# MA3101

# Analysis III

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# 1 Euclidean spaces

# 1.1 $\mathbb{R}^n$ as a vector space

We are familiar with the vector space  $\mathbb{R}^n$ , with the standard inner product

$$\langle \boldsymbol{x}, \boldsymbol{y} \rangle = x_1 y_1 + \dots + x_n y_n.$$

The standard norm is defined as

$$\|\boldsymbol{x} - \boldsymbol{y}\|^2 = \langle \boldsymbol{x} - \boldsymbol{y}, \boldsymbol{x} - \boldsymbol{y} \rangle = \sum_{k=1}^n (x_i - y_i)^2.$$

#### **Exercise 1.1.** What are all possible inner products on $\mathbb{R}^n$ ?

Solution. Note that an inner product is a bilinear, symmetric map such that  $\langle \boldsymbol{x}, \boldsymbol{x} \rangle \geq 0$ , and  $\langle \boldsymbol{x}, \boldsymbol{x} \rangle = 0$  if and only if  $\boldsymbol{x} = \boldsymbol{0}$ . Thus, an product map on  $\mathbb{R}^n$  is completely and uniquely determined by the values  $\langle \boldsymbol{e}_i, \boldsymbol{e}_j \rangle = a_{ij}$ . Let A be the  $n \times n$  matrix with entries  $a_{ij}$ . Note that A is a real symmetric matrix with positive entries. Now,

$$\langle \boldsymbol{x}, \boldsymbol{e}_j \rangle = x_1 a_{1j} + \dots + x_n a_{nj} = \boldsymbol{x}^{\top} \boldsymbol{a}_j,$$

where  $a_j$  is the  $j^{\text{th}}$  column of A. Thus,

$$\langle \boldsymbol{x}, \boldsymbol{y} \rangle = \boldsymbol{x}^{\top} \boldsymbol{a}_1 y_1 + \dots + \boldsymbol{x}^{\top} \boldsymbol{a}_n y_n = \boldsymbol{x}^{\top} A \boldsymbol{y}.$$

Furthermore, any choice of real symmetric A with positive entries produces an inner product.

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**Theorem 1.1** (Cauchy-Schwarz). Given two vectors  $\mathbf{v}, \mathbf{w} \in \mathbb{R}^n$ , we have

$$|\langle \boldsymbol{v}, \boldsymbol{w} \rangle| \leq ||\boldsymbol{v}|| ||\boldsymbol{w}||.$$

*Proof.* This is trivial when w = 0. When  $w \neq 0$ , set  $\lambda = \langle v, w \rangle / ||w||^2$ . Thus,

$$0 \le \|\boldsymbol{v} - \lambda \boldsymbol{w}\|^2 = \|\boldsymbol{v}\|^2 - 2\lambda \langle \boldsymbol{v}, \boldsymbol{w} \rangle + \lambda^2 \|\boldsymbol{w}\|^2.$$

Simplifying,

$$0 \le \|\boldsymbol{v}\|^2 - \frac{|\langle \boldsymbol{v}, \boldsymbol{w} \rangle|^2}{\|\boldsymbol{w}\|^2}.$$

This gives the desired result. Clearly, equality holds if and only if  $\boldsymbol{v} = \lambda \boldsymbol{w}$ .

**Theorem 1.2** (Triangle inequality). Given two vectors  $\mathbf{v}, \mathbf{w} \in \mathbb{R}^n$ , we have

$$\|v + w\| \le \|v\| + \|w\|.$$

Proof. Write

$$\|\boldsymbol{v} + \boldsymbol{w}\|^2 = \|\boldsymbol{v}\|^2 + 2\langle \boldsymbol{v}, \boldsymbol{w} \rangle + \|\boldsymbol{w}\|^2 \le \|\boldsymbol{v}\|^2 + 2|\langle \boldsymbol{v}, \boldsymbol{w} \rangle| + \|\boldsymbol{w}\|^2.$$

Applying Cauchy-Schwarz gives

$$\|\boldsymbol{v} + \boldsymbol{w}\|^2 \le (\|\boldsymbol{v}\| + \|\boldsymbol{w}\|)^2.$$

Equality holds if and only if  $v = \lambda w$  for  $\lambda \geq 0$ .

### 1.2 $\mathbb{R}^n$ as a metric space

Our previous observations allow us to define the standard metric on  $\mathbb{R}^n$ , seen as a point set.

$$d(\boldsymbol{x}, \boldsymbol{y}) = \|\boldsymbol{x} - \boldsymbol{y}\|.$$

**Definition 1.1.** For any  $\delta > 0$ , the set

$$B_{\delta}(\boldsymbol{x}) = \{ \boldsymbol{y} \in \mathbb{R}^n : d(\boldsymbol{x}, \boldsymbol{y}) < \delta \}$$

is called the open ball centred at  $x \in \mathbb{R}^n$  with radius  $\delta$ . This is also called the  $\delta$  neighbourhood of x.

**Definition 1.2.** A set U is open in  $\mathbb{R}^n$  if for every  $\boldsymbol{x} \in U$ , there exists an open ball  $B_{\delta}(\boldsymbol{x}) \subset U$ .

*Remark.* Every open ball in  $\mathbb{R}^n$  is open.

Remark. Both  $\emptyset$  and  $\mathbb{R}^n$  are open.

**Definition 1.3.** A set F is closed in  $\mathbb{R}^n$  if its complement  $\mathbb{R}^n \setminus F$  is open in  $\mathbb{R}^n$ .

Remark. Both  $\emptyset$  and  $\mathbb{R}^n$  are closed.

*Remark.* Finite sets in  $\mathbb{R}^n$  are closed.

**Theorem 1.3.** Unions and finite intersections of open sets are open.

Corollary 1.3.1. Intersections and finite unions of closed sets are closed.

**Definition 1.4.** An interior point x of a set  $S \subseteq \mathbb{R}^n$  is such that there is a neighbourhood of x contained within S.

Example. Every point in an open set is an interior point by definition. The interior of a set is the largest open set contained within it.

**Definition 1.5.** An exterior point x of a set  $S \subseteq \mathbb{R}^n$  is an interior point of the complement  $\mathbb{R}^n \setminus S$ .

**Definition 1.6.** A boundary point of a set is neither an interior point, nor an exterior point.

Example. The boundary of the unit open ball  $B_1(0) \subset \mathbb{R}^n$  is the sphere  $S^{n-1}$ .

**Definition 1.7.** A limit point x of a set  $S \subseteq \mathbb{R}^n$  is such that every neighbourhood of x contains a point from S other than itself.

**Definition 1.8.** The closure of a set  $S \subseteq \mathbb{R}^n$  is the union of S and its limit points. *Remark.* The closure of a set is the smallest closed set containing it.

**Lemma 1.4.** Every open set in  $\mathbb{R}^n$  is a union of open balls.

*Proof.* Let  $U \subseteq \mathbb{R}^n$  be open. Thus, for every  $\boldsymbol{x} \in \mathbb{R}^n$ , we can choose  $\delta_x > 0$  such that  $B_{\delta_x}(\boldsymbol{x}) \subset U$ . The union of all such open balls is precisely the set U.

### 1.3 $\mathbb{R}^n$ as a topological space

**Definition 1.9.** A topology on a set X is a collection  $\tau$  of subsets of X such that

- 1.  $\emptyset \in \tau$
- $2. X \in \tau$
- 3. Arbitrary union of sets from  $\tau$  belong to  $\tau$ .
- 4. Finite intersections of sets from  $\tau$  belong to  $\tau$ .

Sets from  $\tau$  are called open sets.

*Example.* The Euclidean metric induces the standard topology on  $\mathbb{R}^n$ .

Example. The discrete topology on a set X is one where every singleton set is open. This is the topology induced by the discrete metric,

$$d_{\text{discrete}} \colon X \times X \to \mathbb{R}, \qquad (x,y) \mapsto \begin{cases} 0, & \text{if } x = y, \\ 1, & \text{if } x \neq y. \end{cases}$$

*Example.* Let X be an infinite set. The collection of sets consisting of  $\emptyset$  along with all sets A such that  $X \setminus A$  is finite is a topology on X. This is called the Zariski topology.

Example. Consider the set of real numbers, and let  $\tau$  be the collection  $\emptyset$ ,  $\mathbb{R}$ , and all intervals (-x, +x) for x > 0. This constitutes a topology on  $\mathbb{R}$ , very different from the usual one. This topology cannot be induced by a metric; it is not metrizable.

Consider the constant sequence of zeros. In this topology  $(\mathbb{R}, \tau)$ , this sequence converges to *every* point in  $\mathbb{R}$ . Given any  $\ell \in \mathbb{R}$ , the open neighbourhoods of  $\ell$  are precisely the sets  $\mathbb{R}$  and the open intervals (-x, +x) for  $x > |\ell|$ . The tail of the constant sequence of zeros is contained within every such neighbourhood of  $\ell$ , hence  $0 \to \ell$ . Indeed, the element zero belongs to every open set apart from  $\emptyset$  in this topology.

**Definition 1.10.** A topological space is called Hausdorff if for every distinct  $x, y \in X$ , there exist disjoint neighbourhoods of x and y.

Example. Every metric space is Hausdorff. Given distinct x, y in a metric space (X, d), set  $\delta = d(x, y)/3$  and consider the open balls  $B_{\delta}(x)$  and  $B_{\delta}(y)$ .

**Lemma 1.5.** Every convergent sequence in a Hausdorff space has exactly one limit.

*Proof.* Consider a sequence  $\{x_n\}_{n\in\mathbb{N}}$ , and suppose that it converges to distinct  $x_1$  and  $x_2$ . Construct disjoint neighbourhoods  $U_1$  and  $U_2$  around  $x_1$  and  $x_2$ . Now, convergence implies that both  $U_1$  and  $U_2$  contain the tail of  $\{x_n\}$ , which is impossible since they are disjoint and hence contain no elements in common.

**Definition 1.11.** Given a topological space  $(X, \tau)$  and a subset  $Y \subseteq X$ , the collection of sets  $U \cap Y$  where  $U \in \tau$  is a topology  $\tau_Y$  on Y. We call this collection the subspace topology on Y, induced by the topology on X.

### 1.4 Compact sets in $\mathbb{R}^n$

**Definition 1.12.** A set  $K \subset X$  in a topological space is compact if every open cover of K has a finite sub-cover. That is, for every collection if  $\{U_{\alpha}\}_{{\alpha}\in A}$  of open sets such that K is contained in their union, there exists a finite sub-collection  $U_{\alpha_1}, \ldots, U_{\alpha_k}$  such that K is also contained in their union.

Example. All finite sets are compact.

Example. Given a convergent sequence of real numbers  $x_n \to x$ , the collection  $\{x_n\}_{n\in\mathbb{N}}\cup\{x\}$  is compact.

*Example.* In  $\mathbb{R}^n$ , compact sets are precisely those sets which are closed and bounded. This is the Heine-Borel Theorem.

**Theorem 1.6.** The closed intervals  $[a, b] \subset \mathbb{R}$  are compact.

*Remark.* This can be extended to show that any k-cell  $[a_1,b_1] \times \cdots \times [a_n,b_n] \subset \mathbb{R}^n$  is compact.

Proof. Let  $\{U_{\alpha}\}_{{\alpha}\in A}$  be an open cover of [a,b], and suppose that  $I_1=[a,b]$  has no finite sub-cover. Then, at least one of the intervals [a,(a+b)/2] and [(a+b)/2,b] must not have a finite sub-cover; pick one and call it  $I_2$ . Similarly, one of the halves of  $I_2$  must not have a finite sub-cover; call it  $I_3$ . In this process, we generate a sequence of closed intervals  $I_1 \supset I_2 \supset \ldots$ , none of which have a finite sub-cover. The length of each interval is given by

$$|I_n| = 2^{-n+1} ||b - a|| \to 0.$$

Now, pick a sequence of points  $\{x_n\}$  where each  $x_n \in I_n$ . Then,  $\{x_n\}$  is a Cauchy sequence. To see this, given any  $\epsilon > 0$ , we can find sufficiently large  $n_0$  such that  $2^{-n_0+1}||b-a|| < \epsilon$ . Thus,  $x_n \in I_n \subset I_{n_0}$  for all  $n \geq n_0$ , which means that for any  $m, n \geq n_0$ , we have  $x_m, x_n \in I_{n_0}$  forcing<sup>1</sup>

$$||x_m - x_n|| \le |I_{n_0}| = 2^{-n_0+1} ||b - a|| < \epsilon.$$

From the completeness of  $\mathbb{R}$ , this sequence must converge in  $\mathbb{R}$ , specifically in [a,b]. Thus,  $x_n \to x$  for some  $x \in [a,b]$ . It can also be seen that the limit  $x \in I_n$  for all  $n \in \mathbb{N}$ ; if not, say  $x \notin I_{n_0}$ , then  $x \in [a,b] \setminus I_{n_0}$  which is open, hence there is an open interval such that

$$|x_2 - x_1| = x_2 - x_1 \le b - a.$$

<sup>&</sup>lt;sup>1</sup>If  $x_1, x_2 \in [a, b]$  with  $x_1 < x_2$ , note that  $a \le x_1 < x_2 \le b$ , so

 $(x - \delta, x + \delta) \cap I_{n_0} = \emptyset$ . However,  $I_{n_0}$  contains all  $x_{n \geq n_0}$ , thus this  $\delta$ -neighbourhood of x would miss out a tail of  $\{x_n\}$ .

Now, pick the open set  $U \in \{U_{\alpha}\}$  which covers the point x. Thus,  $x \in U$  so U contains some non-empty open interval  $(x - \delta, x + \delta)$  around x. Choose  $n_0$  such that  $2^{-n_0+1}||b-a|| < \delta$ ; this immediately gives  $I_{n_0} \subseteq (x - \delta, x + \delta) \subset U$ . This contradicts that fact that  $I_{n_0}$  has no finite sub-cover from  $\{U_{\alpha}\}$ , completing the proof.

Remark. The fact that Cauchy sequences in  $\mathbb{R}^n$  converge isn't immediately obvious; it is a consequence of the completeness of  $\mathbb{R}^n$ . Start by noting that  $\mathbb{R}$  has the Least Upper Bound property, from which the Monotone Convergence Theorem follows; every monotonic, bounded sequence of reals converges. It can also be shown that any sequence of reals with contain a monotone subsequence, from which it follows that every bounded sequence contains a convergent subsequence (Bolzano-Weierstrass). Finally, it can be shown that if a subsequence of a Cauchy sequence converges, then the entire sequence also converges to the same limit, giving us the desired result for  $\mathbb{R}$ . For sequence in  $\mathbb{R}^n$ , we may apply this coordinate-wise to obtain the result.

#### **Lemma 1.7.** Compact sets in $\mathbb{R}^n$ are closed and bounded.

Proof. Consider a compact set  $K \subset \mathbb{R}^n$ . Let  $x \in \mathbb{R}^n \setminus K$ , and let  $y \in K$ . Since  $x \neq y$ , we choose open balls  $U_y$  around y and  $V_y$  around x such that  $U_y \cap V_y = \emptyset$ . Repeating this for all  $y \in K$ , we generate an open cover  $\{U_y\}$  of K consisting of open balls. The compactness of K guarantees that this has a finite sub-cover, i.e. there is a finite set Y such that the collection  $\{U_y\}_{y \in Y}$  covers X. As a result, the finite intersection of all  $V_y$  for  $y \in Y$  is contained within  $\mathbb{R}^n \setminus K$ . Thus, x is in the exterior of K. Since x was chosen arbitrarily from  $\mathbb{R}^n \setminus K$ , we see that K is closed.

Now, consider the open cover  $\{B_1(x)\}_{x\in K}$ , and extract a finite sub-cover of unit open balls. The distance between any two points in K is at most the maximum distance between the centres of any two balls in our sub-cover, plus two.

#### **Lemma 1.8.** The intersection of a closed set and a compact set is compact.

*Proof.* Let  $F \subseteq \mathbb{R}^n$  be closed and let  $K \subseteq \mathbb{R}^n$  be compact. Suppose that the open cover  $\{U_\alpha\}$  of  $F \cap K$  has no finite sub-cover. Now the complement  $U = F^c$  is open in  $\mathbb{R}^n$ , hence the collection  $\{U_\alpha\} \cup \{U\}$  is an open cover of K, and hence must admit a finite sub-cover of K. In particular, this must be a finite sub-cover of  $F \cap K$ . However, we can remove the set U from this sub-cover since it shares no element with  $F \cap K$ ; as a result, our sub-cover must be a finite sub-collection of sets  $U_\alpha$ , contradicting our assumption. This shows that  $F \cap K$  is compact.

**Lemma 1.9** (Finite intersection property). Let  $\{K_{\alpha}\}$  be a collection of compact sets in  $\mathbb{R}^n$  which have the property that any finite intersection of them is non-empty. Then,

$$\bigcap_{\alpha} K_{\alpha} \neq \emptyset.$$

*Proof.* Suppose to the contrary that the intersection of all  $K_{\alpha}$  is empty. Fix an index  $\beta$ , and note that no element of  $K_{\beta}$  lies in every  $K_{\alpha}$ . Set  $J_{\alpha} = K_{\alpha}^{c}$ , whence the collection  $\{J_{\alpha} : \alpha \neq \beta\}$ 

is an open cover of  $K_{\beta}$ . This must admit a finite sub-cover  $\{J_{\alpha_1}, \ldots, J_{\alpha_k}\}$  of  $K_{\beta}$ . Thus, we must have

$$K_{\beta}^c \cup J_{\alpha_1} \cup \cdots \cup J_{\alpha_k} = \mathbb{R}^n.$$

This immediately gives the contradiction

$$K_{\beta} \cap K_{\alpha_1} \cap \cdots \cap K_{\alpha_k} = \emptyset.$$

**Theorem 1.10** (Heine-Borel). Compact sets in  $\mathbb{R}^n$  are precisely those that are closed and bounded.

*Proof.* Given a compact set in  $\mathbb{R}^n$ , we have already shown that it must be closed and bounded. Next, if  $F \subset \mathbb{R}^n$  is closed and bounded, it can be enclosed within a k-cell which we know is compact. Thus, F is the intersection of the closed set F and the compact k-cell, proving that F must be compact.

#### 1.5 Continuous maps

**Definition 1.13.** A map  $f: X \to Y$  is continuous if the pre-image of every open set from Y is open in X.

**Lemma 1.11.** A map  $f: X \to Y$  is continuous if the pre-image of every closed set from Y is closed in X.

**Theorem 1.12.** The projection maps  $\pi_i \colon \mathbb{R}^n \to \mathbb{R}$ ,  $\boldsymbol{x} \mapsto x_i$  are continuous.

*Proof.* Let  $U \subseteq \mathbb{R}$  be open; we claim that  $\pi_i^{-1}(U)$  is open. Pick  $\mathbf{x} \in \pi_i^{-1}(U)$ , and note that  $\pi_i(\mathbf{x}) = x_i \in U$ . Thus, there exists  $\delta > 0$  such that  $(x_i - \delta, x_i + \delta) \subset U$ . Now examine  $B_{\delta}(\mathbf{x})$ ; for any point  $\mathbf{y}$  within this open ball, we have  $d(\mathbf{x}, \mathbf{y}) < \delta$  hence

$$|x_i - y_i|^2 \le \sum_{k=1}^n (x_k - y_k)^2 = d(\boldsymbol{x}, \boldsymbol{y})^2 < \delta^2.$$

In other words,  $\pi_i(\mathbf{y}) = y_i \in (x_i - \delta, x_i + \delta)$ , hence  $\pi_i B_{\delta}(\mathbf{x}) \subseteq (x_i - \delta, x_i + \delta) \subset U$ . Thus, given arbitrary  $\mathbf{x} \in \pi_i^{-1}(U)$ , we have found an open ball  $B_{\delta}(\mathbf{x}) \subset \pi_i^{-1}(U)$ .

**Lemma 1.13.** Finite sums, products, and compositions of continuous functions are continuous.

**Theorem 1.14.** All polynomial functions of the coordinates in  $\mathbb{R}^n$  are continuous.

*Example.* The unit sphere  $S^{n-1} \subset \mathbb{R}^n$  is closed. It is by definition the pre-image of the singleton closed set  $\{1\}$  under the continuous map

$$\boldsymbol{x} \mapsto x_1^2 + \dots + x_n^2.$$

**Theorem 1.15.** The continuous image of a compact set is a compact set.

*Proof.* Let  $f: X \to Y$  be continuous, where Y is the image of the compact set X, and let  $\{U_{\alpha}\}$  be an open cover of Y. Then, the collection  $\{f^{-1}(U_{\alpha})\}$  is an open cover of X. Using the compactness of X, extract a finite sub-cover  $f^{-1}(U_{\alpha_1}), \ldots, f^{-1}(U_{\alpha_k})$  of X. It follows that the collection  $U_{\alpha_1}, \ldots, U_{\alpha_k}$  is a finite sub-cover of Y.

#### 1.6 Connectedness

**Definition 1.14.** Let X be a topological space. A separation of X is a pair U, V of non-empty disjoint open subsets such that  $X = U \cup V$ .

**Definition 1.15.** A connected topological space is one which cannot be separated.

**Lemma 1.16.** A topological space X is connected if and only if the only sets which are both open and closed are  $\emptyset$  and X.

Example. The intervals  $(a,b) \subset \mathbb{R}$  are connected. To see this, suppose that U,V is a separation of (a,b). Pick  $x \in U, y \in V$ , and without loss of generality let x < y. Define  $S = [x,y] \cap U$ , and set  $c = \sup S$ . It can be argued that  $c \in (a,b)$ , but  $c \notin U, c \notin V$ , using the properties of the supremum.

**Theorem 1.17.** The continuous image of a connected set is connected.

*Proof.* Let f be a continuous map on the connected set X, and let Y be the image of X. If U, V is a separation of Y, then it can be shown that  $f^{-1}(U)$ ,  $f^{-1}(V)$  constitutes a separation of X, which is a contradiction.

**Definition 1.16.** A path  $\gamma$  joining two points  $x, y \in X$  is a continuous map  $\gamma \colon [a, b] \to X$  such that  $\gamma(a) = x$ ,  $\gamma(b) = y$ .

**Definition 1.17.** A set in X is path connected if given any two distinct points in X, there exists a path joining them.

# Lemma 1.18. Every path connected set is connected.

*Proof.* Let X be path connected, and suppose that U, V is a separation of X. Then, pick  $x \in U$ ,  $y \in V$ , and choose a path  $\gamma \colon [0,1] \to X$  between x and y. The sets  $f^{-1}(U)$  and  $f^{-1}(V)$  separate the interval [0,1], which is a contradiction.