

Gate 2015 ECE

Q. 48

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## Question

A plant transfer function is given as  $G(s) = (K_P + \frac{K_I}{s})(\frac{1}{s(s+2)})$ . When the plant operates in a unity feedback configuration, the condition for the stability of the closed loop system is

- ①  $K_P > \frac{K_I}{2} > 0$
- ②  $2K_I > K_P > 0$
- ③  $2K_I < K_P$
- ④  $2K_I > K_P$

## Solution

The closed loop transfer function for unity feedback is

$$\begin{aligned}\frac{G(s)}{1+G(s)} &= \frac{(K_p s + K_i)}{s^2(s+2) + (K_s s + K_i)} \\ &= \frac{(K_p s + K_i)}{s^3 + 2s^2 + K_p s + K_i}\end{aligned}$$

contd...

Using Routh's tabular form:

$S^3$	1	$K_P$
$S^2$	2	$K_I$
$S^1$	$\frac{2K_p - K_i}{2}$	0
$S^0$	$K_p$	

contd...

Sufficient condition for Routh-Hurwitz Stability Criterion: The sufficient condition is that all the elements of the first column of the Routh array should have the same sign.

For system to be Stable:  $K_P > 0$

and  $\frac{2K_P - K_I}{2} > 0$

or

$2K_P - K_I > 0$

or

$K_P > \frac{K_I}{2} > 0$

So, 1st option is correct.

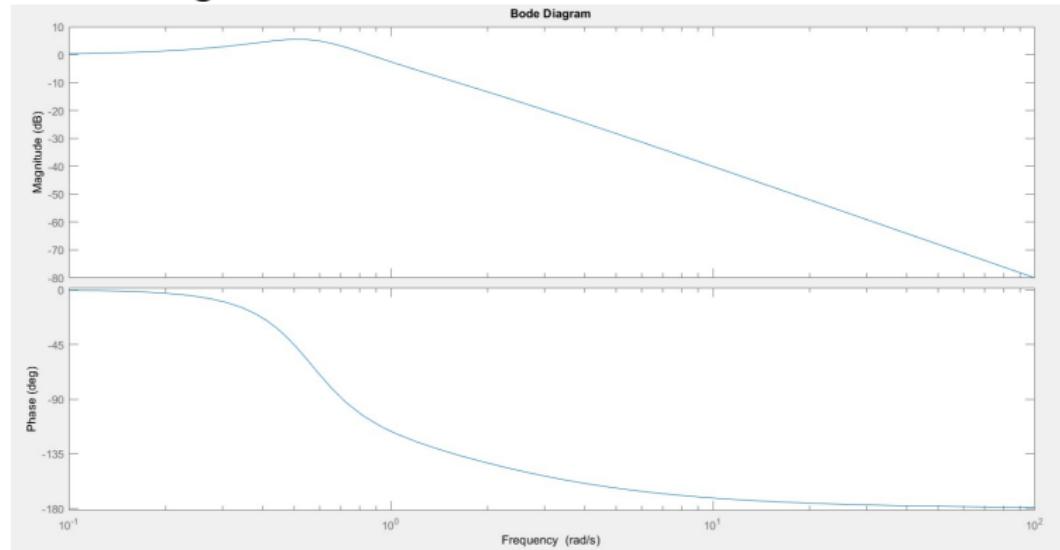
## verification of solution

For a system to be stable Gain Margin should be greater than 1 and Phase Margin Should be Positive.

for  $K_P = 1$  and  $K_I = 0.5$

Gain Margin = infinity

Phase Margin = 73.07



contd..

for  $K_P = -1$  and  $K_I = -0.5$

Gain Margin = infinity

Phase Margin = -180

PM is negative indicates that system is unstable.

