



# An Introduction to Cybernetics

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## Overview

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- What is “Cybernetics”?
- Control Theory and Cybernetics
- Ordinary Differential Equations (ODEs) for Simulation
- ODEs & Isoclines
- ODEs vs Agent Based Simulation

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## Before we start... calculus!

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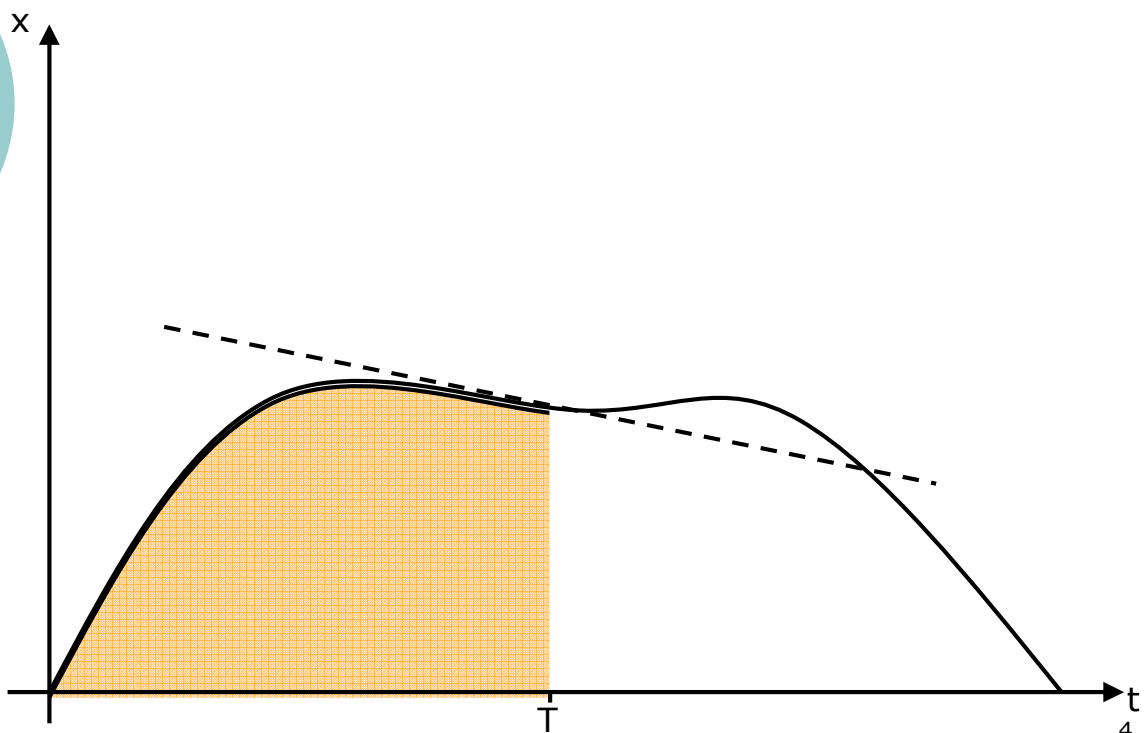
- Integration
  - Calculates the area under a curve
  - Just adds up at each 'sample'
- Differentiation
  - Calculates the gradient of a curve
  - The difference between each 'sample'
- Differentiation is to integration what division is to multiplication

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## Calculus

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## The Original Interdisciplinary Research Topic!

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- Product of The Macy Conferences (1946 – 1953)
- Contributors include
  - Norbert Weiner
  - John Von Neumann
  - Claude Shannon
  - Warren McCulloch
  - Walter Pitts

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## What is Cybernetics?

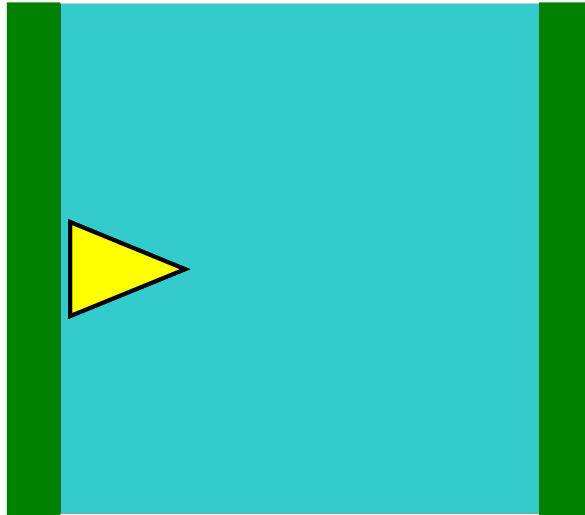
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- a) The study of systems where the input affects the output
- b) The study of control and communication in man and machine
- c) The study of sailors

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## The Steersman (Κυβερνήτης)

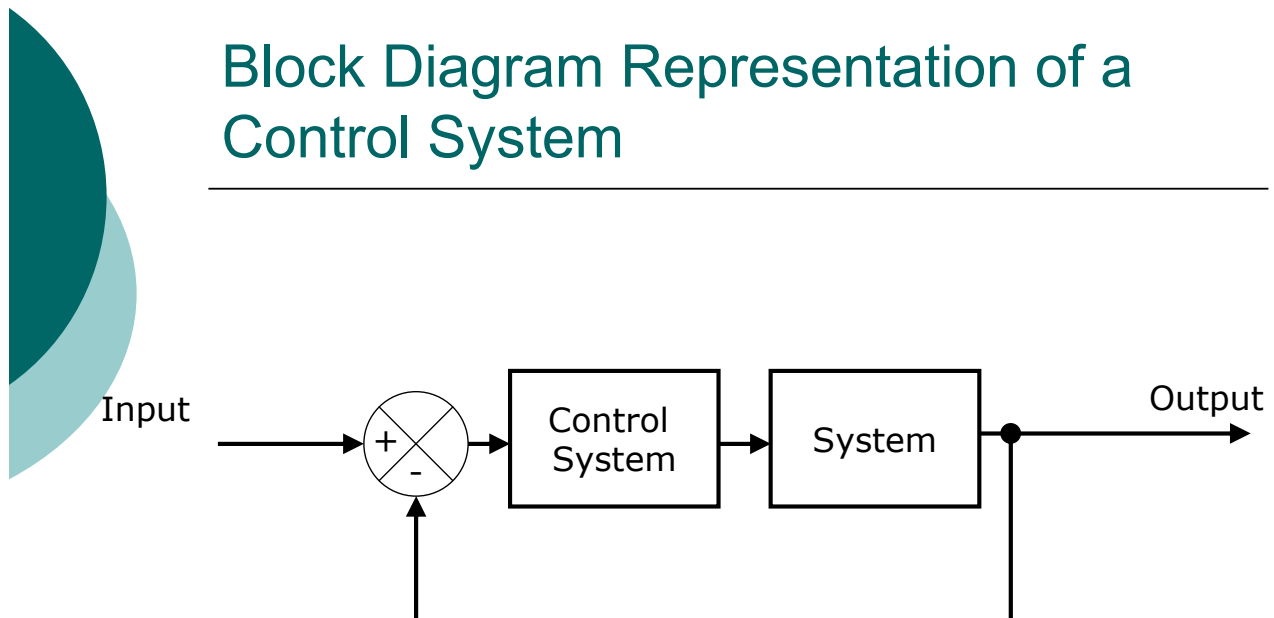
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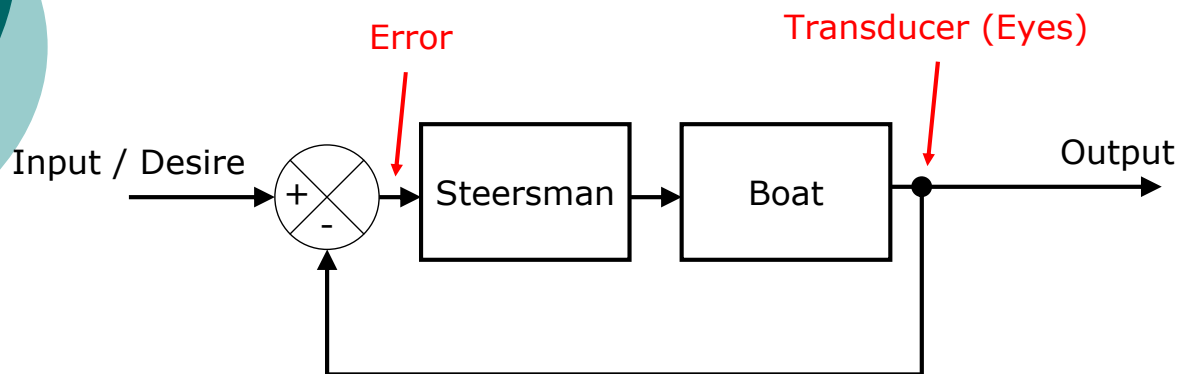
## Block Diagram Representation of a Control System

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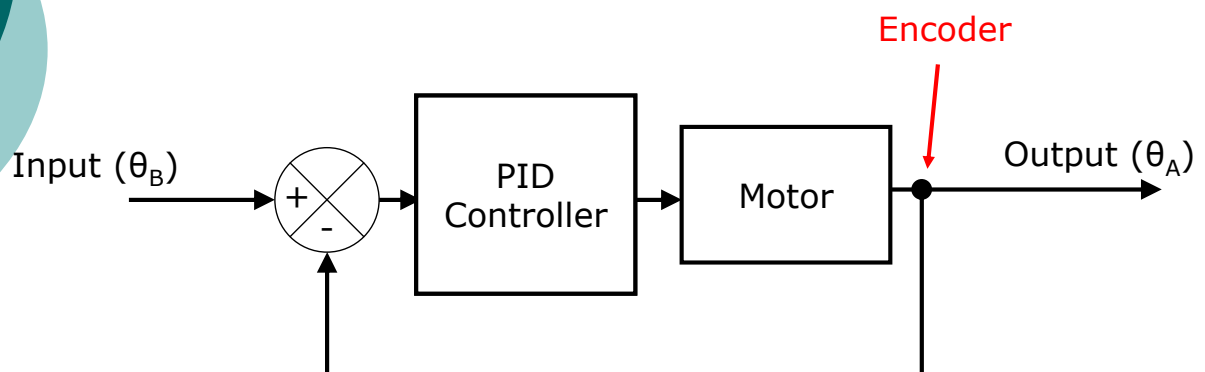
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## Block Diagram Representation of a Control System



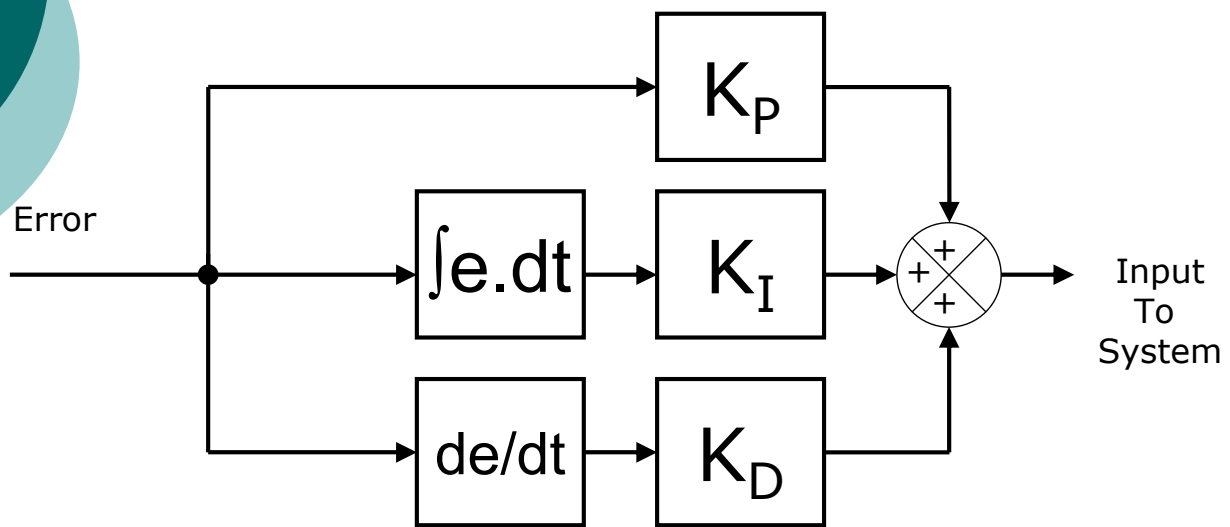
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## Block Diagram Representation of a Control System



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## PID Controller



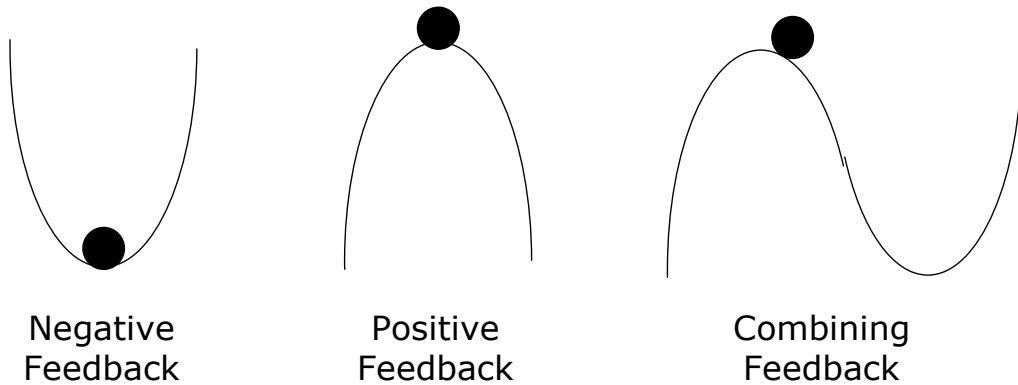
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## Cybernetics vs Control Theory

- Control Theory
  - *Control!*
  - Manipulate inputs
  - Negative feedback is good
  - Positive feedback is bad
- Cybernetics
  - Understand, characterise and unite
  - Feedback is feedback!

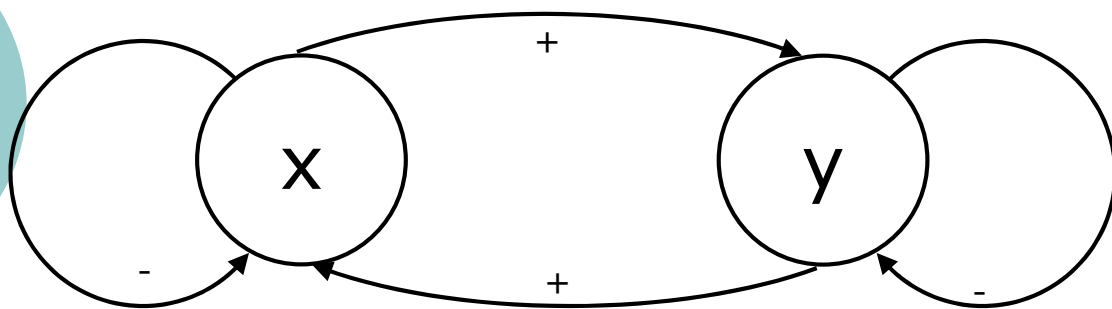
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## Is Positive Feedback Really That Bad?



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## Ordinary Differential Equations (ODEs) for System Representation



$$\frac{dx}{dt} = -13 - 2x^2 + 21y$$

$$\frac{dy}{dt} = -13 + 8x - 3y^2$$

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# Numerical Simulation Based on Differential Equations

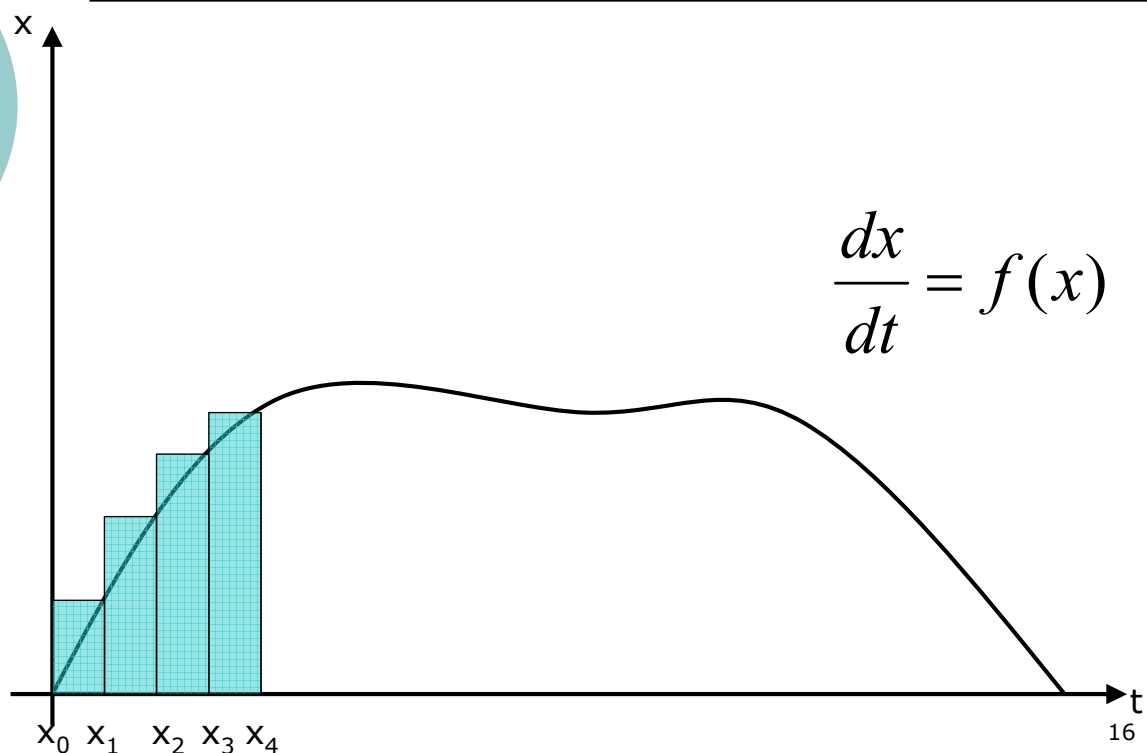
## ○ Euler's Method

$$\frac{dx}{dt} = f(x) - 2x^2 + 21y$$

$$x_{n+1} = x_n + \Delta_t (f(x_n) - 2x_n^2 + 21y_n)$$

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## Euler's Method



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## A Quick Aside

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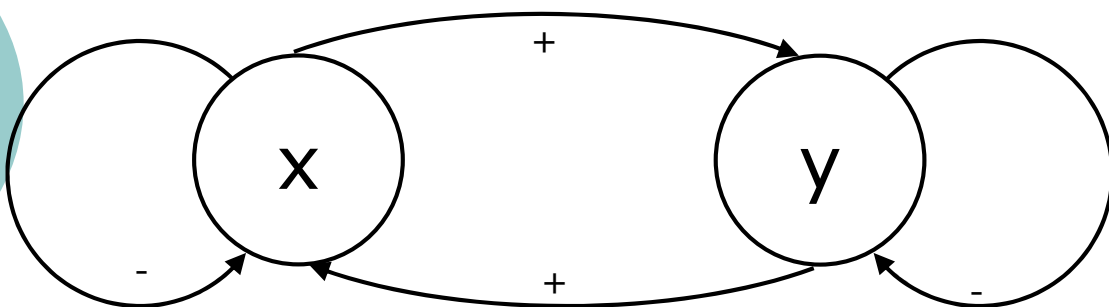
- Better numerical integration techniques exist
- The best one in general is Fourth-Order Runge-Kutta. The wikipedia page is actually very good!

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## Differential Equations for System Representation

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$$\frac{dx}{dt} = -13 - 2x^2 + 21y$$

$$\frac{dy}{dt} = -13 + 8x - 3y^2$$

But where do we start?

This technique can only comment on systems once we know the initial conditions

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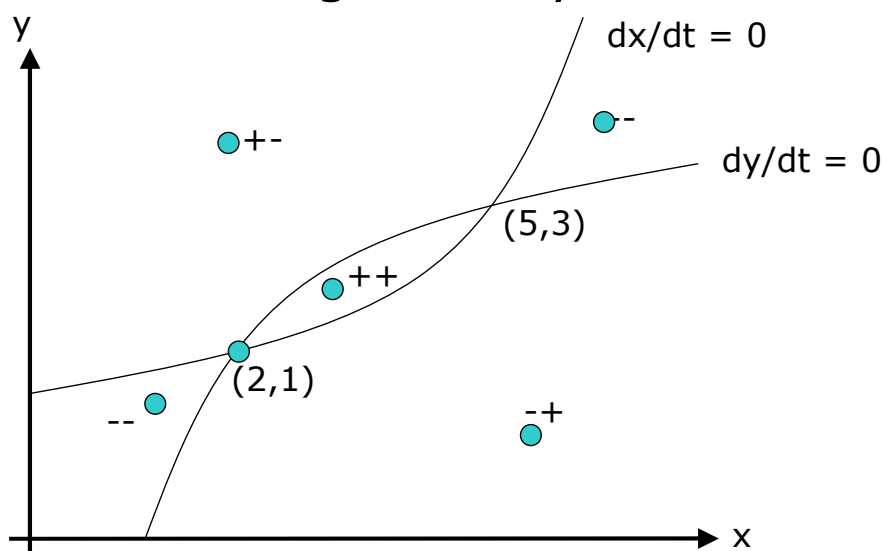
## Isoclines

- There are techniques that allow us to examine a system without knowing the initial conditions
- Examine the isoclines!

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## Isoclines

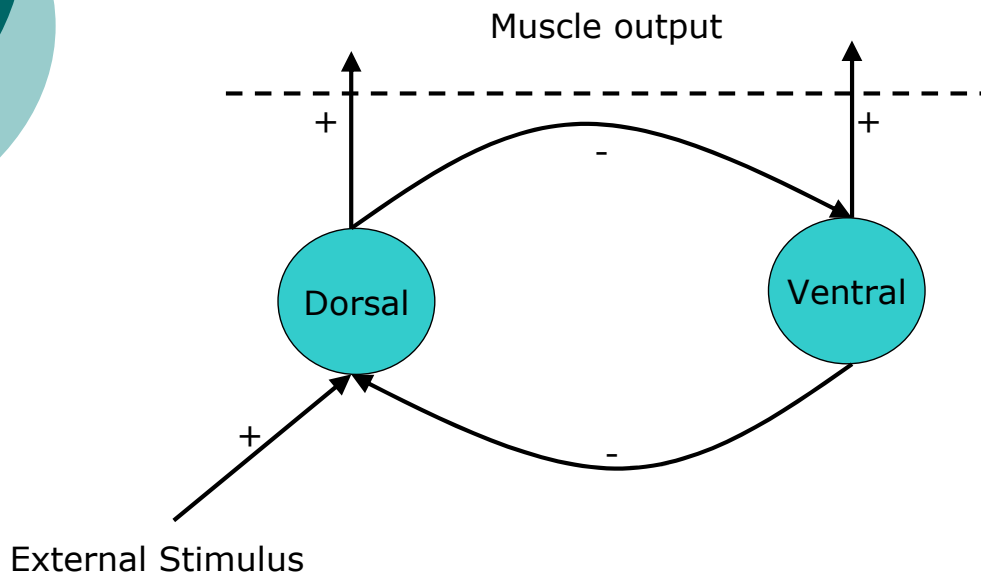
- Assessing stability and “flow”



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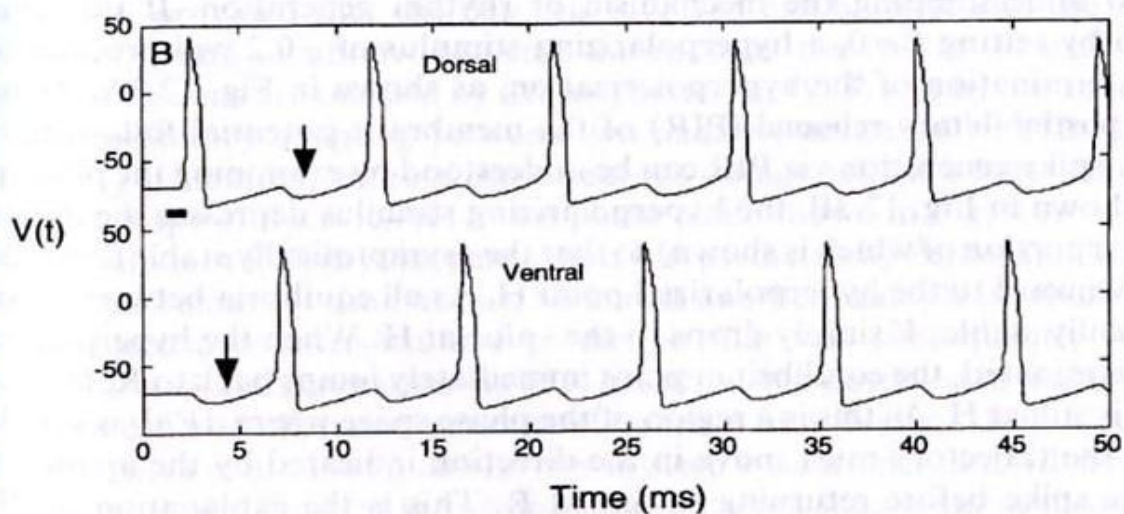
## Sea Angels (Cliones)

<http://www.youtube.com/watch?v=vB5recdpPal>



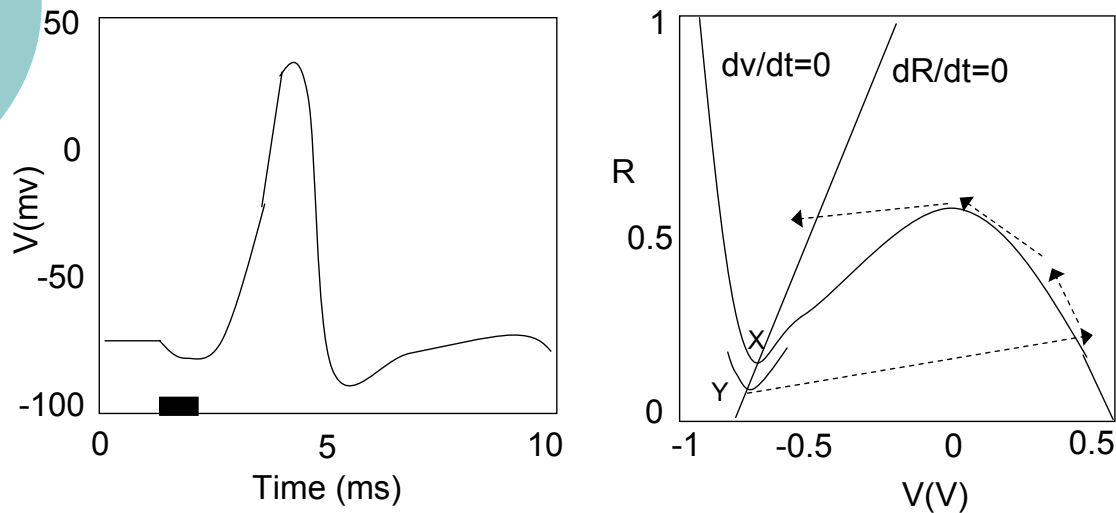
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## Clione Neuron Interaction



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## Isoclines in the Clione Nervous System



$dR/dt$  and  $dV/dt$  models taken from Nagumo et al (1962)

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## Simulation

- ODEs are not the only way to perform simulation
- Many other techniques exist
- It would be interesting to compare ODEs to agent-based simulation

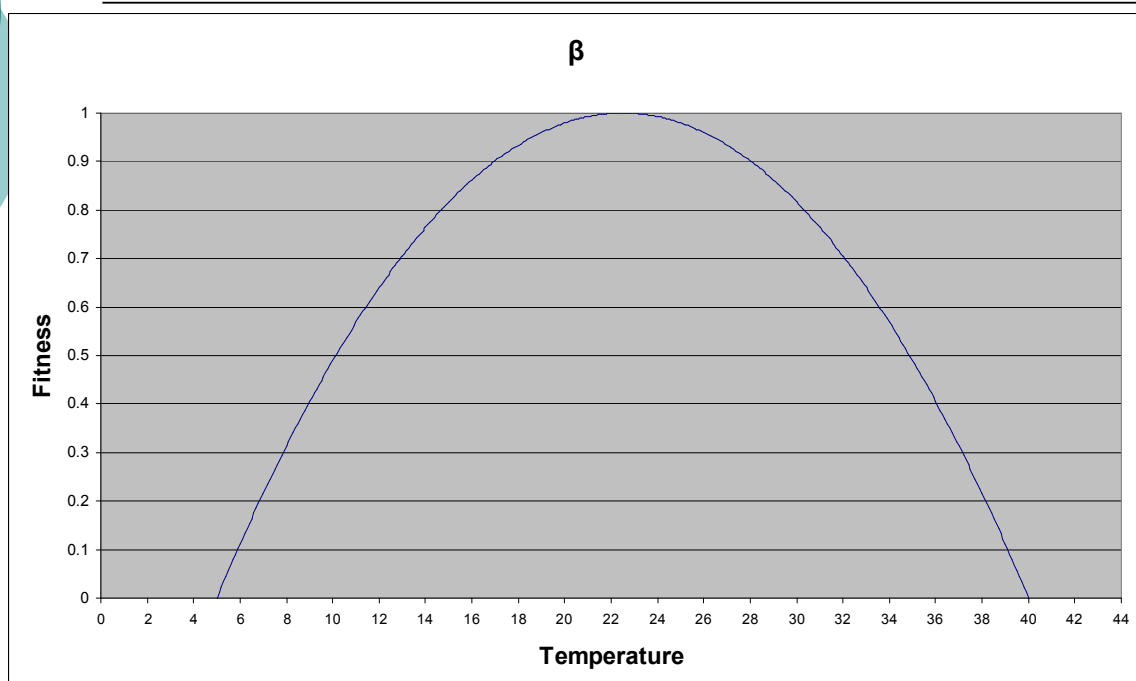
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## Daisyworld – An Investigation into ODE's vs Agent-Based Simulations

- The Parable of Daisyworld
- James Lovelock and Andrew Watson
- Designed to illustrate “Gaia Theory”
- Grey planet
- Two species of daisy – black and white
- A sun getting hotter

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## Daisy Fitness

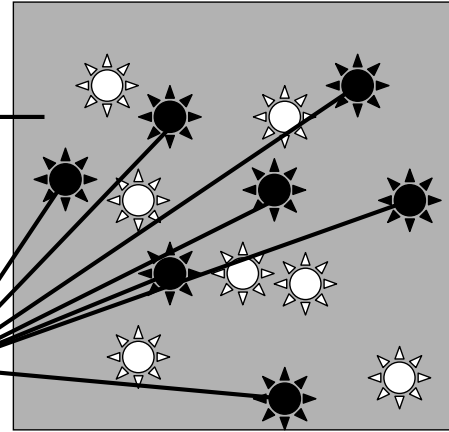


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## Population Dynamics

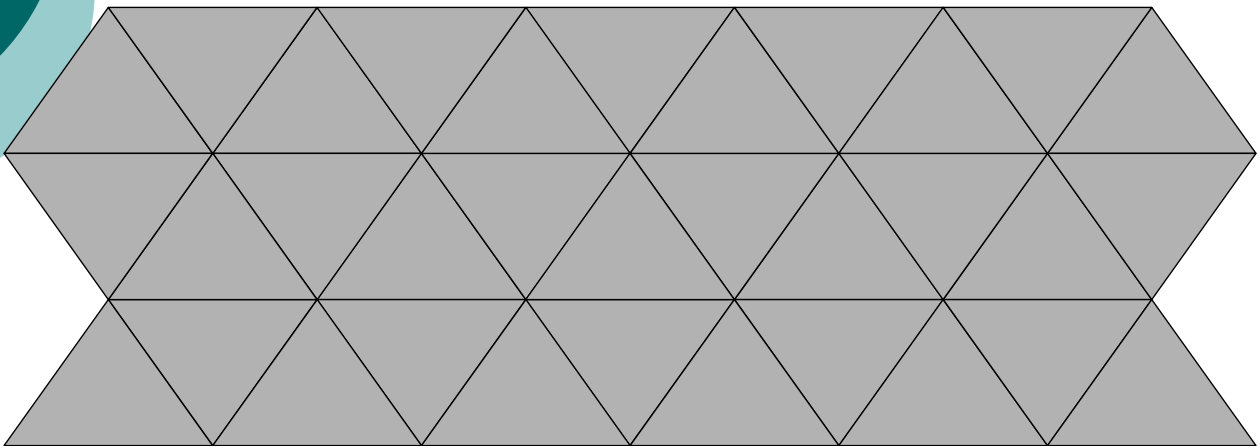
$$\frac{da_P}{dt} = a_P (x\beta - \gamma)$$

Fitness      Death  
Rate



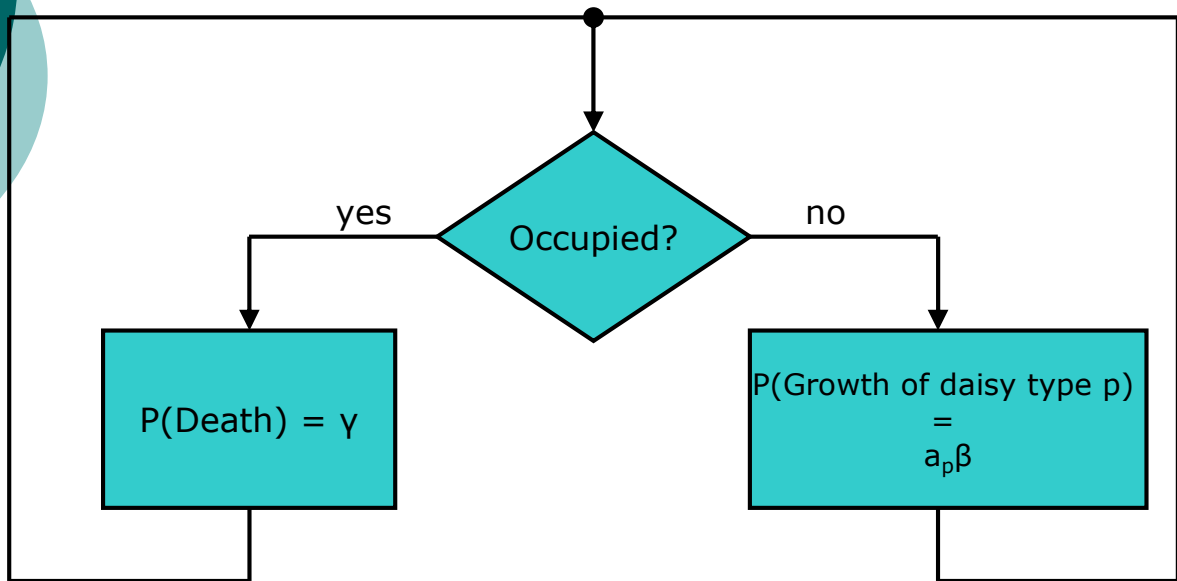
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## Agent-Based System



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## Rules



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## References

- Watson, A. J. and J. E. Lovelock (1983). Biological homeostasis of the global environment: the parable of Daisyworld. *Tellus* 35B, 284-289.
- Isoclines example taken from Dr Richard Mitchell's lecture notes (1999)

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