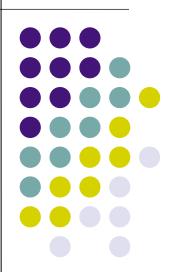
Chord

A scalable peer-to-peer look-up protocol for internet applications

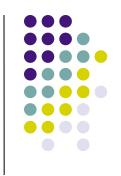


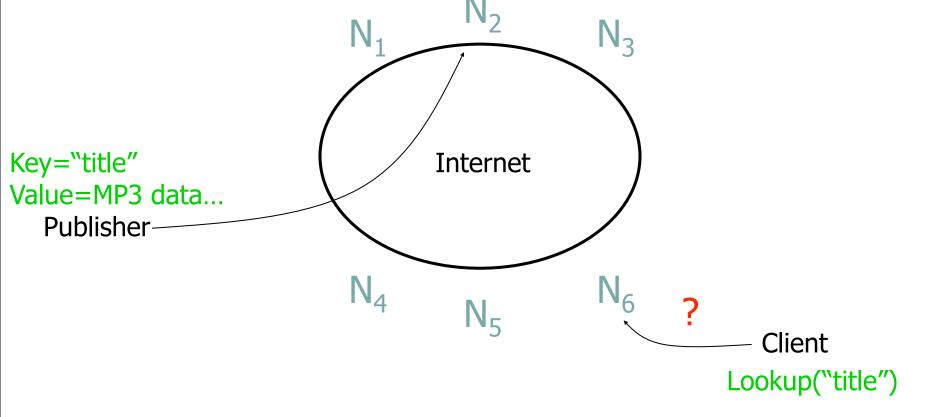
by Ion Stoica, Robert Morris, David Karger, M. Frans Kaashoek, Hari Balakrishnan

Overview

- Introduction
- The Chord Algorithm
 - Construction of the Chord ring
 - Localization of nodes
 - Node joins and stabilization
 - Failure of nodes
- Applications
- Summary
- Questions

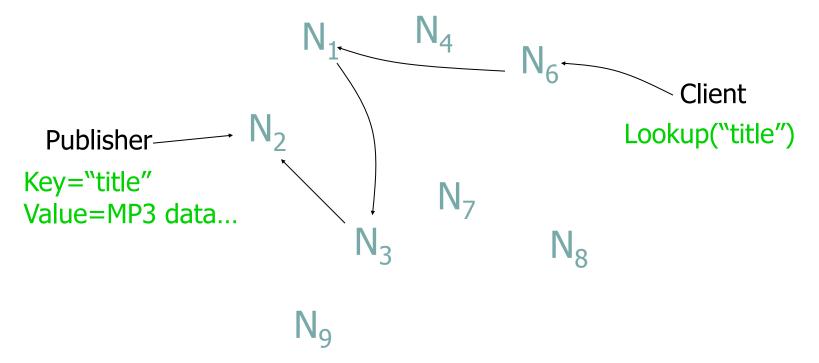
















- Problem addressed: efficient node localization
- Distributed lookup protocol
- Simplicity, provable performance, proven correctness
- Support of just one operation: given a key,
 Chord maps the key onto a node





- 3000 lines of C++ code
- Library to be linked with the application
- provides a lookup(key) function: yields the IP address of the node responsible for the key
- Notifies the node of changes in the set of keys the node is responsible for

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The Chord algorithm – Construction of the Chord ring



 use Consistent Hash Function assigns each node and each key an m-bit identifier using SHA 1 (Secure Hash Standard).

m = any number <u>big enough</u> to make collisions improbable

Key identifier = SHA-1(key)

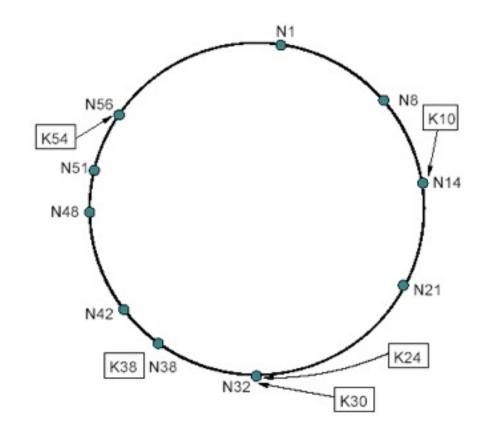
Node identifier = SHA-1(IP address)

- Both are uniformly distributed
- Both exist in the same ID space

The Chord algorithm – Construction of the Chord ring



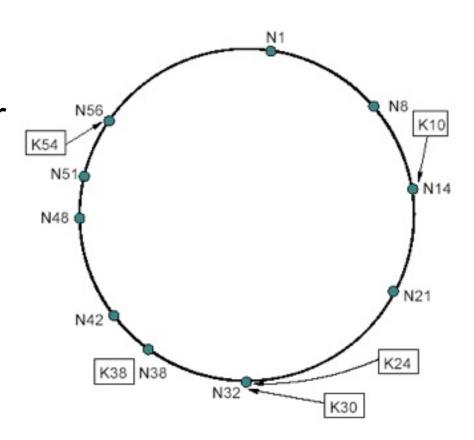
identifiers are arranged on a identifier circle modulo 2^m =>
 Chord ring



The Chord algorithm – Construction of the Chord ring

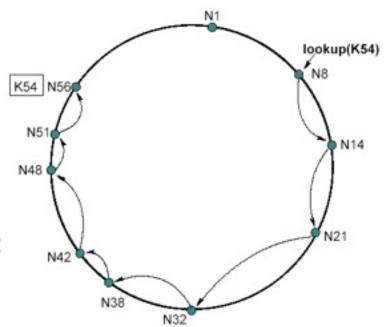


- a key k is assigned to the node whose identifier is equal to or greater than the key's identifier
- this node is called successor(k) and is the first node clockwise from k.





```
// ask node n to find the successor of id
n.find_successor(id)
if (id ∈ (n; successor])
    return successor;
else
    // forward the query around the
        circle
    return successor.find successor(id);
```



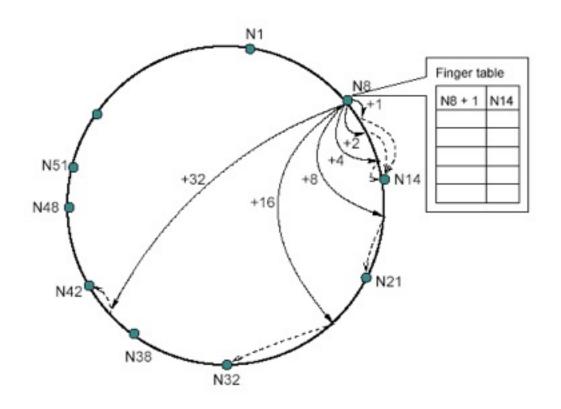
=> Number of messages linear in the number of nodes!



- Additional routing information to accelerate lookups
- Each node n contains a routing table with up to m entries (m: number of bits of the identifiers) => finger table
- ith entry in the table at node n contains the first node s that succeeds n by at least 2ⁱ⁻¹
- $s = successor (n + 2^{i-1})$
- s is called the ith finger of node n

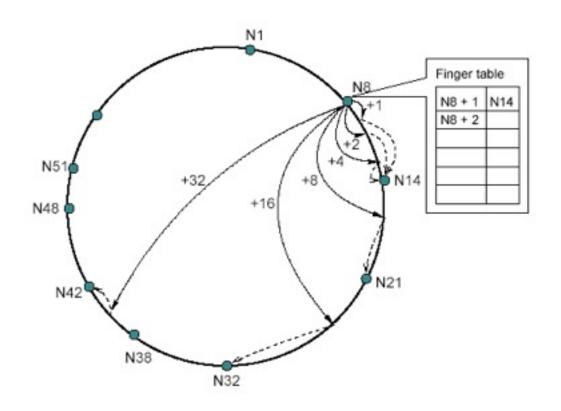


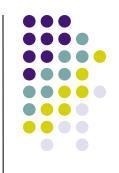
$$finger[i] =$$
 $successor(n + 2^{i-1})$



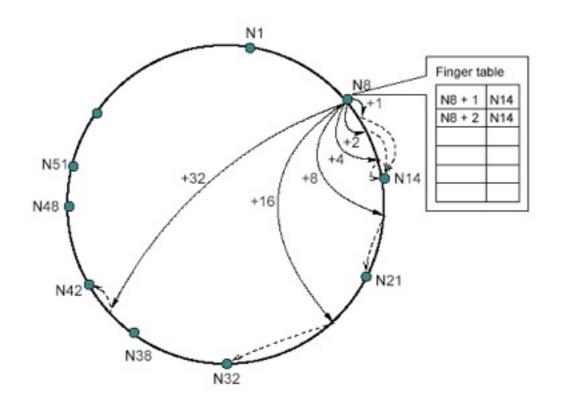


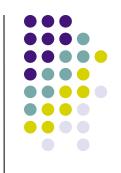
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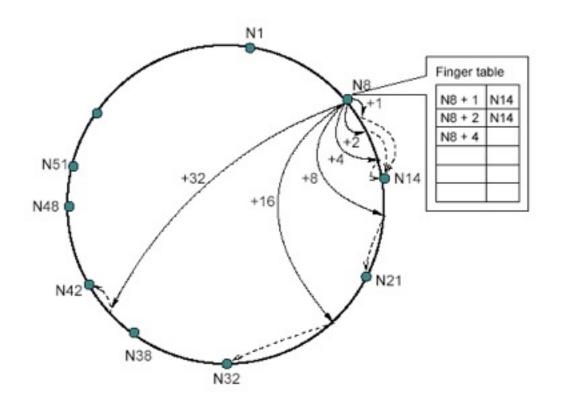


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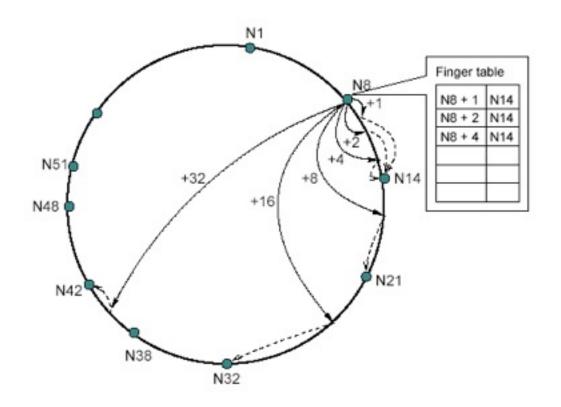


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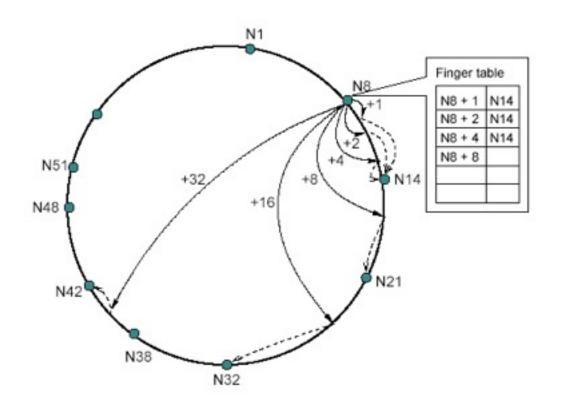


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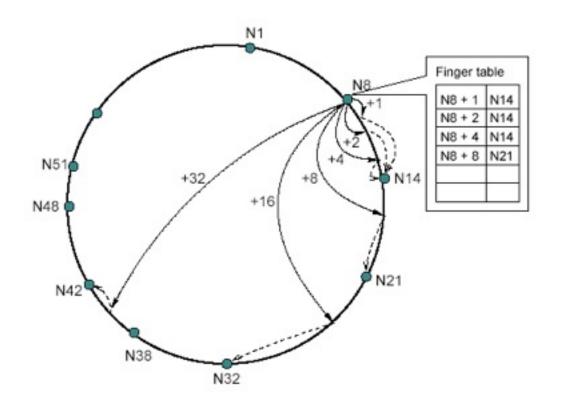


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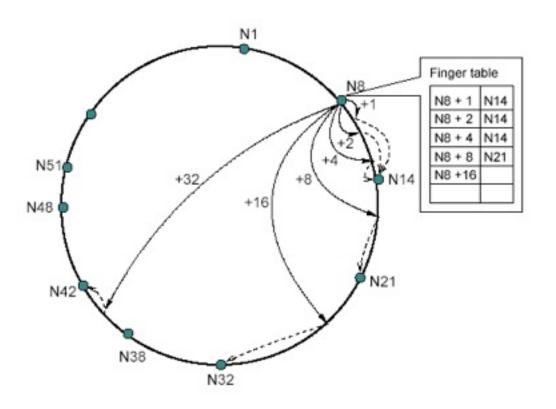


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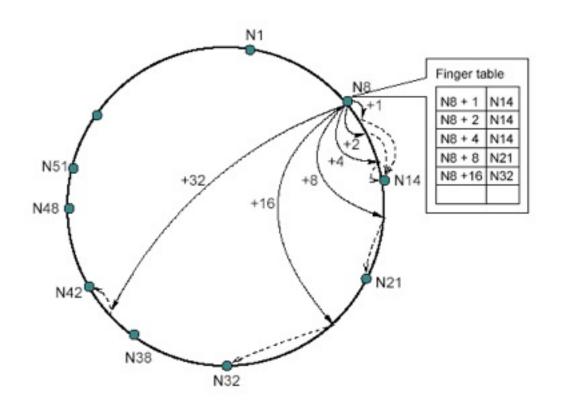


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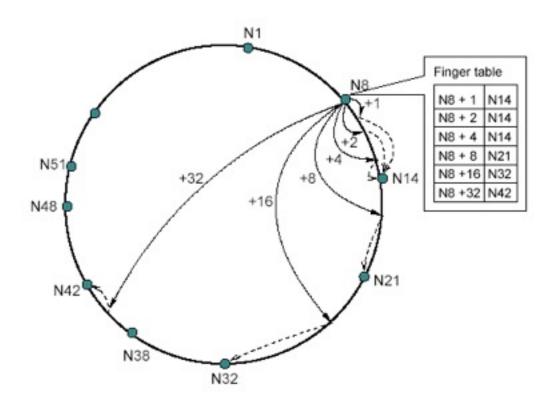


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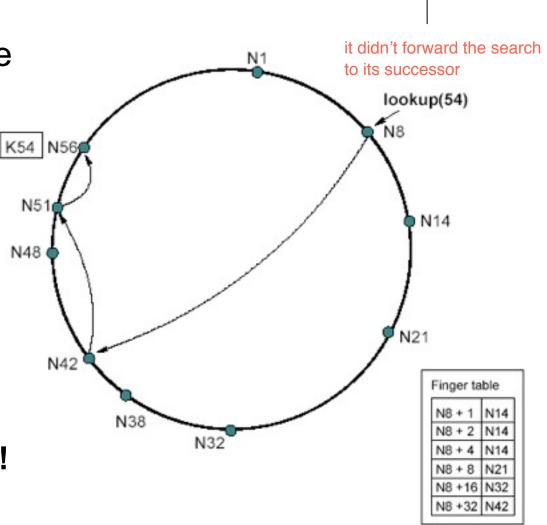


Important characteristics of this scheme:

- Each node stores information about only a small number of nodes (m)
- Each nodes knows more about nodes closely following it than about nodes further away
- A finger table generally does not contain enough information to directly determine the successor of an arbitrary key k

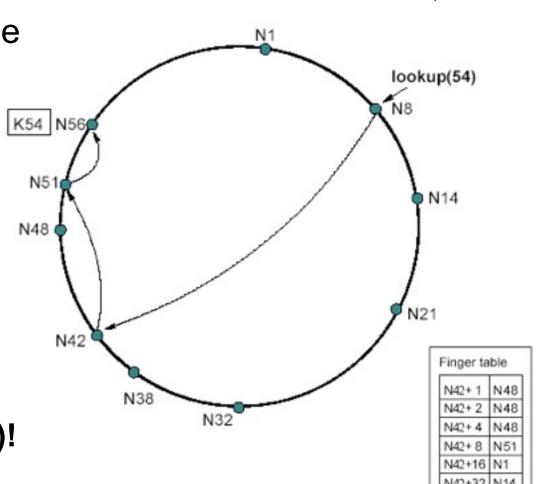
- Search in finger table for the nodes which most immediately precedes id
- Invoke find_successor from that node

=> Number of
 messages O(log N)!

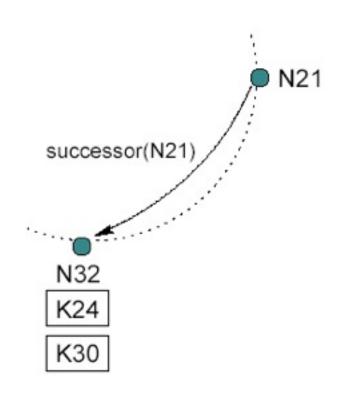


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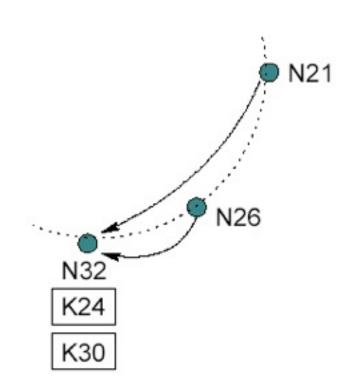
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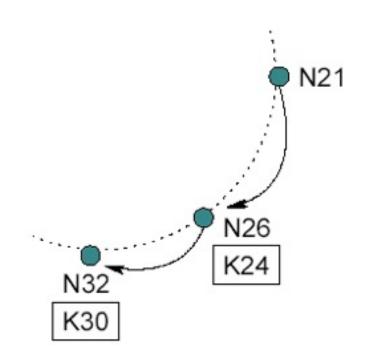


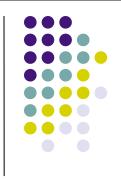












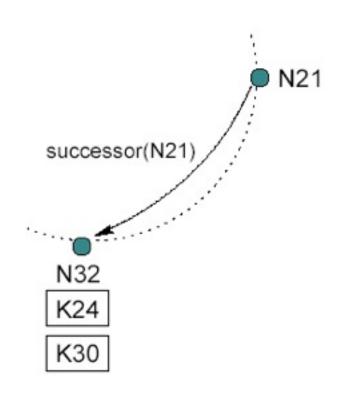
- To ensure correct lookups, all successor pointers must be up to date
- => stabilization protocol running periodically in the background
- Updates finger tables and successor pointers

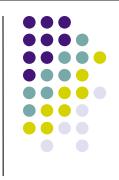


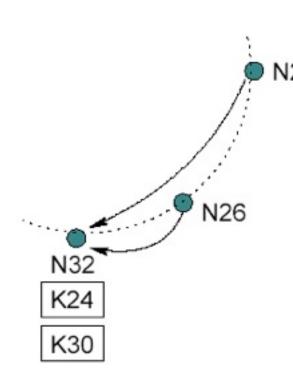
Stabilization protocol:

- Stabilize(): n asks its successor for its predecessor p and decides whether p should be n's successor instead (this is the case if p recently joined the system).
- Notify(): notifies n's successor of its existence, so it can change its predecessor to n
- Fix_fingers(): updates finger tables









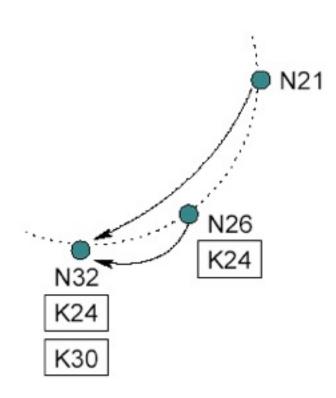
N26 joins the system

N26 acquires N32 as its successor

N26 notifies N32

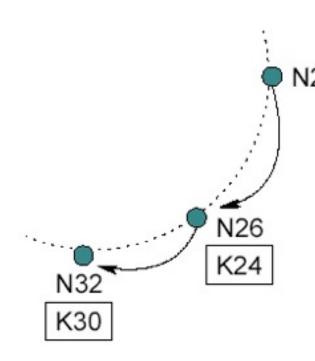
N32 acquires N26 as its predecessor





- N26 copies keys
- N21 runs stabilize() and asks its successor N32 for its predecessor which is N26.





N21 • N21 acquires N26 as its successor

N21 notifies N26 of its existence

N26 acquires N21 as predecessor

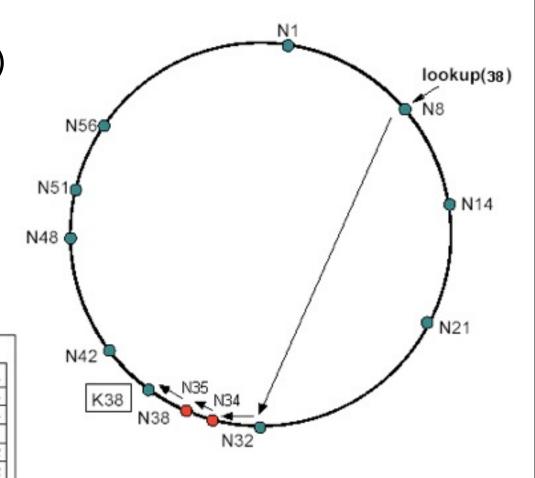
The Chord algorithm – Impact of node joins on lookups

Finger table



 All finger table entries are correct => O(log N) lookups

 Successor pointers correct, but fingers inaccurate => correct but slower lookups



The Chord algorithm – Impact of node joins on lookups



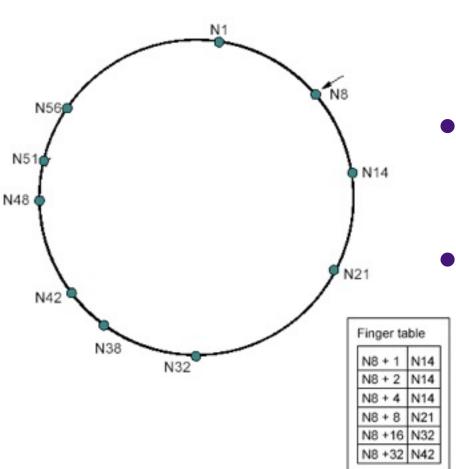
- Incorrect successor pointers => lookup might fail, retry after a pause
- But still correctness!

The Chord algorithm – Impact of node joins on lookups

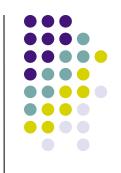


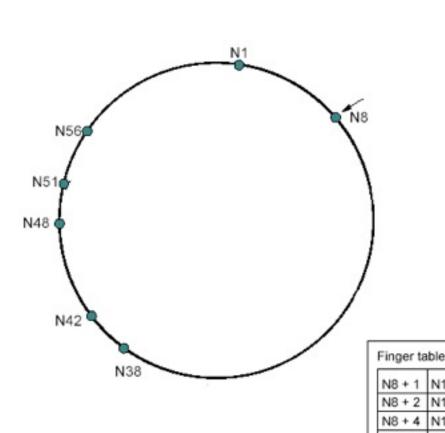
- Stabilization completed => no influence on performance
- Only for the negligible case that a large number of nodes joins between the target's predecessor and the target, the lookup is slightly slower
- No influence on performance as long as fingers are adjusted faster than the network doubles in size





- Correctness relies on correct successor pointers
- What happens, if N14, N21, N32 fail simultaneously?
- How can N8 acquire N38 as successor?





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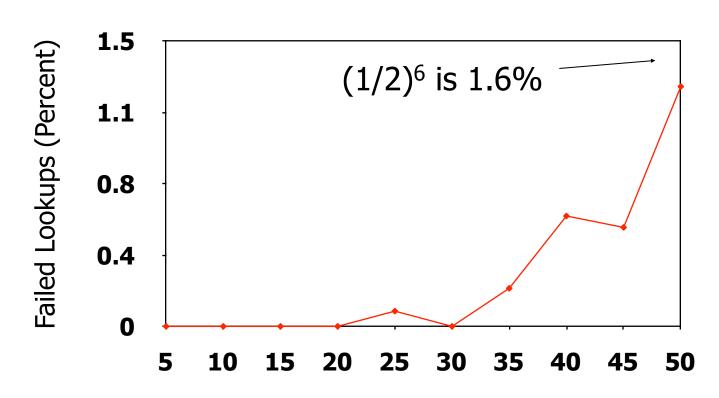
N8 +16 N32



- Each node maintains a successor list of size r
- If the network is initially stable, and every node fails with probability ½, find_successor still finds the closest living successor to the query key and the expected time to execute find_succesor is O(log N)
- Proofs are in the paper



Massive failures have little impact

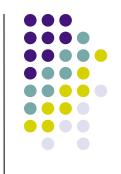


Failed Nodes (Percent)

Overview

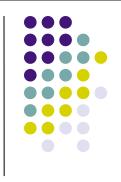
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Applications: Chord-based DNS



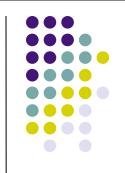
- DNS provides a lookup service keys: host names values: IP addresses
 Chord could hash each host name to a key
- Chord-based DNS:
 - no special root servers
 - no manual management of routing information
 - no naming structure
 - can find objects not tied to particular machines

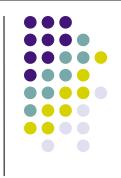




- Simple, powerful protocol
- Only operation: map a key to the responsible node
- Each node maintains information about O(log N) other nodes
- Lookups via O(log N) messages
- Scales well with number of nodes
- Continues to function correctly despite even major changes of the system

Questions?





Thanks!