

MAL7080 Mathematical Modeling and Simulations

10 marks

Tutorial 3

Due date: 1 May, 2024

- You need to submit this tutorial in Jupyter notebook form.
- Late submissions will not be considered.

1. Implement the following numerical differentiation and numerical integration methods: [6]

- (a) First order forward finite difference approximation for y'
- (b) Second order central finite difference approximation for y'
- (c) First order forward finite difference approximation for y''
- (d) Second order central finite difference approximation for y''
- (e) Composite Trapezoidal rule for integration
- (f) Composite Simpson's 1/3 rule

2. Consider the following data of a distance travelled by a vehicle: [1]

t [s]	0	2	4	6	8	10	12	14	16
x [m]	0	0.7	1.8	3.4	5.1	6.3	7.3	8.0	8.4

- (a) Find the velocity and the acceleration at $t = 10$ s.
- (b) Find the velocity and the acceleration at $t = 5$ s.

3. Write a code to obtain first derivative estimates for the following unequally paced data: [1]

x [s]	0.6	1.5	1.6	2.5	3.5
$f(x)$ [m]	0.9036	0.3734	0.3261	0.08422	0.01596

where $f(x) = 5xe^{-2x}$. Compare your results with the true derivatives.

4. The amount of mass transported via a pipe over a period of time can be computed as [1]

$$M = \int_{t_1}^{t_2} Q(t)c(t) dt$$

where M = mass (mg), t_1 = the initial time (min), t_2 = the final time (min), $Q(t)$ = flow rate (m^3/min), and $c(t)$ = concentration (mg/m^3). Suppose that the temporal variation in flow and concentration are defined as:

$$\begin{aligned} Q(t) &= 9 + 5 \cos^2(0.4t), \\ c(t) &= 5e^{-0.5t} + 2e^{0.15t} \end{aligned}$$

Determine the mass transported between $t_1 = 2$ and $t_2 = 8$ min with (a) Composite Trapezoidal rule for integration, (b) composite Simpson's 1/3 rule, (c) composite Simpson's 3/8 rule. Compare your results with the in-built function *quad*.

5. Find the value of $\int_0^1 x e^{-x} dx$ using the above discussed numerical integration methods. Play with the number of sub-intervals. Compare your answer with the exact answer $1 - \frac{2}{e}$. [1]

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