

Homework 7

Sahil Palnitkar
CSCE 411

35.2-3)

Let the optimal tour at the step i as H_i^* and the tour made by the heuristic as H_i . Let the vertex u_i be added such that it is nearest to v_i . The cost function satisfies the triangle inequality, giving us: $c(H_i) \leq c(H_{i-1}) + 2c$. So, $c(H_i) \leq 2 \sum_i c(u_i, v_i)$

The nodes and edges are added in closest point heuristic the same way as Prim's algorithm.

Therefore, the cost of the MST produced by Prim's algorithm is equal to $\sum_i c(u_i, v_i)$.

From the textbook, we see that $c(\text{MST}) \leq c(H^*)$. From that we get.

$$c(H) \leq 2c(\text{MST}) \leq 2c(H^*).$$

So it is proved that a heuristic returns a tour whose total cost is not more than twice the cost of an optimal tour.

35.4-3)

For each vertex v , we will randomly and independently place v in S with a probability $\frac{1}{2}$ and in $V - S$ with probability $\frac{1}{2}$. For an edge e_i , we define the indicator random variable $Y_i = I\{e_i \text{ crossing a cut}\}$. For an edge e_i to cross a cut, its vertices u, v have to be in S and $V - S$ respectively. The probability of such an event is $\Pr\{e_i \text{ crossing a cut}\} = \Pr\{u \text{ in } S \text{ and } v \text{ in } V-S\} \text{ OR } \{u \text{ in } V-S \text{ and } v \text{ in } S\} = \frac{1}{2} \times \frac{1}{2} + \frac{1}{2} \times \frac{1}{2} = \frac{1}{2}$. According to lemma 5.1 in the textbook $E[Y_i] = \frac{1}{2}$. Let Y be the number of edges crossing a cut, so that $Y = Y_1 + Y_2 + \dots + Y_n$, $n = |E|$.

With this we get

$$\begin{aligned} E[Y] &= E\left[\sum_{i=1}^n Y_i\right] \\ &= \sum_{i=1}^n E[Y_i] \text{ (because of expectation linearity)} \\ &= \sum_{i=1}^n \frac{1}{2} \\ &= \frac{1}{2} n \end{aligned}$$

Let c^* be the weight of the max-cut. The upper bound of c^* is the total number of edges, which is $c^* \leq n$.

$$\begin{aligned} \text{We get } c^* &\leq n \\ &= 2 \times \frac{1}{2} n \\ &= 2E[Y] \end{aligned}$$

Therefore we get $c^*/E[Y] \leq 2$ (as this is a maximization problem)

Therefore this is a random 2-approximation problem.

35.4-4)

Let $x : V \rightarrow \mathbb{R}_{\geq 0}$ be an optimal solution for the linear programming relaxation with condition 35.19 removed. Suppose there exists v from V such that $x(v) > 1$. Let x' be such that $x'(u) = x(u)$ for $u \neq v$ and $x'(v) = 1$.

The conditions 35.18 and 35.20 are still satisfied for x' .

$$\begin{aligned} \text{But } \sum_{(u,v) \in E} w(u)x(u) &= \sum_{(u,v) \in E} w(u)x'(u) + w(v)x(v) \\ &> \sum_{(u,v) \in E} w(u)x'(u) + w(v)x'(v) \\ &= \sum_{(u,v) \in E} w(u)x'(u) \end{aligned}$$

which contradicts the assumption that x minimized the objective function. So it must be true that $x(v) \leq 1$ for all v in V . So the condition 35.19 is redundant, proved.

26.2-6)

We can modify this similarly to as it is done in section 26.1. We can create an extra vertex s_i^{hat} for each i and place it between s and s_i . Remove the edge from (s, s_i) and add edges (s, s_i^{hat}) and (s_i^{hat}, s_i) . In the same way, we create an extra vertex t_i^{hat} and place it between t and t_i . Remove the edges (t_i, t) and add edges (t_i, t_i^{hat}) and (t_i^{hat}, t) . Assign $c(s_i^{\text{hat}}, s_i) = p_i$ and $c(t_i^{\text{hat}}, t) = q_i$. If a flow that satisfies the constraints exists, it will assign $f(s_i^{\text{hat}}, s_i) = p_i$. By flow conservation, this implies that $\sum_{(v \in V)} f(s_i, v) = p_i$. Similarly, we must have $f(t_i, t_i^{\text{hat}}) = q_i$ so by flow conservation we get $\sum_{(v \in V)} f(v, t_i) = q_i$.