

EE2227 Control Systems

I - Question

II - Theory
required

III - Solution

IIT Hyderabad
12-2-2020

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12-02-2020

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GATE-2019, EE Section
Problem no.13

Gate Problems

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13) The output response of a system is denoted as $y(t)$, and its Laplace transform is given by

$$Y(s) = \frac{10}{s(s^2 + s + 100(2)^{0.5})}$$

The steady state value of $y(t)$ is

a) $100(2)^{0.5}$

b) $\frac{1}{10(2)^{0.5}}$

c) $10(2)^{0.5}$

d) $\frac{1}{100(2)^{0.5}}$

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The final value theorem states that

$$\lim_{t \rightarrow \infty} y(t) = \lim_{s \rightarrow 0} sY(s)$$

This is valid only when $sY(s)$ has poles that lie in the negative half of the real side.

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If the quadratic equation $ax^2 + bx + c$ has complex roots then the real part of those roots will be $-b/2a$

Hence, verified that the roots of $s^2 + s + 100(2)^{0.5}$ have a negative real part which is -0.5 . So, Final value theorem is applicable.

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Solution:(b)

Steady state value of $y(t) =$

$$\lim_{t \rightarrow \infty} y(t) = \lim_{s \rightarrow 0} sY(s) = \lim_{s \rightarrow 0} \frac{10s}{s(s^2 + s + 100(2)^{0.5})}$$

$$= \frac{10}{100(2)^{0.5}} = \frac{1}{10(2)^{0.5}}$$

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Thank You!