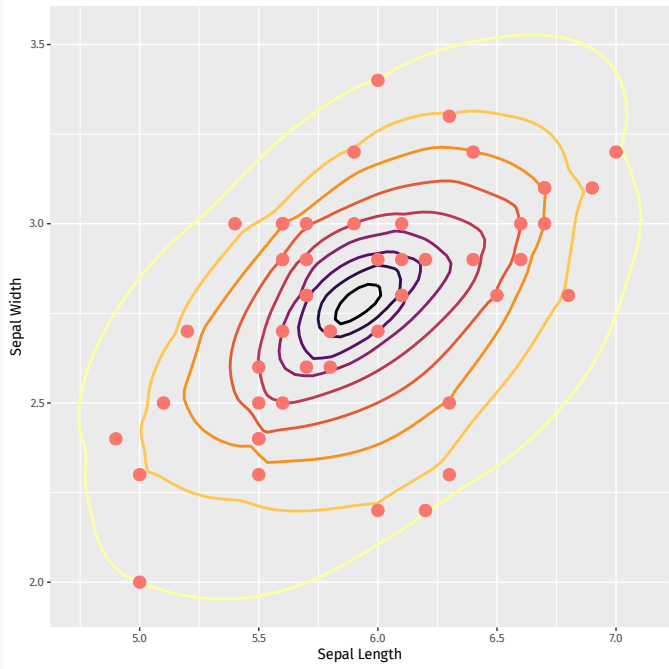
$$D_H(\mathbf{x}, F) = \inf_{\mathbf{v} \in \mathbb{R}^p \setminus \{0\}} P( \underbrace{\mathbf{v}^\top X \leq \mathbf{v}^\top \mathbf{x}}_{\substack{X \text{ is in a halfspace} \\ \text{through } \mathbf{x}}} ).$$



Examine the average of unit vectors pointing out of  $\mathbf{x}$ .

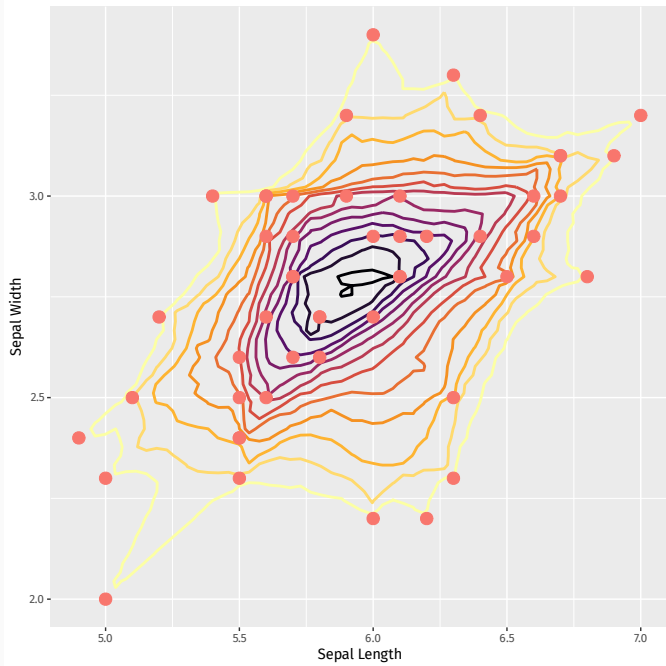
$$D_{Sp}(\mathbf{x}, F) = 1 - \left\| E \left[ \underbrace{\frac{X - \mathbf{x}}{\|X - \mathbf{x}\|}}_{\text{unit vector from } \mathbf{x} \text{ to } X} \right] \right\|.$$

Spatial depth is *not* always monotonic with respect to the deepest point.



Examine the probability of  $\mathbf{x}$  being contained in a random simplex.

$$D_S(x, F) = P(x \in \text{simplex}[X_1, \dots, X_{p+1}] \mid X_i \stackrel{iid}{\sim} F).$$



## Projection depth

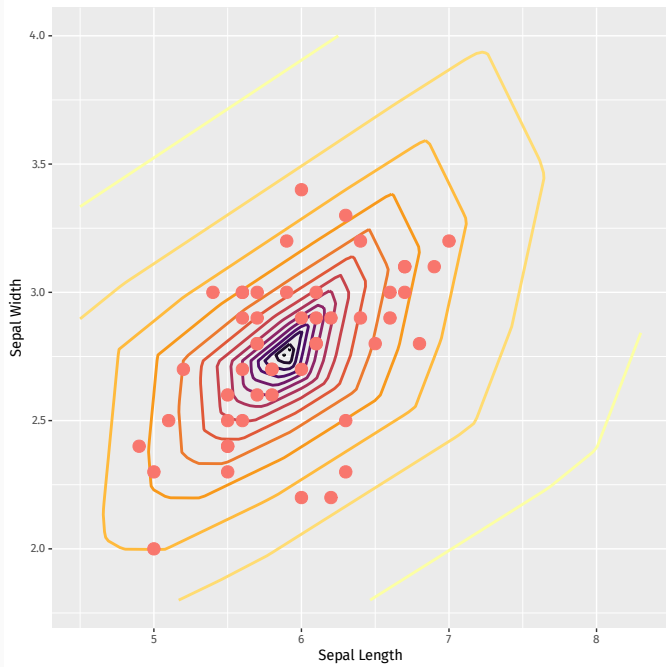
Examine the maximum outlyingness of  $\mathbf{x}$  with respect to projections.

$$D_P(x, F) = \left( 1 + \sup_{\|v\|=1} \frac{v^\top x - \mu(v^\top X)}{\sigma(v^\top X)} \right)^{-1}, \quad X \sim F.$$

A robust version can be defined as

$$D_P^*(x, F) = \left( 1 + \sup_{\|v\|=1} \frac{v^\top x - \text{median}(v^\top X)}{\text{MAD}(v^\top X)} \right)^{-1}, \quad X \sim F,$$

$$\text{MAD}(Y) = \text{median}(|Y - \text{median}(Y)|).$$





Why not use likelihood contours?

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The 'Curse of Dimensionality'.

## The Depth-Depth plot

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## Depth-Depth plots

Let  $F, G$  be two distributions on  $\mathbb{R}^p$ , and let  $D$  be a depth function. We construct the D-D plot

$$DD(F, G) = \{(D(\mathbf{x}, F), D(\mathbf{x}, G)) : \mathbf{x} \in \mathbb{R}^p\}.$$

Given data  $\mathcal{D}_F, \mathcal{D}_G$ , we may instead look at the D-D plot

$$DD(\hat{F}_m, \hat{G}_n) = \left\{ \left( D(\mathbf{x}, \hat{F}_m), D(\mathbf{x}, \hat{G}_n) \right) : \mathbf{x} \in \mathcal{D}_F \cup \mathcal{D}_G \right\}.$$

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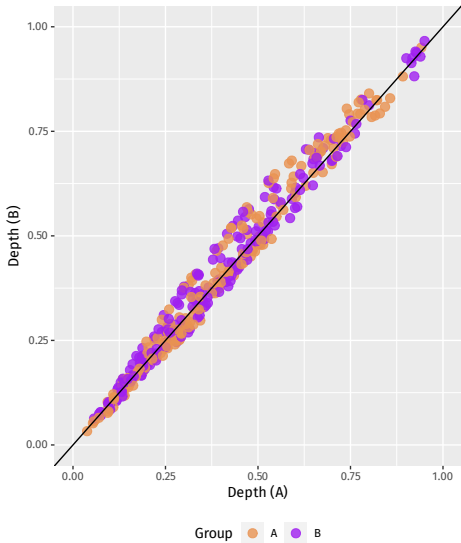
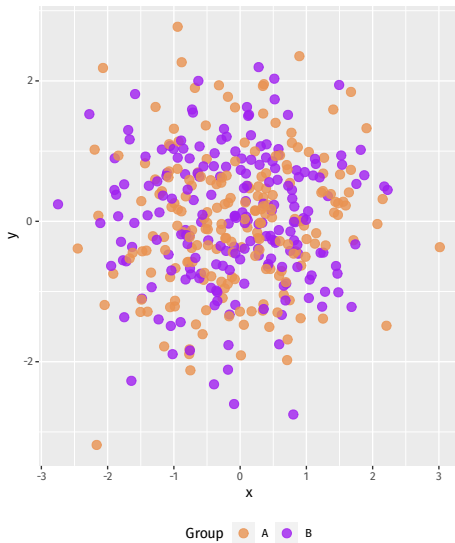
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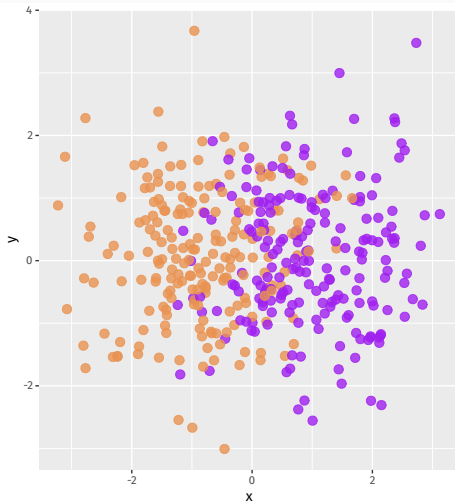
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Liu, R.Y., Parelius, J.M, & Singh, K. (1999) Multivariate analysis by data depth: descriptive statistics, graphics and inference

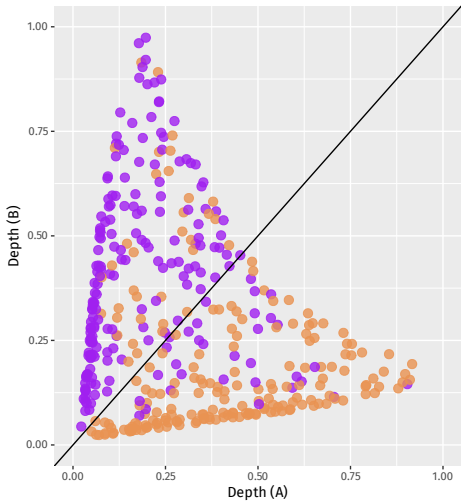
# Identical distributions



# Location difference



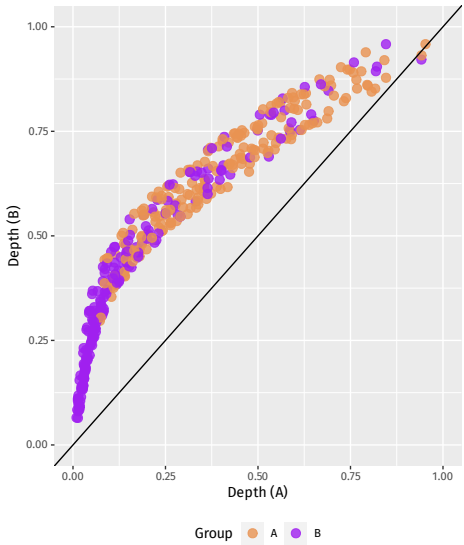
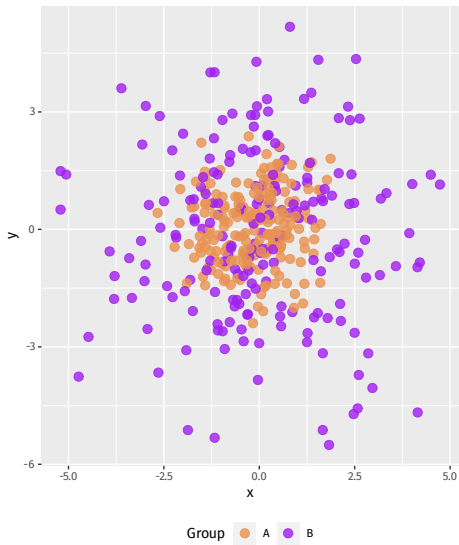
Group ● A ● B



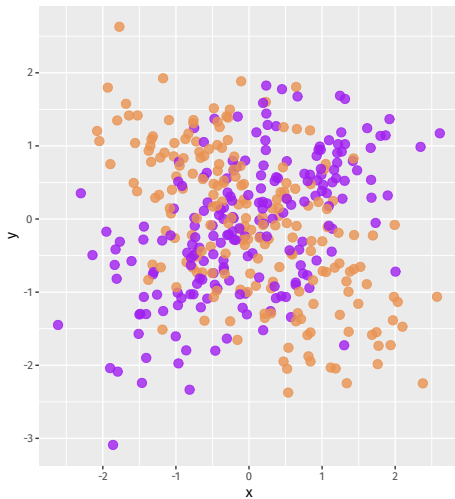
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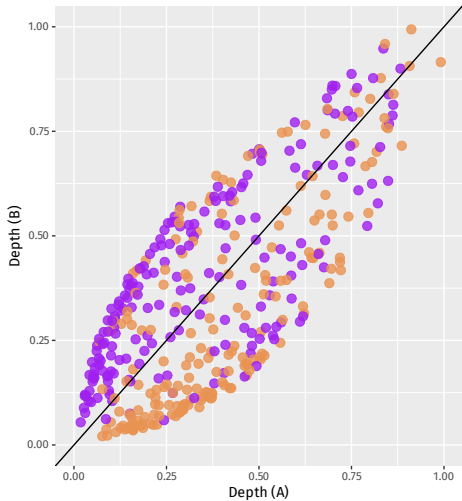
# Scale difference



# Scale difference

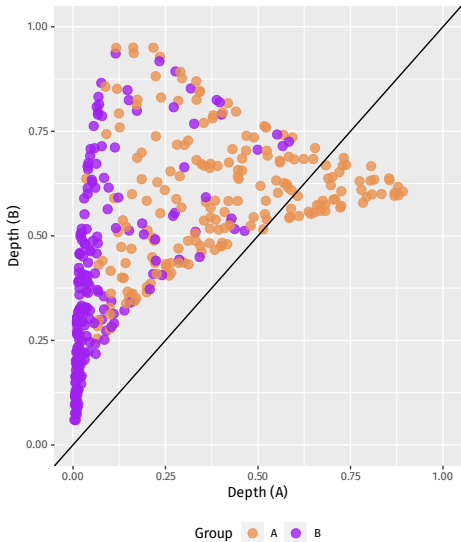
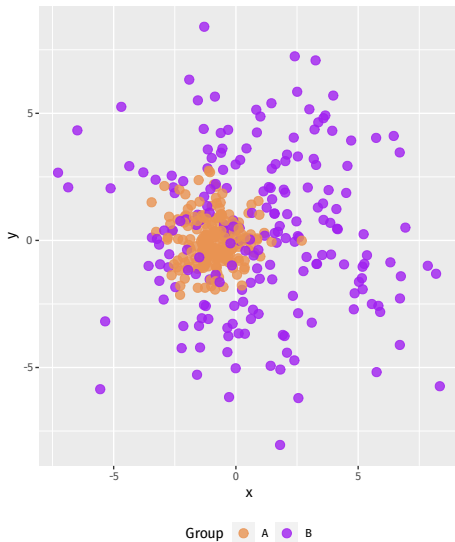


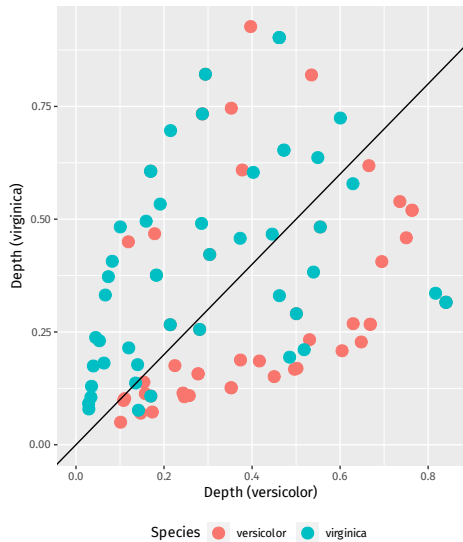
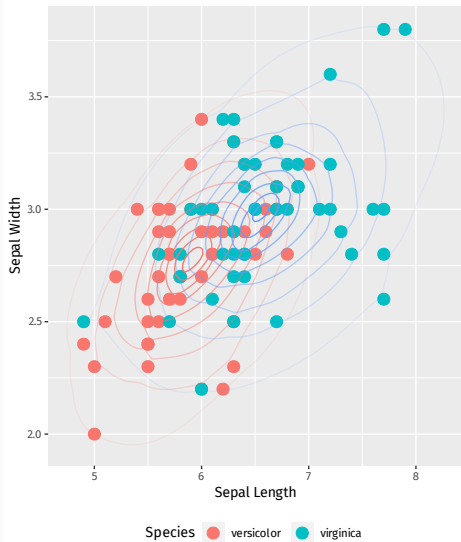
Group ● A ● B

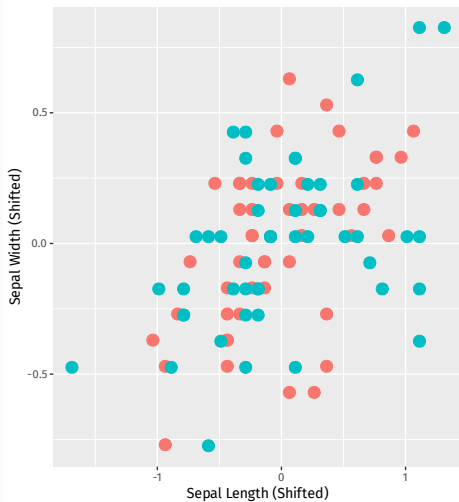


Group ● A ● B

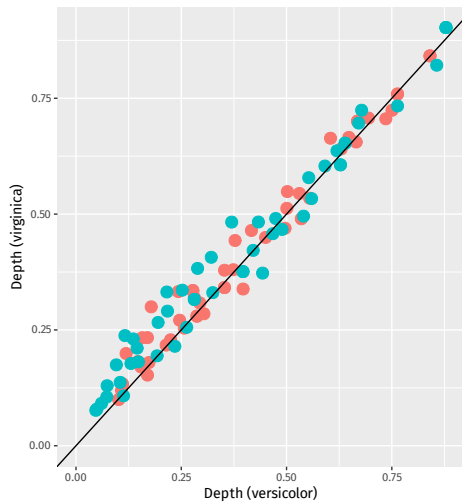
# Location and scale difference







Species ● versicolor ● virginica



Species ● versicolor ● virginica

## Depth based classification

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# Maximum depth classifiers

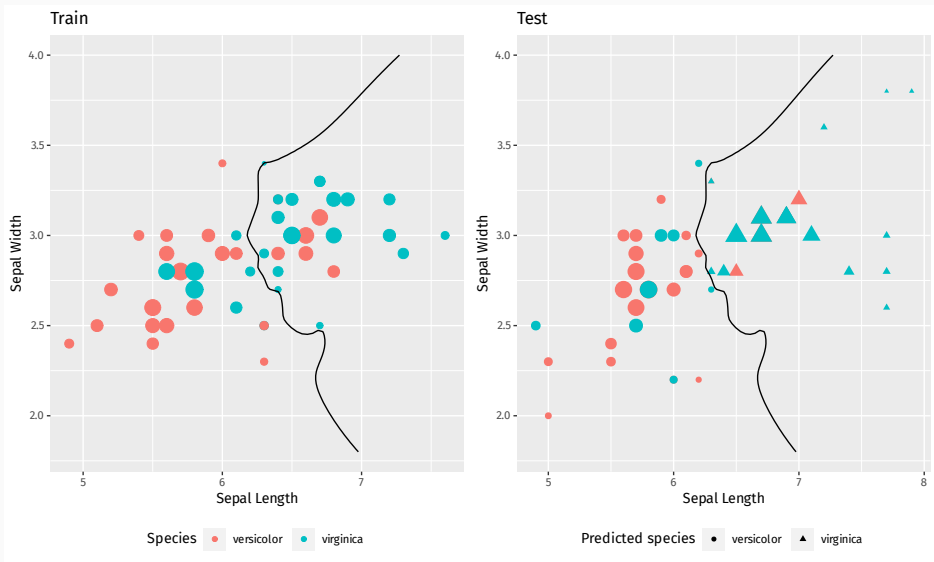
Given a point  $\mathbf{x} \in \mathbb{R}^p$ , assign it to the class with respect to which it has maximum depth. In other words, choose

$$\hat{k}(\mathbf{x}) = \arg \max_j D(\mathbf{x}, \hat{F}_j).$$

Under certain conditions, this asymptotically performs on par with the Bayes classifier.

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Ghosh, A.K., & Chaudhuri, P. (2005) On maximum depth and related classifiers

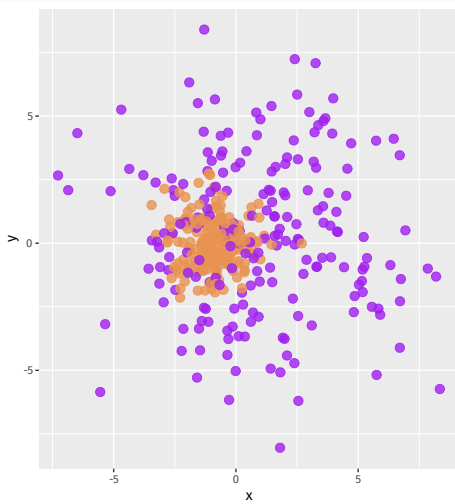




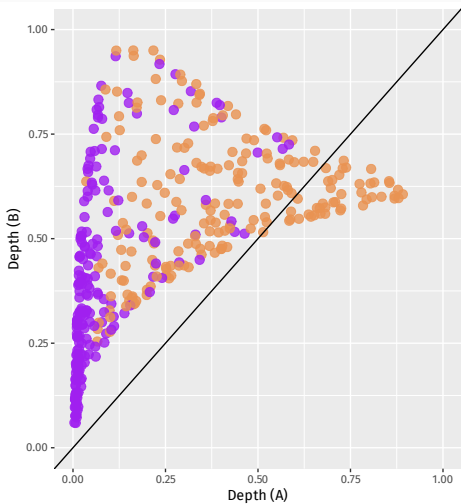
The *relative data depth*

$$\text{ReD}(\mathbf{x}) = D(\mathbf{x}, \hat{F}_{\hat{k}(\mathbf{x})}) - \max_{j \neq \hat{k}(\mathbf{x})} D(\mathbf{x}, \hat{F}_j)$$

gives a measure of confidence in the classification of  $\mathbf{x}$ .



Group ● A ● B



Group ● A ● B

# Depth-Depth classifiers

Given data  $\mathcal{D}_F, \mathcal{D}_G$ , look at the D-D plot

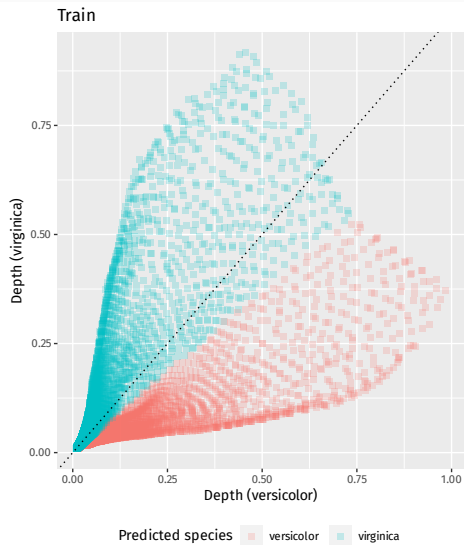
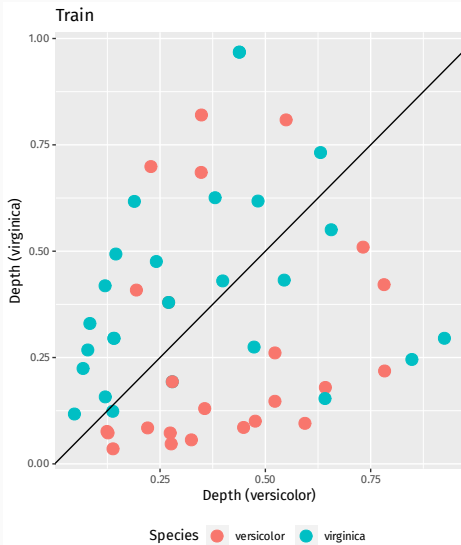
$$DD(\hat{F}_m, \hat{G}_n) = \left\{ \left( D(\mathbf{x}_i, \hat{F}_m), D(\mathbf{x}_i, \hat{G}_n) \right) : \mathbf{x}_i \in \mathcal{D}_F \cup \mathcal{D}_G \right\},$$

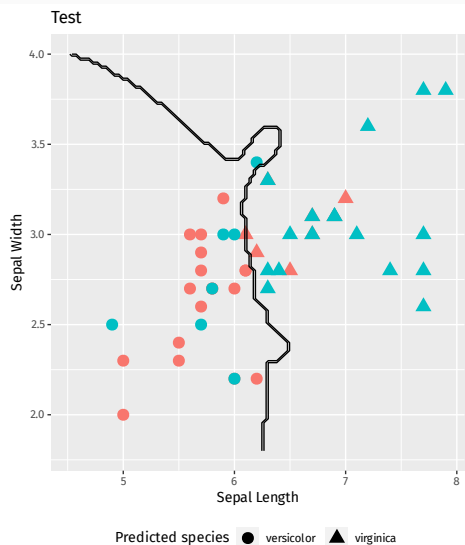
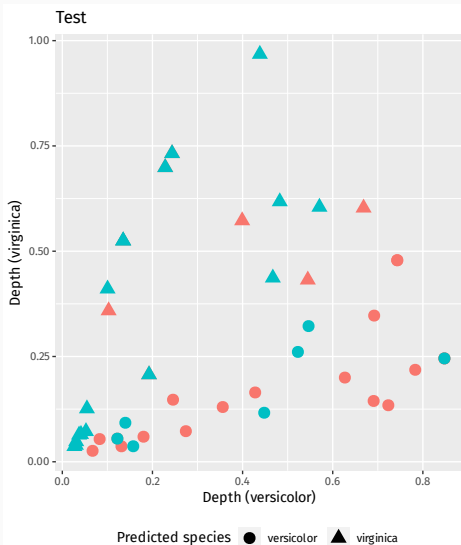
and find a function  $\phi$  which separates points from the two classes.

For  $\mathbf{x} \in \mathbb{R}^p$ , check which region the point  $(D(\mathbf{x}, \hat{F}_m), D(\mathbf{x}, \hat{G}_n))$  lies in, and assign it to the corresponding class.

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Li, J., Cuestas-Albertos, J.A., & Liu, R.Y. (2012) DD-Classifier: Nonparametric Classification Procedure Based on DD-Plot





# Elliptic distributions

Suppose that the underlying population distributions are elliptic, i.e. their density functions are of the form

$$C_i |\Sigma_i|^{-1/2} h_i \left( (x - \mu_i)^\top \Sigma_i^{-1} (x - \mu_i) \right)$$

for strictly decreasing functions  $h_i$ . Then, the *Mahalanobis*, *simplicial*, and *projection* depths  $D(\cdot, F_i)$  are strictly increasing functions of the respective densities.

Thus, the Bayes rule involves comparing  $\phi(D(x, F))$  and  $D(x, G)$  for some strictly increasing function  $\phi$ .

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Li, J., Cuestas-Albertos, J.A., & Liu, R.Y. (2012) DD-Classifer: Nonparametric Classification Procedure Based on DD-Plot

# Depth functions for Functional Data

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# Integrated, infimal, and random projection depths

$$D_{int}(X, F_X) = \int_T D(X(t), F_{X(t)}) w(t) dt.$$

$$D_{inf}(X, F_X) = \inf_{t \in T} D(X(t), F_{X(t)}).$$

$$D_{RP}(X, F_X) = \inf_{\phi} D(\langle X, \phi \rangle, F_{\langle X, \phi \rangle}).$$

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Gijbels, I., & Nagy, S. (2017) On a General Definition of Depth for Functional Data



# Outlyingness matrices

Given a random  $p$ -variate function  $X$ , define a pointwise outlyingness function as

$$\mathbf{O}(X(t), F_{X(t)}) = \left[ \frac{1}{D(X(t), F_{X(t)})} - 1 \right] \cdot \mathbf{v}(t).$$

With this, define

$$\begin{aligned}\mathbf{MO}(X, F_X) &= \int_T \mathbf{O}(X(t), F_{X(t)}) w(t) dt, \\ \mathbf{VO}(X, F_X) &= \int_T \|\mathbf{O}(X(t), F_{X(t)}) - \mathbf{MO}(X, F_X)\|^2 w(t) dt.\end{aligned}$$

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Dai, W., & Genton, M.G. (2018) An outlyingness matrix for multivariate functional data classification

# Outlyingness matrices

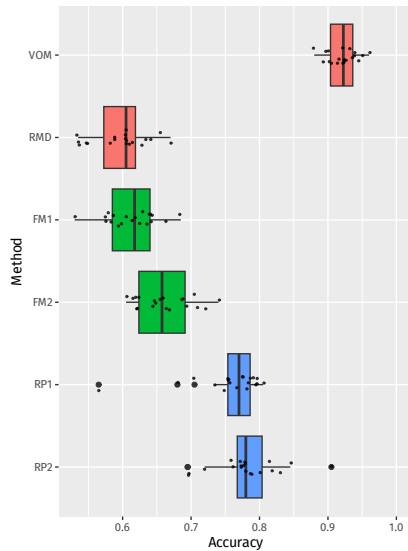
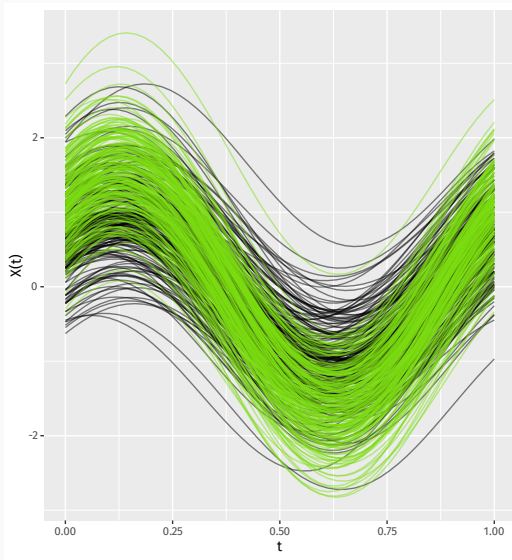
Furthermore, denoting

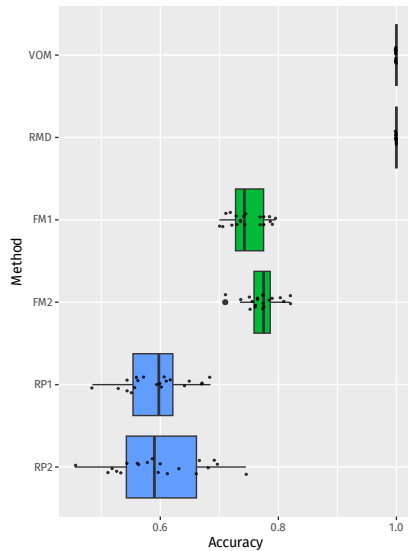
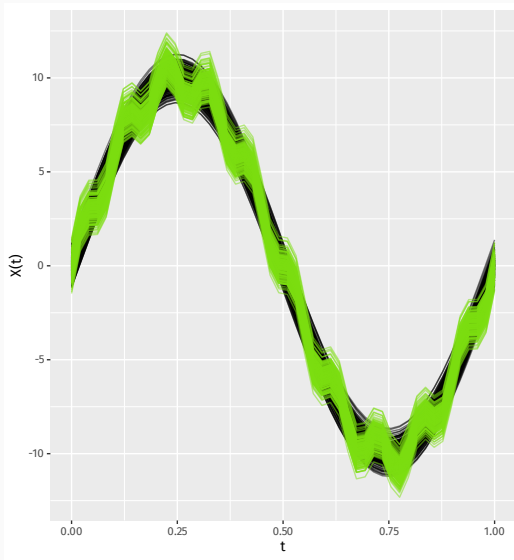
$$\tilde{\mathbf{O}}(X(t), F_{X(t)}) = \mathbf{O}(X(t), F_{X(t)}) - \mathbf{MO}(X, F_X),$$

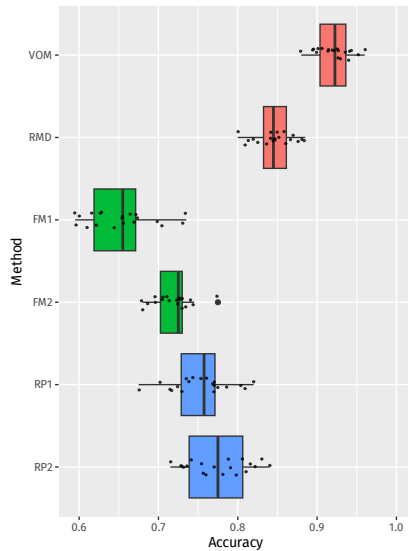
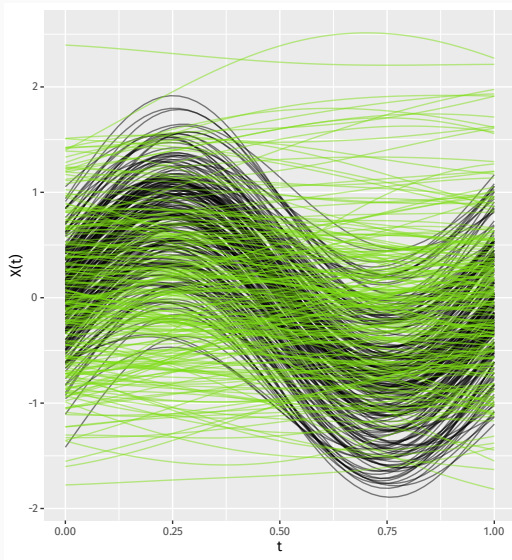
define the *variational outlyingness matrix*

$$\mathbf{VOM}(X, F_X) = \int_T \tilde{\mathbf{O}}(X(t), F_{X(t)}) \tilde{\mathbf{O}}(X(t), F_{X(t)})^\top w(t) dt.$$

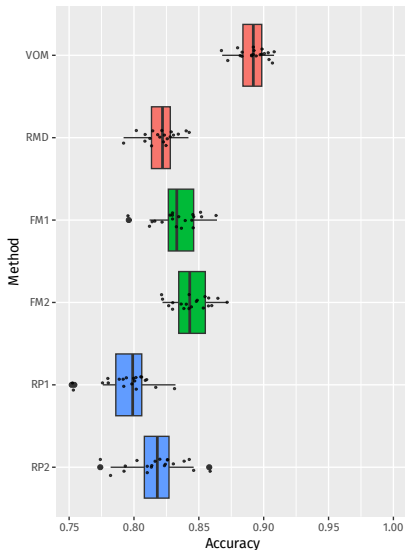
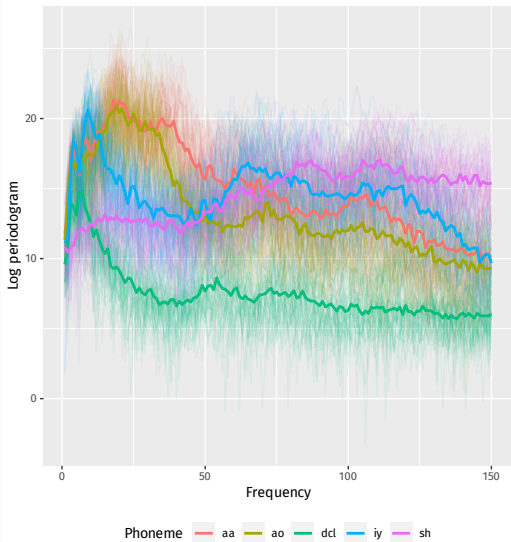
Use either the feature vector  $(\mathbf{MO}^\top, \mathbf{VO})^\top$  or  $\|\mathbf{VOM}\|$  for classification.







# Phonemes in digitized speech

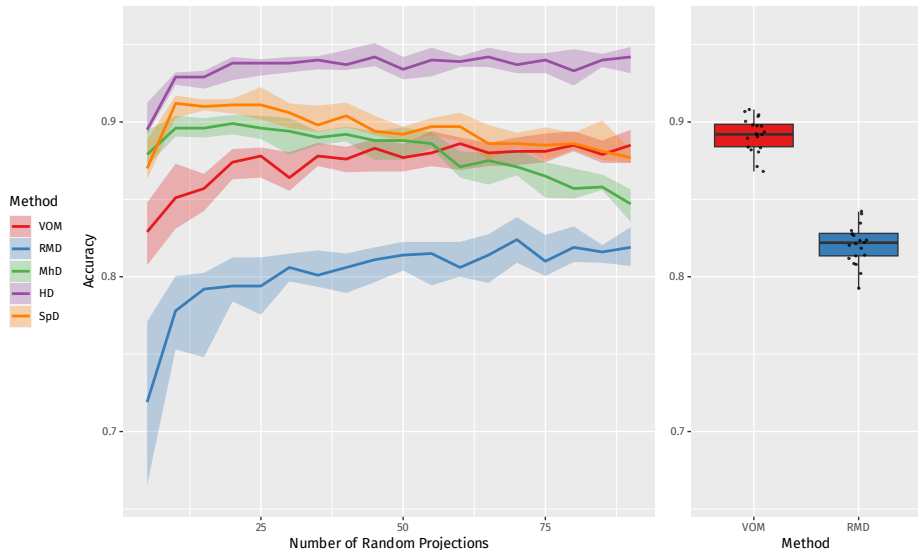


## Functional $\rightarrow$ Multivariate, via random projections

Replace  $\{X(t)\}_{t \in T}$  with  $\{\langle X, \phi_j \rangle\}_{j=1}^{\ell}$ , where  $\phi_1, \dots, \phi_{\ell}$  are random functions and

$$\langle X, \phi \rangle = \int_T \langle X(t), \phi(t) \rangle w(t) dt.$$

# Phonemes in digitized speech revisited





Do depth functions completely characterize  
probability distributions?

Do depth functions completely characterize  
probability distributions?

Sometimes!

# Halfspace depth revisited

The halfspace depth characterizes discrete probability distributions, i.e. if  $D_H(\cdot, P) = D_H(\cdot, Q)$  and one of  $P, Q$  is discrete, then  $P = Q$ .

The halfspace depth also characterizes elliptic probability distributions.

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Cuesta-Albertos, J.A., & Nieto-Reyes, A. (2008) The Tukey and the random Tukey depths characterize discrete distributions

Kong, L., & Zuo, Y. (2010) Smooth depth contours characterize the underlying distribution

## A counterexample

Consider  $X \sim P, Y \sim Q$  where

$$\psi_X(\mathbf{t}) = \exp(-\|\mathbf{t}\|_1^{1/2}), \quad \psi_Y(\mathbf{t}) = \exp(-\|\mathbf{t}\|_{1/2}^{1/2}).$$

Observe that the *marginals* of  $X$  and  $Y$  are identically distributed!

This is because they have the same characteristic function,

$$\psi(t) = \exp(-|t|^{1/2}).$$

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Nagy, S. (2021) Halfspace depth does not characterize probability distributions

## A counterexample

Next, if  $\psi_Z(\mathbf{t}) = \psi(\|\mathbf{t}\|_\alpha)$ , then  $\mathbf{v}^\top \mathbf{Z} \stackrel{d}{=} \|\mathbf{v}\|_\alpha Z_1$ . Such distributions are called  $\alpha$ -symmetric.

Using this, it can be shown that

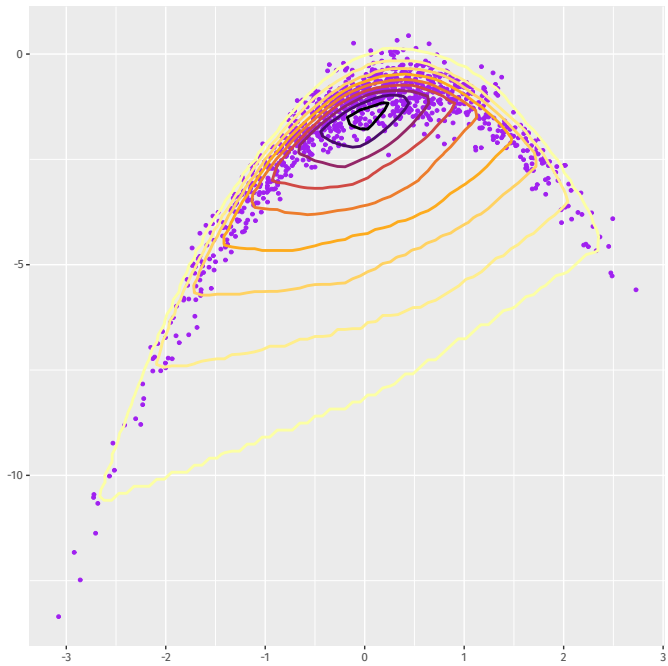
$$D_H(\mathbf{x}, P) = D_H(\mathbf{x}, Q) = F(-\|\mathbf{x}\|_\infty),$$

where  $F$  is the cdf of  $X_1$ .

## Future work

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The notions of depth discussed so far work well with elliptic, unimodal distributions, but fail to capture the natures of more general distributions.





Use ideas from optimal transportation to investigate more canonical notions of depth (for instance, the Monge-Kantorovich depth), and thereby establish procedures independent of the underlying distributions/spaces.

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