SAHIL B SHAH

OBJECTIVE Internship in a startup in areas of computer vision, wearable devices, internet of things or robotics

EDUCATION Carnegie Mellon University, Pittsburgh

Robotics Institute- MS in Robotic Systems Development

James R. Swartz Entrepreneurial Fellow

Birla Institute of Technology and Science, Pilani, India

December 2012

Bachelor of Engineering (Hons.) Computer Science

First Division

Undergraduate Thesis: Pulse rate estimation from facial videos

SKILLS Languages: C, C++, Java, MATLAB, Ruby, Javascript, Python, HTML/CSS

Frameworks &Tools: MATLAB, Android Apps, Unix Utilities, Rails, Heroku, OpenCV

RELEVANT COURSEWORK

Computer Vision Systems Engineering Machine Learning

Artificial Intelligence Mobility, Manipulation & Control Data Structures & Algorithms

EXPERIENCE Tonbo Imaging, Bangalore, India Jul 2013 - Jun 2014

Member of Technical Staff (employee #15)

Video Stabilization (watch: vimeo.com/sahilshah/imu-video-stab-2)

 Implemented real time image stabilization for handheld cameras and UAVs using Inertial Measurement Units (accelerometer and gyroscope)

- Increased frame rate by two times over previous methods
- Prototyped the entire system on TI DM6467 microprocessor and Invensense MPU

Tech: C++, Kalman filters, sensor fusion, Qt Libraries, Embedded Systems Programming

Neuroinformatics & Cognitive Robotics Lab, TU Ilmenau, Ilemanu, Germany Sep 2012 - Nov 2012 Research Intern

Pulse Rate Estimation from Facial Video (deck: slideshare.net/sahilshah15/pulse-detector)

- Implemented a real time application to estimate the pulse rate of a person using video of his face
- Deployed on a robot that assisted residents at home for the aged

Tech: Literature Review, C++, Independent Component Analysis, Fast Fourier Transforms, Face Detection (Viola Jones, Active Appearance Model)

Goldman Sachs & Co., Bangalore, India

May 2013 - Jul 2013

December 2015

Summer Analyst

Apache Solr

- Customized the 'More Like This' feature of Solr to make queries on a database of 7M+ XML records more effective
- Reduced the steps required to analyze suspicious transactions by a factor of 2

Tech: Java, XML, Information Retrieval, tf*idf algorithm, similarity scores

PROJECTS Autonomous Quadcopter Docking & Charging System

Aug 2014 - May 2015

Using the fine precision of computer vision to supplement GPS guidance and enable a UAV to land precisely on a custom manufactured docking station with charging capabilities

Compiler Construction Jan 2012 - May 2012

Implemented compiler logic in C for an experimental programming language

OTHER Reading, startups, physics, gadgets, basketball (college captain, gold medalist), running (half INTERESTS marathon), squash