

## **BUS CONTENTION / BUS ARBITRATION / PRIORITY RESOLVING SCHEMES**

In a Loosely coupled system all processors can use their local bus simultaneously. But the system bus can be used by only one module at a time. Hence there is contest for the system bus. This is called bus contention. It is resolved by various arbitration schemes having different priority methods.

### **A) Daisy Chain Method**

- **All bus masters use the same line for Bus Request.**
- **If the Bus Busy line is inactive, the Bus Controller gives the Bus Grant signal.**
- Bus **Grant** signal is **propagated serially** through all masters **starting from nearest** one.
- The bus **master**, which requires the system bus, **stops this signal, activates** the Bus **Busy** line and **takes control** of the system bus.

#### **Advantage:**

- i. **Design is simple.**
- ii. The **number of control lines is less**. Also **adding** new bus masters is **easy**.

#### **Disadvantage:**

- i. **Priority** of bus masters is **rigid** and **depends** on the **physical proximity** of the bus masters with the bus arbiter i.e. The one nearest to the Bus Arbiter gets highest priority.
- ii. Bus is granted **serially** and hence a **propagation delay** is induced in the circuit.
- iii. **Failure of one** of the devices may **fail** the entire **system**.

### **B) Polling Method**

- Here also **all bus masters** use the **same** line for **Bus Request**.
- Here the **controller generates** binary **address** for the master.  
Eg: To connect 8 bus masters we need 3 address lines ( $2^3 = 8$ ).
- In **response** to a **Bus Request**, the **controller "polls"** the bus masters by **sending a sequence** of bus master **addresses** on the address lines. Eg: 000,010,100,011 etc
- The selected **master activates** the **Bus Busy** line and **takes control** of the bus.

#### **Advantage:**

- i. The **Priority** is **flexible** and can easily be **changed** by **altering** the **polling sequence**.
- ii. If **one** module **fails**, the entire **system does not fail**.

#### **Disadvantage:**

- i. **Adding** more bus masters is **difficult** as **increases** the number of **address lines** of the circuit. Eg: In the above circuit to add the 9<sup>th</sup> Bus Master we need 4 address lines.

### **C) Independent Request Method**

- Here, **all bus masters** have their **individual Bus Request** and **Bus Grant lines**.
- The **controller thus knows which master has requested**, so bus is granted to that master.
- **Priorities** of the masters are **predefined** so on **simultaneous Bus Requests**, the bus is **granted based** on the **priority**, provided the Bus Busy line is not active.
- The **Controller** consists of **encoder** and **decoder** logic for the priorities.

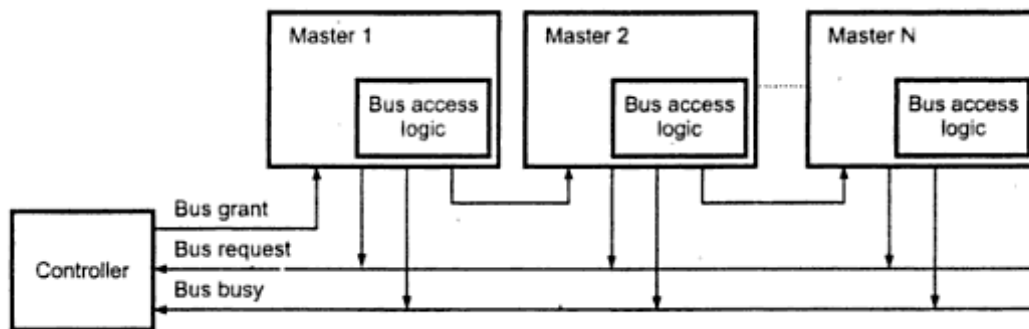
#### **Advantage:**

- i. The Bus **Arbitration is fast**.
- ii. The **speed of Bus Arbitration** is **independent** of the **number** of devices connected.

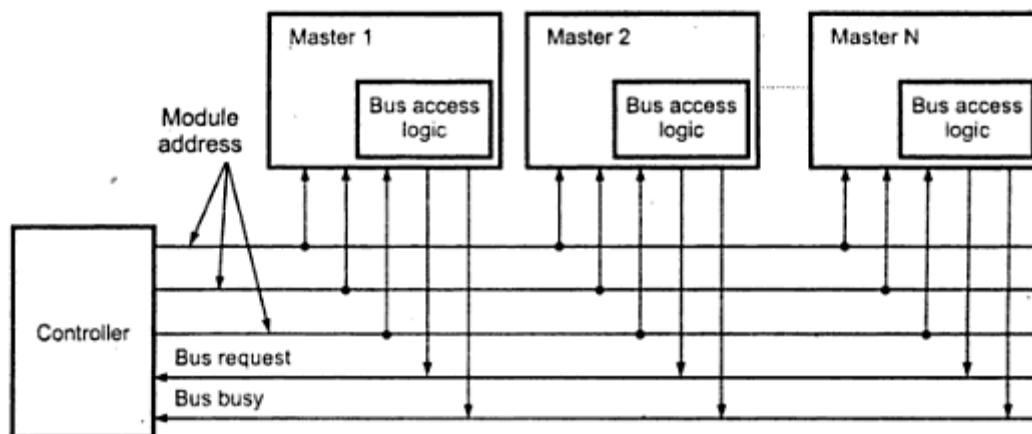
#### **Disadvantage:**

- i. The **number of control lines required is more** ( $2n$  line required for  $n$  devices).

## Daisy Chaining



## Polling



## Independent Requests

