CS754 HW2

Sahasra Ranjan - 190050102

Rahul Prajapat - 190050095

Ques 1

(1) Justify how $\delta_{2s}=1$ could imply that 2s columns of Φ may be linearly dependent.

For integer S the restricted isometry constant (RIC) δ_S of a matrix Φ ,

$$(1 - \delta_S)||\theta||^2 \le ||\Phi\theta||^2 \le (1 + \delta_S)||\theta||^2$$

Now, for θ_1,θ_2 which are S-sparse, if we define $\theta=\theta_1-\theta_2$, trivially θ is atmost 2S-sparse in that basis (discussed in class). Then the following is undesirable

$$\Phi\theta_1 = \Phi\theta_2$$
, for $\theta_1 \neq \theta_2$

Now using the RIP property,

$$(1 - \delta_{2S}) ||\theta||^2 \le ||\Phi \theta||^2 \le (1 + \delta_{2S}) ||\theta||^2$$

But, $\delta_{2S}=1$,

$$0 \le ||\Phi \theta||^2$$

According to this inequality, $||\Phi\theta||$ maybe be equal to 0 for some $\theta \neq 0$ (since, $\theta = \theta_1 - \theta_2$ where $\theta_1 \neq \theta_2$).

Now, since θ is 2S-sparse, a linear combination of columns of Φ will evaluate to 0.

$$\Phi^{(1)}\theta_1 + \Phi^{(2)}\theta_2 + \dots \Phi^{(2S)}\theta_{2S} = 0$$

where, $\Phi^{(i)}$ are columns of Φ and θ_i are the non zero elements of θ .

Hence, we can comclude that 2S columns of Φ maybe linear.

(2) Justify both inequalities.

$$||\Phi(x^*-x)||_{l2} \leq ||\Phi x^*-y||_{l2} + ||y-\Phi x||_{l2} \leq 2\epsilon$$

Using the triangle inequality, we know that,

$$||\hat{a} + \hat{b}|| \le ||\hat{a}|| + ||\hat{a}||$$

Applying this inequality to $||\Phi(x^*-x)||_{l^2}$, we get,

$$||\Phi(x^*-x)||_{l_2} \le ||\Phi x^*-y||_{l_2} + ||y-\Phi x||_{l_2}$$

where, $\hat{a} = \Phi x^* - y$ and $\hat{b} = y - \Phi x$

Now, by theorem 3 constraint, i.e. $||y-\Phi x||_{l^2}\leq \epsilon$, we can state:

$$\begin{split} ||y-\Phi x||_{l2} &\leq \epsilon \\ ||\Phi x^*-y||_{l2} &\leq \epsilon \\ ||y-\Phi x||_{l2} + ||\Phi x^*-y||_{l2} &\leq \epsilon \end{split}$$

Hence, both the inequalities stated are correct.

(3) Justify both inequalities.

$$||h_{T_j}||_{l_2} \leq s^{1/2} ||h_{T_j}||_{l_\infty} \leq s^{-1/2} ||h_{T_{j-1}}||_{l_1}$$

 $x^* = x + h$, and h is decomposed into a sum of vectors ($\Sigma_{i \in T_i} h_i$)

- ullet l₂ norm is square root of square sum of all the values
- l_{∞} norm is the max value (by defn.)

$$egin{aligned} ||h_{T_j}||_{l_2} &= \sqrt{\Sigma_{i \in T_j} h_i^2} \ &\leq \sqrt{s imes max(h_{T_j})^2} \ &= \sqrt{s} imes max(h_{T_j}) \ &= \sqrt{s} ||h_{T_j}||_{l_\infty} \end{aligned}$$

So, first inequality (i.e. $||h_{T_j}||_{l_2} \leq s^{1/2} ||h_{T_j}||_{l_\infty}$) is proved

Now,

- ullet l₁ norm is defined as absolute sum of all the values
- By defn. of h_{T_i} ,
 - $\circ \ \ h_{T_{i-1}}$ will s largest value in $h_{T_{i-2}^c}$
 - $\circ \hspace{0.2cm} h_{T_i}$ will s largest value in $h_{T_i^c}$
- So, highest value in h_{T_i} will be lesser than the smallest value in $h_{T_{i-1}}$.

$$egin{aligned} max(h_{T_j}) & \leq min(h_{T_{j-1}}) \ max(h_{T_j}) & \leq \Sigma_{i \in T_{j-1}} |h_{T_{j-1}}|/s \ ||h_{T_j}||_{l_\infty} & \leq ||h_{T_{j-1}}||_{l_1}/s \ s^{1/2} ||h_{T_j}||_{l_\infty} & \leq s^{-1/2} ||h_{T_{j-1}}||_{l_1} \end{aligned}$$

Combining both the inequalities derived above, we will get the required statement proved.

(4) Justify both inequalities

According to the defn. of h_{T_i} ,

$$||h_{T_1}||_{l_1} + ||h_{T_2}||_{l_1} + \dots \leq ||h_{T_0^c}||_{l_1}$$

Since these are the locations of s largest coefficients of $h_{T_0^c}$

Now using the inequality proved in 3rd part, we can say:

$$\Rightarrow s^{-1/2}(||h_{T_1}||_{l_1} + ||h_{T_2}||_{l_1} + \ldots) \leq s^{-1/2}||h_{T_0^c}||_{l_1}$$

and,

$$egin{align*} ||h_{T_j}||_{l_2} & \leq s^{-1/2} ||h_{T_{j-1}}||_{l_1} \ \Rightarrow \Sigma_{j \geq 2} ||h_{T_j}||_{l_2} & \leq s^{-1/2} (||h_{T_1}||_{l_1} + ||h_{T_2}||_{l_1} + \ldots) \end{split}$$

Combining both the inequalities, we derived the stated inequality

(5) Justify both inequalities

$$||\Sigma_{j\geq 2}||h_{T_j}||_{l_2} \leq s^{-1/2}||h_{T_0^c}||_{l_1}$$

This inequlity was already stated in the 4th part

$$||\Sigma_{j\geq 2}h_{T_j}||_{l_2}\leq \Sigma_{j\geq 2}||h_{T_j}||_{l_2}$$

This inequality follows by the repeated application of the triangle inequality stated in the 2nd part of this problem.

(6) Justify this inequality

$$\sum_{i \in T_0} |x_i + h_i| + \sum_{i \in T_0^c} |x_i + h_i| \ge ||x_{T_0}||_{\ell_1} - ||h_{T_0}||_{\ell_1} + ||h_{T_0^c}||_{\ell_1} - ||x_{T_0^c}||$$

Again, similar to the previous subpart we can use the triangle inequality to prove this inequality

$$\Sigma_{i \in T_0} |x_i + h_i| \geq \Sigma_{i \in T_0} |x_i| - \Sigma_{i \in T_0} |h_i| = ||x_{T_0}||_{l_1} - ||h_{T_0}||_{l_1}$$

Similary for $||x_{T_0}||_{l_1}-||h_{T_0}||_{l_1}$.

From these inequalities we can conclude the required inequality.

(7) Justify this inequality

$$||h_{T_0^c}||_{\ell_1} \leq ||h_{T_0}||_{\ell_1} + 2||x_{T_0^c}||_{\ell_1}.$$

On rearranging the previous inequality and substituting $||x_{T_0^c}|| = ||x-x_s||_{l_1}$, we get

$$||h_{T_0^c}||_{l_1} \leq ||h_{T_0}||_{l_1} + ||x_{T_0^c}||_{l_1} - ||x_{T_0}||_{l_1} + ||x||_{l_1}$$

Using the triangle inequality,

$$||h_{T_0^c}||_{l_1} \leq ||h_{T_0}||_{l_1} + 2||x_{T_0^c}||_{l_1}$$

Hence proved

(8) Justify

$$||h_{(T_0 \cup T_1)^c}||_{\ell_2} \le ||h_{T_0}||_{\ell_2} + 2e_0, \quad e_0 \equiv s^{-1/2} ||x - x_s||_{\ell_1}.$$

Applying (11, inequality in the paper), then the previous inequality and then triangle inequality ($||h_{T_0}||_{l_1} < \sqrt{s}||h_{T_0}||_{l_2}$), we get

$$||h_{(T_0 \cup T_1)^c}||_{l_2} \leq \sqrt{s}(||h_{T_0}||_{l_1} + 2||x_{T_0^c}||_{l_1})$$

Using the triangle inequality mentioned above,

$$||h_{(T_0 \cup T_1)^c}||_{l_2} \leq ||h_{T_0}||_{l_1} + 2e_0$$

where,
$$e_0=s^{-1/2}||x-x_s||_{l_1}.$$
 Since, $||x_{T_0^c}||_{l_1}=||x-x_s||_{l_1}$

(9) Justify

$$|\langle \Phi h_{T_0 \cup T_1}, \Phi h \rangle| \leq \|\Phi h_{T_0 \cup T_1}\|_{\ell_2} \|\Phi h\|_{\ell_2} \leq 2\varepsilon \sqrt{1 + \delta_{2s}} \|h_{T_0 \cup T_1}\|_{\ell_2}.$$

First part can be concluded by the Cauchy-Schwarz inequality i.e., dot product is less than product of the magnitudes

Also as proved in the previous subparts

$$||\Phi h||_{l_2} = ||\Phi(x^*-x)||_{l_2} \leq 2\epsilon$$

$$||\Phi h_{T_0 \cup T_1}||_{l_2} \leq \sqrt{1+\delta_{2s}}||h_{T_0 \cup T_1}||_{l_2}$$

Combining these inequalities, we will get the required inequality.

(10) Justify this carefully. See Lemma 1 in this paper.

$$|\langle \Phi h_{T_0}, \Phi h_{T_j} \rangle| \leq \delta_{2s} ||h_{T_0}||_{\ell_2} ||h_{T_j}||_{\ell_2}$$

Lemma 2.1 in the paper directly states this where s = s, s' = s (given T_0, T_j are s sparse)

(11) Justify

$$\|h_{T_0}\|_{\ell_2} + \|h_{T_1}\|_{\ell_2} \le \sqrt{2} \|h_{T_0 \cup T_1}\|_{\ell_2}$$

Since T_0, T_1 are disjoint, $h_{T_0 \cup T_1} = h_{T_0} + h_{T_1}$

say,
$$|h_{T_0}|_1=a$$
 and $|h_{T_1}|_1=b$,

Then the above inequality is $a+b \leq \sqrt{2}\sqrt{a^2+b^2}$

$$a^2 + b^2 - 2ab \ge 0 \ 2(a^2 + b^2) \ge (a + b)^2 \ a + b \le \sqrt{2(a^2 + b^2)}$$

Hence, proved

(12) Justify both inequalities carefully.

$$(1 - \delta_{2s}) \|h_{T_0 \cup T_1}\|_{\ell_2}^2 \leq \|\Phi h_{T_0 \cup T_1}\|_{\ell_2}^2 \leq \|h_{T_0 \cup T_1}\|_{\ell_2} (2\varepsilon\sqrt{1 + \delta_{2s}} + \sqrt{2}\,\delta_{2s}\sum_{j\geq 2} \|h_{T_j}\|_{\ell_2}).$$

The left inequality is same as that of the RIP left equality ($h_{T_0 \cup T_1}$ is 2S-sparse)

For the right inequality,

$$\left|\left|\Phi h_{T_0\cup T_1}
ight|
ight|_2^2 = \left\langle\Phi h_{T_0\cup T_1},\Phi h
ight
angle - \left\langle\Phi h_{T_0\cup T_1},\Sigma_{j\geq 2}\Phi h_j
ight
angle$$

Using $(a-b \le |a|+|b|)$

$$\left|\left|\Phi h_{T_0\cup T_1}
ight|
ight|_2^2=\left|\left\langle\Phi h_{T_0\cup T_1},\Phi h
ight
angle
ight|+\left|\left\langle\Phi h_{T_0\cup T_1},\Sigma_{j\geq 2}\Phi h_j
ight
angle
ight|$$

From subpart 9 and statement in the paper, we have

$$egin{aligned} \left\langle \Phi h_{T_0 \cup T_1}, \Phi h
ight
angle & \leq 2\epsilon \sqrt{1+\delta_{2s}} |\left| h_{T_0 \cup T_1} \left|
ight|_{l_2} \ & \left| \left\langle \Phi h_{T_0 \cup T_1}, \Sigma_{j \geq 2} \Phi h_j
ight
angle | = \Sigma_{j \geq 2} |\left\langle \Phi h_{T_0 \cup T_1}, \Phi h_j
ight
angle | \end{aligned}$$

Using subpart 10, 11 and the fact that $T_0, T-1$ are disjoint, we get:

$$egin{aligned} \Sigma_{j \geq 2} |\langle \Phi h_{T_0 \cup T_1}, \Phi h_j
angle| &= \Sigma_{j \geq 2} \delta_{2s} ||h_{T_j}||_{l_2} (||h_{T_0}||_{l_2} + ||h_{T_1}||_{l_2}) \ &= \Sigma_{j \geq 2} \; \sqrt{2} \delta_2 ||h_{T_j}||_{l_2} ||h_{T_0 \cup T_1}||_{l_2} \end{aligned}$$

Adding both these inequalities, we get the final right inequality.

(13) Justify.

$$||h_{T_0 \cup T_1}||_{\ell_2} \le \alpha \varepsilon + \rho s^{-1/2} ||h_{T_0^c}||_{\ell_1},$$

Dividing the previous inequality with $1-\delta_{2S}$ will give the above Inequality where,

$$lpha=rac{2\sqrt{1+\delta_{2S}}}{1-\delta_{2S}}$$
 and $ho=rac{\sqrt{2}\delta_{2S}}{1-\delta_{2S}}$

(14) Justify

$$||h_{T_0 \cup T_1}||_{\ell_2} \le \alpha \varepsilon + \rho ||h_{T_0 \cup T_1}||_{\ell_2} + 2\rho e_0$$

We will use these statements derived before:

$$||h_{T_0}||_{l_1} \leq \sqrt{2} ||h_{T_0}||_{l_2}$$

$$||h_{T_0}||_{l_2} \leq ||h_{T_0 \cup T_1}||_{l_2}$$

Substituting these in the inequality (13) in this report, we will get the required inequality.

(15) Justify both inequalities in this line.

$$||h||_{\ell_2} \le ||h_{T_0 \cup T_1}||_{\ell_2} + ||h_{(T_0 \cup T_1)^c}||_{\ell_2} \le 2||h_{(T_0 \cup T_1)}||_{\ell_2} + 2e_0 \le 2(1-\rho)^{-1}(\alpha\varepsilon + (1+\rho)e_0),$$

Left inequality is trivial as: $h = h_{(T_0 \cup T_1)} + h_{(T_0 \cup T_1)^c}$. Follwed by the triangle Inequality we will get the desired Inequality.

The Inequality in the middle can be derive directly from the eq 13 (in the paper) and the fact that $||h_{T_0}||_{l_2} \leq ||h_{T_0 \cup T_1}||_{l_2}$

$$||h_{(T_0 \cup T_1)}||_{l_2} + ||h_{T_0 \cup T_1}||_{l_2} \le 2||h_{T_0 \cup T_1}||_{l_2} + 2e_0$$

The rightmost Inequality can be derived by substituting $||h_{T_0 \cup T_1}||_{l_2} = (1ho)^{-1}(\alpha \varepsilon + 2
ho e_0)$

On adding $2e_0$ to the 2 times of the above equation will give the desired Inequality.

(16) Justify this inequality

$$||h||_{\ell_1} = ||h_{T_0}||_{\ell_1} + ||h_{T_0^c}||_{\ell_1} \le 2(1+\rho)(1-\rho)^{-1}||x_{T_0^c}||_{\ell_1},$$

This is the direct conlusion of these statement in the paper:

$$||h_{T_0}||_{\ell_1} \le \rho \, ||h_{T_0^c}||_{\ell_1},$$

$$||h_{T_0^c}||_{\ell_1} \le 2(1-\rho)^{-1}||x_{T_0^c}||_{\ell_1}.$$

Adding these two will give the desired inequality.

Ques 2

 $\mathsf{RMSE}: norm(x'-x)/norm(x)$

• a) RMSE = 0.0014



• b) RMSE = 0.1182

 $\lambda=1$ gives images with very dark tone so I have canged it to 40.



• c) RMSE = 0.2991

As it is taking too long with the function handles I have restricted iterations to 20.



• d) RMSE = 0.7-0.9

The error is very high for the algorithm to work. The algorithm gives very bad results.

Ques 3

(a) x is a purely sparse signal with the compressive measurements $y=\Phi x+\eta$, where $||\eta||_2\leq \epsilon$. Let \tilde{x} be the oracular solution and we know the indices of non-zero elements of signal x. As defined in the question, take Φ_S a submatrix of Φ with those columns 0 which do not belong to set S.

$$y = \Phi_s ilde{x} \ \Phi_S^T y = \Phi_S^T \Phi_S ilde{x}$$

It is given that the inverse of $\Phi_s^T\Phi_S$ exists,

$$egin{aligned} ilde{x} &= (\Phi_S^T \Phi_S)^{-1} \Phi_S^T y \ ilde{x} &= \Phi_S^\dagger y \end{aligned}$$

Where, Φ_S^\dagger is the pseudo-inverse of the submatrix Φ_S

(b) Using the equation from subpart (a)

$$||\tilde{x} - x||_2 = ||\Phi_S^{\dagger} y - x||$$

= $||\Phi_s^{\dagger} (\Phi x + \eta) - x||$

Since x is purely sparse, it has atmost S non-zero elements, therefore $\Phi_S x = \Phi x$ (according to Φ_S 's definition)

$$\begin{split} ||\Phi_s^{\dagger}(\Phi x + \eta) - x|| \\ &= ||(\Phi_S^T \Phi_S)^{-1} \Phi_S^T \Phi x + \Phi_S^{\dagger} \eta - x|| \\ &= ||(\Phi_S^T \Phi_S)^{-1} \Phi_S^T \Phi_S x + \Phi_S^{\dagger} \eta - x|| \\ &= ||x + \Phi_S^{\dagger} \eta - x|| \\ &= ||\Phi_S^{\dagger} \eta|| \end{split}$$

By Cauchy-Schwarz inequality,

$$|| ilde{x} - x||_2 = ||\Phi_S^\dagger \eta||_2 \leq ||\Phi_S^\dagger||_2 ||\eta||_2$$

(c) Largest singluar value of Φ_S^\dagger is $||\Phi_S^\dagger||_2$

Using RIP,

$$|(1-\delta_{2S})|| ilde{x}-x||_2^2 \leq ||\Phi(ilde{x}-x)||_2^2 \leq (1+\delta_{2S})|| ilde{x}-x||_2^2$$

Using SVD:

$$egin{aligned} \Phi &= U \Sigma V^* \ \Phi^\dagger &= (U \Sigma V^*)^\dagger \ \Phi^\dagger &= V \Sigma^\dagger U^* \end{aligned}$$

 Σ^\dagger is formed from Σ by taking the reciprocal of all the non-zero elements, leaving all the zeros alone

- Ref.(Computing SVD

and pseudoinverse)

Therfore,

$$||\Phi_S||_2^{-2} = 1/||\Phi_S^{\dagger}||_2$$

Using the RIP inequality,

$$\begin{aligned} (1 - \delta_{2S})||\tilde{x} - x||_2^2 &\leq ||\Phi(\tilde{x} - x)||_2^2 \leq (1 + \delta_{2S})||\tilde{x} - x||_2^2 \\ (1 - \delta_{2S}) &\leq \frac{||\Phi(\tilde{x} - x)||_2^2}{||\tilde{x} - x||_2^2} \leq (1 + \delta_{2S}) \\ (1 - \delta_{2S}) &\leq ||\Phi_S||_2^{-2} \leq (1 + \delta_{2S}) \\ \frac{1}{\sqrt{1 + \delta_{2S}}} &\leq ||\Phi_S^{\dagger}||_2 \leq \frac{1}{\sqrt{1 - \delta_{2S}}} \end{aligned}$$

(d)

$$||||||||x-x|||_2^2 = rac{||\Phi_S^\dagger \eta||_2^2}{||\eta||_2^2} ||\eta||_2^2$$

From the previous derivation, we know that,

$$|(1 - \delta_{2S})||\tilde{x} - x||_2^2 \le ||\eta||_2^2 \le (1 + \delta_{2S})||\tilde{x} - x||_2^2$$

Also, $||\eta||_2 \leq \epsilon$,

$$|| ilde{x} - x||_2 \leq rac{\epsilon}{\sqrt{1 - \delta_{2S}}}$$

$$|| ilde{x} - x||_2 \geq rac{\epsilon}{\sqrt{1 + \delta_{2S}}}$$

Now, let x^* be the solution given by theorem 3: $||y - \Phi x^*|| \leq \epsilon$

From the above mentioned inequality,

$$\epsilon \leq (\sqrt{1+\delta_{2S}})||x-\tilde{x}||_2$$

Therefore,

$$||y - \Phi x^*|| \le \epsilon \le (\sqrt{1 + \delta_{2S}})||x - \tilde{x}||_2$$

 $||\Phi(x - x^*)|| \le (\sqrt{1 + \delta_{2S}})||x - \tilde{x}||_2$

But,

$$\sqrt{(1-\delta_{2S})}||x-x^*||_2 \leq ||\Phi(x-x^*)||_2$$

Combining these, we get:

$$||x-x^*||_2 \leq c||x-\tilde{x}||_2$$

where,
$$c=\sqrt{rac{1+\delta_{2S}}{1-\delta_{2S}}}$$

Hence the solution given by Theorem 3 is only a constant factor worse than this solution.

Ques 4

Given, s < t where s and t are positive integers. δ_s , δ_t are the RIC of sensing matrix A (say) of order s and t respectively.

Now since s < t, any s-sparse vector is also t-sparse.

From the RIP, we know (for t-sparse vector):

$$(1-\delta_t)||x||_2^2 \le ||Ax||_2^2 \le (1+\delta_t)||x||_2^2$$

Let v be a s-sparse vector

Vector v will satisfy $(1-\delta_t)||v||_2^2 \leq ||Av||_2^2 \leq (1+\delta_t)||v||_2^2$ since it is also a t-sparse

Now according to the defn, δ_s is the **smallest** constant δ which satisfies

$$|(1-\delta)||v||_2^2 \le ||Av||_2^2 \le (1+\delta)||V||_2^2$$

But δ_t also satisfies this equation. So $\delta_s \leq \delta_t$. Hence proved.

Ques 5

- <u>Error Correction Codes for COVID-19 Virus and Antibody Testing: Using Pooled Testing</u> to Increase Test Reliability
- Key Objective Function:

$$\begin{split} & \text{minimize } ||z||_1 + \lambda ||\mathbf{y} - \mathbf{A}\mathbf{z} - \mathbf{u}||_1, \\ & \text{subject to } ||\mathbf{u}||_2 \leq \epsilon, \\ & z \geq 0, \end{split}$$

where $||z||_1$ is the sum of absolute value of all the elements of z

 $\lambda \in \mathbb{R}$ is a tuning parameter for controlling the tradeoff between $\ ||z||_1 \ \& \ ||\mathbf{A}\mathbf{z} - \mathbf{y} - \mathbf{u}||_1$

 $\epsilon \geq 0$ is a parameter controlling the tolerance for noise, $x \geq 0$ means that every element of x is nonnegative

 $||\mathbf{u}||_2$ is the l_2 norm of \mathbf{u}

Assume that we can get n samples for n subjects with one sample for each, and we will perform m tests to determine the quantities of COVID-19 viruses in these samples.

 $\mathbf{x} \in [0,\infty)^n$: The quantity of the DNA that can be generated from the subjects' viral RNAs

 $\mathbf{P}\in\{0,1\}^{m imes n}$: matrix to denote participation of n samples in m tests ($P_{ij}=1$ if j^{th} sample took part in i^{th} test, else $P_{ij}=0$)

 $\mathbf{W} \in [0,1]^{m imes n}$: W_{ij} is the fraction of the j^{th} sample used in the i^{th} test.

 $\mathbf{A} := \mathbf{P} \circ \mathbf{W}$: our measurement matrix where \circ represents Hadamard multiplication.

The corresponding m mixed samples will go through m quantitative PCR to quantify amount of DNAs. Due to potential background noises and gross errors caused by factors such as dilutions, sample and reagent contamination, and operation mistakes, the final measurements $\mathbf{y} \in \mathbb{R}^m$ from the real-time PCR can be modeled as

$$y = Ax + e + v$$

 $\mathbf{A}\mathbf{x} \in \mathbb{R}^m$: True signal

 $\mathbf{e} \in \mathbb{R}^m$: possible gross error

Our goal is to recover $\mathbf{x} \in [0, \infty)^n$ which is what is achieved by our Key Objective Function where \mathbf{z} is an estimate of \mathbf{x} , \mathbf{u} is an estimate of \mathbf{v} , and $\mathbf{y} - \mathbf{A}\mathbf{z} - \mathbf{u}$ is an estimate of \mathbf{e} .

- The main purpose of error correcting pooled testing is to increase test reliability, not to reduce required test numbers as in tapestry pooling.
 - In error detection codes using pooled testing, it doesn't require the involved signal to be sparse as what we consider in tapestry pooling: the signal can be fully dense in the proposed strategy.
 - The intuition behind tapestry is that the current rate of COVID-19 infections in the world population means that most samples tested are not infected, so most tests are wasted on uninfected samples. So tapestry uses this redundancy by group pooling to save on testing resources.
 - The intuition behnd the proposed strategy is that when each individual's sample is part
 of many pooled sample mixtures, the test results from all of the sample mixtures
 contain redundant information about each individual's diagnosis, which can be
 exploited to automatically correct for wrong test results in exactly the same way that
 error correction codes correct errors introduced in noisy communication channels.
 - Tapestry uses a two-stage approach. In the first stage all the negative pools are identified and the comprising samples are ruled out for the next step. In the second stage compressive sensing is applied to decrease false positives and estimate respective viral loads.
 - The proposed approach uses compressive sensing by assuming the gross error is sparse to estimate viral loads in any regime (undersampled or oversampled) without increasing number of tests required. So it is single stage.

Ques 6

- P1: $\min_x ||x||_1$ s. t. $||y = \phi x||_2 \le \epsilon$
- LASSO: $\min_{x}(||y \phi x||_{2}^{2} + \lambda ||x||_{1})$

Let's take $\epsilon = ||y - \phi x||_2$ where x is solution to LASSO problem

Let's suppose x' is the solution to P1 problem.

So,

$$\begin{split} ||y-\phi x'||_2 &\leq ||y-\phi x||_2 \\ ||y-\phi x'||_2^2 &\leq ||y-\phi x||_2^2 \\ ||y-\phi x'||_2^2 + \lambda ||x'||_1 &\geq ||y-\phi x||_2^2 + \lambda ||x||_1 \\ |\lambda(||x'||_1 - ||x||_1) &\geq ||y-\phi x||_2^2 - ||y-\phi x'||_2^2 \\ |\lambda(||x'||_1 - ||x||_1) &\geq 0 \\ ||x'||_1 &\geq ||x||_1 \\ ||x'||_1 &= ||x||_1 \end{split} \qquad \text{(As x' is a minimizer of P1)}$$

This implies x is also a minimizer of the problem P1. (As $\;||y-\phi x||_2=\epsilon$)

We have proved that for this ϵ it, indeed, is possible.

Therefore, there exists some value of ϵ for which minimizer of LASSO is also a minimizer of P1.