Experiment no. 1

Name :Sahil Yogesh Tike

Class : BE-(B3) Roll No : B212066

```
In []: import sklearn
    from sklearn import datasets
    import pandas as pd
    from sklearn.datasets import load_boston

In [4]: boston=datasets.load_boston();
    df=pd.DataFrame(data=boston.data,columns=boston.feature_names)
    df['target']=boston.target
    df

Out[4]: CRIM ZN INDUS CHAS NOX RM AGE DIS RAD TAX PTRATIO B LSTAT 1
```

t[4]:		CRIM	ZN	INDUS	CHAS	NOX	RM	AGE	DIS	RAD	TAX	PTRATIO	В	LSTAT	1
	0	0.00632	18.0	2.31	0.0	0.538	6.575	65.2	4.0900	1.0	296.0	15.3	396.90	4.98	
	1	0.02731	0.0	7.07	0.0	0.469	6.421	78.9	4.9671	2.0	242.0	17.8	396.90	9.14	
	2	0.02729	0.0	7.07	0.0	0.469	7.185	61.1	4.9671	2.0	242.0	17.8	392.83	4.03	
	3	0.03237	0.0	2.18	0.0	0.458	6.998	45.8	6.0622	3.0	222.0	18.7	394.63	2.94	
	4	0.06905	0.0	2.18	0.0	0.458	7.147	54.2	6.0622	3.0	222.0	18.7	396.90	5.33	
	•••											***		***	
	501	0.06263	0.0	11.93	0.0	0.573	6.593	69.1	2.4786	1.0	273.0	21.0	391.99	9.67	
	502	0.04527	0.0	11.93	0.0	0.573	6.120	76.7	2.2875	1.0	273.0	21.0	396.90	9.08	
	503	0.06076	0.0	11.93	0.0	0.573	6.976	91.0	2.1675	1.0	273.0	21.0	396.90	5.64	
	504	0.10959	0.0	11.93	0.0	0.573	6.794	89.3	2.3889	1.0	273.0	21.0	393.45	6.48	
	505	0.04741	0.0	11.93	0.0	0.573	6.030	80.8	2.5050	1.0	273.0	21.0	396.90	7.88	

506 rows × 14 columns

				DL_1			
Epoch	1/100		5 c	220ms/stan		10551	8 2208
	2/100	_	22	220113/3CEP	_	1055.	0.2200
	[=========]	_	35	216ms/sten	_	loss	6 3248
	3/100		23	210m3/3ccp		1033.	0.3240
	[]	-	25	208ms/step	_	loss:	5.7000
Epoch							
	[======]	-	2s	209ms/step	_	loss:	5.6099
Epoch	-		1000,000	,			
	[======]	-	2s	208ms/step	-	loss:	5.3362
Epoch	6/100						
12/12	[======]	-	2s	207ms/step	-	loss:	5.3381
Epoch							
	[=====]	-	2s	207ms/step	-	loss:	5.2501
Epoch							
	[=======]	-	3s	218ms/step	-	loss:	5.0468
Epoch	9/100 [========]		2.5	212ms/ston		10551	F 0122
	10/100	_	25	212IIIS/5tep	_	1055.	5.0132
Company of the Compan	[=======]	_	3 c	213ms/sten	_	1055.	A 8831
	11/100		23	213113/3ccp		1033.	4.0031
	[=======]	_	3s	229ms/step	_	loss:	4.7286
	12/100						
12/12	[======]	-	3s	218ms/step	-	loss:	4.6593
	13/100						
	[=====]	-	3s	208ms/step	-	loss:	4.6107
	14/100		٦-	244/-+		1 2 2 2 2	4 4474
	[======] 15/100	-	35	211ms/step	-	Toss:	4.41/4
	[========]	-	35	209ms/sten	_	loss:	4.2210
	16/100		,,,	20311137 3 6 6 7		1033.	1.2210
	[=======]	-	2s	209ms/step	_	loss:	4.2192
	17/100						
	[======]	-	3s	218ms/step	-	loss:	4.0420
	18/100						
	[=========]	-	35	210ms/step	-	loss:	3.8996
U-08 000 000-000	19/100 [======]	200	2 c	212mc/ston	2000	1000	2 0217
	20/100	-	23	2121115/5tep	_	1055.	3.331/
	[=======]	_	35	209ms/sten	_	loss:	3.8288
	21/100			,,			
12/12	[======]	-	3s	216ms/step	-	loss:	3.5671
Epoch	22/100						
	[= = = = = = = = = = = = = = = = = = =	-	3s	219ms/step	-	loss:	3.6597
1100 May 2000 May 200	23/100					-	
	[========]	-	35	215ms/step	-	loss:	3.5420
100 May 200 000 000 000 000 000 000 000 000 00	24/100 [=======]		26	200ms/ston		1000	2 E001
	25/100	_	25	2031113/3CEP	_	1055.	3.3301
	[=======]	_	2s	209ms/step	_	loss:	3.5396
	26/100						
12/12	[======]	-	2s	208ms/step	-	loss:	3.5000
	27/100						
	[=====]	-	3s	210ms/step	-	loss:	3.7320
	28/100		_			1 33337	2 225=
	20/100	-	35	223ms/step	-	TOSS:	3.2867
	29/100 [=======]	_	3 c	214ms/stan	_	1055.	3.2880
	30/100		در	m3/3ccp		1000.	3.2000
1100 1100 1100 1100 1100 1100 1100 110	[=======]	-	3s	209ms/step	-	loss:	3.2954
00-001 11 001111111111111111111111111111	-		10.26033			Action of the Control of	

				D 1	
	31/100	_	35	212ms/sten - loss: 3.387	a
	32/100		,,,	2123, 500 1033. 3.307	Ü
	[========]	_	3s	209ms/step - loss: 3.272	8
	33/100				·
	[======]	-	2s	209ms/step - loss: 3.181	6
	34/100			annumentation to the property of the component of the following and the component of the co	
	[======]	-	2s	208ms/step - loss: 3.343	6
	35/100			anapagementation services In encountry/pages anapagement	
12/12	[======]	-	3s	224ms/step - loss: 3.143	3
Epoch	36/100				
12/12	[======]	-	3s	218ms/step - loss: 3.257	6
	37/100				
12/12	[======]	-	3s	221ms/step - loss: 3.032	7
	38/100				
	[]	-	3s	233ms/step - loss: 3.269	5
	39/100				
	[]	-	3s	222ms/step - loss: 2.979	6
	40/100				-
	[======]	-	35	211ms/step - loss: 3.124	1
	41/100		2-	210/	0
	[======================================	-	35	210ms/step - 10ss: 3.165	9
	42/100 [=======]		2.5	210mc/stan loss: 2 001	1
	43/100	-	25	210ms/step - 10ss. 3.081	4
	[=======]	_	3 c	210ms/sten - loss: 2 915	1
	44/100		23	210m3/3ccp 1033. 2.515	_
	[========]	_	35	210ms/sten - loss: 2.912	a
	45/100		,,	210113, 500	Ŭ
	[======]	-	3s	209ms/step - loss: 2.907	9
	46/100			Secure Se	
	[======]	-	3s	210ms/step - loss: 3.067	1
Epoch	47/100			•	
12/12	[======]	-	3s	209ms/step - loss: 2.990	5
	48/100				
	[======]	-	3s	209ms/step - loss: 2.882	8
	49/100				
	[]	-	3s	208ms/step - loss: 2.946	7
	50/100			_	
	[======]	-	3s	208ms/step - loss: 3.021	7
	51/100		-	245/	0
	[=========]	-	35	215ms/step - 10ss: 3.103	8
	52/100		2.0	226ms/ston loss: 2 921	7
	[=====================================	-	35	226ms/step - 10ss: 2.831	/
The state of the s	[======]	_	3 c	222ms/sten = loss: 3 023	2
	54/100		23	222m3/3ccp 1033. 5.025	,
	[=======]		35	215ms/sten - loss: 2.904	8
	55/100		,,,	2133, 500 1033. 2.301	Ŭ
	[=======]	-	3s	214ms/step - loss: 2.845	7
	56/100			once and an experience of the second of the	
	[======]	-	3s	211ms/step - loss: 2.772	9
Epoch	57/100				
12/12	[======]	-	2s	208ms/step - loss: 2.729	2
	58/100				
	[]	-	3s	209ms/step - loss: 2.715	3
	59/100				
	[======]	-	3s	217ms/step - loss: 2.690	6
C. C. S.	60/100			247	_
12/12	[======]	-	35	21/ms/step - 10ss: 2.693	ŏ

				DL_1			
	61/100 [========]		35	217ms/sten	_	loss:	2.8771
	62/100		,,,	22711137 5 6 6 7		1033.	2.0//1
	[======]	-	3s	221ms/step	_	loss:	2.5403
Epoch	63/100			-			
	[]	-	3s	210ms/step	-	loss:	2.6024
	64/100						
	[======]	-	3s	212ms/step	-	loss:	2.6860
	65/100 [========]	0.000	2.0	212mc/c+on	100000	1000	2 4005
	66/100	_	25	212111S/Step	_	1055.	2.4993
U-0-813200-0-101200	[=======]	_	35	215ms/step	_	loss:	2.5381
	67/100						
12/12	[=====]	-	3s	221ms/step	-	loss:	2.6534
	68/100						
	[======]	-	3s	221ms/step	-	loss:	2.5948
	69/100 [========]		2.5	225ms/stan		10551	2 5560
	70/100	_	25	225111S/SCEP	_	1055.	2.5500
C-1	[=======]	_	35	215ms/sten	_	loss:	2.6708
	71/100					2000.	
12/12	[======]	-	2s	207ms/step	-	loss:	2.7450
	72/100						
	[=======]	-	3s	225ms/step	-	loss:	2.6718
20-08 1000 Anderson	73/100 [=======]		3 c	22/ms/ston	-	1055	2 4539
	74/100		23	224113/3CEP		1033.	2.4550
	[=======]	-	3s	231ms/step	-	loss:	2.5960
	75/100			and the second s			
	[]	-	3s	231ms/step	-	loss:	2.4921
	76/100		٦-	225/		1	2 4207
	[=======] 77/100	_	35	225ms/step	-	1055:	2.4387
100 Breeze 200 Care Control	[=======]	_	3s	217ms/step	_	loss:	2.3516
	78/100						
	[=====]	-	3s	229ms/step	-	loss:	2.5124
	79/100					-	
	[========]	-	35	236ms/step	-	loss:	2.3486
	80/100 [=======]	_	3 c	226ms/sten	_	1055.	2 7110
	81/100		23	220m3/3ccp		1033.	2.7110
12/12	[======]	-	3s	223ms/step	-	loss:	2.4707
U-0-8 153,000-0-054,000	82/100						
	[========]	-	3s	215ms/step	-	loss:	2.4113
U-0-8 153,000-0-054,000	83/100 [========]		2 c	212mc/c+on		1000	2 2160
	84/100		23	2121115/5Cep	_	1055.	2.2109
	[=======]	-	3s	222ms/step	_	loss:	2.4254
	85/100			00000000000000000000000000000000000000			
	[]	-	3s	217ms/step	-	loss:	2.4694
C-0100000000000000000000000000000000000	86/100		_	240 / 1		-	2 5225
	[======] 87/100	-	35	219ms/step	_	loss:	2.5235
	[========]	_	35	224ms/step	_	loss:	2.2158
	88/100			, , , , , ,			_,
20-08 1000 Anderson	[======]	-	3s	222ms/step	-	loss:	2.2312
	89/100					=	
	[========]	-	3s	224ms/step	-	loss:	2.3638
11-0-1 132.00 Co-C-50.10.00	90/100	_	3.0	23/mc/ctan	_	10551	2 2216
12/12	LJ	_	25	2341113/3CEP	100	1022.	2.3310

```
Epoch 91/100
   Epoch 92/100
   Epoch 93/100
   Epoch 94/100
   12/12 [============= ] - 3s 214ms/step - loss: 2.4824
   Epoch 95/100
   12/12 [============ ] - 3s 218ms/step - loss: 2.3011
   Epoch 96/100
   Epoch 97/100
   12/12 [============= ] - 3s 209ms/step - loss: 2.4041
   Epoch 98/100
   Epoch 99/100
   Epoch 100/100
   <keras.callbacks.History at 0x2d0675245b0>
Out[7]:
```

In [8]: model.predict((X_test))

4/4 [========] - 0s 26ms/step

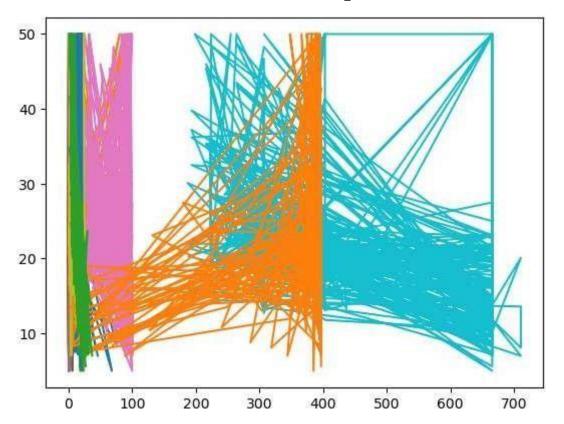
DL_1

```
array([[24.155107],
Out[8]:
                 [26.704992],
                 [42.604877],
                 [49.225105],
                 [26.91773],
                 [22.536083],
                 [25.628548],
                 [31.210789],
                 [26.101076],
                 [19.630585],
                 [10.614275],
                 [23.507631],
                 [49.683273],
                 [17.837542],
                 [41.490562],
                 [27.013577],
                 [17.492441],
                 [15.650462],
                [25.489939],
                 [26.330872],
                 [42.03463],
                [19.57444],
                [22.11166],
                 [29.236668],
                 [13.533901],
                 [32.74338],
                [22.125263],
                 [18.495352],
                 [28.87776],
                 [46.798317],
                 [25.478912],
                [33.037994],
                [35.053116],
                 [27.444939],
                 [24.632837],
                 [23.815311],
                 [24.485205],
                 [19.026493],
                 [28.209705],
                 [22.082712],
                 [35.343296],
                 [22.441381],
                 [24.739674],
                 [ 7.806842],
                 [21.556261],
                 [18.135038],
                 [24.497143],
                 [21.216475],
                 [16.713902],
                 [24.21175],
                 [29.60464],
                 [35.497818],
                 [22.529993],
                 [22.424576],
                 [17.329723],
                 [12.736004],
                 [13.332946],
                 [16.482674],
                [24.102972],
                [22.494728],
```

[13.52064], [42.884537], [9.174245], [29.110098], [23.126114], [24.142935], [24.231573], [19.609184], [43.24405], [16.924202], [11.654197], [17.336828], [24.29897], [18.54296], [37.24492], [25.919687], [20.931717], [25.034023], [15.006087], [24.402405], [26.717808], [19.047731], [24.277414], [15.144766], [22.828379], [26.720642], [22.89563], [9.361913], [27.541096], [19.510933], [35.59269], [21.033262], [29.285742], [15.360097], [16.818747], [19.634361], [19.544327], [14.650892], [44.488613], [16.792057], [29.654623], [22.922697], [17.007618], [19.640774], [27.797935], [19.636595], 30.059 [39.473682], [23.628576], [29.629019], [25.057161], [11.829733], [21.230795], [15.820941], [39.88597], [24.88261], [28.098085], [21.928474], [8.74911],

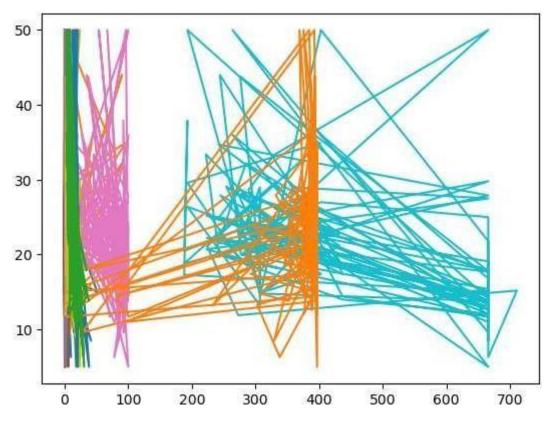
[24.224192],

```
[38.513992],
                 [11.382247],
                 [14.16294],
                 [23.727959],
                 [32.33508],
                 [27.531239],
                 [32.380653]], dtype=float32)
         y_test
 In [9]:
         69
                 20.9
 Out[9]:
         295
                 28.6
         196
                 33.3
         368
                 50.0
         285
                 22.0
                 ....
         141
                 14.4
         77
                 20.8
         292
                 27.9
         311
                 22.1
         89
                 28.7
         Name: target, Length: 127, dtype: float64
In [10]:
         import matplotlib.pyplot as plt
         plt.plot(X_train,y_train)
         [<matplotlib.lines.Line2D at 0x2d000becfa0>,
Out[10]:
          <matplotlib.lines.Line2D at 0x2d000bf9040>,
          <matplotlib.lines.Line2D at 0x2d000bf9160>,
          <matplotlib.lines.Line2D at 0x2d000bf9280>,
          <matplotlib.lines.Line2D at 0x2d000bf93a0>,
          <matplotlib.lines.Line2D at 0x2d000bf94c0>,
          <matplotlib.lines.Line2D at 0x2d000bf95e0>,
          <matplotlib.lines.Line2D at 0x2d000bf9700>,
          <matplotlib.lines.Line2D at 0x2d000bf9820>,
          <matplotlib.lines.Line2D at 0x2d000bf9940>,
          <matplotlib.lines.Line2D at 0x2d000becfd0>,
          <matplotlib.lines.Line2D at 0x2d000bf9a60>,
          <matplotlib.lines.Line2D at 0x2d000bf9c70>]
```



```
In [11]: plt.plot(X_test,y_test)
```

Out[11]:



In []: