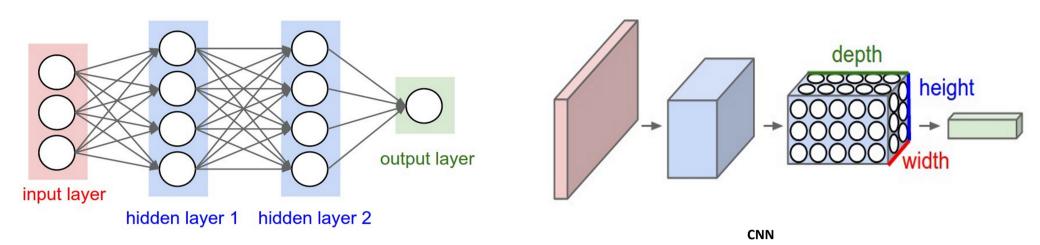
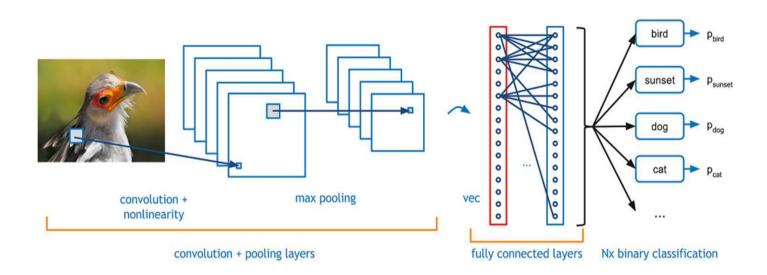
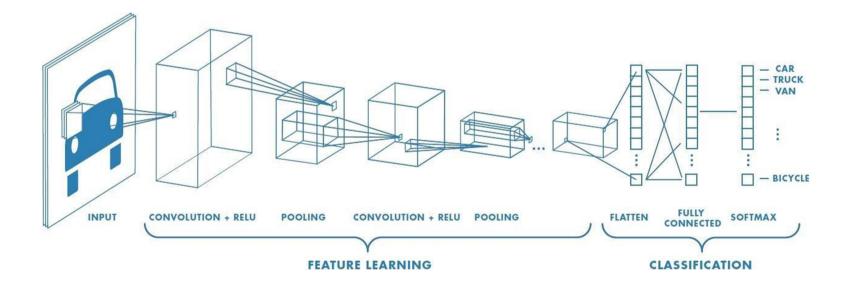
# **Architecture of CNN compared to Normal Neural Network**



**Basic Neural Network** 





## **Layers**

#### **Input Layer:**

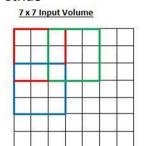
Input Tensor Size: [batch, in height, in width, in channels]

#### **Convolution Layer:**

**Filter size** = [filter height, filter width, in channels, out channels]

**Depth** = out channels = Number of Filters

Stride

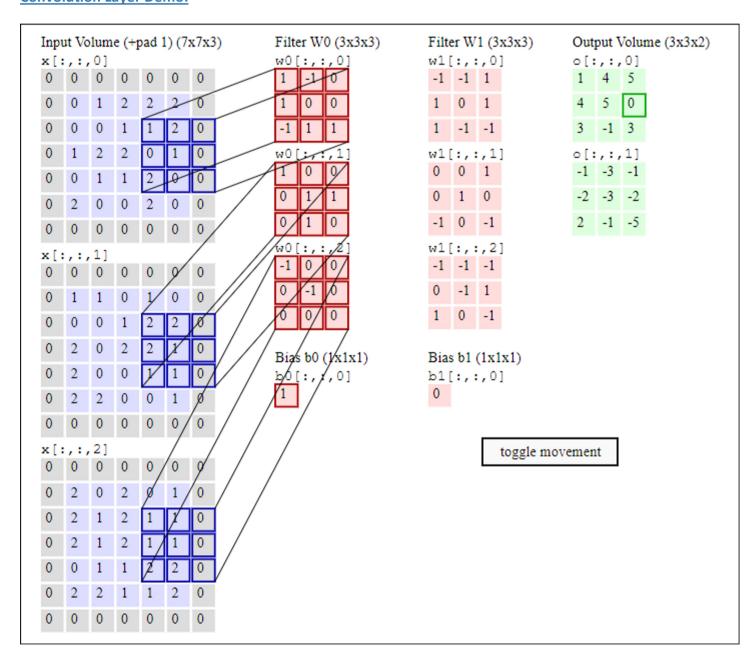


3 x 3 Output Volume



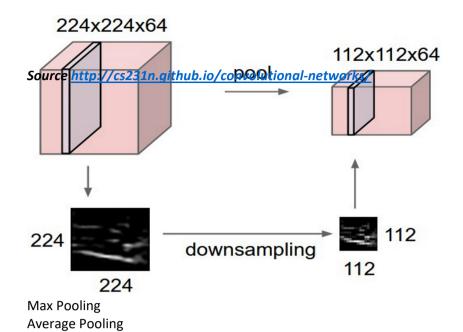
Zero-Padding: Parameter Sharing:

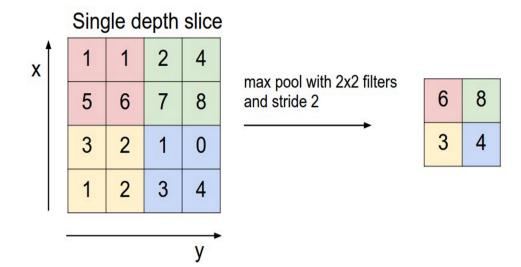
**Convolution Layer Demo:** 



### **Pooling Layer:**

spatial size of the representation to reduce the amount of parameters and computation in the network, and hence to also control over fitting





## **Fully Connected layer:**

Dense Layer RELU

#### **Layer Pattern**

INPUT -> [[CONV -> RELU]\*N -> POOL?]\*M -> [FC -> RELU]\*K -> FC