Uncertainty Principle

$$\begin{split} \Delta x \Delta p &\geq \frac{\hbar}{2} \\ \Delta A \Delta B &\geq \left| \frac{1}{2i} \left\langle [A,B] \right\rangle \right| \\ \Delta E \Delta t &\geq \frac{\hbar}{2} \\ \frac{d}{dt} \left\langle Q \right\rangle &= \frac{d}{dt} \left\langle \psi \right| Q \left| \psi \right\rangle \\ &= \left\langle \frac{d\psi}{dt} \right| Q \left| \psi \right\rangle + \left\langle \psi \right| \frac{dQ}{dt} \left| \psi \right\rangle + \left\langle \psi \right| Q \left| \frac{d\psi}{dt} \right\rangle \\ &= + \frac{i}{\hbar} \left\langle H\psi \right| Q \left| \psi \right\rangle + \left\langle \psi \right| \frac{dQ}{dt} \left| \psi \right\rangle - \frac{i}{\hbar} \left\langle \psi \right| Q \left| H\psi \right\rangle \\ &= + \left\langle \psi \right| \frac{dQ}{dt} \left| \psi \right\rangle + \frac{i}{\hbar} \left\langle \psi \right| HQ \left| \psi \right\rangle - \frac{i}{\hbar} \left\langle \psi \right| QH \left| \psi \right\rangle \\ \frac{d}{dt} \left\langle Q \right\rangle &= \left\langle \frac{dQ}{dt} \right\rangle + \frac{i}{\hbar} \left\langle \psi \right| [H,Q] \left| \psi \right\rangle \\ \frac{d}{dt} \left\langle Q \right\rangle &= \left\langle \frac{dQ}{dt} \right\rangle + \frac{i}{\hbar} \left\langle \left\langle [H,Q] \right\rangle \end{split}$$

If Q does not have any explicit time dependence,

$$\frac{d}{dt} \langle Q \rangle = \frac{i}{\hbar} \langle [H, Q] \rangle$$

If [H,Q] = 0, then <Q> is time-independent

e.g. What is d/dt < X >

$$[H,X] = \left[-\frac{\hbar^2}{2m} \frac{d^2}{dx^2} + V(x), x \right]$$

$$= -\frac{\hbar^2}{2m} \left[\frac{d^2}{dx^2}, x \right]$$

$$\left[\frac{d^2}{dx^2}, x \right] f(x) = \frac{d^2}{dx^2} x f - x \frac{d^2}{dx^2} f$$

$$\left[\frac{d^2}{dx^2}, x \right] f(x) = (2f' + xf'') - xf''$$

$$\left[\frac{d^2}{dx^2}, x \right] = 2 \frac{d}{dx}$$

$$\frac{d \langle X \rangle}{dt} = \frac{i}{\hbar} \frac{-\hbar^2}{2m} 2 \left\langle \frac{d}{dx} \right\rangle$$

 $\frac{d\left\langle X\right\rangle }{dt}=\frac{\left\langle p\right\rangle }{m}$

$$\sigma_H \sigma_Q \ge \left| \frac{1}{2i} \left\langle [H, Q] \right\rangle \right|$$

$$\sigma_H \sigma_Q \ge \left| \frac{1}{2i} \frac{\hbar}{i} \frac{d \langle Q \rangle}{dt} \right|$$

assuming $\langle dQ/dt \rangle = 0$

$$\Delta E \sigma_Q \ge \frac{\hbar}{2} \left| \frac{d \langle Q \rangle}{dt} \right|$$

$$\Delta E \frac{\sigma_Q}{|d\langle Q\rangle/dt|} \ge \frac{\hbar}{2}$$

$$\sigma_Q = \left| \frac{d \langle Q \rangle}{dt} \right| \Delta t$$

 Δt is the time it takes for Q to change by one standard deviation

 $\Delta E \Delta t \ge h/2$: so if Δt is small, then the system is changing quickly and ΔE must be big

A rapidly changing system has a very uncertain energy

On the other hand, if $\Delta E=0$, $\Delta t=\infty$: energy eigenstates are stable