Computer Science 2XC3: Final Project

This project will include a final report and your code. Your final report will have the following. You will be submitting .py (NOT *.ipynb) files for this final project.

- Title page
- Table of Content
- Table of Figures
- An executive summary highlighting some of the main takeaways of your experiments/analysis
- An appendix explaining to the TA how to navigate your code.

For each experiment, include a clear section in your lab report which pertains to that experiment. The report should look professional and readable.

PLEASE NOTE: This is the complete Part I and II. Complete Parts 1-5 in group. Part 6 needs to be completed individual. Please refer to the plagiarism policy in Syllabus.

Part 1: Single source shortest path algorithms

Part 1.1: In this part you will implement variation of Dijkstra's algorithm. It is a popular shortest path algorithm where the current known shortest path to each node is updated once new path is identified. This updating is called *relaxing* and in a graph with n nodes it can occur at most n-1 times. In this part implement a function dijkstra (graph, source, k) which takes the graph and source as an input and where each node can be relaxed on only k times where, 0 < k < N-1. This function returns a distance and path dictionary which maps a node (which is an integer) to the distance and the path (sequence of nodes).

<u>Part 1.2</u>: Consider the same restriction as previous and implement a variation of Bellman Ford's algorithm. This means implement a function bellman_ford(graph, source, k) which take the graph and source as an input and finds the path where each node can be relaxed only k times, where, 0 < k < N - 1. This function also returns a distance and path dictionary which maps a node (which is an integer) to the distance and the path (sequence of nodes).

<u>Part 1.3</u>: Design an experiment to analyze the performance of functions written in Part 1.1 and 1.2. You should consider factors like graph size, graph. density and value of k, that impact the algorithm performance in terms of its accuracy, time and space complexity.

Part 2: All-pair shortest path algorithm

Dijkstra's and Bellman Ford's are single source shortest path algorithms. However, many times we are faced with problems that require us to solve shortest path between all pairs. This means that the algorithm needs to find the shortest path from every possible source to every possible destination. For every pair of vertices u and v, we want to compute shortest path distance(u, v) and the second-to-last vertex on the shortest path previous(u, v). How would you design an all-pair shortest path algorithm for both positive edge weights and negative edge weights? Implement a function that can address this. Dijkstra has complexity $\Theta(E + VlogV)$, or $\Theta(V2)$ if the graph is dense and Bellman-Ford has complexity $\Theta(VE)$, or $\Theta(V3)$ if the graph is dense. Knowing this, what would you conclude the complexity of your two algorithms to be for dense graphs? Explain your conclusion in your report. You do not need to verify this empirically.

Part 3: A* algorithm

In this part, you will analyze and experiment with a modification of Dijkstra's algorithm called the A* (we will cover this algorithm in next lecture, but you are free to do your own research if you want to get started on it). The algorithm essentially, is an "informed" search algorithm or "best-first search", and is helpful to find best path between two given nodes. Best path can be defined by shortest path, best time, or least cost. The most important feature of A* is a heuristic function that can control it's behavior.

<u>Part 3.1</u>: Write a function A_Star (graph, source, destination, heuristic) which takes in a directed weighted graph, a sources node, a destination node, and a heuristic "function". Assume h is a dictionary which takes in a node (an integer), and returns a float. Your method should return a 2-tuple where the first element is a predecessor dictionary, and the second element is the shortest path the algorithm determines from source to destination. **This implementation should be using priority queue.**

<u>Part 3.2</u>: In your report explain the following:

- What issues with Dijkstra's algorithm is A* trying to address?
- How would you empirically test Dijkstra's vs A*?
- If you generated an arbitrary heuristic function (like randomly generating weights), how would Dijkstra's algorithm compare to A*?
- What applications would you use A* instead of Dijkstra's?

Part 4: Compare Shortest Path Algorithms

In this part, you will compare the performance of Dijkstra's and A* algorithm. While generating random graphs can give some insights about how algorithms might be performing, not all algorithms can be assessed using randomly generated graphs, especially for A* algorithm where heuristic function is important. In this part you will compare the performance of the two algorithms on a real-world data set. Enclosed are a set of data files that contain data on London Subway system. The data describes the subway network with about 300 stations, and the lines represent the connections between them. Represent each station as a node in a graph, and the edge between stations should exists if two stations are connected. To find weights of different edges, you can use latitude and longitude for each station to find the distance travelled between the two stations This distance can serve as the weight for a given edge. Finally, to compute the heuristic function, you can use the physical direct distance (NOT the driving distance) between the source and a given station. Therefore, you can create a hashmap or a function, which serves as a heuristic function for A*, takes the input as a given station and returns the distance between source and the given station.

Once you have generated the weighted graph and the heuristic function, use it as an input to both A* and Dijkstra's algorithm to compare their performance. It might be useful to check all pairs shortest paths, and compute the time taken by each algorithm for all combination of stations. Using the experiment design, answer the following questions:

- When does A* outperform Dijkstra? When are they comparable? Explain your observation why you might be seeing these results.
- What do you observe about stations which are 1) on the same lines, 2) on the adjacent lines, and 3) on the line which require several transfers?
- Using the "line" information provided in the dataset, compute how many lines the shortest path uses in your results/discussion?

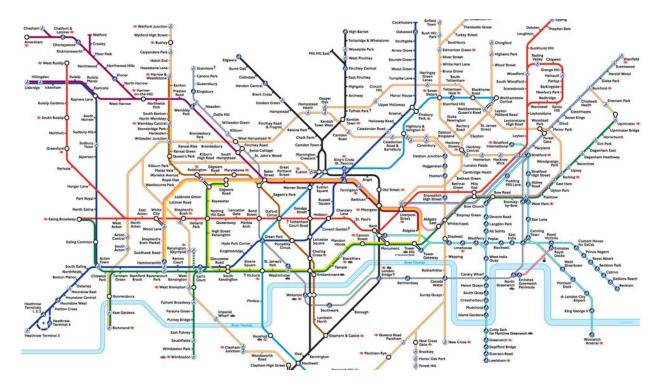


Figure 1: London Subway Map

Part 5: Organize your code as per UML diagram

Organize you code as per the below Unified Modelling Language (UML) diagram in Figure 2. Furthermore, consider the points listed below and discuss these points in a section labelled Part 4 in your report (where appropriate).

- Instead of re-writing A* algorithm for this part, treat the class from UML as an "adapter".
- Discuss what design principles and patterns are being used in the diagram.
- The UML is limited in the sense that graph nodes are represented by the integers. How would you alter the UML diagram to accommodate various needs such as nodes being represented Strings or carrying more information than their names.? Explain how you would change the design in Figure 2 to be robust to these potential changes.
- Discuss what other types of graphs we could have implement "Graph". What other implementations exist?

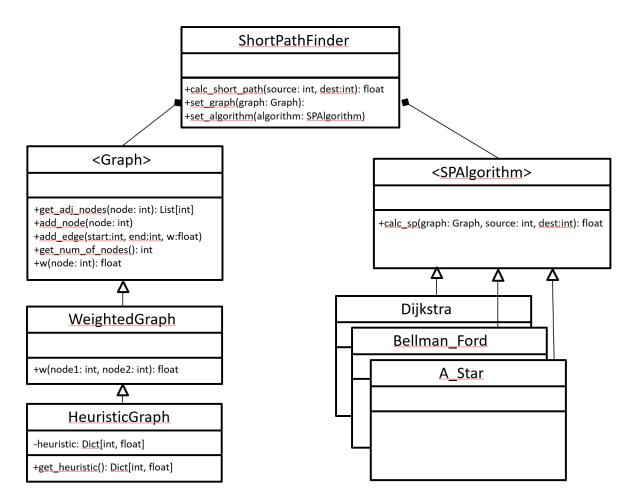


Figure 2: UML Diagram

Part 6: Unknown Algorithm (To work on Individually)

In the code posted with this document, you will find a *unknown()* function. It takes a graph as input. Do some reverse engineering. Try to figure out what exactly this function is accomplishing. You should explore the possibility of testing it on graphs with negative edge weights (create some small graphs manually for this). Determine the complexity of this function by running some experiments as well as inspecting the code. Given what this code does, is the complexity surprising? Why or why not?

Grade Breakup:

| Part | Submission Type | Points |
|--|-----------------|--------|
| Part 1: Single source shortest path algorithms | Group | 25 |
| Part 2: All-pair shortest path algorithm | Group | 15 |
| Part 3: A* algorithm | Group | 20 |
| Part 4: Compare Shortest Path Algorithms | Group | 30 |
| Part 5: Organize your code as per UML diagram | Group | 10 |
| Part 6: Unknown Algorithm | Individual | 50 |