

# EE2227 Control Systems

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GATE-2019, EE Section  
Problem no.13

# Gate Problems

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I - Question

II - Theory  
required

III - Solution

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13) The output response of a system is denoted as  $y(t)$ , and its Laplace transform is given by

$$Y(s) = \frac{10}{s(s^2 + s + 100(2)^{0.5})}$$

The steady state value of  $y(t)$  is

- a)  $100(2)^{0.5}$                       b)  $\frac{1}{10(2)^{0.5}}$   
c)  $10(2)^{0.5}$                       d)  $\frac{1}{100(2)^{0.5}}$

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The final value theorem states that

$$\lim_{t \rightarrow \infty} y(t) = \lim_{s \rightarrow 0} sY(s)$$

This is valid only when  $sY(s)$  has poles that lie in the negative half of the real side.

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If the quadratic equation  $ax^2 + bx + c$  has complex roots then the real part of those roots will be  $-b/2a$

Hence, verified that the roots of  $s^2 + s + 100(2)^{0.5}$  have a negative real part which is  $-0.5$ . So, Final value theorem is applicable.

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Solution:(b)

Steady state value of  $y(t)$  =

$$\begin{aligned}\lim_{t \rightarrow \infty} y(t) &= \lim_{s \rightarrow 0} sY(s) = \lim_{s \rightarrow 0} \frac{10s}{s(s^2 + s + 100(2)^{0.5})} \\ &= \frac{10}{100(2)^{0.5}} = \frac{1}{10(2)^{0.5}}\end{aligned}$$

Thank You!