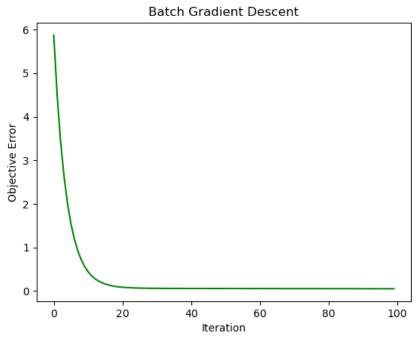
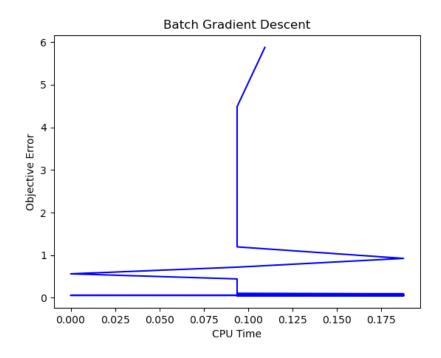
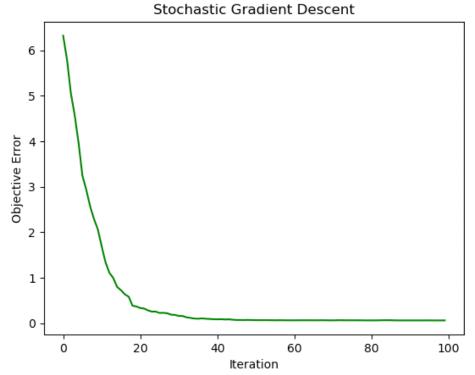
Problem 1:



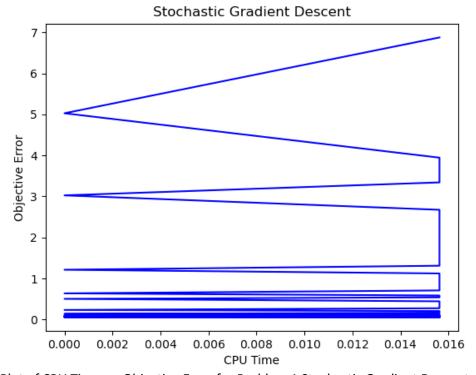
Plot of Batch Gradient Descent for Problem 1 (Iteration vs. Objective Error)



Plot of CPU Time vs. Objective Error for Problem 1 Batch Gradient Descent

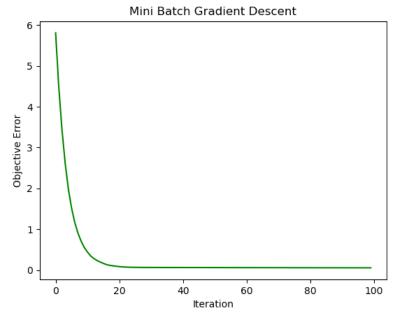


Plot of Stochastic Gradient Descent for Problem 1 (Iteration vs. Objective Error)

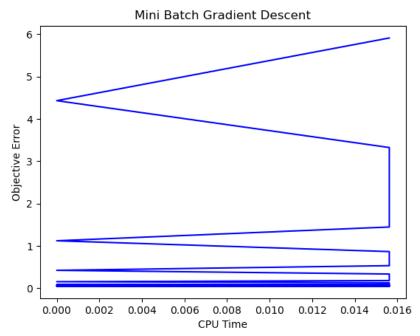


Plot of CPU Time vs. Objective Error for Problem 1 Stochastic Gradient Descent

Problem 1 Even More Continued:



Plot of Mini Batch Gradient Descent for Problem 1 (Iteration vs. Objective Error)



Plot of CPU Time vs. Objective Error for Problem 1 Mini Batch Gradient Descent

Problem 1 Discussion:

We see that in all cases we are generating a Theta vector that is clearly minimizing the objective error. Because this is gradient descent we expect to see the objective error decrease and it indeed does.

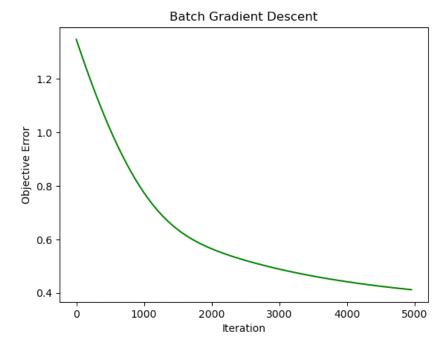
For Batch Gradient Descent we see that it becomes incredibly accurate in a short number of iterations but takes a lot of time between iterations

For Stochastic Gradient Descent we see that it does become quite accurate but not as accurate as Batch Gradient Descent. But the per iteration cost/time is incredibly small

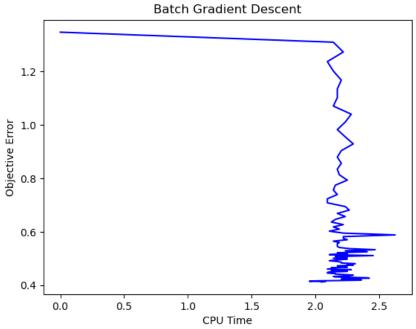
For Mini Batch Gradient Descent we have a happy medium between the 2. It minimizes the objective error quickly without sacrificing too much time for iterations but is still not as fast as Stochastic Gradient Descent or as accurate as Batch Gradient Descent.

The linear regression convergence theory holds

Problem 2:

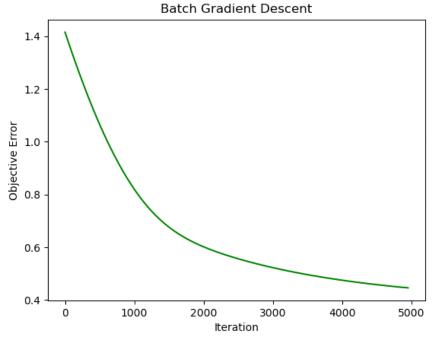


Plot of Batch Gradient Descent for Problem 2 (Iteration vs. Objective Error) With $\lambda=0$

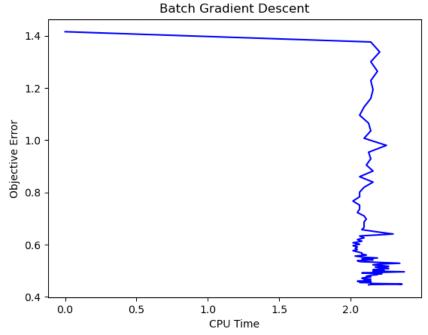


Plot of CPU Time vs. Objective Error for Problem 2 Batch Gradient Descent With $\lambda=0$

Problem 2 Continued:



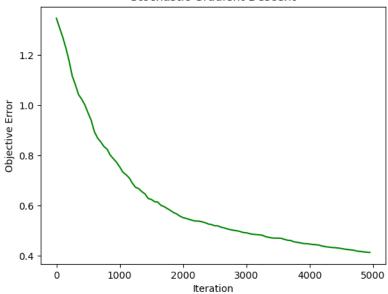
Plot of Batch Gradient Descent for Problem 2 (Iteration vs. Objective Error) With $\lambda=0.01\,$



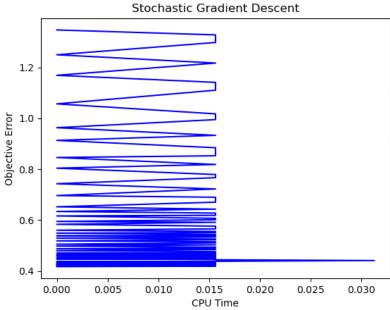
Plot of CPU Time vs. Objective Error for Problem 2 Batch Gradient Descent With $\lambda=0.01\,$

Problem 2 Even More Continued

Stochastic Gradient Descent



Plot of Stochastic Gradient Descent for Problem 2 (Iteration vs. Objective Error) With $\lambda=0$



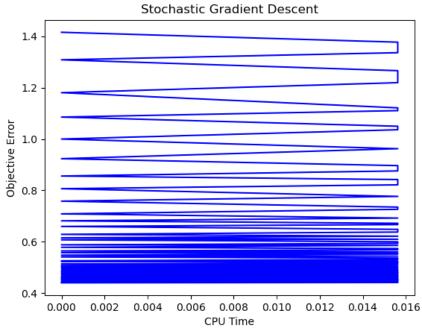
Plot of CPU Time vs. Objective Error for Problem 2 Stochastic Gradient Descent With $\lambda=0$

Problem 2 Even Further Continued:

Stochastic Gradient Descent 1.4 - 1.2 - 1.0 - 1

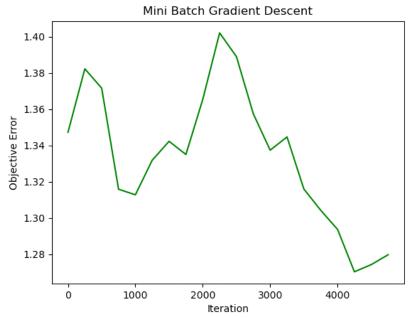
Plot of Stochastic Gradient Descent for Problem 2 (Iteration vs. Objective Error) With $\lambda=0.01\,$

Iteration

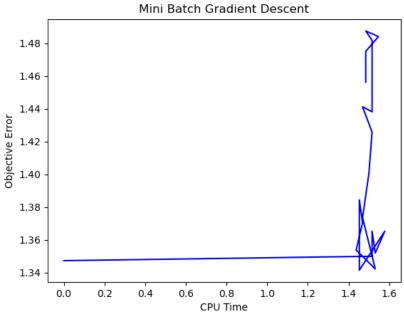


Plot of CPU Time vs. Objective Error for Problem 2 Stochastic Gradient Descent With $\lambda=0.01\,$

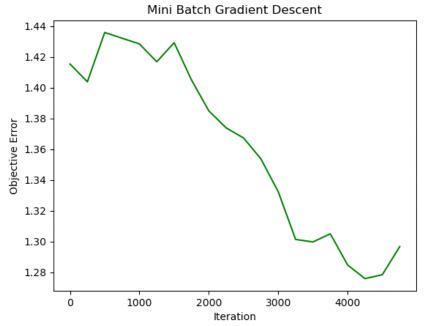
Problem 2 Even More Further Continued:



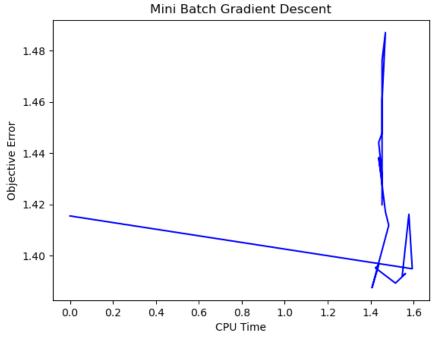
Plot of Mini Batch Gradient Descent for Problem 2 (Iteration vs. Objective Error) With $\lambda=0$



Plot of CPU Time vs. Objective Error for Problem 2 Mini Batch Gradient Descent With $\lambda=0$



Plot of Mini Batch Gradient Descent for Problem 2 (Iteration vs. Objective Error) With $\lambda=0.01$



Plot of CPU Time vs. Objective Error for Problem 2 Mini Batch Gradient Descent With $\lambda=0$

Problem 2 Discussion:

We see that in all cases (excluding Mini Batch this will be discussed) we are generating a Theta vector that is minimizing the objective error. Because this is gradient descent we expect to see the objective error decrease and it indeed does.

For Batch Gradient Descent we see that it becomes accurate in over a long time but takes a lot of time between iterations

For Stochastic Gradient Descent we see that it does become quite accurate but not as accurate as Batch Gradient Descent. But the per iteration cost/time is incredibly small.

For Mini Batch Gradient Descent we almost have a happy medium between the 2. Having the regularization constant in there makes the algorithm a lot more accurate than without It minimizes the objective error quickly without sacrificing too much time for iterations but is still not as fast as Stochastic Gradient Descent or as accurate as Batch Gradient Descent.

For this problem the logistics regression does hold as $iterations \rightarrow \infty$

But for all of these runs we are using many more iterations than Linear Regression. This can be due to a number of reasons. The first one being improper implementation of Mini Batch specifically, but the others as well.

For this problem I did not do any pre-processing to remove outlier data. Because the data set was so small, to my eye I was not able to see any outliers. However this may not be the case and removing those outliers would have made my algorithms more accurate. This was the case for Problem 1.

I also think that due to that inclusion of bad data the Mini Batch algorithm took a significant hit. When running Stochastic Gradient only 1 sample is chosen per iteration. That is much more unlikely to include bad data as compared to the Mini Batch choosing 50/350 samples. Because Mini Batch depends on solely what it randomly chooses the algorithm appears to randomly work and not work in my case.

```
#Problem 1 HW 2 Code
#Saaif Ahmed - 661925946 - ahmeds7
import pandas as pd
import numpy as np
import openpyxl
import matplotlib.pyplot as plt
from time import process time
#The cost function as defined in the homework
def linreg cost(output, feature, theta):
  x=0
  for i in range(len(output)):
     x = (\text{output}[i] - \text{np.dot}(\text{feature}[i], \text{theta}))**2
  x=x/(len(output))
  return x
#batch gradient descent update method by using matrices
#butter is just a placeholder term that came to mind
def update theta bgd(theta, lr, output, feature):
  butter = np.matmul(feature.transpose(),feature)
  butter = np.matmul(butter,theta.transpose())
  butter = butter - np.matmul(feature.transpose(),output.transpose())
  butter = (lr*2/len(output)) * butter
  butter = theta.transpose() - butter
  return butter.transpose()
#stochastic gradient descent. For 1 iteration
#uniformly randomly chooses an entry in the feature matrix
#to update theta
def update theta sgd(theta, lr, output, feature, k):
  i=0
  while i <k
     index = np.random.randint(0,len(output),1)
     xn = feature[index]
     vn = output[index]
     test = (np.dot(theta, xn[0]) - yn)*xn[0]
     theta = theta - lr * test
     i+=1
  return theta
#Mini batch gradient descent. Uniformly randomly chooses 50
#samples of the whole dataset and performs gradient descent.
#Adapted to use the matrix methodology from batch gradient descent
def update theta mbgd(theta, lr, output, feature, k):
  index = \Pi
  index.append(np.random.randint(0,len(output),k))
  features = feature[index,:]
  features = features[0]
  outputs = []
  for i in index:
     outputs.append(output[i])
  outputs = np.array(outputs)[0]
  butter = np.matmul(features.transpose(),features)
  butter = np.matmul(butter,theta.transpose())
  butter = butter - np.matmul(features.transpose(),outputs.transpose())
```

```
butter = (lr*2/len(outputs)) * butter
  butter = theta.transpose() - butter
  return butter.transpose()
if name == ' main ':
  #control for deciding which operation to run
  operation = float(input("input the number you are doing (1.1, 1.2, 1.3): "))
  #beginning of parsing. Reads in Excel file. Gets rid of Date and Time columns
  df = pd.read excel('AirQualityUCI.xlsx')
  df = df.drop(['Date', 'Time'], axis=1)
  #inserts x^0 power column to the feature matrix
  df.insert(0,'col1',1)
  feature matrix = np.array(df)
  #Preprocessing begins
  bad index = []
  for i in range(len(feature matrix)):
     count = 0
     for j in range(len(feature matrix[i])):
       if(feature matrix[i][j] == -200):
          count += 1
     if count >= 2:
       bad index.append(i)
  #If a row has 2 or more -200 (bad sensors) in it remove that row
  feature matrix = np.delete(feature matrix,bad_index,0)
  #replacing the remaining -200 with 0
  for i in range(len(feature matrix)):
     for j in range(len(feature matrix[i])):
       if(feature matrix[i][j] == -200):
          feature matrix[i][j] =0
  #normalize the matrix by scaling by 1/1000
  #grab the benzene column and remove from feature matrix
  #make initial theta guess
  feature matrix = 1/\overline{1000} * feature_matrix
  output vector = feature matrix[:,4]
  feature matrix = np.delete(feature matrix,4, axis=1)
  theta = np.random.default rng(42).random((13))
  #Setup for plotting
  iteration index = []
  error =[]
  cpu = []
  #Run a number of iterations of Batch Gradient Descent
  if operation == 1.1:
     print("Running Problem 1 BGD")
     while i<100:
       t start = process time()
```

```
theta = update theta bgd(theta,0.01,output vector,feature matrix)
    iteration index.append(i)
    error.append(linreg cost(output vector, feature matrix, theta))
    t end = process time()
    cpu.append(t end-t start)
    i+=1
  plt.title("Batch Gradient Descent")
  print("Finished P1 BGD")
#Run a number of iterations of Stochastic Gradient Descent
elif operation == 1.2:
  print("Running Problem 1 SGD")
  while i<100:
    t start = process time()
    theta = update theta sgd(theta,0.01,output vector,feature matrix, 1)
    iteration index.append(i)
    error.append(linreg cost(output vector, feature matrix, theta))
    t end = process time()
    cpu.append(t end-t start)
    i+=1
  plt.title("Stochastic Gradient Descent")
  print("Finished P1 SGD")
#Run a number of iterations of Mini Batch Gradient Descent
elif operation == 1.3:
  print("Running Problem 1 MBGD")
  while i<100:
    t start = process time()
    theta = update theta mbgd(theta, 0.01, output vector, feature matrix, 50)
    iteration index.append(i)
    error.append(linreg cost(output vector,feature matrix,theta))
    t end = process time()
    cpu.append(t end-t start)
    i+=1
  plt.title("Mini Batch Gradient Descent")
  print("Finished P1 SGD")
#Finish plotting and output a graph
#plt.xlabel("Iteration")
plt.xlabel("CPU Time")
plt.ylabel("Objective Error")
#plt.plot(np.array(iteration index), np.array(error), color = "green")
plt.plot( np.array(cpu), np.array(error),color ="blue")
plt.show()
```

```
#Problem 2 HW 2 Code
#Saaif Ahmed - 661925946 - ahmeds7
import pandas as pd
import numpy as np
import openpyxl
import matplotlib.pyplot as plt
from time import process time
import math
#The cost function of log regression as defined in the homework
def logreg cost(feature, output, theta, lam):
  x = 0
  for i in range(len(output)):
     x += math.log(1+math.exp(-1*output[i]*np.dot(feature[i],theta)))
  x = x/len(output)
  x += (lam/2)*(np.linalg.norm(theta)**2)
  return x
#The batch gradient descent using the derived
#gradient of the loss equation in the homework
def logreg bgd(feature, output, theta, lr,lam):
  for i in range(len(theta)):
     sum = 0
     for j in range(len(output)):
       a = math.exp(-1*output[j] * np.dot(feature[j],theta))
       c = -1*output[i]*feature[i][i]
       sum += (a*c)/(a+1)
     sum = sum/len(output)
     sum = sum + (lam)*theta[i] * (1/len(output))
     theta[i] = theta[i] - (lr/len(output))*sum
  return theta
#stochastic gradient descent. Same derivative but
#chooses 1 sample of the data set randomly
def logreg sgd(feature, output, theta, lr, lam):
  index = np.random.randint(0,len(output))
  for i in range(len(theta)):
     sum = 0
     a = math.exp(-1*output[index] * np.dot(feature[index],theta))
     c = -1*output[index]*feature[index][i]
     sum += (a*c)/(a+1)
     sum = sum/len(output)
     sum = sum + lam*theta[i] * (1/len(output))
     theta[i] = theta[i] - lr*sum
  return theta
#uniformly chooses 50 random components to make a subset
#of the whole dataset and runs batch gradient descent on that subset
def logreg mbgd(feature, output, theta, lr, lam, k):
  index = \Pi
  index.append(np.random.randint(0,len(output),k))
  features = feature[index,:]
  features = features[0]
  outputs = []
```

```
for i in index[0]:
     outputs.append(output[i])
  for i in range(len(theta)):
     sum = 0
     for i in range(len(outputs)):
       a = math.exp(-1*outputs[j] * np.dot(features[j],theta))
       c = -1*output[j]*features[j][i]
       sum += (a*c)/(a+1)
     sum = sum/50
     sum = sum + (lam)*theta[i] * (1/50)
     theta[i] = theta[i] - (lr/50)*sum
  return theta
if name == ' main ':
  #parsing begins
  #deletes columns that are consistently 0
  #and adds in a colume of 1 to represent x^0
  df = pd.read csv('ionosphere.csv', header=None)
  df = df.drop(df.columns[[1]], axis=1)
  df.insert(0,'col1',1)
  #does the mapping of b \rightarrow -1
  # and g -> 1
  feature matrix = np.array(df)
  output vector = feature matrix[:,34]
  feature matrix = np.delete(feature matrix,34, axis=1)
  for i in range(len(output vector)):
     if output vector[i] == 'b':
       output vector[i] = -1
     elif output vector[i] == 'g':
       output vector[i] = 1
  #initial theta guess and running of iterations
  theta = np.random.default rng(42).random((34))
  i = 0
  iteration index = []
  error =[]
  cpu = []
  t_start = process time()
  while i < 5000:
     if(i \%250 == 0):
       print(i)
       iteration index.append(i)
       error.append(logreg cost(feature matrix,output vector,theta,0.01))
       t end = process time()
       cpu.append(t end-t start)
       t start = process time()
     #theta = logreg bgd(feature matrix,output vector,theta,1,0.01)
     #theta = logreg sgd(feature matrix,output vector,theta,1,0.01)
     theta = logreg mbgd(feature matrix,output vector,theta,1,0.01,50)
     i+=1
  #plot set up and output
  plt.title("Mini Batch Gradient Descent")
```

```
#plt.xlabel("Iteration")
plt.xlabel("CPU Time")
plt.ylabel("Objective Error")
#plt.plot(np.array(iteration_index), np.array(error), color ="green")
plt.plot( np.array(cpu), np.array(error), color = "blue")
plt.show()
```