#### THIRD YEAR B. TECH FIFTH SEMESTER

#### **ELECTRONICS AND COMMUNICATION ENGINEERING DEPARTMENT**

HDL MINI PROJECT (ECL 303)

ON

Washing Machine Control System on Modelsim using Verilog

Ву

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(An Institution of National Importance by Act of Parliament)

#### **ABSTRACT**

This paper aims to showcase the capabilities and versatility of Verilog Hardware Description Language (HDL) by developing the control system for an automated washing machine. The project successfully achieves this goal through the implementation of the washing machine's control system using the Finite State Machine model. This control system generates the necessary signals to oversee and manage the washing machine's overall operation. The digital design is rigorously tested and simulated using MODELSIM software, a product by Mentor Graphics.

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### Summary

The Automatic Washing Machine controller encompasses a range of essential functionalities. The washing machine operates within distinct states, including Check\_Door, Fill\_Water, Add\_Detergent, Drain\_Water, and Spin. The controller comprises two fundamental blocks: a Finite-State Machine (FSM) block and a Timer block. The FSM block receives inputs from the user, timer, and hardware components like the door sensor, while its outputs regulate the Timer block and other washing machine components. Table1 delineates the FSM's input and output signals and their respective functions.

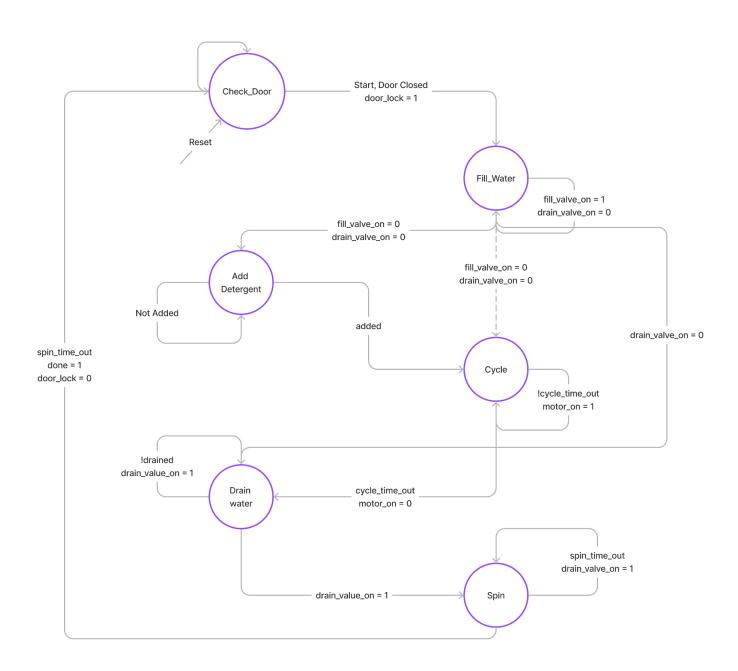
The Timer block plays a pivotal role in generating precise time periods for each washing cycle, following a reset. It is composed of an up-counter and combinational logic to provide accurate time signals once specific count values are reached. The timer values are contingent on the clock frequency employed within the system, ensuring proper timing for the washing machine's operation.

# Specifications:

Signal Name	Direction	Purpose
Clock	input	Clock, positive edge triggered.
Reset	input	Reset, synchronous and active high.
Start	Input	Should generate a pulse; 1 = start washing process; 0 =
		don't start. This start should be used to generate a pulse
		to trigger an internal flag register.
Door_close	Input	Used to see if the door is closed;
		Door_close = 0; Machine stops (in any state).
		Door_close = 1; Machine resumes/starts.
Filled	Input	From some sensor; Filled = 1 means water filled OK.
Drained	Input	From some sensor; Drained = 1 means drained OK.
Added	Input	From user; Added = 1 means detergent added OK.
Cycle_Timeout	Input	From timer; Cycle_Timeout = 1 means time finished go
		to next state
Spin_Timeout	Input	From timer; Spin_Timeout = 1 means time finished go to
		next state
Motor_on	output	Motor_on = 1; drive the motor.
		Motor_on = 0; motor off, not driven.
Fill_Valve_on	output	Fill_valve_on = 1; valve open& filling will proceed.
		Fill_valve_on = 0; valve closed & filling stops.
Drain_valve_on	output	Drain_valve_on = 1; drain valve open & draining in
		progress.
		Drain_valve_on = 0; drain valve closed and draining
		stopped.
Door_lock	output	To lock the door (some mechanism)
		Door_lock = 1 when the machine has started
		Door_lock = 0 when the machine has done washing
		The essential condition for the Door_lock is that there
		must be no Water inside the machine. That is, Door_lock
		can only be 0 when Draining has been finished.
Done	output	Done = 1 when draining has been finished and washing
		has been finished. This should also deassert Door_lock.

Table 1: Alphabetical listing of input and output signals for the FSM

# FSM Diagram



The working of the washing machine control system

### **Explanation**

In the design of the source code, it was chosen that a case statement be the preference for the design. A FSM-structure was chosen for the design. It was chosen that based on the amount of states, a 3 bit signal would be enough to represent the state. There were a total of 6 states in our design. There is 1 "off" state for when the power is off, 1 "Check\_Door" state for when the machine is not running, or incrementing, and 6 states for the washing machine. We originally wanted to add two scenarios that we could handle, which are if the machine asynchronously loses power, or if the door asynchronously opens. We were successful in implementing both signals in simulation. Then After the Check Door State there is Fill Water state which checks that the water is filled in the drum .After that there is Add Detergent state which checks if the detergent has been added .After it the Cycle stage is there which accomplishes the washing cycle ,After that Drain Water stage has been encountered which checks if the water has been draind out or not and finally there is Spin stage and when the process has been completed the process is Finally Done and each stage has been changed after the encounter of the positive pulse of the clock only.

## Verilog Code

```
module Automatic_Washing_Machine (
    input Clock,
    input Reset,
    input Start,
    input Door Close,
    input Filled,
    input Drained,
    input Detergent_Added,
    input Cycle Timeout,
    input Spin_Timeout,
    output reg Motor_on,
    output reg Fill valve on,
    output reg Drained_valve_on,
    output reg Door_Lock,
    output reg Done
);
parameter Check_Door = 3'b000;
parameter Fill_Water = 3'b001;
parameter Add_Detergent = 3'b010;
parameter Cycle = 3'b011;
parameter Drain_Water = 3'b100;
parameter Spin = 3'b101;
reg [2:0] Current_State, Next_State;
always @(posedge Clock, negedge Reset) begin
    if (Reset == 0) begin
        Current_State <= Check_Door;</pre>
    end else begin
        Current_State <= Next_State;</pre>
    end
end
always a(*) begin
    case (Current_State)
        Check_Door: begin
            if (Start == 1 && Door_Close == 1) begin
                Next_State = Fill_Water;
                Motor_on <= 0;
                Fill_valve_on <= 0;</pre>
                Drained valve on <= 0;
                Door_Lock <= 1;</pre>
```

```
Done \leftarrow 0;
    end else begin
         Next_State = Current_State;
         Motor on <= ∅;
         Fill_valve_on <= 0;</pre>
         Drained_valve_on <= 0;</pre>
         Door_Lock <= 0;</pre>
         Done \leftarrow 0;
    end
end
Fill_Water: begin
    if (Filled == 1) begin
         Next_State = Add_Detergent;
         Motor_on <= 0;</pre>
         Fill_valve_on <= 0;</pre>
         Drained_valve_on <= 0;</pre>
         Door_Lock <= 1;</pre>
         Done <= 0;
    end else begin
         Next_State = Current_State;
         Motor_on <= 0;</pre>
         Fill_valve_on <= 1;</pre>
         Drained_valve_on <= 0;</pre>
         Door_Lock <= 1;</pre>
         Done \leftarrow 0;
    end
end
Add_Detergent: begin
    if (Detergent_Added == 1) begin
         Next_State = Cycle;
         Motor_on <= 0;
         Fill_valve_on <= 0;</pre>
         Drained_valve_on <= 0;</pre>
         Door_Lock <= 1;</pre>
         Done <= 0;
    end else begin
         Next_State = Current_State;
         Motor_on <= 0;
         Fill_valve_on <= 0;</pre>
         Drained_valve_on <= 0;</pre>
         Door_Lock <= 1;</pre>
         Done <= 0;
    end
end
Cycle: begin
    if (Cycle_Timeout == 1) begin
```

```
Next State = Drain Water;
         Motor_on <= 0;</pre>
         Fill_valve_on <= 0;</pre>
         Drained valve on <= 0;
         Door_Lock <= 1;</pre>
         Done <= 0;
    end else begin
         Next_State = Current_State;
         Motor_on <= 1;</pre>
         Fill_valve_on <= 0;</pre>
         Drained_valve_on <= 0;</pre>
         Door_Lock <= 1;</pre>
         Done <= 0;
    end
end
Drain Water: begin
    if (Drained == 1) begin
         Next_State = Spin;
         Motor on <= 0;
         Fill_valve_on <= 0;</pre>
         Drained_valve_on <= 1;</pre>
         Door_Lock <= 1;</pre>
         Done <= 0;
    end else begin
         Next_State = Current_State;
         Motor_on <= 0;
         Fill_valve_on <= 0;</pre>
         Drained_valve_on <= 1;</pre>
         Door_Lock <= 1;</pre>
         Done <= 0;
    end
end
Spin: begin
    if (Spin_Timeout == 1) begin
         Next_State = Check_Door;
         Motor_on <= 0;
         Fill valve on <= 0;
         Drained_valve_on <= 0;</pre>
         Door_Lock <= 0;</pre>
         Done <= 1;
    end else begin
         Next_State = Current_State;
         Motor_on <= 0;
         Fill_valve_on <= 0;</pre>
         Drained_valve_on <= 1;</pre>
         Door_Lock <= 1;</pre>
```

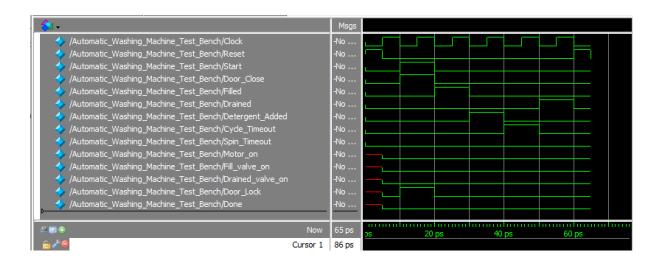
```
Done <= 0;
    end
    end
    default: begin
        Next_State = Check_Door;
    end
    endcase
end
endmodule</pre>
```

#### Test Bench

```
module Automatic_Washing_Machine_Test_Bench;
  reg Clock, Reset, Start, Door_Close, Filled, Drained, Detergent_Added,
Cycle_Timeout, Spin_Timeout;
  wire Motor on, Fill valve on, Drained valve on, Door Lock, Done;
  Automatic_Washing_Machine Customer1(
    .Clock(Clock),
    .Reset(Reset),
    .Start(Start),
    .Door_Close(Door_Close),
    .Filled(Filled),
    .Drained(Drained),
    .Detergent_Added(Detergent_Added),
    .Cycle Timeout(Cycle Timeout),
    .Spin_Timeout(Spin_Timeout),
    .Motor_on(Motor_on),
    .Fill_valve_on(Fill_valve_on),
    .Drained_valve_on(Drained_valve_on),
    .Door_Lock(Door_Lock),
    .Done(Done)
  );
  initial begin
$monitor("Time=%d,Clock=%b,Reset=%b,Start=%b,Door_Close=%b,Filled=%b,Dra
ined=%b,Detergent Added=%b,Cycle Timeout=%b,Spin Timeout=%b,Motor on=%b,
Fill_valve_on=%b,Drained_valve_on=%b,Door_Lock=%b,Done=%b",
      $time, Clock, Reset, Start, Door_Close, Filled, Drained,
Detergent_Added, Cycle_Timeout, Spin_Timeout,
```

```
Motor_on, Fill_valve_on, Drained_valve_on, Door_Lock, Done);
 end
 initial begin
   Clock = 0;
   Reset = 1;
   Start = 0;
   Door_Close = 0;
   Filled = 0;
   Drained = 0;
   Detergent_Added = 0;
   Cycle_Timeout = 0;
   Spin_Timeout = 0;
   #5 Reset = 0;
   #5 Start = 1;
   Door Close = 1;
   #10 Filled = 1;
   Start = 0;
   Door Close = 0;
   #10 Detergent_Added = 1;
   Filled = 0;
   #10 Cycle_Timeout = 1;
   Detergent_Added = 0;
   #10 Drained = 1;
   Cycle Timeout = 0;
   #10 Spin_Timeout = 1;
   Drained = 0;
   Spin_Timeout = 0;
   // Reset the state machine for the next test case
   Reset = 1;
   #5 Reset = 0;
   // Add additional test cases if needed
   // End the simulation
   $finish;
 end
 always begin
   #5 Clock = ~Clock;
 end
endmodule
```

#### Waveform



## **Output Transcript**

```
view signals

* main pane objects.interior.cs.body.tree

* inn mill

* Time

* O,Clocke0, Reset=1, Start=0, Door_Close=0, Filled=0, Drained=0, Detergent_Added=0, Cycle_Timeout=0, Motor_on=x, Fill_valve_on=x, Drained_valve_on=x

* Door_Locke0, Done=0

* Time

* Door_Locke1, Done=0

* Time

* Door_Locke0, Done=0

* Time

* Time

* Door_Locke0, Done=0

* Time

* Ti
```

#### Time=

0,Clock=0,Reset=1,Start=0,Door\_Close=0,Filled=0,Drained=0,Detergent\_Adde
d=0,Cycle\_Timeout=0,Spin\_Timeout=0,Motor\_on=x,Fill\_valve\_on=x,Drained\_va
lve\_on=x,Door\_Lock=x,Done=x

# Time=

5,Clock=1,Reset=0,Start=0,Door\_Close=0,Filled=0,Drained=0,Detergent\_Adde
d=0,Cycle\_Timeout=0,Spin\_Timeout=0,Motor\_on=0,Fill\_valve\_on=0,Drained\_va
lve\_on=0,Door\_Lock=0,Done=0

# Time=

10,Clock=0,Reset=0,Start=1,Door\_Close=1,Filled=0,Drained=0,Detergent\_Add

```
ed=0,Cycle_Timeout=0,Spin_Timeout=0,Motor_on=0,Fill_valve_on=0,Drained_v
alve_on=0,Door_Lock=1,Done=0
# Time=
15,Clock=1,Reset=0,Start=1,Door Close=1,Filled=0,Drained=0,Detergent Add
ed=0,Cycle Timeout=0,Spin Timeout=0,Motor on=0,Fill valve on=0,Drained v
alve_on=0,Door_Lock=1,Done=0
# Time=
20,Clock=0,Reset=0,Start=0,Door Close=0,Filled=1,Drained=0,Detergent Add
ed=0,Cycle_Timeout=0,Spin_Timeout=0,Motor_on=0,Fill_valve_on=0,Drained_v
alve_on=0,Door_Lock=0,Done=0
# Time=
25,Clock=1,Reset=0,Start=0,Door Close=0,Filled=1,Drained=0,Detergent Add
ed=0,Cycle Timeout=0,Spin Timeout=0,Motor on=0,Fill valve on=0,Drained v
alve_on=0,Door_Lock=0,Done=0
# Time=
30,Clock=0,Reset=0,Start=0,Door Close=0,Filled=0,Drained=0,Detergent Add
ed=1,Cycle_Timeout=0,Spin_Timeout=0,Motor_on=0,Fill_valve_on=0,Drained_v
alve_on=0,Door_Lock=0,Done=0
# Time=
35,Clock=1,Reset=0,Start=0,Door Close=0,Filled=0,Drained=0,Detergent Add
ed=1,Cycle_Timeout=0,Spin_Timeout=0,Motor_on=0,Fill_valve_on=0,Drained_v
alve_on=0,Door_Lock=0,Done=0
# Time=
40,Clock=0,Reset=0,Start=0,Door_Close=0,Filled=0,Drained=0,Detergent_Add
ed=0,Cycle Timeout=1,Spin Timeout=0,Motor on=0,Fill valve on=0,Drained v
alve_on=0,Door_Lock=0,Done=0
# Time=
45,Clock=1,Reset=0,Start=0,Door Close=0,Filled=0,Drained=0,Detergent Add
ed=0,Cycle_Timeout=1,Spin_Timeout=0,Motor_on=0,Fill_valve_on=0,Drained_v
alve_on=0,Door_Lock=0,Done=0
# Time=
50, Clock=0, Reset=0, Start=0, Door_Close=0, Filled=0, Drained=1, Detergent_Add
ed=0,Cycle_Timeout=0,Spin_Timeout=0,Motor_on=0,Fill_valve_on=0,Drained_v
alve on=0,Door Lock=0,Done=0
# Time=
55,Clock=1,Reset=0,Start=0,Door_Close=0,Filled=0,Drained=1,Detergent_Add
ed=0,Cycle Timeout=0,Spin Timeout=0,Motor on=0,Fill valve on=0,Drained v
alve_on=0,Door_Lock=0,Done=0
# Time=
60,Clock=0,Reset=1,Start=0,Door Close=0,Filled=0,Drained=0,Detergent Add
ed=0,Cycle Timeout=0,Spin Timeout=0,Motor on=0,Fill valve on=0,Drained v
alve_on=0,Door_Lock=0,Done=0
# ** Note: $finish
                      : C:/Users/sahil/OneDrive/Documents/washing
machine/Automatic_Washing_Machine_Test_Bench.v(62)
     Time: 65 ps Iteration: 0 Instance:
/Automatic_Washing_Machine_Test_Bench
```

## Conclusion

In conclusion, this project successfully demonstrates the practical application of Verilog Hardware Description Language (HDL) in the development of an Automatic Washing Machine controller. By implementing the controller using a Finite-State Machine (FSM) model, we have showcased the versatility of Verilog HDL in designing complex control systems.