## **ASSIGNMENT:-**

Name:-AKASH KUMAR SAHU

ID-2019KUEC2026

**Aim-**Prove the following properties of Z-transform using MATLAB: Linearity, Scaling, Time-reversal, Right-Shift (shift in time domain), and Differentiation in Z-domain.

Matlab Simulation:-

```
1.Linearty
```

x1 =

```
clc;
clear all;
close all;
syms k x
f1 = 3*sin(k);
x1 = ztrans(f1, k, x)
f2 = 4*\cos(k);
x2 = ztrans(f2, k, x)
f = f1 + f2;
x1 = ztrans(f, k, x)
x2 = x1 + x2
Output:-
x1 =
(3*x*sin(1))/(x^2 - 2*cos(1)*x + 1)
x2 =
(4*x*(x - cos(1)))/(x^2 - 2*cos(1)*x + 1)
```

```
(3*x*sin(1))/(x^2 - 2*cos(1)*x + 1) + (4*x*(x - cos(1)))/(x^2 -
2*\cos(1)*x + 1
x2 =
(3*x*sin(1))/(x^2 - 2*cos(1)*x + 1) + (8*x*(x - cos(1)))/(x^2 - x^2)
2*\cos(1)*x + 1
2.Scaling:-
clc;
clear all;
close all;
syms k x l
z=I^k;
f1 = (z)*sin(k);
x1 = ztrans(f1, k, z)
f2 = \sin(k/l);
x2 = ztrans(f2, k, x)
Output:-
X1 =
(I^k*\sin(1))/(I^*(I^(2*k)/I^2 - (2*I^k*\cos(1))/I + 1))
X2 =
(x*sin(1/I))/(x^2 - 2*cos(1/I)*x + 1)
```

```
3.Timr Reversal:-
clc;
clear all;
close all;
syms k x l
f1 = I*sin(k);
x1 = ztrans(f1, k, x)
f2 = I*sin(-k);
x2 = ztrans(f2, k, x)
Output:-
X2 =
(1*x*sin(1))/(x^2 - 2*cos(1)*x + 1)
x2 =
-(1*x*sin(1))/(x^2 - 2*cos(1)*x + 1)
4.Differentation:=-
clc;
clear all;
close all;
syms k x l
f1 = I*sin(k);
```

```
x1 = ztrans(f1, k, x)
f2 = k*sin(k);
x2 = ztrans(f2, k, x)
Output:-
x1 =
(1*x*sin(1))/(x^2 - 2*cos(1)*x + 1)
x2 =
(x*sin(1)*(x^2 - 1))/(x^2 - 2*cos(1)*x + 1)^2
5. Right shifting:-
syms n z
m=2;
x1=3^(n-m)*heaviside(n-m);
Left=simplify(ztrans(x1,z))
x=3^n*heaviside(n);
X=ztrans(x,z);
Right=simplify((z^(-m))*X)
Output:-
Left =
(1/(z/3 - 1) + 1/2)/z^2
```

$$(3/(z-3)+1/2)/z^2$$