

$$T_1 = (3 \text{ kg})a$$

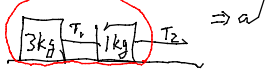
$$T_2 - T_1 = (1 \text{ kg})a$$

$$T_2 = T_1 + (1 \text{ kg})a$$

$$T_2 = (3 \text{ kg})a + (1 \text{ kg})a$$

$$= (4 \text{ kg})a$$

single object



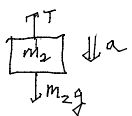
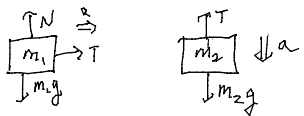
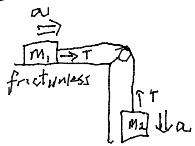
$$F_{\text{net}} = T_2$$

T_1 is an internal force
 and doesn't affect
 object as a whole

$$F_{\text{net}} = ma$$

$$T_2 = (4 \text{ kg})a$$

Only external
 forces affect
 object's
 overall motion.



↓ +

$$T = m_1 a$$

$$m_2 g - T = m_2 a$$

$$m_2 g - m_1 a = m_2 a$$

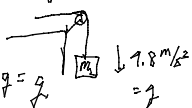
$$m_2 g = (m_1 + m_2) a$$

$$a = \frac{m_2}{m_1 + m_2} g$$

Try certain "limits" of m_1 & m_2

Suppose
 e.g. $m_1 = 0$

$$a = \frac{m_2}{0 + m_2} g = \frac{m_2}{m_2} g = g$$



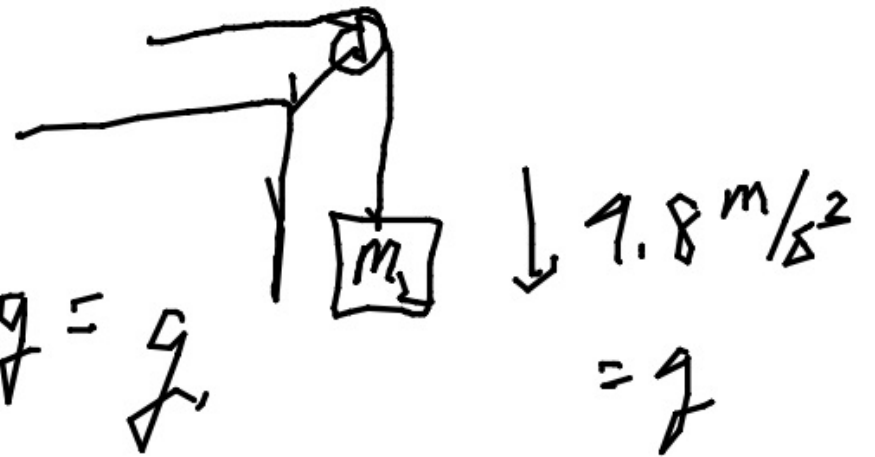
Suppose $m_2 = 0$



Try certain "limits" of m_1 & m_2

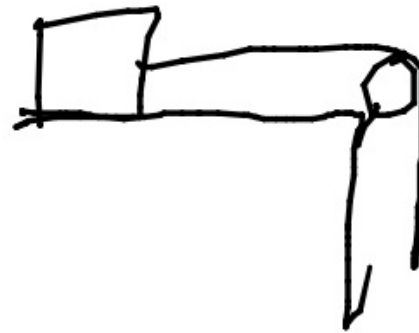
Suppose
e.g. $m_1 = 0$

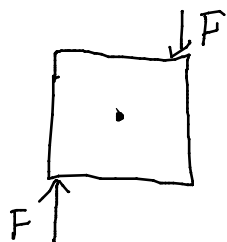
$$a = \frac{m_2}{0 + m_2} g = \frac{m_2}{m_2} g = g$$



Suppose $m_2 = 0$

$$a = \frac{0}{m_1 + 0} g = 0$$





$F_{\text{net}} = 0$
but block spins!

$$F_{\text{net}} = ma$$

$$a = 0?$$

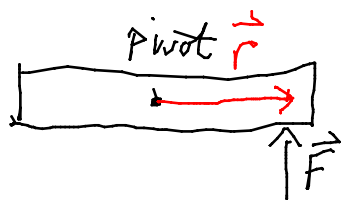
Here, a means acceleration
of the center of mass

center is stationary but
block moves

— —

Torque

- tendency of a force
to cause rotation
around an axis (3D)
or a pivot (2D)



\vec{r} : "lever arm"
vector from
pivot to where
the force is applied

if $\vec{r} \perp \vec{F}$, τ_{av}

torque: $\tau = rF$