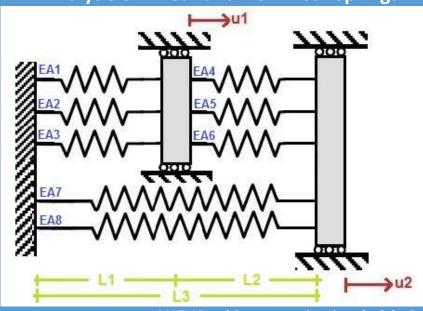
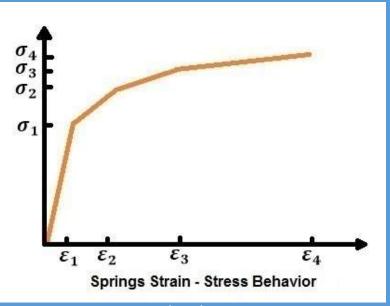
#### >> IN THE NAME OF GOD <<

# Analysis of Linear and Nonlinear Springs with Displacement Control in MATLAB and C++





MATLAB and C++ program is written by Salar Delavar Ghashghaei – Publication Date: 14/June/2017 E-mail: salar.d.ghashghaei@gmail.com

#### **Define Parameters:**

```
% Define Parameters in Free Unit
P1 = 0; % External force [DOF(1)]
P2 = 0; % External force [DOF(2)]
D2 = 0.1; % Initial Incremental Displacement [DOF(2)]
itermax = 500;% maximum number of iterations
tolerance = 1e-12; % specified tolerance for convergence
u = 0;% initial guess value
```

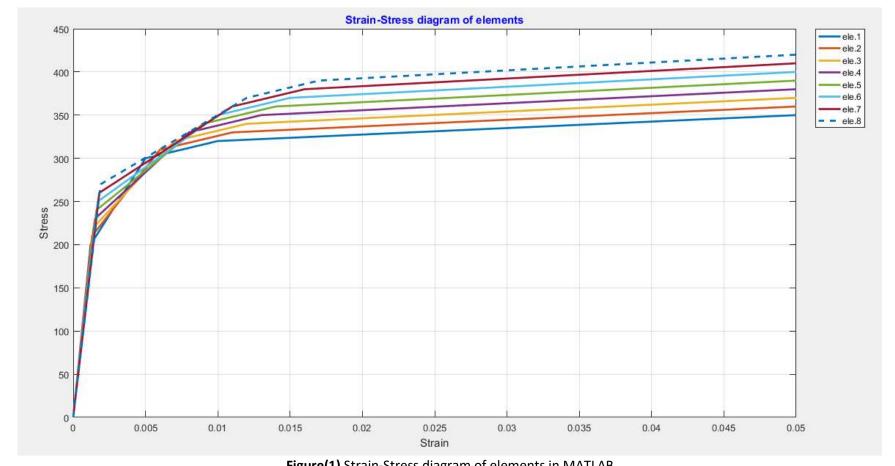
### **Spring Properties:**

```
.0017 250 .01 350 .015 370 .05 400 10;
          .0018 260 .011 360 .016 380 .05 410 20;
          .0019 270 .012 370 .017 390 .05 420 20];
L1 = 1000; % Length of spring 1
L2 = 1000; % Length of spring 2
L3 = 2000; % Length of spring 3
D2max=L1*max(DATA(:,7)); % Maximum displacement [DOF(2)]
for i=1:8
A(i) = DATA(i, 9);
E1(i) = (DATA(i, 2) - 0) / (DATA(i, 1) - 0);
E2(i) = (DATA(i, 4) - DATA(i, 2)) / (DATA(i, 3) - DATA(i, 1));
E3(i) = (DATA(i, 6) - DATA(i, 4)) / (DATA(i, 5) - DATA(i, 3));
E4(i) = (DATA(i, 8) - DATA(i, 6)) / (DATA(i, 7) - DATA(i, 5));
end
m = D2max/D2 +1; % Number of steps increment
# Pushover Analysis of Nonlinear Springs #
(+)Increment 1: It is converged in 2 iterations
(+)Increment 2: It is converged in 2 iterations
(+)Increment 3: It is converged in 2 iterations
(+)Increment 4: It is converged in 2 iterations
(+)Increment 5: It is converged in 2 iterations
(+)Increment 6: It is converged in 2 iterations
```

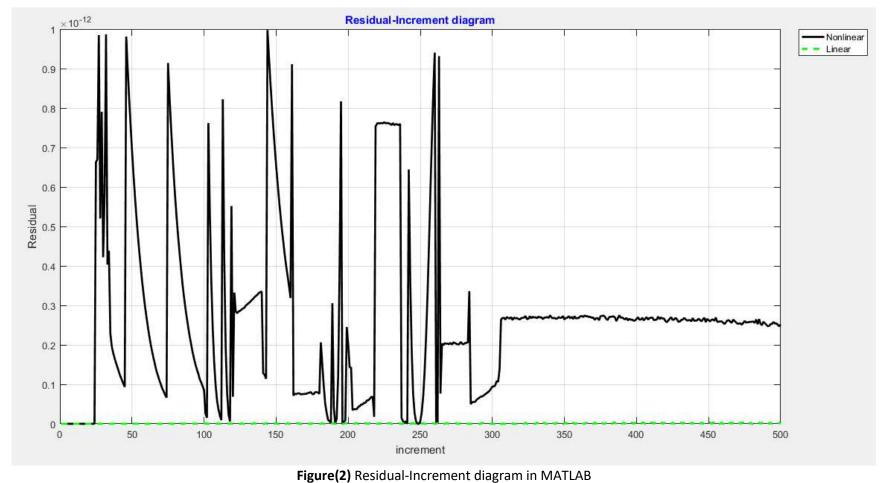
(+)Increment 7: It is converged in 2 iterations (+)Increment 8: It is converged in 2 iterations (+)Increment 9: It is converged in 2 iterations (+)Increment 10: It is converged in 2 iterations (+)Increment 490: It is converged in 11 iterations (+)Increment 491: It is converged in 11 iterations (+)Increment 492: It is converged in 11 iterations (+)Increment 493: It is converged in 11 iterations (+)Increment 494: It is converged in 11 iterations (+)Increment 495: It is converged in 11 iterations (+)Increment 496: It is converged in 11 iterations (+)Increment 497: It is converged in 11 iterations (+)Increment 498: It is converged in 11 iterations (+)Increment 499: It is converged in 11 iterations (+)Increment 500: It is converged in 11 iterations ## Displacement reached to ultimate displacement ##

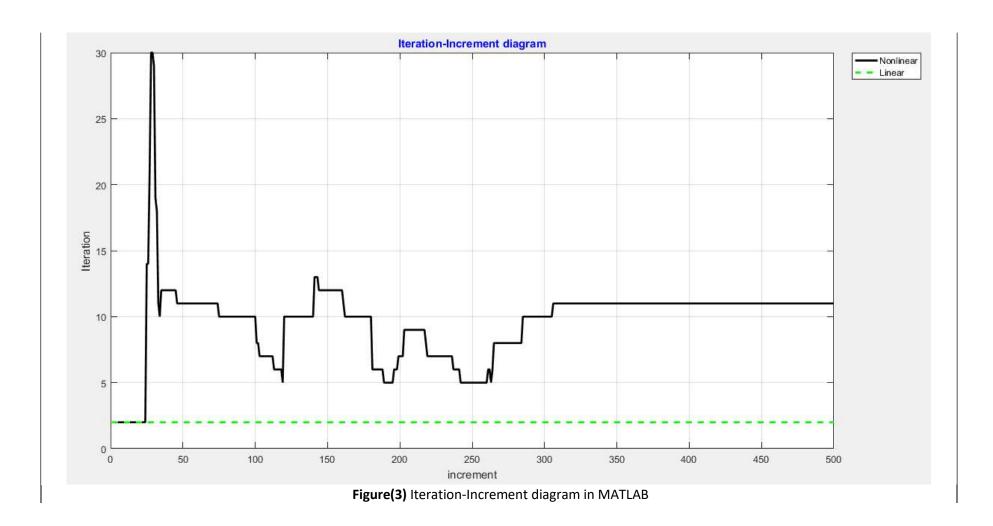
## # Pushover Analysis of Linear Springs # (+)Increment 1: It is converged in 2 iterations (+)Increment 2: It is converged in 2 iterations (+)Increment 3: It is converged in 2 iterations (+)Increment 4: It is converged in 2 iterations (+)Increment 5: It is converged in 2 iterations (+)Increment 6: It is converged in 2 iterations (+)Increment 7: It is converged in 2 iterations (+)Increment 8: It is converged in 2 iterations (+)Increment 9: It is converged in 2 iterations (+)Increment 490: It is converged in 2 iterations (+)Increment 491: It is converged in 2 iterations (+)Increment 492: It is converged in 2 iterations (+)Increment 493: It is converged in 2 iterations (+)Increment 494: It is converged in 2 iterations (+)Increment 495: It is converged in 2 iterations (+)Increment 496: It is converged in 2 iterations (+)Increment 497: It is converged in 2 iterations (+)Increment 498: It is converged in 2 iterations (+)Increment 499: It is converged in 2 iterations (+)Increment 500: It is converged in 2 iterations

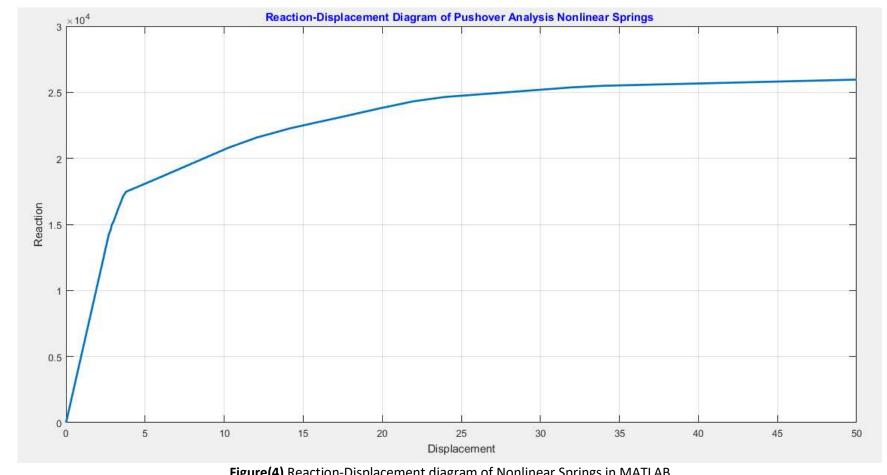
Plot:



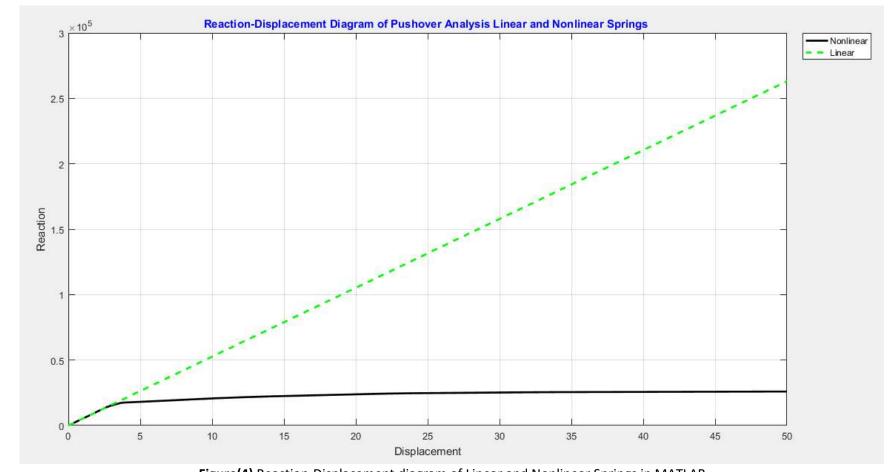
Figure(1) Strain-Stress diagram of elements in MATLAB



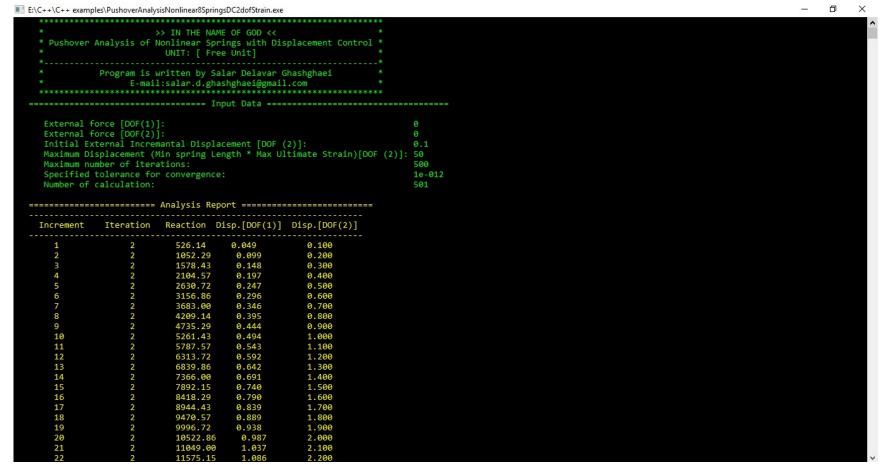




Figure(4) Reaction-Displacement diagram of Nonlinear Springs in MATLAB



Figure(4) Reaction-Displacement diagram of Linear and Nonlinear Springs in MATLAB



Figure(5) Pushover analysis of Nonlinear springs with Displacement control in C++

```
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■ E:\C++\C++ examples\PushoverAnalysisNonlinear8SpringsDC2dofStrain.exe
         478
                                      25892.60
                                                     24.336
                                                                     47.800
                                     25895.53
25898.45
25901.38
                                                                    47.900
48.000
48.100
                                                     24.387
24.438
         479
480
                          11
         481
                          11
                                                     24.489
         482
                                     25904.30
                                                     24.540
                                                                     48.200
         483
                                     25907.23
                                                     24.591
                                                                     48.300
                          11
11
11
11
11
         484
                                      25910.16
                                                     24.642
                                                                     48.400
         485
                                      25913.08
                                                     24.693
                                                                     48.500
         486
487
                                     25916.01
25918.93
25921.86
                                                                     48.600
48.700
48.800
                                                     24.744
                                                     24.795
24.846
         488
         489
                                     25924.79
                                                     24.897
                                                                     48.900
         490
                                     25927.72
                                                     24.948
                                                                     49.000
         491
                                     25930.64
                                                     24.998
                                                                     49.100
         492
                                     25933.57
                                                     25.049
                                                                     49.200
         493
494
495
496
                                     25936.50
25939.43
25942.35
25945.28
                                                                     49.300
49.400
49.500
                                                     25.100
                                                     25.151
25.202
                                                     25.253
                                                                     49.600
                                     25948.21
         497
                                                     25.304
                                                                     49.700
         498
                          11
11
                                                                     49.800
                                      25951.14
                                                     25.355
         499
                                      25954.07
                                                     25.406
                                                                     49.900
         500
                                     25957.00
                                                     25.457
                                                                     50.000
      ## Displacement reached to ultimate displacement ##
     Section ductility ratio: 12.103 - Over strength factor: 1.194
          Bilinear curve fitted
     = Disp.[DOF(2)] Reaction =
            4.1312
                            21735.917
                            25956.998
            50.0000
  CPU time : 0.507 seconds
  Date and Time : Wed Jun 14 13:22:59 2017
```

Figure(6) Pushover analysis of Nonlinear springs with Displacement control in C++