

UNLV ME 729 – Advanced Robotics

COURSE OUTLINE - Syllabus

Instructor: Prof. Paul Oh Office: HRC 245 Phone: 702-895-0168
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Office Hours: By Appointment

Required or Recommended: None (course notes will be provided on the course website)

Books:

Required Reading: None (course notes will be provided on the course website)

Assignments

- Library and information resources: Not applicable
- In- and out-of-class assignments and due dates: provided on course website
- Relative weight of assignments and course grade: Described below
- Date/time and location of final examination if known: Estimated 12/12/16 in location below
- Policies to be contained wholly within syllabus (see below)

Lecture/Lab Location: FAB Building (1325 E. Flamingo Rd)

Time: Mondays 18:00-20:30

Course Catalog description: "In-depth study of advanced automation concepts and robotic manipulators. Topics include 3-D kinematics, trajectory generation, compliance analysis, dynamic control of robotics along with concept of assembly operations and machine vision. Prerequisite: ME 421 or consent of instructor."

Objectives:

Preamble: The above course catalog description documents the only advanced robotics course offered at UNLV. As a 700-level course, it suggests target audiences are UNLV graduate level (Masters/PhD) students, primarily majoring in mechanical engineering.

ME729 has not been offered for many years. Since its last offering, advancements in robotics have been significant. As such, a contemporary course in advanced robotics demands re-vamping material. ME425/625, preferably taken with the instructor of ME729, is a pre-requisite. The undergraduate ME425/625 gives foundations in mechanism design, system identification, open and PID-based closed-loop control, and C programming – essentially a broad “cookbook” robotics with “recipes” to design robot systems. Without this foundation, progress in ME729 will likely prove to be slow and futile and inappropriate for MS/PhD level training.

The objective of Advanced Robotics is an in-depth study in robot sensing; actuation; communications; control; computer vision; and path/motion planning. Each of these is typically a stand-alone course in university robotics programs. With only ME729 as the only official offering for advanced robotics in the UNLV Catalog, capturing these six concepts into a single course demands a re-vamping that is effective, efficient, and holistic. To meet the objectives effectively, labs to reinforce theoretical concepts were developed. To be efficient both time- and resource-wise, labs employ LEGO-based NXT systems and the NXC programming language which reduces the need and risks of sourcing and fabricating components. Lastly, to meet objectives holistically, ME425/625 introduced LEGO NXT and NXC hardware and software, so their continued usage in ME729 is a natural segue; many of today’s robots share similarities in sensing, actuation, communications and control that can be demonstrated with and scaled from the NXT and NXC.

The objective will be met leveraging the NXT’s internal hardware to reinforce digital and interfacing concepts (analog-to-digital, pulse-width modulation, and I2C bus) for robotic sensing, actuation, and communications. LEGO components will be used to construct systems that demands advanced control (LQR). Lastly, non-LEGO software packages (e.g. the popular and ubiquitous AR Toolkit for computer vision) will be used to exercise system integration and yield trajectory generation (motion planning). Weekly labs culminate in 2 or 3 projects: student-designed custom-made sensors; a LEGO-based inverted pendulum or ball-and-beam balancer (3-D kinematics, dynamic control); and

robot navigation (trajectory generation, machine vision). *Lectures and labs are designed to develop technical skills in conducting experiments and analyzing data, to produce several distinct outcomes required by the accrediting body, (Criteria 3 a-k), to contribute to the MEM educational objectives, and to satisfy professional components specified by ASME.*

Grade Breakdown

Item	Scheme
Attendance (Lectures and Labs)	5%
Project 1 Sensors (Presentation, Report and Reproducibility)	15%
Project 2 Control (Presentation, Report and Reproducibility)	15%
Project 3 Navigation (Presentation, Report and Reproducibility)	15%
Homework	10%
Mid-term	20%
Final	20%

AO	85-100		C+	60-64
A-	80-84		CO	55-59
B+	75-79		C-	50-54
BO	70-74		D	45-49
B-	65-69		F	0-44

Core Technical Skills:

Provide a “hands-on” experience with robotic sensors, actuators, communications, control, computer vision, and trajectory generation	An understanding the 6 fundamental components of robotics
Relate mechanical, electrical and computer engineering concepts to design, control, and interface robots	An understanding of and application of hardware and software concepts to realize robots
Develop the ability to work together in groups and the organizational and leadership skills required to perform a technical analysis and engineering evaluation	An increased skill level in general experimental methods, systems integration, and effective report writing

ABET Relation to Program Objective

(0 = No content; 1 = some content; 2 = significant content)

Objective	Content	Explanation	Evidence*
1. To deliver a comprehensive mechanical engineering curriculum which emphasizes both the foundations and breadth of the mechanical engineering profession	2	Advanced laboratory experience in robotics	Project reports and lab exercises

2. To provide an education that equips students with the tools necessary to become successful mechanical engineers based on their experience, strong communication skills and awareness for the need of continuous professional development.	2	Students are exposed to hardware and software tools, simulation and report writing.	Class discussions, project reports, class handouts.
3. To provide an education that will allow mechanical engineering students to understand the social, economic, environmental, political and ethical importance of their future profession.	1	Digital concepts through hardware and software are essential in the design of robotic systems in automobiles, power plants and other vital areas of the economy.	Brief videos of robots and robot-based platforms for society e.g. driverless cars are introduced and discussed.
4. To provide mechanical engineering students with a thorough understanding of impact of mechanical engineers and the mechanical engineering profession in the development, implementation and creation of future technology	2	Development and innovation of robotics will be part of the future technology	Brief videos of robots and robot-based platforms for society e.g. driverless cars are introduced and discussed.

Relation to ABET Criteria 3 Learning Outcomes

(0 = No content; 1 = some content; 2 = significant content)

Criteria a - k	Content	Explanation	Evidence
a. <i>An ability to apply knowledge of mathematics, science and engineering</i>	2	Relevant physics, equations of motion, state space realizations and control techniques are derived	In-class lectures, lab exercises and homework
b. <i>An ability to design and conduct experiments as well as to analyzed and interpret data</i>	2	Students write software and interface mechanical and electrical hardware. They are also required to analyze and interpret the experimental data in the report.	Lab exercises and projects
c. <i>An ability to design a system, component or process to meet desired needs</i>	2	Controllers are both simulated and implemented experimentally.	Lab Exercises and projects
d. <i>An ability to function on multidisciplinary teams</i>	2	Students work as a team to use their knowledge in electronics, and computers to achieve the objective of each experiment in this course.	Lab Exercises and projects
e. <i>An ability to identify, formulate and solve engineering problems</i>	2	The students are required to formulate and solve the control problem based on theory and to verify their experimental results with expected theoretical results.	Lab exercises and homework
f. <i>An understanding of professional and ethical responsibility</i>	1	This is emphasized as part of the design engineer's overall responsibility.	Guest Lecturers
g. <i>An ability to communicate effectively</i>	2	Oral and written presentations of the	Project reports

		experimental procedure and results are required.	
<i>h. The broad education necessary to understand the impact of engineering solutions in a global or societal context</i>	1	The impact of engineering design on the environment (pollution, greenhouse effect, etc.) and society are covered.	Videos and discussion
<i>i. A recognition of the need for and an ability to engage in lifelong learning</i>	1	Improvements in control come from innovations and advanced technology. Need for lifelong learning is recognized.	Videos and discussion
<i>j. A knowledge of contemporary issues</i>	1	Design of control systems is related to contemporary issues	Videos and discussion
<i>k. An ability to use the techniques, skills and modern engineering tools necessary for engineering practice</i>	2	Students use modern engineering instrumentation and software	Lab exercises and project reports

Contribution to Professional Component:

ME729 Advanced Robotics builds upon ME425/725 and provides hands-on laboratory reinforcement of fundamental mechanical engineering courses – specifically kinematics, dynamics, mechanisms and design. It therefore helps integrate analytical experimental, digital and programming techniques to solve real engineering problems. ME729 contributes toward the 1-½ year of engineering topics appropriate to developing the ability to work in the controls and dynamic systems area.

Policies (as per UNLV) to be listed in Syllabus:

Academic Misconduct—Academic integrity is a legitimate concern for every member of the campus community; all share in upholding the fundamental values of honesty, trust, respect, fairness, responsibility and professionalism. By choosing to join the UNLV community, students accept the expectations of the Student Academic Misconduct Policy and are encouraged when faced with choices to always take the ethical path. Students enrolling in UNLV assume the obligation to conduct themselves in a manner compatible with UNLV's function as an educational institution.

An example of academic misconduct is plagiarism. Plagiarism is using the words or ideas of another, from the Internet or any source, without proper citation of the sources. See the *Student Academic Misconduct Policy* (approved December 9, 2005) located at: <https://www.unlv.edu/studentconduct/student-conduct>.

Copyright—The University requires all members of the University Community to familiarize themselves **with** and to follow copyright and fair use requirements. **You are individually and solely responsible for violations of copyright and fair use laws. The university will neither protect nor defend you nor assume any responsibility for employee or student violations of fair use laws.** Violations of copyright laws could subject you to federal and state civil penalties and criminal liability, as well as disciplinary action under University policies. Additional information can be found at: <http://www.unlv.edu/provost/copyright>.

Disability Resource Center (DRC)—The UNLV Disability Resource Center (SSC-A 143, <http://drc.unlv.edu/>, 702-895-0866) provides resources for students with disabilities. If you feel that you have a disability, please make an appointment with a Disabilities Specialist at the DRC to discuss what options may be available to you. If you are registered with the UNLV Disability Resource Center, bring your Academic Accommodation Plan from the DRC to the instructor during office hours so that you may work together to develop strategies for implementing the accommodations to meet both your needs and the requirements of the course. Any information you provide is private and will be treated

as such. To maintain the confidentiality of your request, please do not approach the instructor in front of others to discuss your accommodation needs.

Religious Holidays Policy— Any student missing class quizzes, examinations, or any other class or lab work because of observance of religious holidays shall be given an opportunity during that semester to make up missed work. The make-up will apply to the religious holiday absence only. It shall be the responsibility of the student to notify the instructor **within the first 14 calendar days of the course for fall and spring courses (excepting modular courses), or within the first 7 calendar days of the course for summer and modular courses**, of his or her intention to participate in religious holidays which do not fall on state holidays or periods of class recess. For additional information, please visit: <http://catalog.unlv.edu/content.php?catoid=6&navoid=531>.

Transparency in Learning and Teaching—The University encourages application of the transparency method of constructing assignments for student success. Please see these two links for further information: <https://www.unlv.edu/provost/teachingandlearning>
<https://www.unlv.edu/provost/transparency>

Incomplete Grades—The grade of I—Incomplete—can be granted when a student has satisfactorily completed three-fourths of course work for that semester/session but for reason(s) beyond the student's control, and acceptable to the instructor, cannot complete the last part of the course, and the instructor believes that the student can finish the course without repeating it. The incomplete work must be made up before the end of the following regular semester for undergraduate courses. Graduate students receiving "I" grades in 500-, 600-, or 700-level courses have up to one calendar year to complete the work, at the discretion of the instructor. If course requirements are not completed within the time indicated, a grade of F will be recorded and the GPA will be adjusted accordingly. Students who are fulfilling an Incomplete do not register for the course but make individual arrangements with the instructor who assigned the I grade.

Tutoring and Coaching—The Academic Success Center (ASC) provides tutoring, academic success coaching and other academic assistance for all UNLV undergraduate students. For information regarding tutoring subjects, tutoring times, and other ASC programs and services, visit <http://www.unlv.edu/asc> or call 702-895-3177. The ASC building is located across from the Student Services Complex (SSC). Academic success coaching is located on the second floor of the SSC (ASC Coaching Spot). Drop-in tutoring is located on the second floor of the Lied Library and College of Engineering TEB second floor.

UNLV Writing Center—One-on-one or small group assistance with writing is available free of charge to UNLV students at the Writing Center, located in CDC-3-301. Although walk-in consultations are sometimes available, students with appointments will receive priority assistance. Appointments may be made in person or by calling 702-895-3908. The student's Rebel ID Card, a copy of the assignment (if possible), and two copies of any writing to be reviewed are requested for the consultation. More information can be found at: <http://writingcenter.unlv.edu/>.

Rebelmail— By policy, faculty and staff should e-mail students' Rebelmail accounts only. Rebelmail is UNLV's official e-mail system for students. It is one of the primary ways students receive official university communication such as information about deadlines, major campus events, and announcements. All UNLV students receive a Rebelmail account after they have been admitted to the university. Students' e-mail prefixes are listed on class rosters. The suffix is always @unlv.nevada.edu. **Emailing within WebCampus is acceptable.**

Final Examinations—The University requires that final exams given at the end of a course occur at the time and on the day specified in the final exam schedule. See the schedule at: <http://www.unlv.edu/registrar/calendars>.

Any other class specific information—(e.g., absences, make-up exams, status reporting, extra credit policies, plagiarism/cheating consequences, policy on electronic devices, specialized department or college tutoring programs, bringing children to class, policy on recording classroom lectures, etc.)