# Homework 2 Solution and Grading Policy

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## Homework Policy: (READ BEFORE YOU START TO WORK)

- Copying from other students' solution is not allowed. If caught, all involved students get 0 point on that particular homework. Caught twice, you will be asked to drop the course.
- Collaboration is welcome. You can work together with **at most one partner** on the homework problems which you find difficult. However, you should write down your own solution, not just copying from your partner's.
- Your partner should be the same for the entire homework.
- Put your collaborator's name beside the problems that you collaborate on.
- When citing known results from the assigned references, be as clear as possible.

## 1. (Mixture of random processes) [14]

In this problem we look at different ways to generate mixtures of random processes, and the entropy rate of the mixture of random processes. Consider two stationary random processes  $\{X_0[i] | i \in \mathbb{N}\}$  and  $\{X_1[i] | i \in \mathbb{N}\}$  taking values in disjoint alphabets  $\mathcal{X}_0$  and  $\mathcal{X}_1$  respectively. The two processes are independent from each other, that is,  $\{X_0[i]\} \perp \{X_1[i]\}$ , and they have entropy rates  $\mathcal{H}_0$  and  $\mathcal{H}_1$  respectively. Let  $\{\Theta_i | i \in \mathbb{N}\}$  be a **stationary** Bernoulli random process, independent of everything else.

- a) Let  $\Theta_i = \Theta$  for all  $i \in \mathbb{N}$ , where  $\Theta \sim \text{Ber}(q)$ . Is the random process  $\{X_{\Theta_i}[i]\}$  stationary? What is its entropy rate?
- b) Let  $\{\Theta_i\}$  be Markov with a probability transition matrix

$$\mathsf{P}_{\Theta_2|\Theta_1} = \begin{bmatrix} 1 - \alpha & \alpha \\ \beta & 1 - \beta \end{bmatrix}, \text{ for } \alpha, \beta \in (0, 1).$$

Suppose that both  $\{X_0[i]\}$  and  $\{X_1[i]\}$  are i.i.d. processes in this problem. Is the random process  $\{X_{\Theta_i}[i]\}$  stationary? What is its entropy rate? [8]

#### **Solution:**

a) Since  $\{X_0[i]\}$  and  $\{X_1[i]\}$  are stationary, we have

$$\begin{split} \mathsf{P}_{X_{\Theta_1}[1],\dots,X_{\Theta_n}[n]} &= (1-q)\mathsf{P}_{X_0[1],\dots,X_0[n]} + q\mathsf{P}_{X_1[1],\dots,X_1[n]} \\ &= (1-q)\mathsf{P}_{X_0[l+1],\dots,X_0[n]} + q\mathsf{P}_{X_1[1],\dots,X_1[l+n]} \quad \text{(by stationariness)} \\ &= \mathsf{P}_{X_{\Theta_{l+1}}[l+1],\dots,X_{\Theta_{l+n}}[l+n]} \end{split}$$

By definition,  $\{X_{\Theta_i}[i]\}$  is stationary. Let  $Y_i = X_{\Theta_i}[i]$ .

$$\mathcal{H}(X_{\Theta_{i}}[i]) = \lim_{n \to \infty} H\left(Y_{n} \middle| Y^{n-1}\right)$$

$$= \lim_{n \to \infty} H\left(Y_{n}, \Theta_{n} \middle| Y^{n-1}, \Theta^{n-1}\right) \qquad \text{(since } \mathcal{X}_{0} \text{ and } \mathcal{X}_{1} \text{ are disjoint)}$$

$$= \lim_{n \to \infty} H\left(Y_{n} \middle| Y^{n-1}, \Theta^{n}\right) + H\left(\Theta_{n} \middle| Y^{n-1}, \Theta^{n-1}\right)$$

$$= \lim_{n \to \infty} H\left(Y_{n} \middle| \Theta_{n}\right) + H\left(\Theta_{n} \middle| \Theta_{n-1}\right)$$

$$= \lim_{n \to \infty} H\left(Y_{n} \middle| \Theta\right) + H\left(\Theta \middle| \Theta\right)$$

$$= q\mathcal{H}_{1} + (1 - q)\mathcal{H}_{0} + 0$$

b) Since we know in advance that  $\{\Theta_i\}$  is stationary, we can conclude that  $\Pr\{\Theta_1=0\}=\frac{\beta}{\alpha+\beta}$  and  $\Pr\{\Theta_1=1\}=\frac{\alpha}{\alpha+\beta}$ . As a result,  $\{X_{\Theta_i}[i]\}$  can be shown to be stationary by decomposing  $\mathsf{P}_{X_{\Theta_1}[1],\dots,X_{\Theta_n}[n]}$  and  $\mathsf{P}_{X_{\Theta_{l+1}}[+1],\dots,X_{\Theta_{l+n}}[l+n]}$  simply by showing that  $\Pr\{\Theta_n=0\}=\frac{\beta}{\alpha+\beta}$  and  $\Pr\{\Theta_n=1\}=\frac{\alpha}{\alpha+\beta}$  for all n.

Next, let 
$$Y_i = X_{\Theta_i}[i]$$
.  $\mathcal{H}(\{X_{\Theta_i}[i]\}) = \lim_{n \to \infty} \mathcal{H}(Y_n | Y^{n-1})$ .

$$\begin{split} & \operatorname{H}\left(Y_{n}\big|Y^{n-1}\right) \\ & = \operatorname{H}\left(Y_{n}, \Theta_{n}\big|Y^{n-1}\right) \\ & = \operatorname{H}\left(Y_{n}\big|\Theta_{n}, Y^{n-1}\right) + \operatorname{H}\left(\Theta_{n}\big|Y^{n-1}\right) \\ & = \operatorname{H}\left(Y_{n}\big|\Theta_{n}, Y^{n-1}\right) + \operatorname{H}\left(\Theta_{n}\big|Y^{n-1}\right) \\ & = \operatorname{Pr}\{\Theta_{n} = 1\}\operatorname{H}\left(X_{1}[n]\big|X_{1}^{n-1}\right) + \operatorname{Pr}\{\Theta_{n} = 0\}\operatorname{H}\left(X_{0}[n]\big|X_{0}^{n-1}\right) + \operatorname{H}\left(\Theta_{n}\big|Y^{n-1}\right) \\ & = \operatorname{Pr}\{\Theta_{n} = 1\}\operatorname{H}\left(X_{1}[n]\big|X_{1}^{n-1}\right) + \operatorname{Pr}\{\Theta_{n} = 0\}\operatorname{H}\left(X_{0}[n]\big|X_{0}^{n-1}\right) + \operatorname{H}\left(\Theta_{n}\big|\Theta^{n-1}\right) \\ & = \frac{\alpha}{\alpha + \beta}\mathcal{H}_{1} + \frac{\beta}{\alpha + \beta}\mathcal{H}_{0} + \operatorname{H}\left(\Theta_{2}\big|\Theta_{1}\right) \\ & = \frac{\alpha}{\alpha + \beta}(\mathcal{H}_{1} + \operatorname{H}_{b}(\beta)) + \frac{\beta}{\alpha + \beta}(\mathcal{H}_{0} + \operatorname{H}_{b}(\alpha)) \end{split}$$

## **Grading Policy:**

- a) Stationaryiness and reason [2] calculation of entropy rate [4]
- b) Stationaryiness and reason [2] calculation of entropy rate [6]

## 2. (Binary hypothesis testing) [16]

Let  $X_1, X_2, ...$  be a sequence of i.i.d. Bernoulli p random variables, that is,

$$\Pr\{X_i = 1\} = 1 - \Pr\{X_i = 0\} = p.$$

Based on the observations so far, the goal is of a decision maker to determine which of the following two hypotheses is true:

$$\mathcal{H}_0: p = p_0$$
  
 $\mathcal{H}_1: p = p_1$ 

where  $0 < p_0 < p_1 \le 1/2$ .

- a) (Warm-up) Consider the problem of making the decision based on  $X_1$ . Draw the optimal  $(\pi_{1|0}, \pi_{0|1})$  trade-off curve. [4]
- b) Suppose the decision maker waits until an 1 appears and makes the decision based on the whole observed sequence. Sketch the optimal  $(\pi_{1|0}, \pi_{0|1})$  trade-off curve. [4]
- c) Now suppose the decision maker waits until in total n 1's appear and makes the decision based on the whole observed sequence. Let  $\varpi_{0|1}^*(n,\epsilon)$  denote the minimum type-II error probability subject to the constraint that the type-I error probability is not greater than  $\epsilon$ ,  $0 < \epsilon < 1$ . Does  $\lim_{n \to \infty} \frac{1}{n} \log \frac{1}{\varpi_{0|1}^*(n,\epsilon)}$  exist? If so, find it. Otherwise, show that the limit does not exist.

#### Solution:

a) By Neyman-Pearson theorem, the optimal test is randomized LRT. So, by leveraging the parameters of the randomized LRT, that is,  $\tau$  and  $\gamma$ , we can derive the optimal trade-off curve. Note that the likelihood ratio can only take two values:  $\frac{p_1}{p_0}$ ,  $\frac{1-p_1}{1-p_0}$ . Therefore, discuss the range of  $\tau$  we get

$$\begin{cases} \pi_{1|0} = 1, \pi_{0|1} = 0, & 0 \leq \tau < \frac{1-p_1}{1-p_0} \\ \pi_{1|0} = p_0 + \gamma(1-p_0), \pi_{0|1} = (1-\gamma)(1-p_1) = \frac{1-p_1}{1-p_0}(1-\pi_{1|0}), & \tau = \frac{1-p_1}{1-p_0} \\ \pi_{1|0} = p_0, \pi_{0|1} = 1-p_1, & \frac{1-p_1}{1-p_0} < \tau < \frac{p_1}{p_0} \\ \pi_{1|0} = \gamma p_0, \pi_{0|1} = (1-\gamma)p_1 + (1-p_1) = 1 - \frac{p_1}{p_0} \pi_{1|0}, & \tau = \frac{p_1}{p_0} \\ \pi_{1|0} = 0, \pi_{0|1} = 1, & \tau > \frac{p_1}{p_0}. \end{cases}$$

We can then draw the trade-off curve using the equations derived above.

b) Note that our observation can only be  $1,01,001,0001,\cdots$ , let L be the length of the observation, we have

$$\mathcal{H}_0: L \sim \text{Geo}(p_0)$$
  
 $\mathcal{H}_1: L \sim \text{Geo}(p_1)$ 

Similar to a), we can discuss the range of  $\tau$  and get:

$$\begin{cases} \pi_{1|0} = 0, \pi_{0|1} = 1, \ \tau > \frac{p_1}{p_0} \\ \pi_{1|0} = \sum_{i=1}^{n-1} (1 - p_0)^{i-1} p_0 + \gamma (1 - p_0)^{n-1} p_0, \\ \pi_{0|1} = \sum_{i=n+1}^{\infty} (1 - p_1)^{i-1} p_1 + (1 - \gamma) (1 - p_1)^{n-1} p_1, \ \tau = \frac{(1 - p_1)^{n-1} p_1}{(1 - p_0)^{n-1} p_0} \\ \pi_{1|0} = \sum_{i=1}^{n} (1 - p_0)^{i-1} p_0, \pi_{0|1} = \sum_{i=n+1}^{\infty} (1 - p_1)^{i-1} p_1, \ \frac{(1 - p_1)^{n-1} p_1}{(1 - p_0)^{n-1} p_0} > \tau > \frac{(1 - p_1)^n p_1}{(1 - p_0)^{n} p_0}. \end{cases}$$

And we can draw the trade-off curve using the equations derived above.

c) The observation can be viewed as n i.i.d. geometric random variables. To see this, for any realization of observation, insert a "—" symbol in front of the sequence, also insert a "—" right after a "1". For example, if n=4 and the realization is 010001101, we write it as |01|0001|1|01|. Appearantly, the length of the subsequence between two—is a geometric random variable. Hence, in this subproblem, we are testing  $\text{Geo}(p_0)^{\otimes n}$  and  $\text{Geo}(p_1)^{\otimes n}$ . By Chernoff-Stein lemma,

$$\lim_{n \to \infty} \frac{1}{n} \log \frac{1}{\varpi_{0|1}^*(n, \epsilon)} = D(\text{Geo}(p_0) || \text{Geo}(p_1)) = \log \frac{p_0}{p_1} + \left(\frac{1 - p_0}{p_0}\right) \log \frac{1 - p_0}{1 - p_1}.$$

## Grading Policy:

- a) Specify the trade-off curve [2] Argue the optimality [2]
- b) Specify the trade-off curve [2] Argue the optimality [2]
- c) Formulate the problem as a hypothesis testing with n instances [3], Chernoff-Stein lemma [2], and calculation [3]

## 3. (Mixture of information divergences) [8]

For m discrete probability distributions  $P_1, P_2, \ldots, P_m$  with the same support  $\mathcal{X}$ , consider the following minimization problem:

$$\min_{Q \in \mathcal{P}(\mathcal{X})} \sum_{i=1}^{m} \lambda_i \mathrm{D}(P_i || Q),$$

where  $\mathcal{P}(\mathcal{X})$  denotes the collection of probability distributions over  $\mathcal{X}$ ,  $\sum_{i=1}^{m} \lambda_i = 1$ , and  $\lambda_i > 0$  for i = 1, 2, ..., m. Show that  $\sum_{i=1}^{m} \lambda_i P_i$  is a minimizer to the above problem.

## Solution:

Let 
$$\overline{\mathsf{P}} = \sum_{i=1}^{m} \lambda_i \mathsf{P}_i$$
, we have  $\forall \mathsf{Q} \in \mathcal{P}(\mathcal{X})$ , that

$$\sum_{i=1}^{m} \lambda_{i} D(P_{i} \| Q) - \sum_{i=1}^{m} \lambda_{i} D(P_{i} \| \overline{P})$$

$$\begin{split} &= \sum_{i=1}^m \sum_{x \in \mathcal{X}} \lambda_i \mathsf{P}_i(x) \log \frac{\overline{\mathsf{P}}(x)}{\mathsf{Q}(x)} \\ &= \sum_{x \in \mathcal{X}} \left( \sum_{i=1}^m \lambda_i \mathsf{P}_i(x) \right) \log \frac{\overline{\mathsf{P}}(x)}{\mathsf{Q}(x)} \\ &= \sum_{x \in \mathcal{X}} \overline{\mathsf{P}}(x) \log \frac{\overline{\mathsf{P}}(x)}{\mathsf{Q}(x)} \\ &= \mathsf{D}\left( \overline{\mathsf{P}} \big\| \mathsf{Q} \right) \geq 0. \end{split}$$

Hence,  $\overline{P}$  is a minimizer.

## **Grading Policy**

Reasonable Procedure[4] Correctness [4] Per mistake [-1]

## 4. (Rényi's divergence) [12]

Alfréd Rényi introduced the following generalization of information divergence called  $R\acute{e}nyi$ 's divergence of order  $\alpha$  (for simplicity, only deal with the discrete case):

$$D_{\alpha}(\mathsf{P}\|\mathsf{Q}) := \frac{1}{\alpha - 1} \log \left( \sum_{a \in \mathcal{X}} \mathsf{P}(a)^{\alpha} \mathsf{Q}(a)^{1 - \alpha} \right), \quad \alpha \in (0, 1) \cup (1, \infty),$$

where P, Q are both probability distributions over a finite alphabet  $\mathcal{X}$ , and  $supp P \subseteq supp Q$ .

- a) (Non-negativity) Show that  $D_{\alpha}(P||Q) \geq 0$ , with equality if and only if P = Q. [4]
- b) (Relation with KL divergence) Show that  $D_{\alpha}(P||Q) \ge D(P||Q)$  for  $\alpha > 1$  and  $D_{\alpha}(P||Q) \le D(P||Q)$  for  $\alpha < 1$ . Furthermore,  $\lim_{\alpha \to 1} D_{\alpha}(P||Q) = D(P||Q)$ . [4]
- c) (Data processing) Show that  $D_{\alpha}(P||Q)$  satisfies the data processing inequality. [4]

#### **Solution:**

a) We divide the value of  $\alpha$  into two cases: If  $\alpha \in (0,1)$ , we can lower bound  $D_{\alpha}(P||Q)$  by Hölder's inequality, which states that for any p,q>1 and  $\frac{1}{p}+\frac{1}{q}=1$ , we have

$$\sum_{i=1}^{n} |x_i y_i| \le \left(\sum_{i=1}^{n} |x_i|^p\right)^{\frac{1}{p}} \left(\sum_{i=1}^{n} |y_i|^q\right)^{\frac{1}{q}},$$

the equality holds iff  $(|x_1|^p, ..., |x_n|^p)$  and  $(|y_1|^q, ..., |y_n|^q)$  are linearly dependent.

$$D_{\alpha}(P||Q) = \frac{1}{\alpha - 1} \log \left( \sum_{a \in \mathcal{X}} P(a)^{\alpha} Q(a)^{1 - \alpha} \right)$$
$$\geq \frac{1}{\alpha - 1} \log \left( \sum_{a \in \mathcal{X}} (P(a)^{\alpha})^{\frac{1}{\alpha}} \right)^{\alpha} \left( \sum_{a \in \mathcal{X}} (Q(a)^{1 - \alpha})^{\frac{1}{1 - \alpha}} \right)^{1 - \alpha}$$

(by Hölder's inequality with 
$$p = \frac{1}{\alpha}, q = \frac{1}{1-\alpha}$$
) = 0

If  $\alpha \in (1, \infty)$ , we can bound it by Jensen's inequality,

$$\begin{split} \mathbf{D}_{\alpha}(\mathsf{P}\|\mathsf{Q}) &= \frac{1}{\alpha - 1} \log \left( \sum_{a \in \mathcal{X}} \mathsf{P}(a)^{\alpha} \mathsf{Q}(a)^{1 - \alpha} \right) \\ &= \frac{1}{\alpha - 1} \log \left( \sum_{a \in \mathcal{X}} \mathsf{P}(a) \left( \frac{\mathsf{P}(a)}{\mathsf{Q}(a)} \right)^{\alpha - 1} \right) \\ &= \frac{1}{\alpha - 1} \log \mathsf{E}_{X \sim \mathsf{P}} \left[ \left( \frac{\mathsf{P}(X)}{\mathsf{Q}(X)} \right)^{\alpha - 1} \right] \\ &\geq \frac{1}{\alpha - 1} \mathsf{E}_{X \sim \mathsf{P}} \left[ \log \left( \frac{\mathsf{P}(X)}{\mathsf{Q}(X)} \right)^{\alpha - 1} \right] \\ &= \mathsf{E}_{X \sim \mathsf{P}} \left[ \log \frac{\mathsf{P}(X)}{\mathsf{Q}(X)} \right] = \mathsf{D}(\mathsf{P}\|\mathsf{Q}) \geq 0 \end{split}$$

Furthermore, both equality holds iff P(a) = Q(a) for all  $a \in \mathcal{X}$ , which is P = Q.

b) In a), we have proved the case when  $\alpha > 1$ . For the case when  $\alpha < 1$ , we can directly obtain the result by substituting the inequality since  $\frac{1}{\alpha-1} < 0$  here. Thus, it suffices to show that  $\lim_{\alpha \to 1} D_{\alpha}(P||Q) = D(P||Q)$ .

$$\lim_{\alpha \to 1} D_{\alpha}(P||Q) = \lim_{\alpha \to 1} \frac{\log \left( \sum_{a \in \mathcal{X}} P(a)^{\alpha} Q(a)^{1-\alpha} \right)}{\alpha - 1}$$

$$\stackrel{H}{=} \lim_{\alpha \to 1} \frac{\sum_{a \in \mathcal{X}} P(a)^{\alpha} Q(a)^{1-\alpha} \log \left( \frac{P(a)}{Q(a)} \right)}{\sum_{a \in \mathcal{X}} P(a)^{\alpha} Q(a)^{1-\alpha}}$$

$$= \sum_{a \in \mathcal{X}} P(a) \frac{P(a)}{Q(a)} = D(P||Q)$$

c) Follow the notation proving data processing inequality used in lecture, we have  $\forall x, y$ ,

$$\frac{\mathsf{P}_{X,Y}(x,y)}{\mathsf{Q}_{X,Y}(x,y)} = \frac{\mathsf{P}_{X}(x)W_{Y|X}(y|x)}{\mathsf{Q}_{X}(x)W_{Y|X}(y|x)} = \frac{\mathsf{P}_{X}(x)}{\mathsf{Q}_{X}(x)}$$

As a result,

$$D_{\alpha}(\mathsf{P}_{X,Y}||\mathsf{Q}_{X,Y}) = \frac{1}{\alpha - 1} \sum_{a \in \mathcal{X}} \sum_{b \in \mathcal{Y}} \mathsf{P}_{X,Y}(a,b) \left( \frac{\mathsf{P}_{X,Y}(a,b)}{\mathsf{Q}_{X,Y}(a,b)} \right)^{\alpha - 1}$$
$$= \frac{1}{\alpha - 1} \sum_{a \in \mathcal{X}} \mathsf{P}_{X}(a) \left( \frac{\mathsf{P}_{X}(a)}{\mathsf{Q}_{X}(a)} \right)^{\alpha - 1} = D_{\alpha}(\mathsf{P}_{X}||\mathsf{Q}_{X})$$

Therefore,

$$\begin{split} \mathbf{D}_{\alpha}(\mathsf{P}_{X}\|\mathsf{Q}_{X}) &= \mathbf{D}_{\alpha}(\mathsf{P}_{X,Y}\|\mathsf{Q}_{X,Y}) \\ &= \frac{1}{\alpha - 1}\mathsf{E}_{X,Y \sim \mathsf{Q}_{X,Y}} \left[ \left( \frac{\mathsf{P}_{X,Y}(X,Y)}{\mathsf{Q}_{X,Y}(X,Y)} \right)^{\alpha} \right] \\ &= \frac{1}{\alpha - 1}\mathsf{E}_{Y \sim \mathsf{Q}_{Y}} \left[ \mathsf{E}_{X \sim \mathsf{Q}_{X|Y = Y}} \left[ \left( \frac{\mathsf{P}_{X,Y}(X,Y)}{\mathsf{Q}_{X,Y}(X,Y)} \right)^{\alpha} \middle| Y \right] \right] \\ &\geq \frac{1}{\alpha - 1}\mathsf{E}_{Y \sim \mathsf{Q}_{Y}} \left[ \mathsf{E}_{X \sim \mathsf{Q}_{X|Y = Y}} \left[ \left( \frac{\mathsf{P}_{X,Y}(X,Y)}{\mathsf{Q}_{X,Y}(X,Y)} \right) \middle| Y \right]^{\alpha} \right] \\ &= \frac{1}{\alpha - 1}\mathsf{E}_{Y \sim \mathsf{Q}_{Y}} \left[ \left( \frac{\mathsf{P}_{Y}(Y)}{\mathsf{Q}_{Y}(Y)} \right)^{\alpha} \right] = \mathsf{D}_{\alpha}(\mathsf{P}_{Y}\|\mathsf{Q}_{Y}) \end{split}$$

## **Grading Policy**

- a) Proof of inequality [3] Equivalent condition of equality [1]
- b) Proof of inequalities [2] Calculation of limit [2]
- c) Correct proof [4] Wrong for some  $\alpha$  [-1]