Knapsack Problem

Fractional Knapsack ( Oncedy)

0/1 Knapsack C Dynamic Programming

Fractional Knapsack Problem

15 Kg

Problem statement:

How you will select the items
so that you will get maximum

Profit Maximization problem

Max Profit

objects:

Profit (P): 5 10 15 7 8 9 4

weight (w): 1 3 5 4 1 3 2

Objects	Profit(P)	Neight (w)	Remaining weight
3	15	5	15-5=10
2	10	3	10-3=7
6	9	3	7-3=4
5	8	1	4-1 =3
4	7×3 = 5.25	3	3-3 = 0

Total Profit = 47.25

Minimum Luight

Objects	Profit (P)	Leight (w)	Remaining
1	5	1	15-4=14
5	8	1	14-1= 13
7	4	2	13-2 = 11
2	10	3	11-3 =8
6	9	3	8-3 = 5
	7	4	5-4=[]
3	15 × = -3	1	1-1=10

Total Profit = 46

Maximum P/w Ratio

Objects: 1234567

Profit (P): 5 10 15 7 8 9 4

Neight (N): 1 3 5 4 1 3 2

(P/w): 5 3.3 3 1.75 8 3 2

Objects	Protit (P)	Height (w)	Remaining
	8	1	15-1 = 14
5	5	I .	14-1 = 13
2	10	.3	13-3 = 10
3	15	5	10-5 = 5
6	9	3	5-3 = 2
7	4	2	2-2 = 0

Total Profit = 51

Maximum profit is attained by
Profit / Ratio. This is the fractional Knapsack which is solved by Creedy method.

Algorithm

for Algorithm: Oucedy - Fractional - Knapsack

Cw[in] > P[in] > N)

fox i= 1 ton

do x[i] = 0

weight =0

fox i= 1 ton

if weight + W[i] & H then

×[i]=1

weight = weight + w[i]

else

×(i)= (H-weight) /w[i]

weight = N

break.

11tuen x

Analysis

If the provided items are already soxted in descending order of Pi then the whileloop takes time D(n). They one the total time including the sort is O(nlogn).

		1000					3		
18CSC204J-DESIGN AND ANALYSIS OF ALGORITHM									
Example	C	and i		33		1933			
Neight CHO)	7	3		4		5			
Profit (Po)	42	12		40		25			
	Bag capacity (m)=10 {constraint - 2 xihi = m}								
Po/vi	6	4		10		5			
(06×7=1)	6/7	D				0	10		
MEIO	10-4=6				26	*			

 $\angle x_i R_i = (6/7)^* + 0^* + 0^* + 1^* + 0^* = 10$  $\angle x_i R_i = (6/7)^* + 2 + 0^* + 1^* + 1^* + 0 + 0^* = 10$ 

Knapsack Using Brute force Technique C Exhaustive Search) Capacity CH) = 10

S.No	1	2	3	4
Leight (wi)	7	3	4	5
Value (vi)	942	912	440	9 25

Subset	Total beight	Total value
9	0	90
9,4	7	942
£23	3	9 12
£37	4	940
ર્વયુ	5	925
1,523	10	954
11339	l <sub>1</sub>	Not feasible
2043	12	Not feasible
12,334	7	952
22043	8	437
(23)439	9	\$65
1 122334	14	Not feasible
£ 152543	15	Not feasible
113343	16	Not fearible
\$ 203047 \$ 10 20 30 479	12	Not fearthe
200019	19	Not feasible

Total Items (n)=4

Time Complexity 
$$O(n) = 2^{4} = 16$$
.

 $O(n) = 2^{n}$ 

$$m=8$$
  $P = {102,5,6}$   
 $n=4$   $w = {2,3,4,5}$ 

				1	2	3	4	5	6	_	8
Pi	Wi	0	0	0	10	10	10	10	0	To	10
1 1	2		0	0	1	1	1	- 1	1 1	1	1
2	3	2	0	0	1	2	2	3	3	3	3
5	4	3	0	0	1	2,	5	5	C	7	7
6	5	4	0	0	1	2	5	6	6	7	8
		-			1			-		-	

$$V[isw] = \max \left\{ V[i-1sw], V[i-1sw-w] \right\}$$

$$\chi_1 \quad \chi_2 \quad \chi_3 \quad \chi_4 \quad 8-6=2 \quad \text{ProA};$$

$$0 \quad 1 \quad 0 \quad 1 \quad 2-2=0$$

c- xow

w- column

Wi-i) - prev row value wis- web of an object

P(i) - protit of an object

Algorithm

Algorithm DP\_Binary Knapsack (V, N, M)

11 Description: Solve binary Knapsack problem using dynamic programming

11 Input: Set of items X, set of weight W,

Profit of items V and Knapsack

capacity M

11 Output: Array v, which holds the solution of problem

for i E 1 ton do V [iso] 60 end for i E 1 to M do V[osi] 6 0 end for i E 1 to n do for j = 0 to M do if bu (i) = j then v (isj) = max { v [i-1)j], v [i] + V [i-1, j-w[i]]74 else V (isi) ← V(i-1) V(i-1.)] /1w(i)>j end end

Algorithm Trace Knapsack (w, v, M) 11 cuis away of weight of n items 11 V is away of value of n items 11 M is the knapsack capacity SWE & 4 Ruming time complexity SP = 24 wing DP can be solved  $i \leftarrow n$ by n Chumbu of items) JE M & M (Capacity of Knapsact) while (j>0) do if (V[i,j) == V([i-1sj) then O (nm) is the i ← 1-1 time complexity else v (i, j) ← v (i, j) - vi J E j - w [i] SW = SW + W(i) SPE SPHV(i) end end.

$$V[[i,j]] = \begin{cases} 0 & \text{if } i = 0 \text{ ox } j = 0 \\ V[[i-1,j]] & \text{if } j \geq \omega \end{cases}$$

$$| \text{Imax } \{V[[i-1,j]], vi + V[[i-1,j] - \omega i] \} \}$$

$$| \text{if } j \geq \omega \end{cases}$$

$$| \text{Imax } \{V[[i-1,j]], vi + V[[i-1,j] - \omega i] \} \}$$

$$| \text{if } j \geq \omega \end{cases}$$

$$| \text{Imax } \{V[[i-1,j]], vi + V[[i-1,j] - \omega i] \} \}$$

$$| \text{if } j \geq \omega \end{cases}$$

$$| \text{Imax } \{V[[i-1,j]], vi + V[[i-1,j]], vi + V[[i-1,j]$$

## 18CSC204J-DESIGN AND ANALYSIS OF ALGORITHM Minimum Spanning Tree What is spanning Tree? CH = (V) E) GI- Graph E - Edges Spanning Tree of Or? C' = (V', E') Conditions for spanning tree V'= V -> Same No: of varies E' ∈ | -, No: of eager would be E' = | V | - | no: of varices - | -> A graph ban have more than one spanning Example tree.

# 18CSC204J-DESIGN AND ANALYSIS OF ALGORITHM is Minimum spanning Tree? Suppose the heaph contains weight, the minimum cost of the total weights is the minimum spanning tree Considu the edge which is having loss Cost

### Properties of Spanning Tree

-> Removing one edge from spanning tree will make it disconnected

> Adding one edge to the ST will create a

If each edge has distinct weight then there will be only one & unique MST

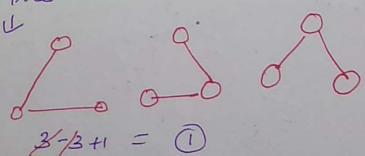
-> A complete undirected graph can have n
no: of spanning tree

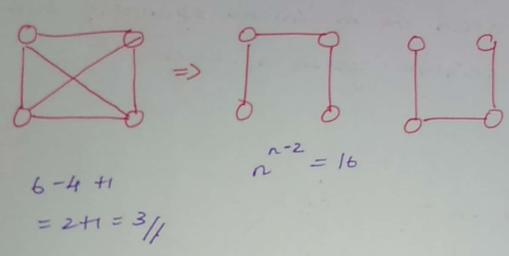
> Every connected undirected graph has atleast one spanning tree

Disconnected graph does not have any Spanning tree

-) From a complete graph by removing max (e-n+1) edges we can construct

a spanning Tree





Prim's Algorithm

Steps

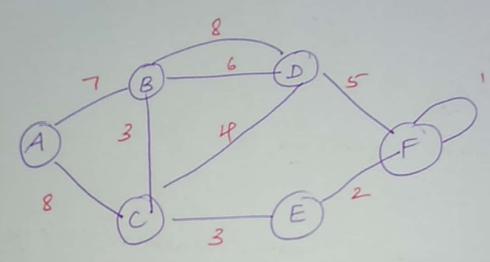
First check if Creaph contains a loop edge or farallel edge

=> 2. If it contains loop edge, remove there

If it contains parallel egge, remove the parallel edge that is having more cost.

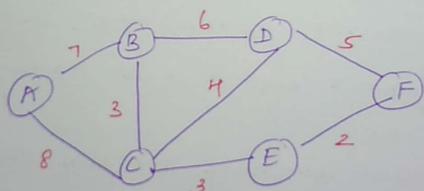
=> 4. Now select any node and from that find the edge having minimum const and in all steps we have to check the Previous steps edges that are not Selected for minimum cost. Follow the steps

till vutices in minimum spanning true and original graph is same.



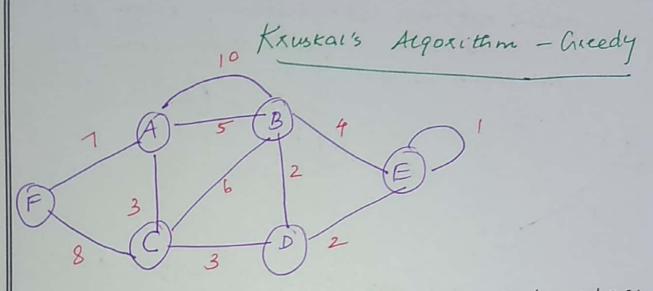
Remove all loops and parallel edges

8 & 6 take minimum edge

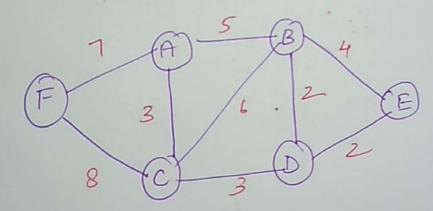


Choose any arbitrary rode as the

# 18CSC204J-DESIGN AND ANALYSIS OF ALGORITHM check out all the outgoing edges farm this root node from that choose the ninimum weight Now check all the outgoing edges from A as well as B 8,3 &6 (minimum) we have to choose 8, 6, 2, 2, 4 8, 6, 3 84 5,2,4,6,8 Time complexity OCCV+ED LOGV



1) Remove all loops & ponallel edges.



2) Assange all edges according to edge weight in inacasing acdus of weight.

BD = 2 DE = 2 AC = 3 CD = 3  $BE = 4 \times$   $AB = 5 \times$   $BC = 6 \times$  AF = 7 FC = 8 DE = 2 AB = 2 AB = 2 AB = 3 CD = 3 CD = 3 DD = 2 DD = 3 DD =

-> MST does not contain any cycles

-> MST does not contain any cycles

-> If n number of vertices in a Cuaph

then it should have same number

of vertices and n-1 edges.

Time Complexity

[Q[E log E) OX D (E log V)

Greedy Approach

Feasible: It has to satisfy the problem's constraints.

Locally optimal: It has to be the best local.

choice among all feasible choices

avoilable on that step.

Inevolable: once made, it cannot be changed on subsequent steps of the algorithm.

Tree Travusal

Inorder: Left Root Right

Priordu: Root Leff Right

Postordu: Left Right Root

Inoxdu:

BDAGECHFI

Preorder:

ABDCEGFHI

Postorda:

DBGEHIFCA

Inorder Traversal

Algorithm

Until all nodes are traversed-

Step 1 - Recursively traverse left subtree

Step2 - Visit Root nade

Step3 - Recursively traverse zight subtree

Pre-ordu Traversal

Algorithm

all nodes are traversed Until

Step1 - Visit xoot node

Recursively traverse lett subtree

Remerively travous right subtree Step 3 -

Post-order Traversal

Algorithm

Untill all nodes are traversed-

Step 1 - Rumsively traverse left subtree

Step2 - Recursively traverse right subtree

- Visit Root Node Step3

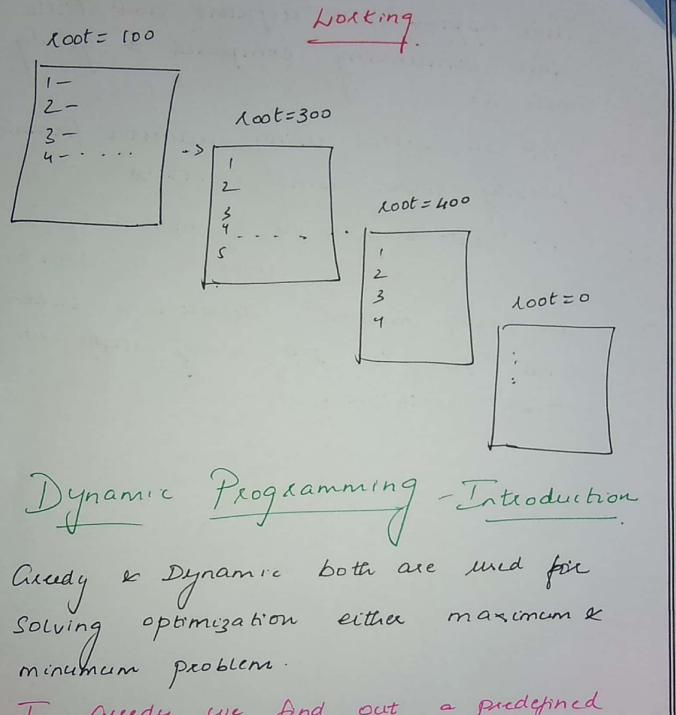
Program

void main ()

struct node \* root. printf (" Preorder is: "); Precide (100t);

```
Inordu (100t);
Postordy (2006);
void Preordy (struct node * root)
   if (200t ==0)
   L setur;
  else
   2 printf ("/d", xoot > data);
     Preordy (200t -> (4t);
     Preorder (200t -> right).
void Inordu (Etruit node * 200t)
     if (100t = =0)
     E setun;
     che
      Inoidu (200t -> left);
      Print ("yd", root -) data);
      Thorder Croot -> right).
```

### 18CSC204J-DESIGN AND ANALYSIS OF ALGORITHM 4 4 void Postardy (struct node \* 200t) else L post order (200+ -> left) postorder ( root -) Right); Look Pring (" y.d" root -) data); 300 250 400 800 10 Inordu = Left Poot Right 400 800 2 9 5 8 4 101 Preorder = Root & Right = 4 5 78 101



In accedy we find out a predefined method for solven, pptimum solution but in dynamic we find out all possibilities for optimum solution.

- -> This approach is different and little time consuming compared to greedy method.
- -> DP are solved using securitive formulas.
- -> Mostly solved using ctuations
- -> DP follows principle of optimality ->

  It means taking sequence of decisions
- -) In acedy method decision is taken once but in DP every stage we take decisions.