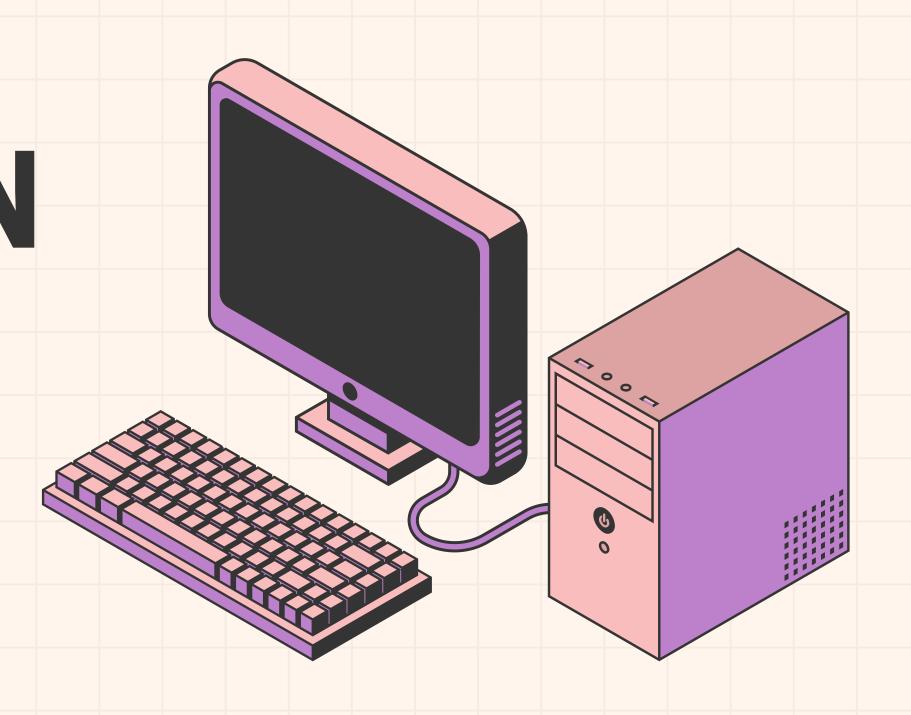
MNIST DIGIT CLASSIFICATION ACCELERATED WITH CUDA

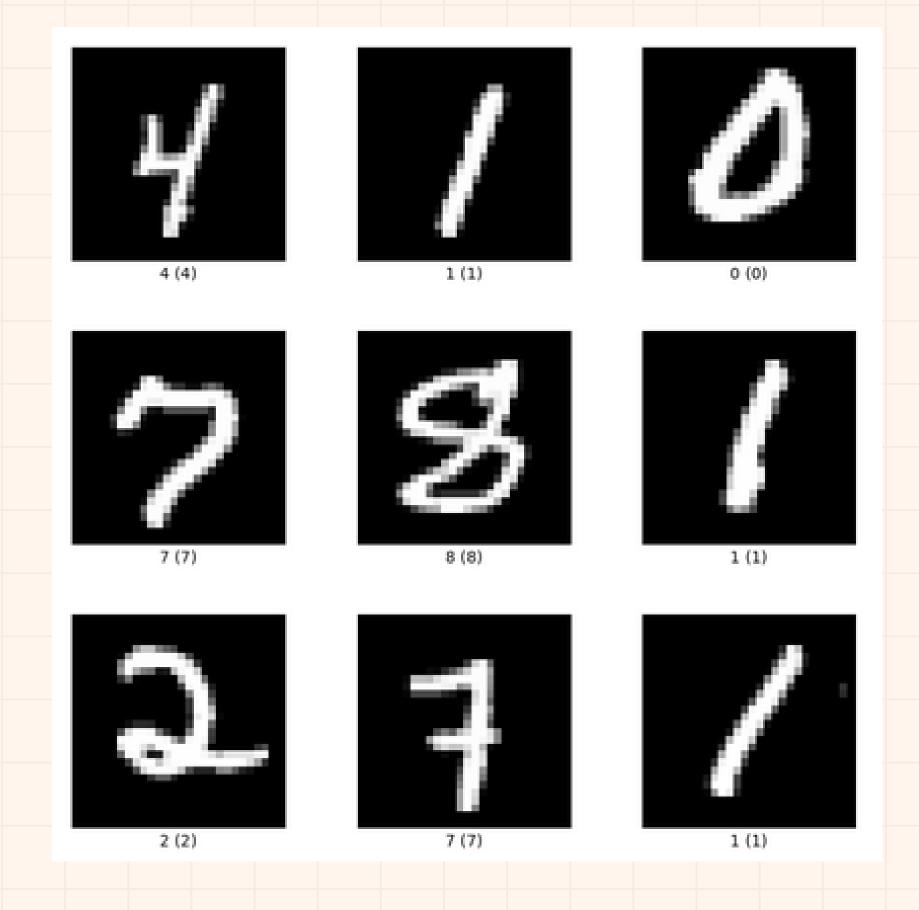
Sahrish Mustafa 22i0977 Aalyan Raza Kazmi 22i0833



MNIST

(Modified National Institute of Standards and Technology database)

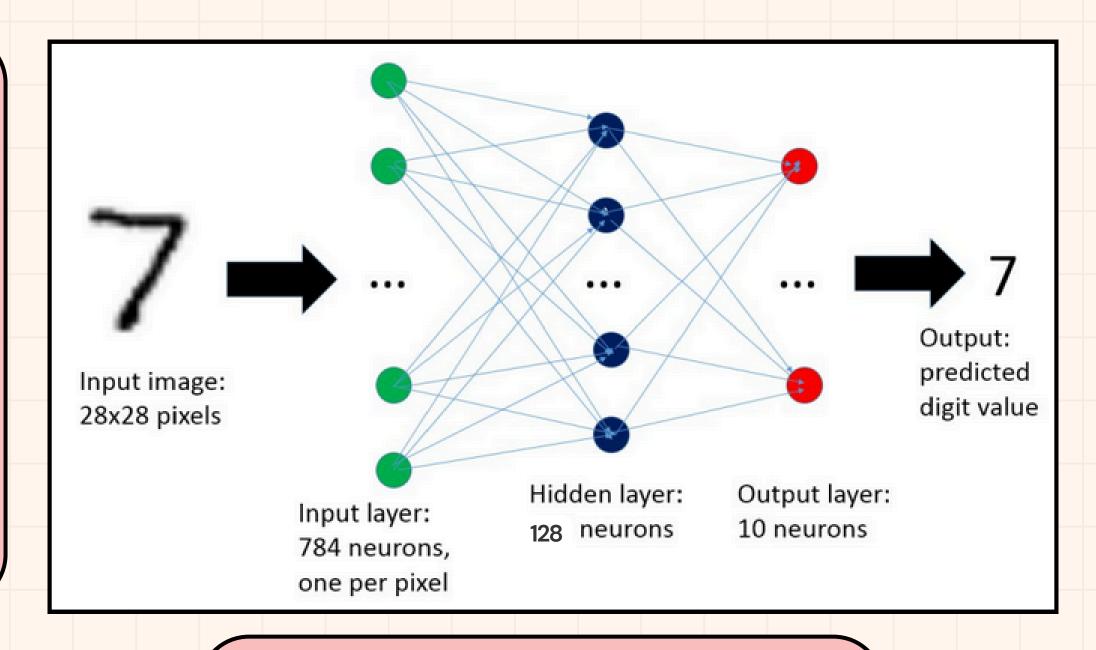
- Handwritten Digits
- 70,000 Images
- 28x28 pixels
- 10 classes (0-9)



NEURAL NETWORK - V1

INPUT LAYER

- Size: 784 neurons
- 28x28 pixel
 grayscale images.
 Flattened, each
 image becomes a
 784-dimensional
 vector.

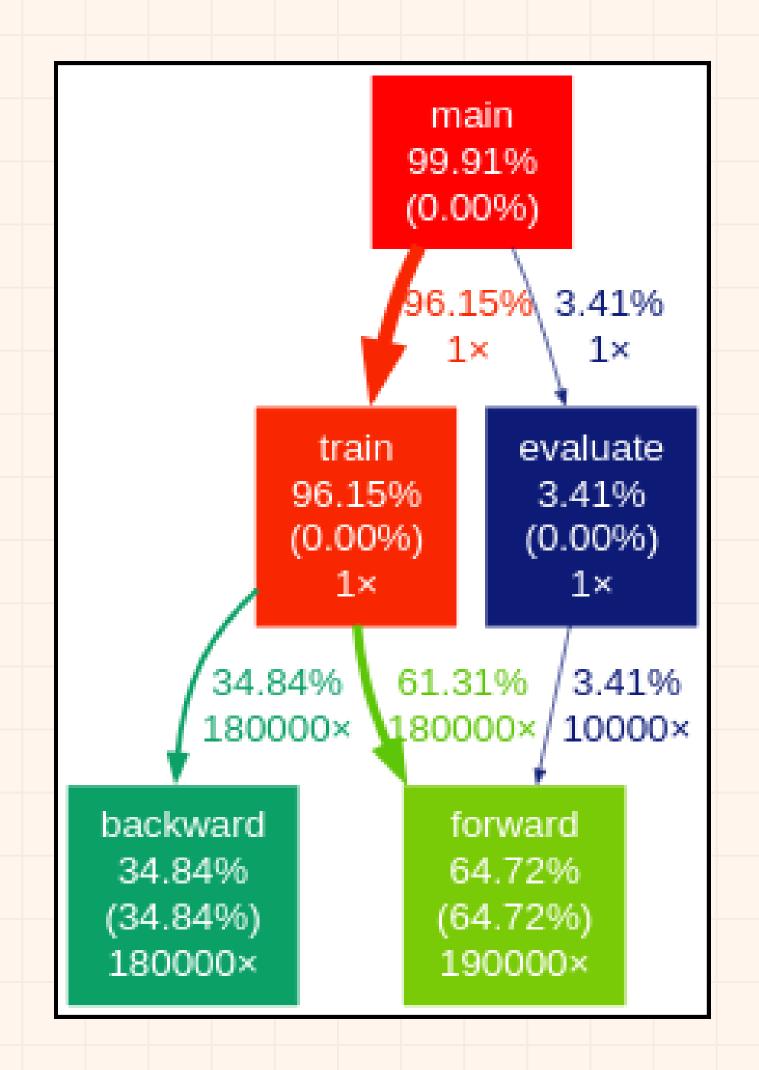


OUTPUT LAYER

- Size: 10 neurons
- Weights (W2): A matrix of size 10 x 128
- Biases (b2): A vector of size 10
- Activation Function:
 Softmax (raw outputs to probabilities)

HIDDEN LAYER

- Size: 128 neurons
- Weights (W1): A matrix of size 128 x 784
- Biases (b1): A vector of size 128
- Activation Function: ReLU (max(0, x))



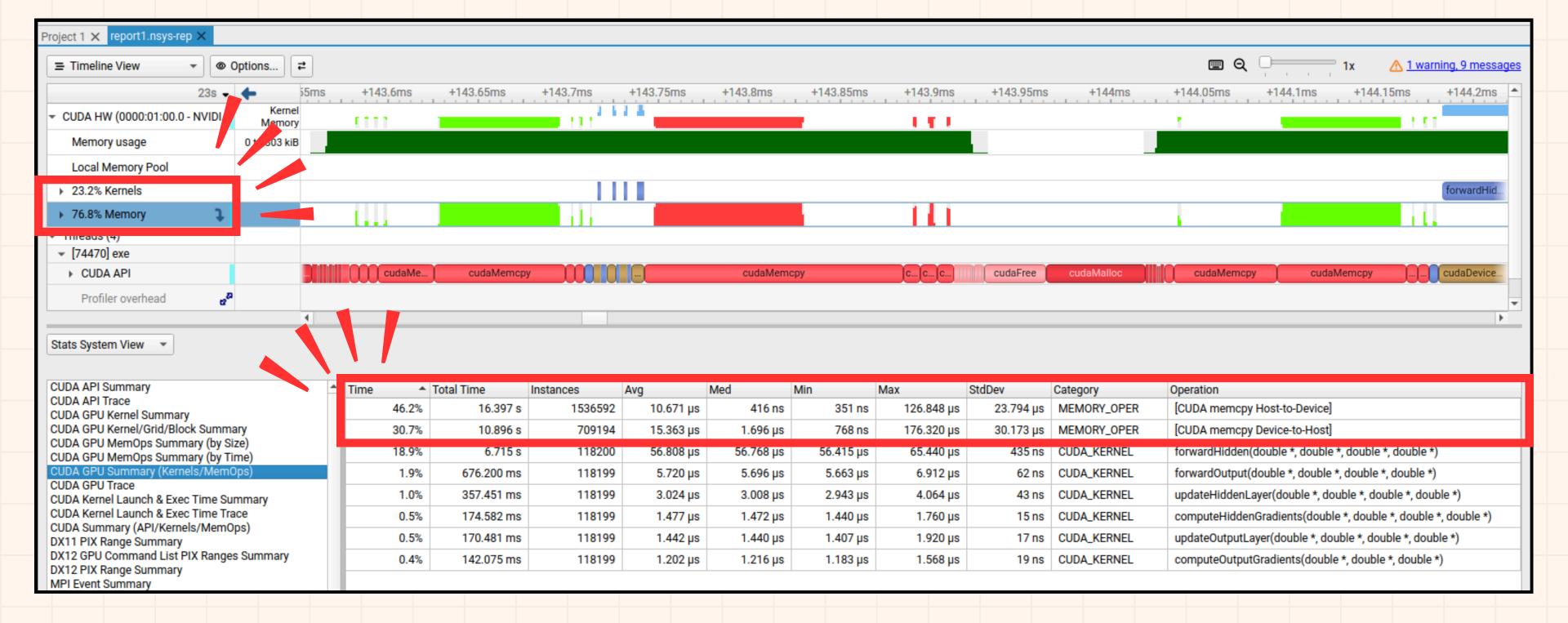
parallelize forward() and backward()
 by converting loops to kernels running
 on the GPU

FORWARD PROPAGATION

V1 V2

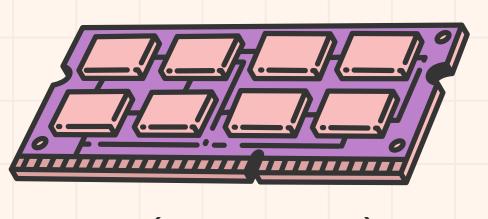
```
1. FUNCTION FORWARD PROPAGATION(INPUT):
      // COMPUTE HIDDEN LAYER
      FOR I IN RANGE(HIDDEN SIZE):
      SUM = BIAS1[I]
    FOR J IN RANGE(INPUT SIZE):
              SUM += W1[I][J] * INPUT[J]
          HIDDEN[I] = RELU(SUM)
7.
8.
      // COMPUTE OUTPUT LAYER
      FOR I IN RANGE(OUTPUT SIZE):
10.
          SUM = BIAS2[I]
11.
          FOR J IN RANGE(HIDDEN SIZE):
12.
              SUM += W2[I][J] * HIDDEN[J]
13.
          OUTPUT[I] = SUM // SOFTMAX APPLIED LATER
14.
```

```
1. KERNEL FORWARDHIDDEN(W1, B1, INPUT, HIDDEN):
       I = THREADIDX.X
      IF I < HIDDEN SIZE:
           SUM = B1[I]
          FOR J IN RANGE(INPUT SIZE):
               SUM += W1[I][J] * INPUT[J]
          HIDDEN[I] = RELU(SUM)
 9. KERNEL FORWARDOUTPUT(W2, B2, HIDDEN, OUTPUT):
       I = THREADIDX.X
10.
      IF I < OUTPUT SIZE:
11.
          SUM = B2[I]
12.
13.
          FOR J IN RANGE(HIDDEN_SIZE):
               SUM += W2[I][J] * HIDDEN[J]
14.
          OUTPUT[I] = SUM // SOFTMAX ON HOST
15.
```



- TOO MUCH MEMORY TRANSFER TIME!
- REDUCE MEMORY TRANSFER (DTH / HTD)

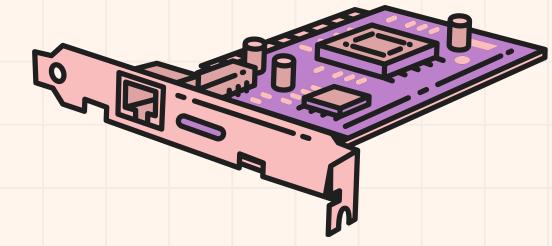




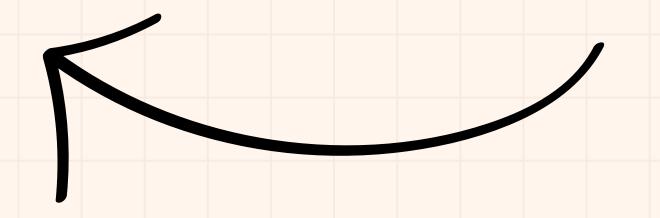
CPU RAM (HOST STORAGE)

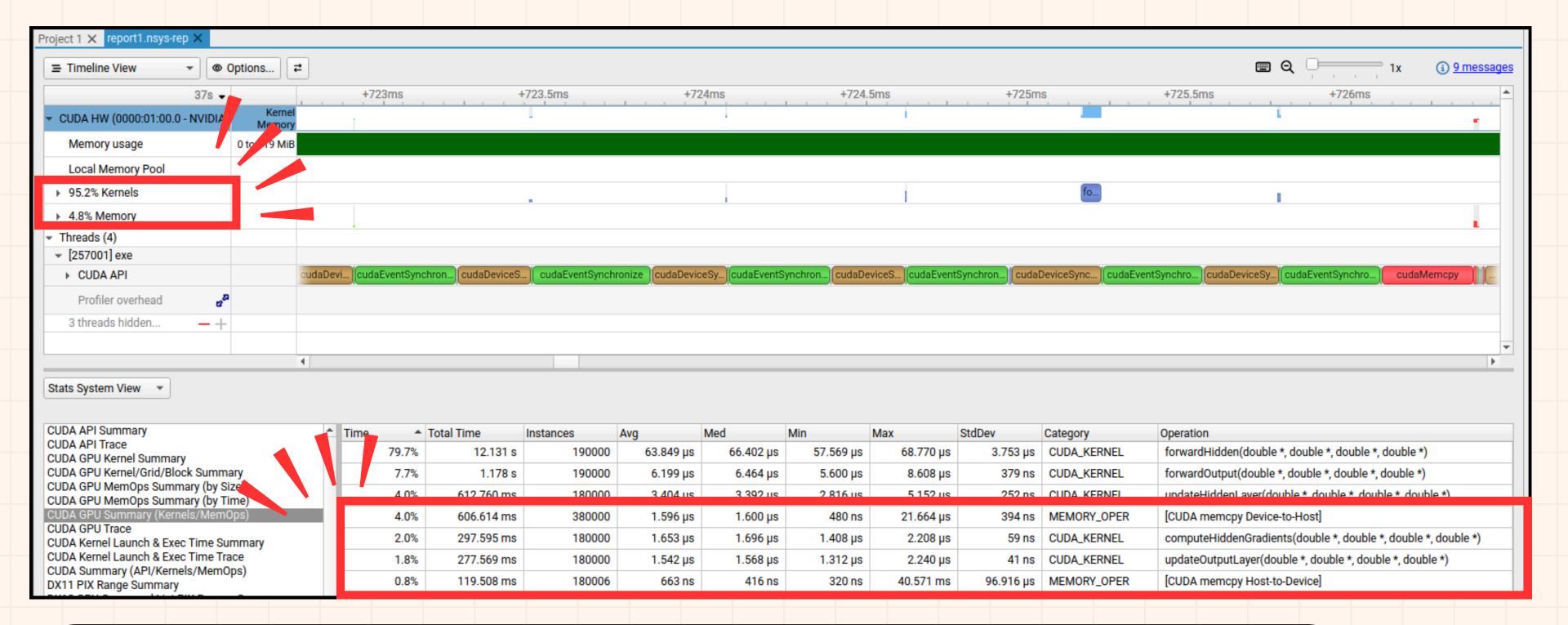
previously, we were copying each image from the host to the device 60,000 times per epoch during training.

Now, we copy the entire dataset in the beginning only once



GPU GLOBAL MEMORY (DEVICE STORAGE)





- > 13 SECONDS ON KERNELS
- ... SPEED UP KERNELS

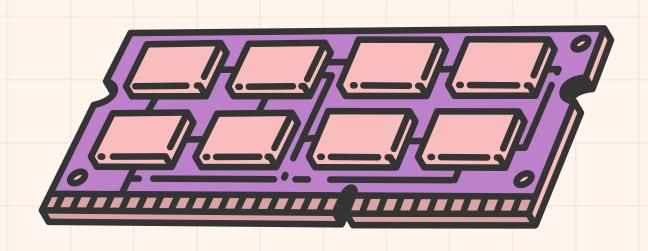
OPTIMIZED GPU VERSION - V3

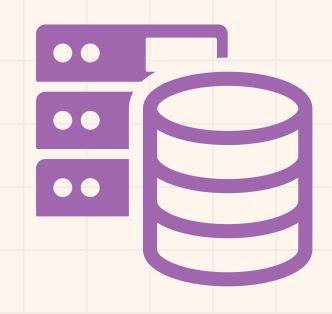
Optimizing launch configurations
 Shared memory
 Half-precision (FP16) datatype
 Coalesced memory access

LAUNCH CONFIGURATIONS

```
FORWARDHIDDEN<<<4, 32>>>
FORWARDOUTPUT<<<1, 64>>>
COMPUTEHIDDENGRADIENTS<<<16, 4>>>
UPDATEOUTPUTLAYER<<<OUTPUT_SIZE, HIDDEN_SIZE>>>
UPDATEHIDDENLAYER<<<HIDDEN_SIZE, INPUT_SIZE>>>
```

OPTIMIZED GPU VERSION - V3





SHARED MEMORY

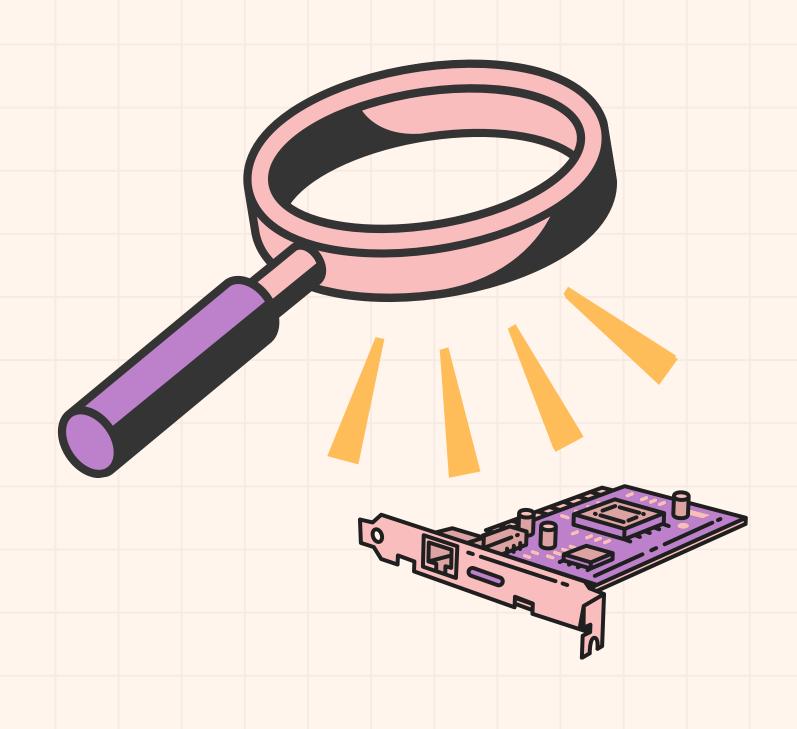
MEMORY COALESCION

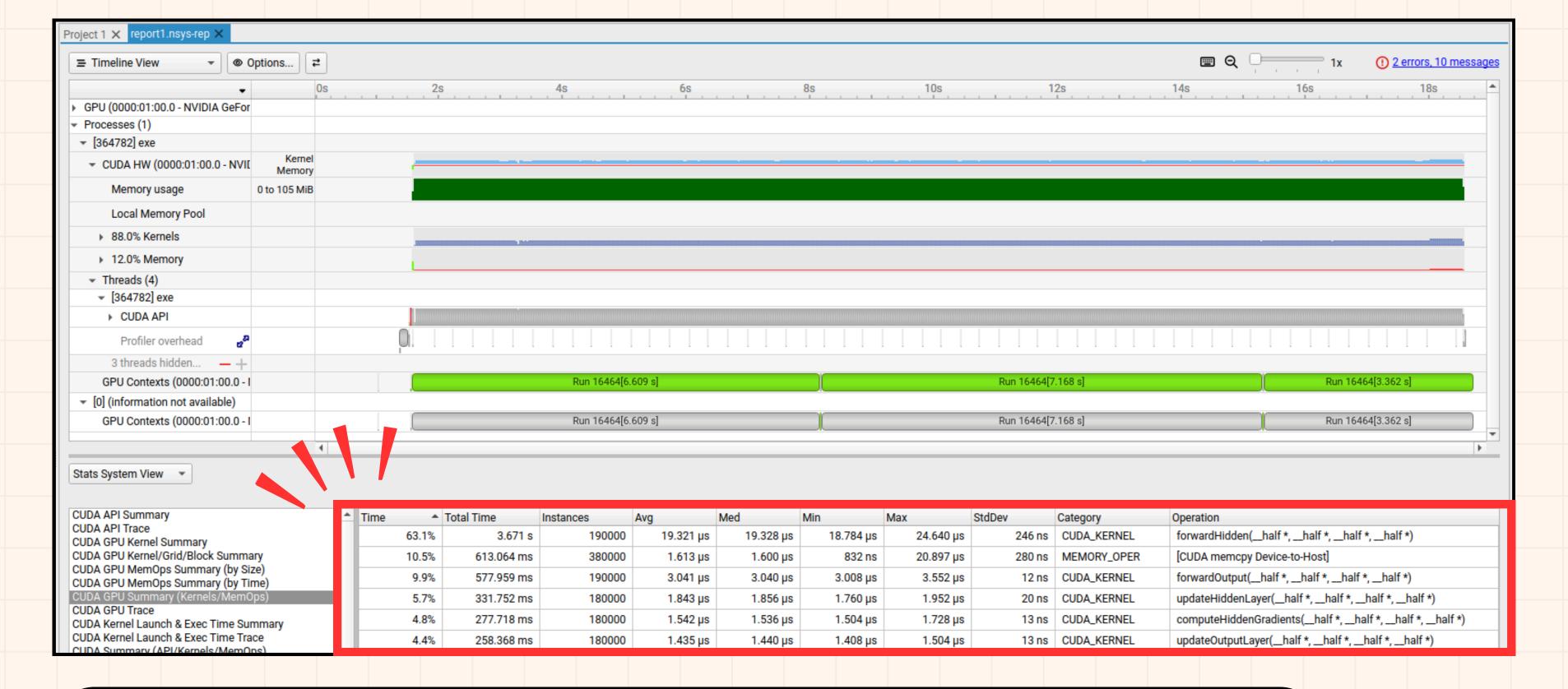
Shared memory is used to cache input data, hidden layer activations, and output gradients within each thread block. This reduces global memory access and speeds up forward and backward passes in the neural network.

The weight matrix is transposed to ensure memory coalescing during access by parallel threads. This improves global memory access efficiency, reducing latency during matrix multiplications.

FP 16 HALF PRECISION

- Uses half type to store inputs, weights, and activations.
- Functions like __float2half() and __half2float() are used to convert between 32-bit and 16-bit values.
- Reduces memory usage and enables faster computation on supported GPUs.
- Ideal for deep learning workloads where precision trade-offs are acceptable.

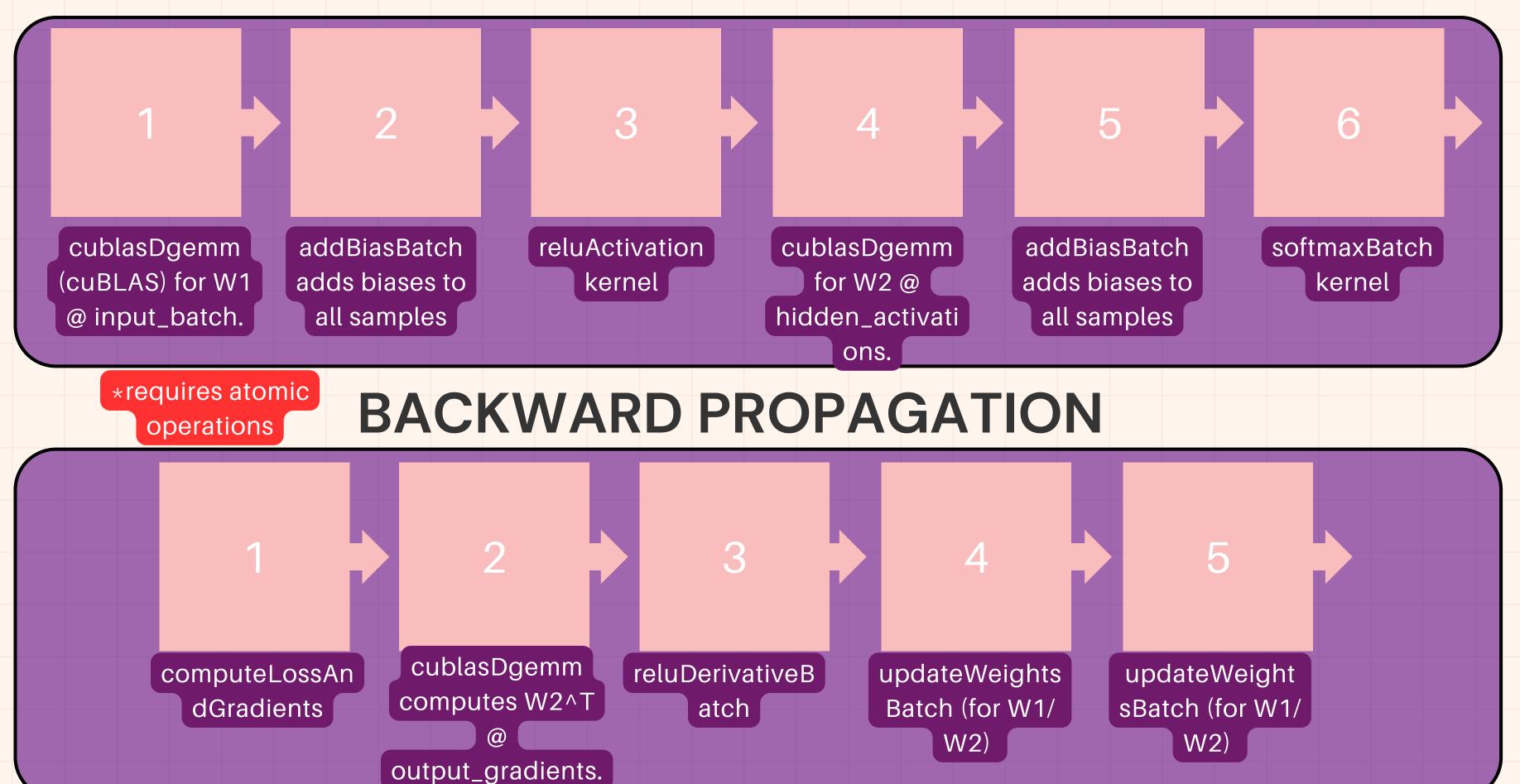


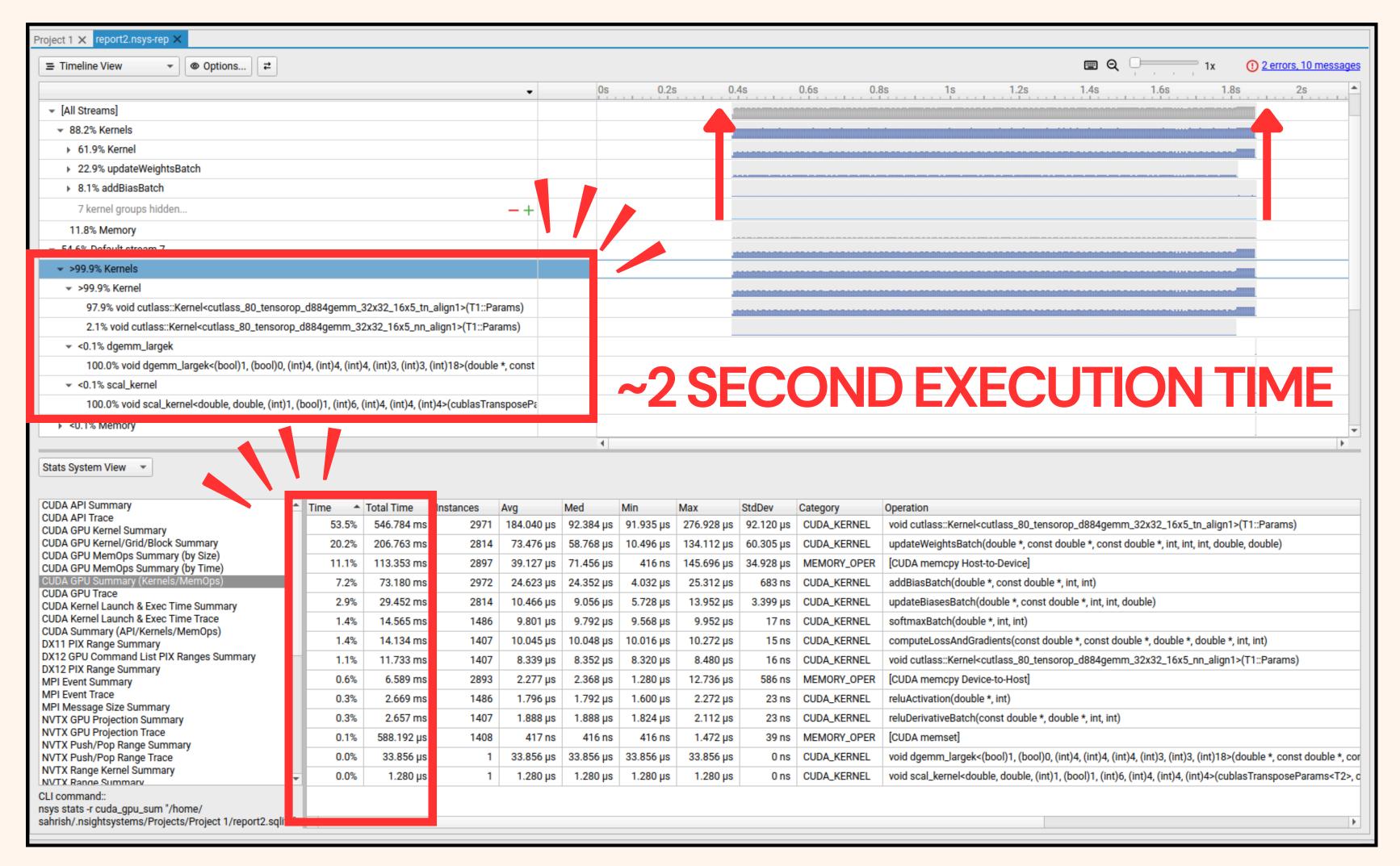


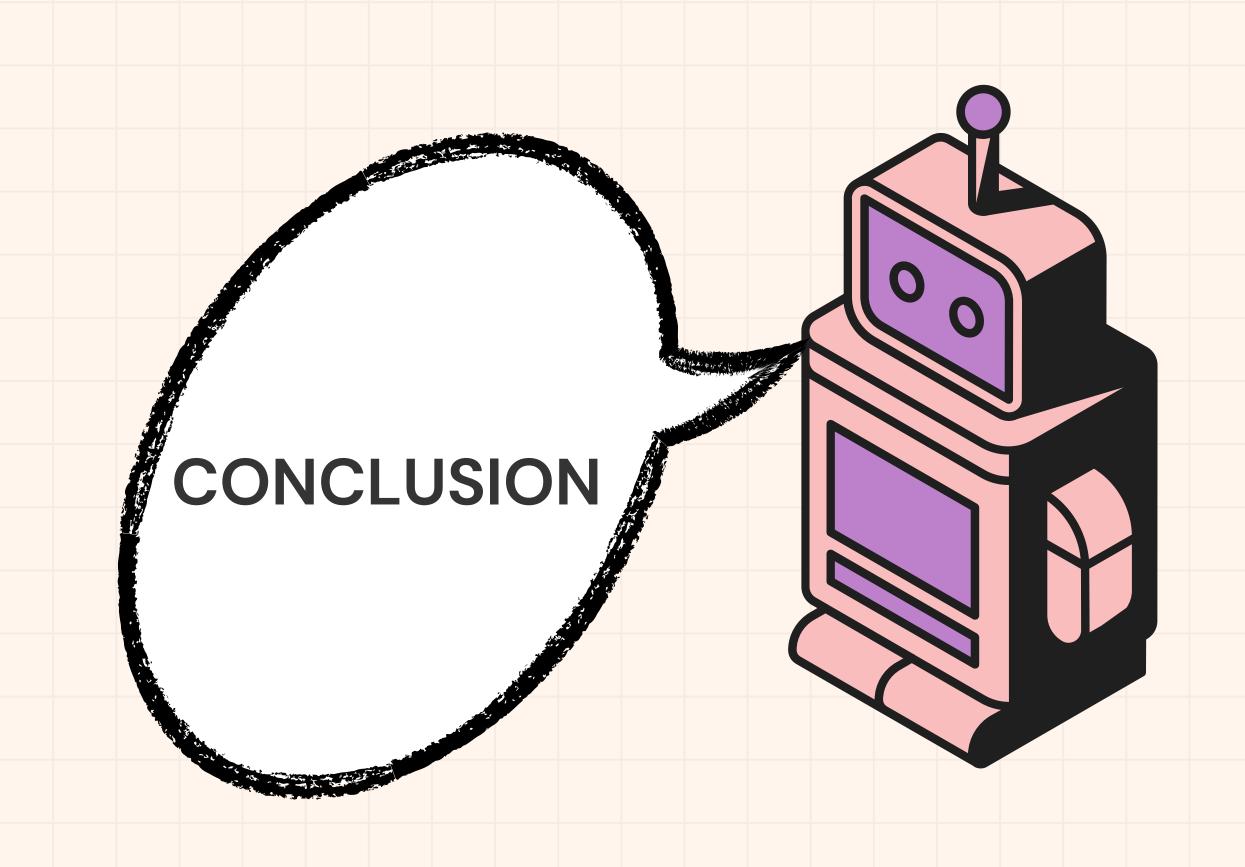
- BATCH PROCESSING
- TENSOR CORES

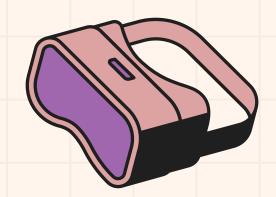
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FORWARD PROPAGATION









THANK YOU

